

Paper Notes: Bag of tricks to improve Pretrain-Finetune Paradigm

Tianjian Li

Johns Hopkins University

May 12, 2022

1 BART

BART[15] is work by Facebook published at ACL 2020. It aims to generalize BERT [11]. BERT uses a bidirectional encoder that replaces random token with masks and is trained only on the loss between the masked tokens and the ground truth. GPT is trained in a unidirectional autoregressive way, generating words according to their leftward context.

BART combines the two models by including a denoising autoencoder that encodes the corrupted document then autoregressively maps the encoded document to its original uncorrupted counterpart. The encoder is the standard transformer[4], with a slight modification that changes the activating function from ReLU to GeLU[2]. In each layer of the decoder, the model calculates the cross attention over the final hidden layer of the encoder.

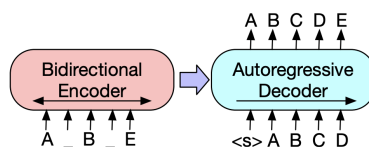


Figure 1: BART

The paper introduces a few corrupting tricks during the pretraining phase:

- Token Masking: Similar to BERT[5].
- Token Deleting : Random deletes input tokens
- Text Infilling : Sample text spans and replace them with a single mask token.

- Sentence Permutation
- Document Rotation:
A token is chosen uniformly random and the document is rotated so that it begins with this token.

For various downstream tasks:

- Sequence Classification:
Feed the pretrained encoder and decoder the same input and use let the decoder output a class token, similar to the CLS token in BERT.
- Token Classification(SQuAD):
Feed the pretrained encoder and decoder the same input and use the final hidden state of the decoder as the representation for each word.
- Sequence Generation:
The Encoder takes the input and the decoder outputs the generated sequence autoregressively.
- Machine Translation:
The entire BART model is viewed as an decoder, combined with an additional encoder that takes the source language as input. The model is trained in two steps: 1) Freeze most the parameters of the BART model and only update the parameters of the new encoder, BART positional embeddings and the attention input matrix of the first layer of BART's encoder. 2) Train the entire model for a small number of steps.

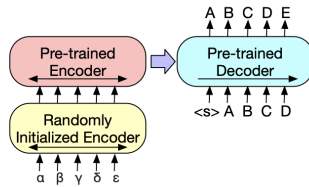


Figure 2: Illustration of Machine Translation Task

2 PET

PET[25]:Exploiting Cloze Questions for Few Shot Text Classification and Natural Language Inference is published at EACL2021. GPT[11] teaches us that a pretrained model with the correct task descriptions can perform better in downstream tasks than the commonly used pretrain-fintune paradigm. PET proposes that cloze style input phrases can help language model understand a given task.

GPT provides hints for our language model to generalize to tasks(Reading Comprehension, Question Answering)in a zero-shot context. In contrast, PET provides task descriptions can be combined with supervised learning in few shot settings.

A *pattern function* P takes a sequence of sentences as its input and outputs **one** sentence that contains only **one** masked token. The output can be viewed as a cloze question. A *verbalizer* v is a injective function that maps a label to a word in the vocabulary.

We can find pair of P, v to solve specific tasks. For example, if we need to solve a Question Answering(QA) task, given training example Q, A . We define our P as follows:

$$P((Q, A)) = Q. \text{---}, A.$$

The task now changes from having to assign a label without inherent meaning to answering whether the most likely choice for the masked position in a "Yes" or a "No".

During Training, the cross entropy loss between the predicted label and the groundtruth is minimized. Nevertheless, the nature of few shot supervised learning means that "catastrophic forgetting"[25] can occur. So the final loss is a combined loss of the masked language model and the cross entropy loss. (Experiment setting $\alpha = 1 * 10^{-4}$)

$$L = (1 - \alpha)L_{CE} + \alpha \cdot L_{MLM}$$

2.1 Key Challenges of PET

One of the challenges of PET is that we need to manually search for a good pattern function P . The author uses knowledge distillation[1] to ensemble a group of potentially good pattern functions.

