

ECE 6143 Homework 2

Qianyong Tang

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1 Problem 1

Since $y_i \in \{-1, 1\}$, denote $y'_i = \frac{1}{2}(1 - y_i) \in \{0, 1\}$. Choose $x_j = 10^{-j}$ (where $i, j = 1, 2, 3, \dots, h$), and $\omega = \pi(1 + \sum_{i=1}^h y'_i 10^i)$

$$\begin{aligned}\omega x_j &= \pi(1 + \sum_{i=1}^h y'_i 10^i) 10^{-j} \\&= \pi(10^{-j} + \sum_{i=1}^h y'_i 10^{i-j}) \\&= \pi(10^{-j} + \sum_{i=1}^{j-1} y'_i 10^{i-j} + y'_j + \sum_{i=j+1}^h y'_i 10^{i-j}) \\&= \pi(10^{-j} + \sum_{i=1}^{j-1} y'_i 10^{i-j} + y'_j) + 10\pi \sum_{i=j+1}^h y'_i 10^{i-(j+1)}\end{aligned}$$

Since $10\pi \sum_{i=j+1}^h y'_i 10^{i-(j+1)} = 2k\pi$, we can omit this part for $f(x) = \text{sign}(\sin(\omega x))$, then

$$\begin{aligned}\omega x_j &= \pi(10^{-j} + \sum_{i=1}^{j-1} y'_i 10^{i-j} + y'_j) \\&= \pi(10^{-j} + 10^{-j} \sum_{i=1}^{j-1} y'_i 10^i + y'_j) \\&\leq \pi(10^{-j} + 10^{-j} \sum_{i=1}^{j-1} 10^i + y'_j) \\&< \pi(10^{-j} + 10^{-j}(10^j - 1) + y'_j) \\&= \pi(1 + y'_j)\end{aligned}$$

Since $10^{-j} + \sum_{i=1}^{j-1} y'_i 10^{i-j} > 0$, it is obvious that $\omega x_j > \pi y'_i$, so $\pi y'_i < \omega x_j < \pi(1 + y'_i)$
For $y_i = -1 \Rightarrow y'_i = 1$:

$$\begin{aligned}\pi &< \omega x_j < 2\pi \\ f(x_j) &= \text{sign}(\sin(\omega x_j)) = -1\end{aligned}$$

For $y_i = 1 \Rightarrow y'_i = 0$:

$$\begin{aligned}0 &< \omega x_j < \pi \\ f(x_j) &= \text{sign}(\sin(\omega x_j)) = 1\end{aligned}$$

Since no matter what the value of h is, the classifier can always classifies correctly, so the classifiers operating in one dimension with input space $X = [0, 2\pi]$ is infinite.

2 Problem 2

2.1

First, we derive $\frac{\partial E}{\partial w_{ji}}$, which can be expressed by the chain rule:

$$\frac{\partial E}{\partial w_{ji}} = \frac{\partial E}{\partial x_i} \frac{\partial x_i}{\partial s_i} \frac{\partial s_i}{\partial w_{ji}}$$

We find the value of each part separately

$$\frac{\partial E}{\partial x_i} = (-1) \left(\frac{t_i}{x_i} + \frac{1 - t_i}{1 - x_i} (-1) \right) = \frac{x_i - t_i}{x_i(1 - x_i)}$$

$$\frac{\partial x_i}{\partial s_i} = (-1)(1 + e^{-s_i})^{-2} e^{-s_i} (-1) = x_i(1 - x_i)$$

$$\frac{\partial s_i}{\partial x_{ji}} = y_i$$

So,

$$\frac{\partial E}{\partial w_{ji}} = (x_i - t_i) y_i$$

Then, we derive $\frac{\partial E}{\partial w_{kj}}$. Similarly, applying chain rule and the equations obtained above, we get

$$\begin{aligned}\frac{\partial E}{\partial w_{kj}} &= \frac{\partial E}{\partial s_j} \frac{\partial s_j}{\partial w_{kj}} \\ &= \sum_i \frac{\partial E}{\partial s_i} \frac{\partial s_i}{\partial y_j} \frac{\partial y_j}{\partial s_j} \frac{\partial s_j}{\partial w_{kj}} \\ &= \sum_i (x_i - t_i) \cdot w_{ji} \cdot y_j (1 - y_j) \cdot z_k\end{aligned}$$

Therefore, we obtain the update rule

$$w_{ji}^{p+1} = w_{ji}^p - \eta \frac{\partial E}{\partial w_{ji}} \quad w_{kj}^{p+1} = w_{kj}^p - \eta \frac{\partial E}{\partial w_{kj}}$$

2.2

$$\begin{aligned}
\frac{\partial E}{\partial w_{ji}} &= \sum_k \frac{\partial E}{\partial x_k} \frac{\partial x_k}{\partial w_{ji}} \\
&= \sum_k \frac{\partial E}{\partial x_k} \left(\sum_p \frac{\partial x_k}{\partial s_p} \frac{\partial s_p}{\partial w_{ji}} \right) \\
&= \sum_k \left(-\frac{t_k}{x_k} \right) \left(\sum_p x_p (\delta_{kp} - x_k) \delta_{pi} y_j \right) \\
&= \sum_k \left(-\frac{t_k}{x_k} \right) [x_i (\delta_{ki} - x_k) y_i] \\
&= \left(-\frac{t_i}{x_i} \right) [x_i (1 - x_i) y_i] + \sum_{k \neq i} \left(-\frac{t_k}{x_k} \right) [x_i (-x_k) y_i] \\
&= x_i y_i \sum_k t_k - t_i y_i \\
&= y_i (x_i - t_i)
\end{aligned}$$

