q1_starter.py 11/14/16, 2:01 AM

```
import numpy as np
import matplotlib.pyplot as plt
from sklearn.datasets import load iris, load digits
from sklearn.tree import DecisionTreeClassifier
from sklearn.cross_validation import StratifiedKFold, train_test_split
from sklearn import metrics
def cv_error(clf, X, y, k=5):
    0.00
        Splits the data, X and y, into k-folds. Trains a classifier on K-1
            folds and
        testing on the remaining fold. Calculates the cross validation train
            and test
        error for classifier clf by averaging the performance across folds.
        Input:
          clf- an instance of any classifier
          X- (n,d) array of feature vectors, where n is # of examples
             and d is # of features
          v-(n_i) array of binary labels \{1,-1\}
          k- int, # of folds (default=5)
        Returns: average train and test error across the k folds as np.float64
    skf = StratifiedKFold(y, k)
    train scores, test scores = [], []
    for train, test in skf:
       X_train, X_test, y_train, y_test = X[train], X[test], y[train], y[test]
        clf.fit(X_train, y_train)
        train_scores.append(clf.score(X_train, y_train))
        test scores.append(clf.score(X test, y test))
   return 1 - np.array(train_scores).mean(), 1 - np.array(test_scores).mean()
def plot_error(X, y):
   Plots the variation of 5-fold cross-validation error w.r.t. maximum
    depth of the decision tree
        X- (n, d) array of feature vectors, where n is # of examples
             and d is # of features
       y- (n, ) array of labels corresponding to X
   # ----- make your implementation here-----
    train error = []
    test error = []
   max_depth = list(range(1, 21))
   for i in range(1,21):
        clf = DecisionTreeClassifier(criterion="entropy", max_depth=i)
        result = cv_error(clf, X, y, 5)
        train error.append(result[0])
        test error.append(result[1])
   plt.plot(max_depth, train_error, label="train error")
   plt.plot(max_depth, test_error, label="test error")
   plt.legend(bbox_to_anchor=(0., 1.02, 1., .102), loc=3,
           ncol=2, mode="expand", borderaxespad=0.)
```