1. During finetuning, training different models for each pattern function P .
2. During ensembling, computes scores by a uniformly weighted or accuracy weighted ensemble of the models. Use softmax to transform the scores into a probability distribution. Use $T = 2$ to get a soft distribution[1]. All of the pairs form a new training set T_C
3. Finetune PLM with a standard sequence classification on T_C .

3 Adapter Layers

Adapter Layers was introduced to NLP in [7] published at ICML 2019. The main paradigms in transfer learning are 1)feature based transfer and 2)Fine-tuning. While the former learns an embedding for each word/token then feeds the embedding into models for downstream tasks, the latter is not trained in an end to end way. We first pre-train to learn weights, then fine-tune for a small number of epochs.

However, as the author points out, both 1) and 2) are not parameter efficient because they require additional parameters to train in order to achieve performance, we can see this in the figure below.

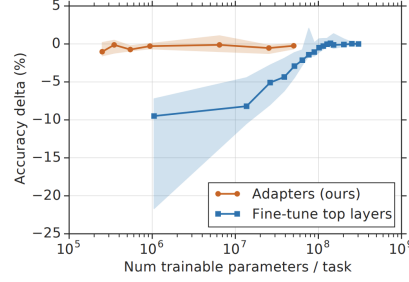


Figure 3: Fine-tuning vs Adapters from [7]

Adapters are new modules added between layers of a **pre-trained** network. The main properties of adapters are:

- Initialized as identity functions
- Very few parameters added

In this paper, the adapter layers is specifically designed, implemented and experimented on transformers[4] for NLP tasks. Although it is also useful in transfer learning in Computer Vision[3].

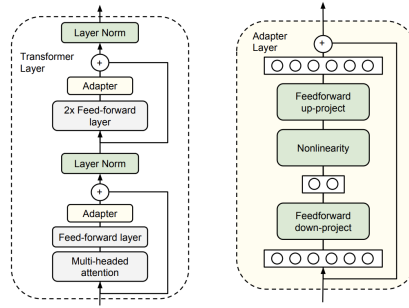


Figure 4: Illustration of adapter layers from [7]

A transformer block mainly contains one multi-head self attention layer and a feed forward network followed by a layer normalization. The adapter layers are added after the output of each layer and before the residual connection. In order to constraint the number of parameters, the adapter layer first projects the d dimensional input into a m dimensional tensor where $w \ll d$, apply a nonlinear function then projects back to its original d dimension. The down

projection adds $md + m$ parameters, the up projection adds $md + d$ parameters. The total added number of parameters are $2md + d + m$ including the bias. Importantly, the model also trains new layer normalization parameters for each downstream task.

4 Transformer-XL

Transformer-XL[6] is a architecture that enables learning dependency beyond a fixed length without disrupting temporal coherence based on the Transformers[4]. To design a model based on transformer to capture long range dependencies, we start with segmenting the inputs. We first cut the corpus into smaller segments, then only train our model within each segment.

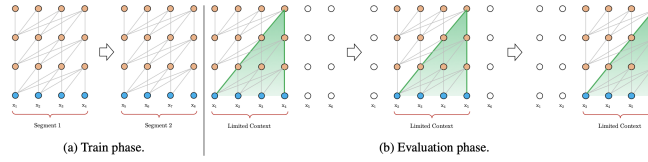


Figure 5: Vanilla Transformers, figure taken from [6]

Under this training paradigm, information never flows across segments in either the forward or backward pass. This raises two problems: 1) The largest possible dependencies captured by the model is strictly bounded by the length of the segment. 2) In practice we simply chunk the corpora into fixed size segments, paying no heed to the start and/or end of sentences. Cutting a sentence into two pieces and making them unable to learn context from each other results in a major performance drop.

Transformer-XL incorporates the idea of RNN into segmented Transformers. During training, the hidden state sequence computed for the previous segment is fixed and cached to be reused as an extended context when the model processes the next new segment.

