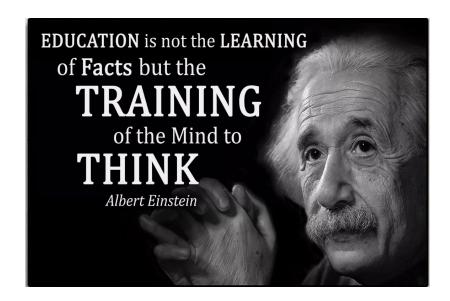
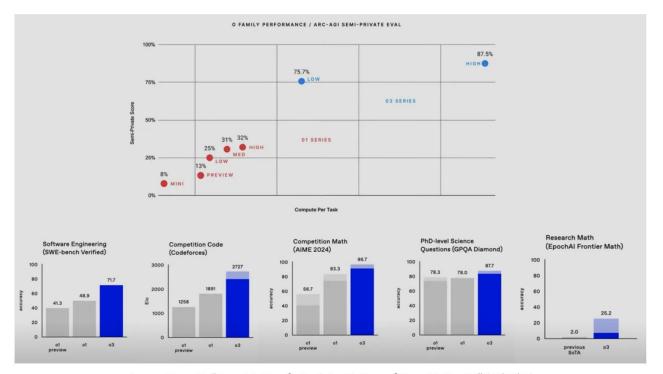
## Teaching LLMs to Think

Tianbing Xu Jan. 2025



#### O3 Results in Math, Coding, Science, SWE, AGI (OpenAl 2024)



Source: OpenAI, "OpenAI o3 and o3-mini—12 Days of OpenAI: Day 12" (12/20/24)

## What is Reasoning for Al?



Image Generated by AI (ChatGPT)

#### **Reasoning = Search** (Rationale Space) + **Learning** (World Model)

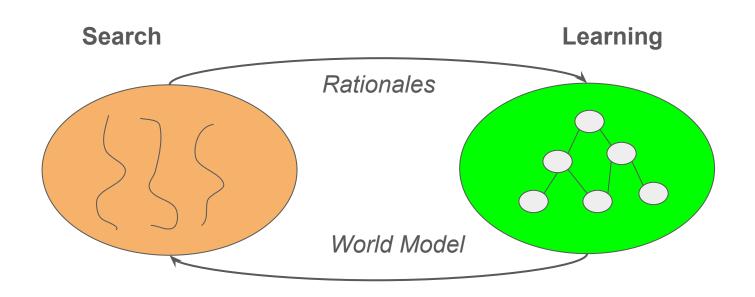
#### Search

Guided by the World Model, search *explores* rationales by navigating the Chain-of-Thoughts (CoT) space or sampling from the probabilistic distribution of rationales to generate plausible explanations.

#### Learning

The World Model **evolves** by refining its understanding based on the generated rationales, improving its ability to guide future searches effectively.

#### Inter-play of Search and Learning



# Rationales (Chain-of-Thoughts)

## Chain-of-Thoughts (Wei et. al. NeurIPS 2022)

#### Standard Prompting

#### **Model Input**

Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now?

A: The answer is 11.

Q: The cafeteria had 23 apples. If they used 20 to make lunch and bought 6 more, how many apples do they have?

#### Chain-of-Thought Prompting

#### Model Input

Q: Roger has 5 tennis balls. He buys 2 more cans of tennis balls. Each can has 3 tennis balls. How many tennis balls does he have now?

A: Roger started with 5 balls. 2 cans of 3 tennis balls each is 6 tennis balls. 5 + 6 = 11. The answer is 11.

Q: The cafeteria had 23 apples. If they used 20 to make lunch and bought 6 more, how many apples do they have?

#### **Model Output**

A: The answer is 27.



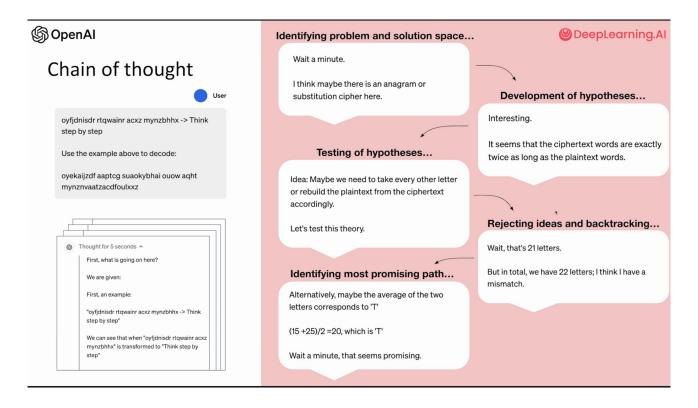
#### **Model Output**

A: The cafeteria had 23 apples originally. They used 20 to make lunch. So they had 23 - 20 = 3. They bought 6 more apples, so they have 3 + 6 = 9. The answer is 9.