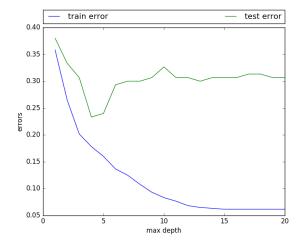
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```
plt.ylabel('errors')
    plt.xlabel('max depth')
    plt.savefig('max depth vs error.png')
    #plt.show()
def majority vote(pred list):
    Given a list of m (n, ) arrays, each (n, ) array containing the predictions
    same set of n examples (using different classifiers), return a (n, ) array
    containing majority vote prediction of the m (n, ) arrays
    Input:
        pred_list- a list of m (n, ) arays
    Output:
        y_pred- (n, ) array containing majority vote prediction using pred_list
    y_pred = []
    for i in range(len(pred list[0])):
        lst = [row[i] for row in pred list]
        y_pred.append(max(set(lst), key = lst.count))
    return y_pred
def bagging_ensemble(X_train, y_train, X_test, y_test, m = None, n_clf = 10):
    Returns accuracy on the test set X test with corresponding labels y test
    using a bagging ensemble classifier with n clf decision trees trained with
    training examples X_train and training labels y_train.
    Input:
        X_train- (n_train, d) array of training feature vectors, where n_train
            is # of examples and d is # of features
        y_train- (n_train, ) array of labels corresponding to X_train
        X_test- (n_test, d) array of testing feature vectors, where n_test is
            # of examples and d is # of features
        y_test- (n_test, ) array of labels corresponding to X_test
        m - int, # of features to consider when looking for the best split
        n_clf- # of decision tree classifiers in the bagging ensemble, default
            value of n_clf is 10
    Output:
        Accuracy of the bagging ensemble classifier on X_test
    # ----- make your implementation here-----
    bagging ratio = 0.6
    total_size = y_train.shape[0]
    bagging size = int(bagging ratio * total size)
    bagsX = []
    bagsY = []
    for i in range(0, n clf):
        tempx = []
        tempy = []
        for j in range(0, bagging_size):
            rand = np.random.randint(0, total_size)
            tempx.append(X_train[rand, :])
```

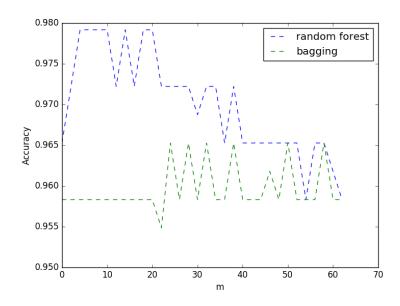
```
tempy.append(y_train[rand])
        bagsX.append(tempx)
        bagsY.append(tempy)
   clfs = []
    accuracy = 0
    for i in range(0, n clf):
        clfs.append(DecisionTreeClassifier(max features=m));
   for i in range(0, n_clf):
        clfs[i].fit(bagsX[i], bagsY[i])
   preds = []
    for i in range(0, n_clf):
        temp = clfs[i].predict(X_test)
        preds.append(temp)
   y_pred = majority_vote(preds)
   count = 0
    for i in range(0, y_test.shape[0]):
        if y_pred[i] == y_test[i]:
           count = count + 1
    accuracy = count / y_test.shape[0]
   return accuracy
def random_forest(X_train, y_train, X_test, y_test, m, n_clf = 10):
   Returns accuracy on the test set X_test with corresponding labels y_test
   using a random forest classifier with n_clf decision trees trained with
    training examples X train and training labels y train.
    Input:
        X train- (n train, d) array of training feature vectors, where n train
            is # of examples and d is # of features
        y_train- (n_train, ) array of labels corresponding to X_train
       X_test- (n_test, d) array of testing feature vectors, where n_test is
            # of examples and d is # of features
        y_test- (n_test, ) array of labels corresponding to X_test
        n_clf- # decision tree classifiers in the random forest, default
            value of n_clf is 10
    Output:
       Accuracy of the random forest classifier on X_test
    # ----- make your implementation here-----
    accuracy = bagging_ensemble(X_train, y_train, X_test, y_test, m, n_clf)
   return accuracy
def plot histograms(random forest scores, bagging scores):
   Plots histogram of values in random_forest_scores and bagging_scores
    overlayed on top of each other
    Input:
        random_forest_scores- a list containing accuracy values for random
           forest classifier
        for 100 different train and test set splits
        bagging_scores- a list containing accuracy values for bagging ensemble
```

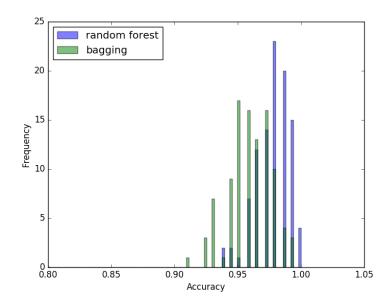
```
classifier
        using decision trees for the same 100 different train and test set
            splits
        as random_forest_scores
    bins = np.linspace(0.8, 1.0, 100)
    plt.figure()
    plt.hist(random_forest_scores, bins, alpha=0.5, label='random forest')
    plt.hist(bagging_scores, bins, alpha=0.5, label='bagging')
    plt.xlabel('Accuracy')
    plt.ylabel('Frequency')
    plt.legend(loc='upper left')
    plt.savefig('histogram.png')
    print("all done")
    #plt.show()
def q1a():
    # Load Iris dataset
    iris = load iris()
    X, y = iris.data[:,:2], iris.target
    # PLot cross-validation error vs max depth
    plot error(X, y)
def q1b():
    # Load digits dataset
    digits = load digits(4)
    X, y = digits.data, digits.target
    # Calculate accuracy of bagging ensemble and random forest for 100 random
        train/test splits
    # Analyze how the performance of bagging & random forest changes with m
    results1, results2 = [], []
    for j in range(0, 64, 2):
        print (j / 64 * 100, "%")
        bagging_scores, random_forest_scores = [], []
        for i in range(100):
            X_{train}, X_{test}, y_{train}, y_{test} = train_{test}, train_{test}
            random_forest_scores.append(random_forest(X_train, y_train, X_test,
                y_test, j+1))
            bagging_scores.append(bagging_ensemble(X_train, y_train, X_test,
                y_test))
        results1.append(np.median(np.array(random forest scores)))
        results2.append(np.median(np.array(bagging scores)))
    plt.figure()
    plt.plot(range(0, 64, 2), results1, '--', label = 'random forest')
    plt.plot(range(0, 64, 2), results2, '--', label = 'bagging')
    plt.xlabel('m')
    plt.ylabel('Accuracy')
    plt.legend(loc='upper right')
    plt.savefig('second_plot.png')
    #plt.show()
```

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Looks like a depth of 4 works pretty well





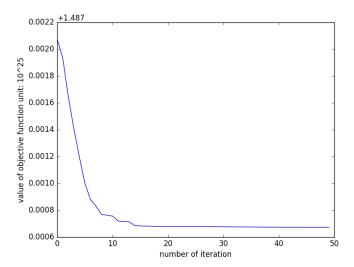
m = 15 is ok, as m becomes larger, the performance of random forest actually decreases.