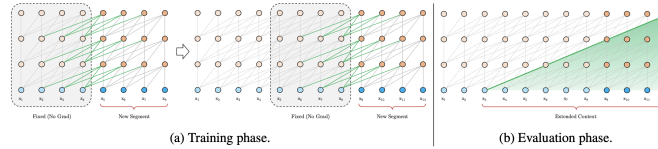


Figure 6: Transformers-XL, figure taken from [6]

Formally, if the first sentence is $s_i = [x_i^1, \dots, x_i^L]$ and the next sentence is $s_{i+1} = [x_{i+1}^1, \dots, x_{i+1}^L]$ we have the following update rule for the hidden states h_{i+1}

$$\begin{aligned}
\tilde{h}_{i+1} &= \text{concat}(\text{stop_gradient}(h_i), h_{i+1}) \\
(q_{i+1}, k_{i+1}, v_{i+1}) &= \text{linear_transform}(h_{i+1}, \tilde{h}_{i+1}, \tilde{h}_{i+1}) \\
h_{i+1} &= \text{Transformer}(q_{i+1}, k_{i+1}, v_{i+1})
\end{aligned}$$

Another trick adopted by Transformer-XL is **Relative Positional Encoding**. This is straightforward because if we apply the original encoding methods in Transformers, the model fails to distinguish between the i th word of the previous sentence and the i th word of the current sentence. Observing that the difference between positions matters more than the actual position of our **query** token and **key** token, we use the difference between positions to encode the words. If we use E as the word embedding and P as the positional embedding, then attention weight in vanilla transformer (before scaling and softmax) is:

$$\begin{aligned}
&(E_Q + P_Q)W_Q^\top W_K(E_K + P_K) \\
&= E_Q W_Q^\top W_K E_K + E_Q W_Q^\top W_K P_K + P_Q W_Q^\top W_K E_K + P_Q W_Q^\top W_K P_K
\end{aligned}$$

In Transformer-XL, the model trains two vectors q_E and $q_{\text{Diff}}(u, v$ in the original paper) for $P_Q W_Q$ and uses the encoding of the difference as P_K , the attention score becomes:

$$E_Q W_Q^\top W_K E_K + E_Q W_Q^\top W_K \text{Diff}_{q,k} + q_E W_K E_K + q_{\text{Diff}} W_K \text{Diff}_{q,k}$$

There are a few implementing tricks and optimizations for Transformer-XL, they are beyond the scope of this note. The main takeaways are the two tricks for long range dependencies: **caching hidden states and relative positional encoding**.

5 XLNet

5.0.1 Model Design and Implementation

Autoregressive (AR) language modelling performs pretraining by maximizing the likelihood under the forward autoregressive factorization:

$$\max_{\theta} \log p_{\theta}(x) = \sum_{t=1}^T \log p_{\theta}(x_t | x_{<T}) = \sum_{t=1}^T \frac{\exp(h_{\theta}(x_{1:t-1})^\top e(x_t))}{\sum_{x'} \exp(h_{\theta}(x_{1:t-1})^\top e(x'))}$$

whereas **Autoencoding (AE)** language modelling aims to reconstruct the original text corpus from a corrupted text:

$$\max_{\theta} \log p_{\theta}(x_{\text{masked}} | x_{\text{corrupted}}) = \sum_{t=1}^T m_t \log p_{\theta}(x_t | x_{\text{corrupted}}) = \sum_{t=1}^T \frac{\exp(H_{\theta}(x_{\text{corrupted}})^\top e(x_t))}{\sum_{x'} \exp(h_{\theta}(x_{\text{corrupted}})^\top e(x'))}$$

here m_t is a indicator function of where the token at t is masked.

The following table compares two paradigm AR and AE models of Transformers[4] and BERT[5], respectively.

Type	AR	AE
Example	Transformers[4]	BERT[5]
Independence Assumption	No assumption	masked tokens are independent of each other(which is not always true)
Input Noise	No input noise	Corrupted input leads to discrepancy between pretrain and finetune
Context Dependency	Unidirectional	Bidirectional

To enable AR methods to capture bidirectional context, the authors of XLNet[10] proposes maximizing the expected likelihood over **all permutations** of the factorization order. During implementation, XLNet keeps the original sequence order, use the positional encoding corresponding to the original sequence, and rely on a proper attention mask in Transformers to achieve permutation of the factorization order.