## O1 Chain of Thoughts (OpenAl 2024)

Through reinforcement learning, o1 learns to hone its chain of thought and refine the strategies it uses. It learns to recognize and **correct its mistakes**. It learns to **break down tricky steps into simpler ones**. It learns to **try a different approach** when the current one isn't working.

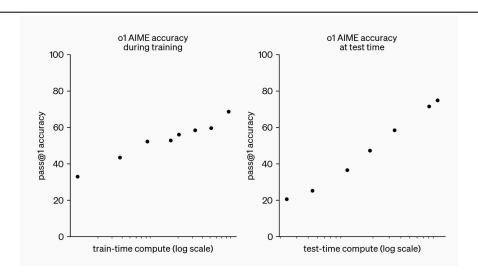
## O1 Chain of Thoughts (OpenAl 2024)



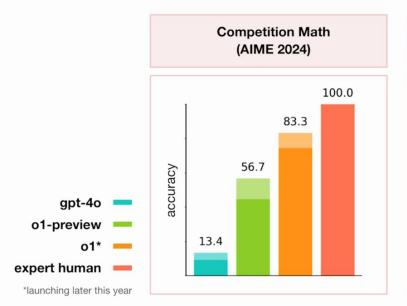
# Learning to Reason

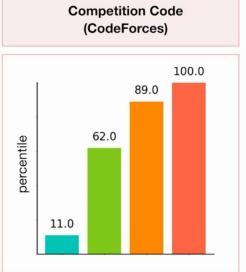
#### Learning to reason with LLMs (OpenAl 2024)

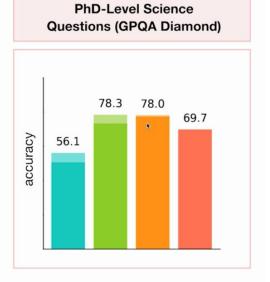
Our large-scale **reinforcement learning** algorithm teaches the model how to think productively using its **chain of thought** in a highly *data-efficient training* process.



#### O1 Results in Math, Coding, Science (OpenAl 2024)







## Self-Taught Reasoner (Zelikman et. al. NeurIPS 2022)

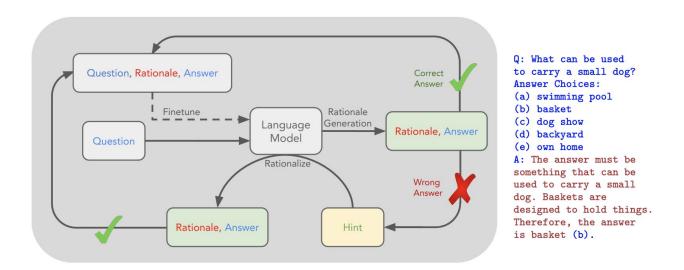


Figure 1: An overview of STaR and a STaR-generated rationale on CommonsenseQA. We indicate the fine-tuning outer loop with a dashed line. The questions and ground truth answers are expected to be present in the dataset, while the rationales are generated using STaR.

#### STaR Algorithm

#### **Algorithm 1** STaR

```
Input M: a pretrained LLM; dataset \mathcal{D} = \{(x_i, y_i)\}_{i=1}^D (w/ few-shot prompts)

1: M_0 \leftarrow M # Copy the original model

2: for n in 1...N do # Outer loop

3: (\hat{r}_i, \hat{y}_i) \leftarrow M_{n-1}(x_i) \quad \forall i \in [1, D] # Perform rationale generation

4: (\hat{r}_i^{\text{rat}}, \hat{y}_i^{\text{rat}}) \leftarrow M_{n-1}(\text{add\_hint}(x_i, y_i)) \quad \forall i \in [1, D] # Perform rationalization

5: \mathcal{D}_n \leftarrow \{(x_i, \hat{r}_i, y_i) \mid i \in [1, D] \land \hat{y}_i = y_i\} # Filter rationales using ground truth answers

6: \mathcal{D}_n^{\text{rat}} \leftarrow \{(x_i, \hat{r}_i^{\text{rat}}, y_i) \mid i \in [1, D] \land \hat{y}_i \neq y_i \land \hat{y}_i^{\text{rat}} = y_i\} # Filter rationalized rationales

7: M_n \leftarrow \text{train}(M, \mathcal{D}_n \cup \mathcal{D}_n^{\text{rat}}) # Finetune the original model on correct solutions - inner loop

8: end for
```