```
from __future__ import division
from scipy.ndimage import imread
import numpy as np
from matplotlib import pyplot as plt
def compute distances using numpy(X, ClusterMeans, n, k):
    X row norms = np.linalg.norm(X) **2
    M_row_norms = np.linalg.norm(ClusterMeans) **2
    D = (np.outer(X_row_norms, np.ones(k)) + np.outer(np.ones(n), M_row norms)
        - 2 * np.dot(X, ClusterMeans.T))
    return D
# Load the mandrill image as an NxNx3 array. Values range from 0.0 to 255.0.
mandrill = imread('mandrill.png', mode='RGB').astype(float)
N = int(mandrill.shape[0])
M = 2
k = 64
# Store each MxM block of the image as a row vector of X
X = np.zeros((N**2//M**2, 3*M**2))
for i in range(N//M):
    for j in range(N//M):
        X[i*N//M+j,:] = mandrill[i*M:(i+1)*M,j*M:(j+1)*M,:].reshape(3*M**2)
# TODO: Implement k-means and cluster the rows of X, then reconstruct the
# compressed image using the cluster center for each block, as specified in
# the homework description.
size = X.shape[1]
n = X.shape[0]
cluster_pool = np.zeros([k, size])
cluster_pool_save = np.zeros([k, size])
blank = []
points_pool = []
points_pool_save = []
#prepare the initial random clusters
for i in range(0, k):
    rand = np.random.randint(0, n)
    cluster_pool[i, :] = X[rand, :]
#initialize point pool
for i in range(0, k):
    temp = []
    points_pool.append(temp)
    blank.append(temp)
count = 0
objective = []
iteration = []
#while not np.array_equal(cluster_pool, cluster_pool_save):
while count < 50:
```