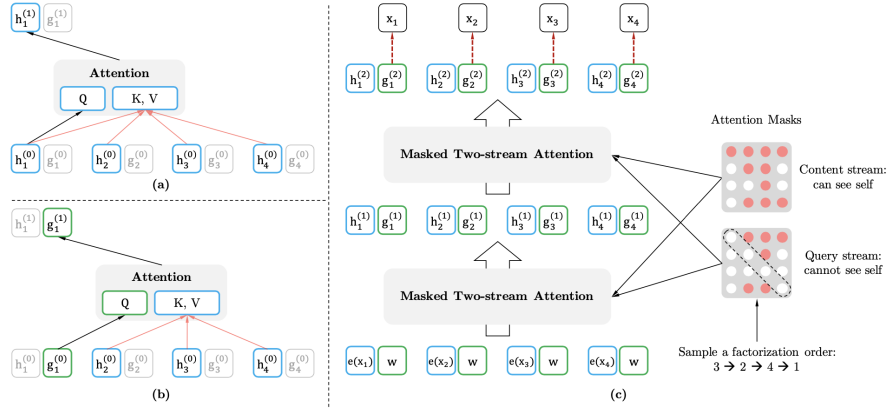


Figure 7: XLNet model architecture, figure from[10].

If we only use the hidden representations in Transformers[4]. Notice that the representation $h_\theta(x_{z < t})$ does not depend on which position it will predict, i.e., the value of z_t . Consequently, the same distribution is predicted regardless of the target position, which is not able to learn useful representations. To avoid this problem, we propose to re-parameterize the next-token distribution to be target position aware.

To resolve such a contradiction, XLNet propose to use two sets of hidden representations instead of one:

- The content representation $h_\theta(x_{z < t})$, or abbreviated as h_{z_t} , which serves

a similar role to the standard hidden states in Transformer. This representation encodes both the context and x_{z_t} itself.

- The query representation $g_\theta(x_{z<t}, z_t)$, which only has access to the contextual information $x_{z<t}$ and the position z_t , but not the content x_{z_t} .

Therefore XLNet[10] updates two sets of hidden outputs: g_{z_t} , which uses z_t but cannot see x_{z_t} , and h_{z_t} , which uses both the position z_t and also the content x_{z_t} . Formally:

$$g_{z_t}^{(m)} = \text{Attention}(Q = g_{z_t}^{(m-1)}, KV = h_{z_t}^{(m-1)}; \theta)$$

$$h_{z_t}^{(m)} = \text{Attention}(Q = h_{z_t}^{(m-1)}, KV = h_{z_t}^{(m-1)}; \theta)$$

The probability distribution $p(X_{z_t} = x | x_{z<t})$ of the next token is computed with the position aware and content blind hidden outputs $g_{z_t}^{(L)}$, where L denotes the number of transformer layers.

$$p(X_{z_t} = x | x_{z<t}) = \frac{\exp(e(x)^\top g_\theta(x_{z<t}, z_t))}{\sum_{x'} \exp(e(x')^\top g_\theta(x_{z<t}, z_t))}$$

5.1 Transformer-XL

As discussed in the previous note of Transformer-XL[6], Transformers fails to efficiently capture long range language dependencies. XLNet solves this issue by using Transformer-XL, to cut long sentences/documents into smaller chunks and caching the previous hidden state(the hidden state output of the previous chunk).

$$h_{z_t}^{(m)} = \text{Attention}(Q = h_{z_t}^{(m-1)}, KV = [\tilde{h}^{(m-1)}, h_{z_t}^{(m-1)}]; \theta)$$

Where $\tilde{h}^{(m)}$ denotes the cached hidden output of the previous segment/chunk. Note that we need to store the hidden output of all of the layers to acquire a hidden output of a specific layer m .

5.2 Future works

XLNet outperforms autoencoding methods(BERT) in a reading comprehension, text classification because these tasks needs to caputure long range dependencies and also need to find hidden relationships between different parts of the text. BERT assumes that the masked positions are independent, while XLNet does not depend on this assumption. XLNet was published in 2019. In year 2022, the idea of combining autoregressive models and autoencoding methods in few-shot/zero-shot learning scenarios with prompt tuning achieve great success[18].