## **RL Policy Gradient**

STaR can be seen as an approximation to an RL-style policy gradient objective. To see this, note that M can be viewed as a discrete latent variable model  $p_M(y \mid x) = \sum_r p(r \mid x)p(y \mid x, r)$ ; in other words, M first samples a latent rationale r before predicting y. Now, given the indicator reward function  $\mathbb{I}(\hat{y} = y)$ , the total expected reward across the dataset is

$$J(M, X, Y) = \sum_{i} \mathbb{E}_{\hat{r}_i, \hat{y}_i \sim p_M(\cdot | x_i)} \mathbb{1}(\hat{y}_i = y_i), \tag{1}$$

$$\nabla J(M, X, Y) = \sum_{i} \mathbb{E}_{\hat{r}_i, \hat{y}_i \sim p_M(\cdot \mid x_i)} \left[ \mathbb{1}(\hat{y}_i = y_i) \cdot \nabla \log p_M(\hat{y}_i, \hat{r}_i \mid x_i) \right], \tag{2}$$

## Expert Iteration Framework (Anthony et. al. NIPS 2017)

The Imitation Learning step is analogous to a human improving their intuition for the task by studying example problems, while the expert improvement step is analogous to a human using their improved intuition to guide future analysis.

#### **Algorithm 1** Expert Iteration

```
1: \hat{\pi}_0 = \text{initial\_policy}()

2: \pi_0^* = \text{build\_expert}(\hat{\pi}_0)

3: for i = 1; i \leq \text{max\_iterations}; i + + \mathbf{do}

4: S_i = \text{sample\_self\_play}(\hat{\pi}_{i-1})

5: D_i = \{(s, \text{imitation\_learning\_target}(\pi_{i-1}^*(s))) | s \in S_i\}

6: \hat{\pi}_i = \text{train\_policy}(D_i)

7: \pi_i^* = \text{build\_expert}(\hat{\pi}_i)

8: end for
```

## Reinforced Self-Training (Gulcehre et. al. Deepmind 2023)

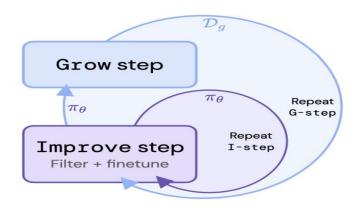


Figure 1 | *ReST* method. During Grow step, a policy generates a dataset. At Improve step, the filtered dataset is used to fine-tune the policy. Both steps are repeated, Improve step is repeated more frequently to amortise the dataset creation cost.

# Learning to Search

## Tree-of-Thoughts (Yao et. al. NeurIPS 2023)

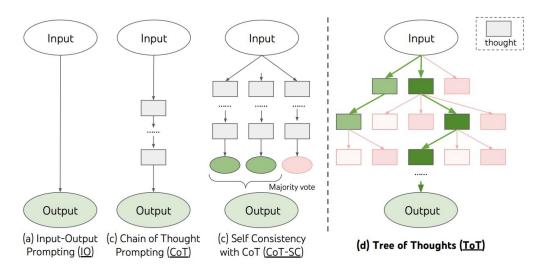


Figure 1: Schematic illustrating various approaches to problem solving with LLMs. Each rectangle box represents a *thought*, which is a coherent language sequence that serves as an intermediate step toward problem solving. See concrete examples of how thoughts are generated, evaluated, and searched in Figures 2,4,6.

## Stream of Search (Gandhi et. al. COLM 2024)

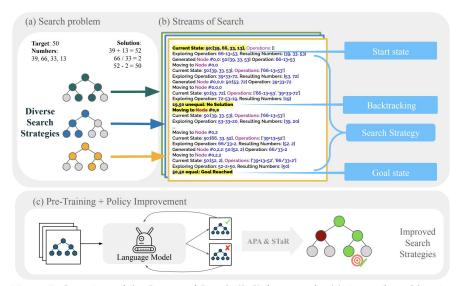


Figure 1: Overview of the Stream of Search (SoS) framework. (a) A search problem in Countdown is instantiated with input numbers and a target number. The input numbers need to be combined with simple arithmetic operations to get to the target. (b) The Stream of Search dataset contains search trajectories generated by diverse search strategies, including exploration and backtracking. (c) The language model is first trained on the SoS dataset and then iteratively improved using policy improvement techniques such as APA and STaR.