```
#associate each point with a cluster_pool
    print("count: ", count)
    iteration.append(count)
    distance = compute_distances_using_numpy(X, cluster_pool, n, k)
    points pool = blank
    sum_distance = 0
    for i in range(0, n):
        min_val = float('inf')
        min_index = 0
        for j in range(0, k):
            if distance[i][j] < min_val:</pre>
                min_val = distance[i][j]
                min_index = j
        sum_distance = sum_distance + min_val * min_val
        points_pool[min_index].append(i)
    print("value of objective function: ", sum_distance)
    objective.append(sum_distance / (10**25))
    #update cluster using the mean of all the associated points
    cluster_pool_save = np.array(cluster_pool)
    for i in range(0, k):
        total = np.zeros([1, size])
        totalnumber = len(points_pool[i])
        if totalnumber != 0:
            for j in range(0, totalnumber):
                index = points pool[i][j]
                total = total + X[index, :]
            total = total / totalnumber
            cluster_pool[i, :] = total
    count = count + 1
for i in range(0, k):
    total = np.zeros([1, size])
    for j in range(0, len(points_pool[i])):
        index = points_pool[i][j]
        X[index, :] = cluster_pool[i, :]
mandrill_cpy = np.array(mandrill)
for i in range(N//M):
    for j in range(N//M):
        mandrill_cpy[i*M:(i+1)*M,j*M:(j+1)*M,:] = X[i*N//M+j,:].reshape(M,M,3)
difference = np.array(mandrill)
for i in range(mandrill.shape[0]):
    for j in range(mandrill.shape[1]):
        for k in range(mandrill.shape[2]):
            difference[i][j][k] = mandrill[i][j][k] - mandrill_cpy[i][j][k] +
                128
sum_abs = 0
```

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```
for i in range(0, N):
    for j in range(0, N):
        for k in range(0, 3):
            sum_abs = sum_abs + np.abs(mandrill_cpy[i][j][k] - mandrill[i][j][k
                1)
absolute_error = sum_abs / (255 * 3 * N * N)
print("relative absolute error: ", absolute_error)
# To show a color image using matplotlib, you have to restrict the color
# color intensity values to between 0.0 and 1.0. For example,
plt.plot(iteration, objective)
plt.ylabel('value of objective function unit: 10^25')
plt.xlabel('number of iteration')
plt.savefig('error_curve.png')
plt.show()
plt.imshow(mandrill/255)
plt.savefig('original.png')
#plt.show()
plt.imshow(mandrill_cpy/255)
plt.savefig('compressed.png')
#plt.show()
plt.imshow(difference/255)
plt.savefig('difference.png')
#plt.show()
```



the nose is more clear than other part. The part with more contrast will be better preserved.

M = 2;

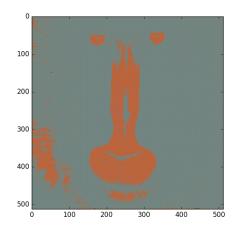
k = 64;

absolute error is 0.158

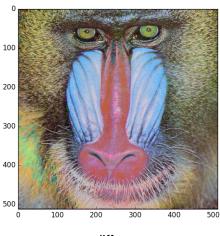
$$\frac{k}{n^2} + \frac{Log[2, k]}{24 M^2}$$

0.0627441

n = 512.0;



compressed



difference

Problem 4.

Original \Rightarrow 24 bits per pixel, 8 bits /color

image \Rightarrow 3:20 N×N

M, N, k

for M, each M×M block can be considered as / pixel

Now the resolution is $(\frac{1}{M})^2$ assumily

For each block we need to store which cluster it belongs
to which takes $\log_2 k$ bits.

And we need to store the color for clusters, $k \times 24$ bits/pixel

which is 24 k bits.

By digether \Rightarrow $\frac{24k + \log_2 k \times (\frac{N}{M})^2}{N^2} = \frac{24k + \log_2 k}{M^2}$ bits/pixel

Compression radio = $(\frac{24k}{N^2} + \frac{\log_2 k}{N^2})/24 = \frac{k}{N^2} + \frac{\log_2 k}{24m^2}$

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43	↓19	Sahil Misra	0.66531	2	Wed, 05 Oct 2016 22:02:47 (-0h)
44	↓19	GuangyuWang	0.66364	1	Mon, 31 Oct 2016 22:16:57
45	↓19	cneeruko	0.66333	8	Wed, 09 Nov 2016 18:13:13 (-35.6d)
46	↓19	Redmond Xia	0.66298	1	Thu, 03 Nov 2016 02:35:25
47	new	minkyan	0.66220	12	Mon, 14 Nov 2016 02:46:08 (-2.6h)
48	new	TianhaoZhou	0.66137	5	Mon, 14 Nov 2016 06:57:15
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