6 ELECTRA

ELECTRA was proposed in **Pre-training Text Encoders as Discriminators Rather Than Generators**[13] in ICLR 2020. The major contributions of this paper are

- Introducing an more sample-efficient "replaced token detection"[13] pre-training objective as opposed to the *de facto* inefficient Masked Language Modeling(MLM).
- Experimented applying reinforcement learning methods and pointing out that Generative Adversarial Nets(GAN) generally fails in natural language understanding. (Note: For a more detailed explanation of why GAN doesn't work on language models, please refer to [12].)

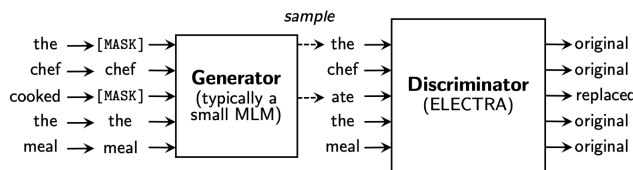


Figure 8: Overview of Replaced Token Detection. Copied from [13]

An higher order explanation of the replaced token detection objective is given as follows: given an input sentence, we use a small generative network trained with a Masked Language Modeling(MLM) objective to reconstruct masked tokens. Then, instead of training a model that predicts the original identities of the "corrupted" tokens, we train a **discriminative** model that predicts whether each token in the corrupted input was replaced by a generator sample or not.

A few notations on the methods are 1) If the generative model generates the groundtruth token, the token is considered to be "real" instead of "fake", meaning that the discriminator should predict such a token not been replaced by the generator. 2) The generator is trained to maximize the likelihood of the groundtruth token rather than trained to fool the discriminator. The latter, according to experiments, performs much worse though the reasons are not stated in the paper.

The authors conducted a series of experiments, notable conclusions includes

- The Replaced Token Detection method benefits from having a loss over all tokens rather than just a subset, evidenced by the fact that if you only use 15% of the tokens(the masked tokens) to compute the loss, the performance becomes much worse(GLUE score -3).

- BERT suffers from the pretrain - finetune mismatch in that during finetuning, BERT does not see the token [MASK]. Evidenced by Replace MLM slightly outperforming vanilla BERT(GLUE score +0.2).

6.1 My Thoughts

The proposed method of replaced token detection investigates every token from a given sentence as opposed to MLM which only examines the masked tokens. The discrepancy between pretrain and finetune, though influential in theory, actually makes little difference in GLUE dataset(+0.2). To use this training method on low resource languages could be more effective than high resource languages.

7 LM-BFF

LM-BFF[19] is proposed in **Making Pre-trained Language Models Better Few-shot Learners** in ACL 2021 by Tianyu Gao, Adam Fisch, and Danqi Chen. The major contributions of LM-BFF are

- Proposing a pipeline for automating prompt generation
- Proposing sampling semantically close demonstrations to facilitate learning of Language Models.

LM-BFF is built on the work of **Pattern-Exploiting Training**[25], which transforms various downstream tasks(Question Answering, Text Classification, Named Entity Recognition) into fill-in-the-blank cloze questions.

Another way to let pretrained language models perform a specific task is to use prompts and task demonstrations as the context of the input. GPT-3[11] achieves remarkable performance in few-shot learning.

The authors mentions two problems with GPT-3's in context learning: The demonstration examples are randomly chosen from different classes, which is hard to learn from; The amount of examples are bounded by the models maximum input length. Prompt based learning requires careful prompt engineering. In [24], the authors points out that the quality of prompts can have a huge impact on the performance of language model. To engineer a high quality prompt requires language-specific and task-specific prior knowledge.

7.1 Generating words given template

Therefore, task-agnostic and language-agnostic prompting is at the crux of prompt engineering. The work of LM-BFF aims to automate prompt engineering by using a **discrete template**. For constructing a set of label words of class c given a fixed template, we select all the training examples of class c ,

plug them into the language model to generate possible words, and sum the log probabilities for each single candidate of label word and take the top k. Mathematically speaking, given a label word w and template T , its score is computed by

$$\sum_{x_{class}=c} \log P([MASK] = w | T(x_{class}))$$

We manually select k words with the highest scores for each class. The total number of label words are $C * k$.