## Learning to Search

(Exploration, Expansion, Prune, Backtracking, Learning from Mistakes)

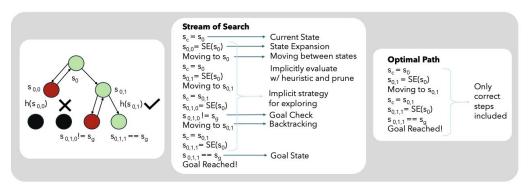
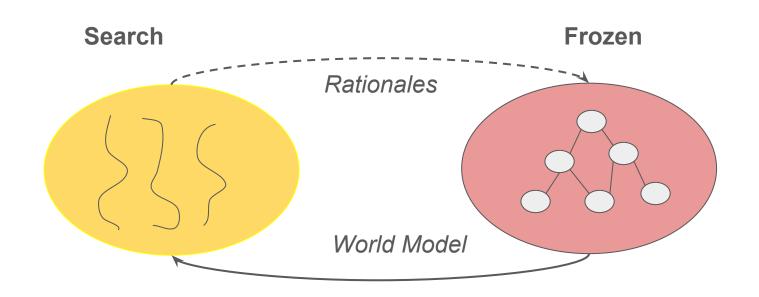


Figure 2: A visualization of how a search process is translated into a stream of search with a language for search. (left) The search process represented as a tree, with different states and operations. The colored states represent the search trajectory  $\mathcal{T}$ , the green states represent the correct path to the goal  $\mathcal{P}$  and the arrows represent transitions between the states. The black circles represent unexplored states. (center) The search process serialized as text to create a stream of search. The labels specify the different components of the process. See Fig. 1b for how this is realized in Countdown. (right) The optimal path,  $\mathcal{P}$ , to the goal state. Backtracking, exploration and the messy process of search are excluded.

## Inference

#### Inference = Search (Rationale Space) + Frozen (World Model)



# Verifier: PRM (Lightman et. al. OpenAI, ICLR 2024)

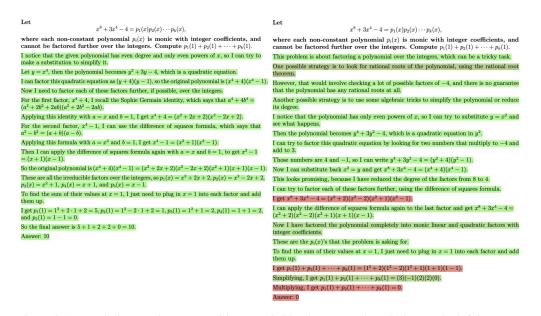


Figure 2: Two solutions to the same problem, graded by the PRM. The solution on the left is correct while the solution on the right is incorrect. A green background indicates a high PRM score, and a red background indicates a low score. The PRM correctly identifies the mistake in the incorrect solution.

### Test-Time Compute (Snell et. al. Deepmind 2024)

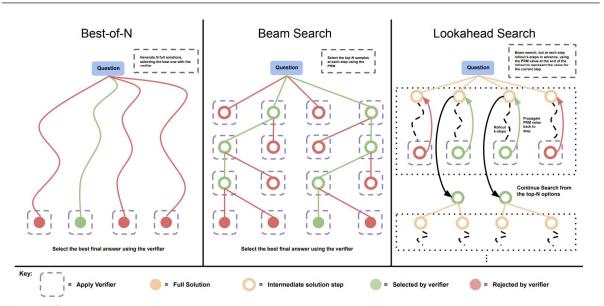


Figure 2 | Comparing different PRM search methods. Left: Best-of-N samples N full answers and then selects the best answer according to the PRM final score. Center: Beam search samples N candidates at each step, and selects the top M according to the PRM to continue the search from. Right: lookahead-search extends each step in beam-search to utilize a k-step lookahead while assessing which steps to retain and continue the search from. Thus lookahead-search needs more compute.

#### Reference

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- 4. <u>Tree of Thoughts: Deliberate Problem Solving with Large Language Models</u>
- 5. STaR: Self-Taught Reasoner Bootstrapping Reasoning With Reasoning
- 6. Thinking Fast and Slow with Deep Learning and Tree Search
- 7. Reinforced Self-Training (ReST) for Language Modeling
- 8. Stream of Search (SoS): Learning to Search in Language
- 9. Scaling LLM Test-Time Compute Optimally can be More Effective than Scaling Model Parameters