7.2 Generating template given words

LM-BFF uses the T5[16] model to fill in missing spans in the template. The authors propose three simple meta-templates

$\langle Input \rangle \rightarrow \langle Span1 \rangle \text{ label_word } \langle Span2 \rangle \langle Input \rangle$

$\langle Input \rangle \rightarrow \langle Input \rangle \langle Span1 \rangle \text{ label_word } \langle Span2 \rangle$

$\langle Input1 \rangle \langle Input2 \rangle \rightarrow \langle Input1 \rangle \langle Span1 \rangle \text{ label_word } \langle Span2 \rangle \langle Input2 \rangle$

and T5 is used to fill in the missing spans. Somehow these templates are semi-automated because you still need to manually define a meta-template. We select the template for each task(or for each training set)that maximizes the log conditional probability of the template(the sentence) given meta-template. Mathematically speaking, the score of a template given task t is given by

$$\sum_{i=1}^{|T|} \sum_{x_{train} \in t} \log P_{T5}(t_i | t_0, \dots, t_{i-1}, T(x_{train}))$$

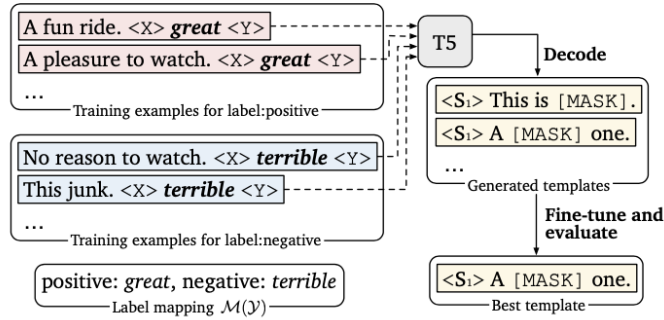


Figure 2: Our approach for template generation.

Figure 9: Template Generation, copied from [19].

7.3 Demonstrations based on similarity

The authors first encode the raw sentences into a sentence level encoder. Here they use Sentence BERT(or SBERT)[17]. For given query x_{test} and a given label c , for all training examples x_{train} labelled as c , we calculate the cosine similarity of the embeddings of x_{train} and x_{test} . We sample from the top 50% similar sentences for each label as context.

7.4 My Thoughts

Although the experiments show promising results of the automated search process, there have been various studies showing that a discrete template is sub-optimal compared to "soft prompts"[22][23]. The usage of "template of templates" also limits prompt engineering.

8 Prefix-Tuning

Prefix Tuning[21] is proposed in **Prefix-tuning: Optimizing continuous prompts for generation.** in ACL 2021 by Xiang Lisa Li and Percy Liang. The major contributions of Prefix-Tuning are

- Introducing a lightweight alternative to the state-of-the-art paradigm of finetuning every parameter for a specific task.
- Proposing that gradient based optimization of soft tokens/prompts can be effective as well as discrete tokens.

The problem for finetuning happens when we are using a very large language model, usually over billions of parameters. For each downstream task, we need to store a task-specific copy of the parameters, which is "prohibitively expensive"[21].

Previous attempts to solve this problem often freeze most of the pretrained parameters and only finetune on a smaller subset of parameters. In previous section I have introduced the application of **adapters** in NLP[8], which inserts layers in transformer blocks for finetuning. Nevertheless, adapters still need to train 3.6% of the original parameters, which is huge compared to the amount of finetune parameters used in prefix-tuning(0.1%)

8.1 Prefix Tuning Method

As shown in the picture, prefix tuning appends a learn-able prefix to an already pretrained autoregressive language model. The dimension of the prefix is manually defined to be the same as the transformer dimension and the length of the prefix is a fixed hyper-parameter. The model is pretrained as the same as before but finetuned with additional prefixes.

One notable aspect of prefix tuning is that instead of randomly initializing the prefix embeddings, the author uses a smaller embedding and then use a linear

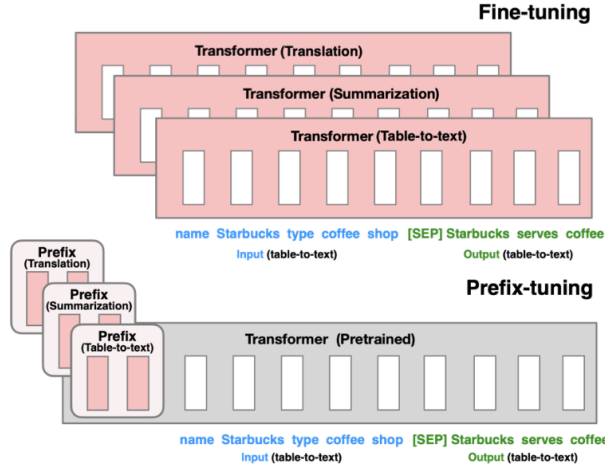


Figure 1: Fine-tuning (top) updates all LM parameters (the red Transformer box) and requires storing a full model copy for each task. We propose prefix-tuning (bottom), which freezes the LM parameters and only optimizes the prefix (the red prefix blocks). Consequently, we only need to store the prefix for each task, making prefix-tuning modular and space-efficient. Note that each vertical block denote transformer activations at one time step.

Figure 10: Prefix Tuning, copied from [21]

layer to transform it into the dimension of a transformer block. Quoting from the paper "Empirically, directly updating the P_θ parameters leads to unstable optimization and a slight drop in performance." [21] Also, "Initializing the prefix with activations of real words significantly improves generation." [21].

8.2 My Thoughts

The experiments results evidenced that prefix tuning(adding additional parameters in front of transformer blocks) achieve better results than adapters(adding additional parameters within transformer blocks) for a same pretrained model. Still prefix tuning still slightly underperforms full finetuning(which requires a lot of space and time).

Another problem is that the results are evaluated only on GPT-2(single directional), which might not be the case for other autoregressive models with bidirectional context. The authors also states the superiority in expressive power of continuous soft prompt as opposed to discrete prompts. Admitted that the

expressive power of soft prompts are better, they require a lot of computational power to search of a optimal prompt, even if the prompts were discretely initialized. Whereas the GPT-3 style in context transfer might yield better results.

9 GPT understands, too

This paper was published in 2021.3 by Xiao, Liu et al. The major contributions of this paper are

- Proposing trainable continuous prompt embeddings as a general method to improve LM’s transfer learning ability.
- Showing that continuous prompt can achieve comparable, if not better results than discrete prompts proposed in [25].

P-Tuning defines a template T as

$$T = \{[P_{0:i}], x, [P_{i+1:m}], y\}$$

where x is [MASK] and y is [CLS](The classification head). A discrete prompting methods maps every token in the template to the word embedding. P-Tuning treats each P_i as psudo tokens and maps the template to

$$\{h_0, ..., h_i, \mathbf{e}(x), h_{i+1}, ..., h_m, \mathbf{e}(y)\}$$

Here $h_i \in R^d$ where d is the dimension of embedding vector(768 for BERT). The embedding might not corresponds to a discrete token.

One problem for this schema is that the target word embedding is discrete and while the prompt is continuous. The authors also states that if the embeddings are randomly initialized, it could easily fall into local minima. Also to associate each individual prompt token, the author uses a bidirectional LSTM network to encode the embeddings and then passes them through a single linear layer with ReLU activation function. (In Prefix Tuning[21], the author uses only a single layer MLP to transform low dimensional embeddings to a higher dimension).

9.1 My Thoughts

The paper is similar to [21] to propose continuous prompts, which achieve better results than Manuall Prompts + Finetuning(which is the case in [25]). In the following table, we can see that the gain on Language Models pretrained in a bidirectional denoising objective(BERT) is not as significant as the gain on unidirectional autoregressive models(GPT-2). It is possible for an ensemble of high quality manual prompts to achieve better performance.

Model	MP	FT	MP+FT	P-tuning
BERT-base (109M)	31.7	51.6	52.1	52.3 (+20.6)
-AutoPrompt (Shin et al., 2020)	-	-	-	45.2
BERT-large (335M)	33.5	54.0	55.0	54.6 (+21.1)
RoBERTa-base (125M)	18.4	49.2	50.0	49.3 (+30.9)
-AutoPrompt (Shin et al., 2020)	-	-	-	40.0
RoBERTa-large (355M)	22.1	52.3	52.4	53.5 (+31.4)
GPT2-medium (345M)	20.3	41.9	38.2	46.5 (+26.2)
GPT2-xl (1.5B)	22.8	44.9	46.5	54.4 (+31.6)
MegatronLM (11B)	23.1	OOM*	OOM*	64.2 (+41.1)

* MegatronLM (11B) is too large for effective fine-tuning.

Figure 11: Experiments comparing MP+FT to P-Tuning, copied from [22]

10 Null Prompting

Null Prompting is proposed in **Cutting Down on Prompts and Parameters: Simple Few-Shot Learning with Language Models**[20]. It aims to solve two major problems in transfer learning in NLP:

1. prompt-based finetuning([25], [19], [22]) have large memory requirements as they need to update all the model parameters as well as continuous prompt parameters if needed.
2. In-context learning[11] "requires significant prompt engineering"[20], despite the fact that it does not require us to update any parameter of the model, essentially reusing the pretrained model in its "as is" form.

The major contributions of the paper are

- Proposing a novel prompting method that does not require prompt engineering(Although verbalizer engineering is required to achieve the best result).
- Experimenting with lightweight finetune alternatives, although on relatively small(number of params \leq 500M) models.
- Discussing the significance of prompting and prompt engineering in natural language understanding tasks.

The null prompting methods is simple and straightforward. For example:

Prompt-Based Finetuning (Previous Works)	{Will GST affect the price level in India?} ₁ ? [MASK], I want to know {Will GST effect the price level in India?} ₂
Null Prompts	{Will GST affect the price level in India?} ₁ {Will GST effect the price level in India?} ₂ [MASK]

The above example removes all the prompting words "I want to know" and instead uses an [MASK] token to predict the answer. To answer the question of "Will GST affect the price level in India", one only need to restate the question

followed by a [MASK] token. Note that the verbalizer "Yes" still need to be manually defined. For a general question(Yes-no question) this can be simple. However for a classification question in Named Entity Recognition, for example, { What is the entity of Manchester in Manchester United} and the answer should be {Organization} instead of {Location} Since Manchester United is a Football Club. In this case the verbalizer word label {*location*} need to be manually defined.

You can see a comparison of different prompting methods in the following table.

Method	Finetuned Params	Prompt Design	Few-shot
AUTOPROMPT (Shin et al., 2020)	None	Learned (Discrete)	✗
Prompt Tuning (Lester et al., 2021)	Prompt Token Embeds	Learned (Continuous)	✗
OPTIPROMPT (Zhong et al., 2021)	Prompt Token Embeds	Learned (Continuous)	✗
Soft Prompts (Qin and Eisner, 2021)	All Contextualized Embeds	Learned (Continuous)	✗
GPT-3 (Brown et al., 2020)	None	Manual	✓
PET (Schick and Schütze, 2021a)	All	Manual	✓
LM-BFF (Gao et al., 2021)	All	Learned (Discrete)	✓
P-Tuning (Liu et al., 2021)	All + Prompt Token Embeds	Learned (Continuous)	✓
Null Prompts + Bitfit (Ours)	Bias Terms	None	✓

Figure 12: Comparison of different prompting methods, table copied from [20]

The experiment results shows that in ALBERT(223M)[14] and RoBERTa(330M)[9]

- **Manual Prompts** achieves the best performance, although a careful selection of prompts is required since prompts with out engineering perform worse.
- **Null Prompts + Manual Verbalizers** perform roughly the same, if not better than Prompt Tuning.
- **Bias-Only Finetuning** performs the best than other lightweight finetuning methods, and is comparable, if not better to finetuning all parameters.

10.1 My Thoughts

It is extremely important to notice that the result are obtain only from two models that are under 500M parameters. Which might not be the lase in either 1)Large Models(1B params) or 2)Autoregressive Models, therefore the results should be closely examined case by case(or model by model) in order to come up with a conclusion of different prompting methods.

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