Similarly, we can get $\frac{\partial E}{\partial w_{kj}}$

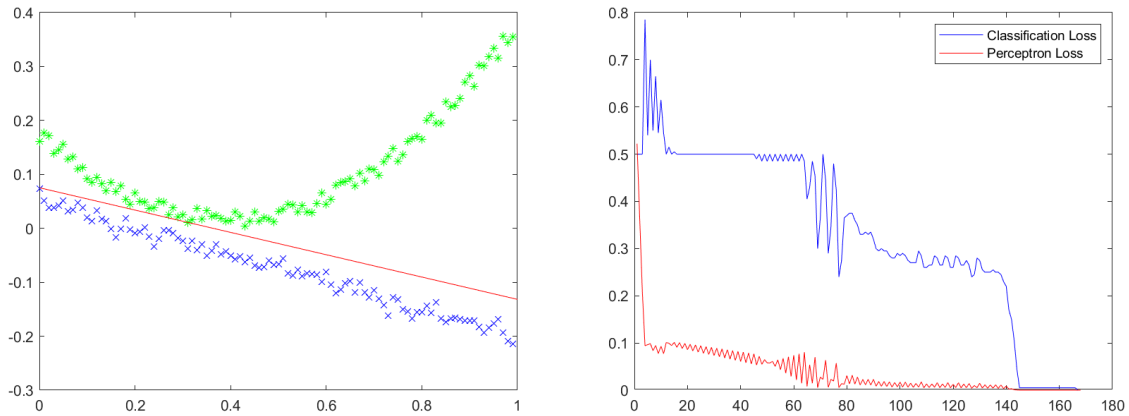
$$\begin{aligned}
\frac{\partial E}{\partial w_{kj}} &= \sum_i \frac{\partial E}{\partial s_i} \sum_j \frac{\partial s_i}{\partial y_j} \sum_a \frac{\partial y_j}{\partial s_a} \frac{\partial s_a}{\partial w_{kj}} \\
&= \sum_i (x_i - t_i) w_{ji} y_j (1 - y_j) z_k
\end{aligned}$$

Therefore, we obtain the update rule

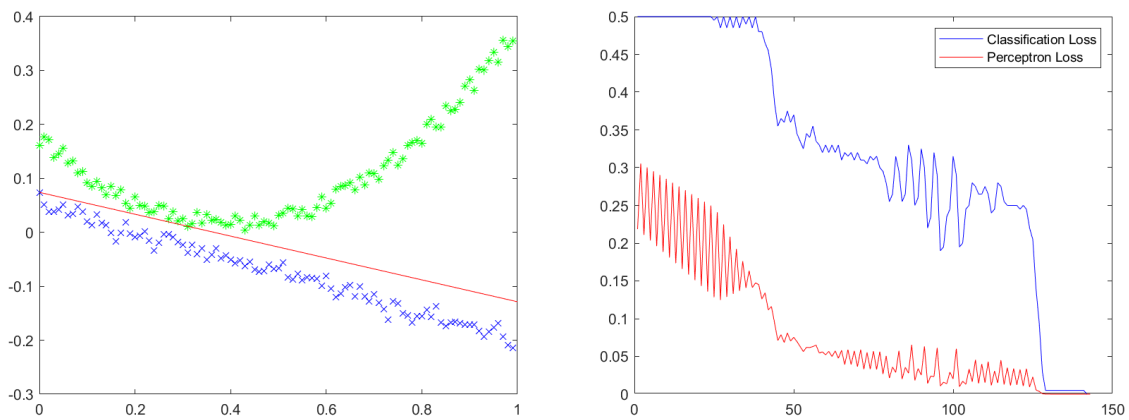
$$w_{ji}^{p+1} = w_{ji}^p - \eta \frac{\partial E}{\partial w_{ji}} \quad w_{kj}^{p+1} = w_{kj}^p - \eta \frac{\partial E}{\partial w_{kj}}$$

3 Problem 3

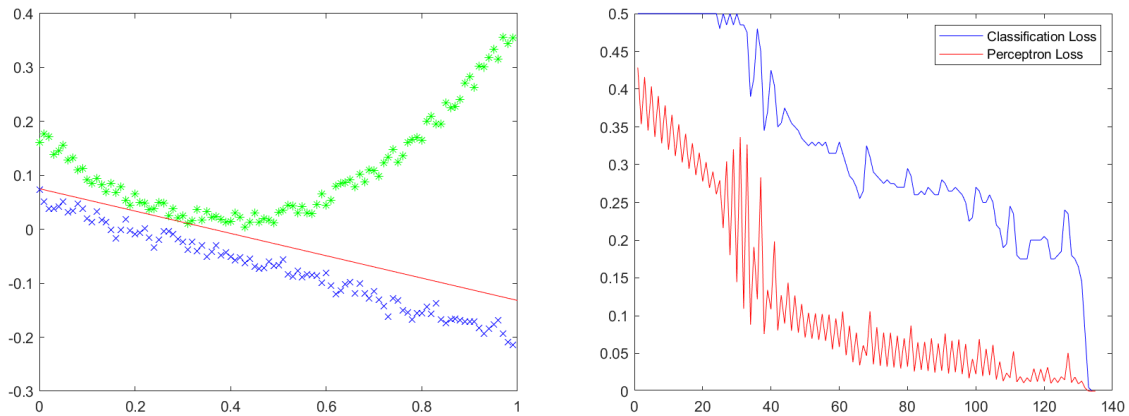
Using Gradient Descent (GD), set step = 0.5, tolerance = 0.0001



Using Gradient Descent (GD), set step = 1.5, tolerance = 0.0001



Using Gradient Descent (GD), set step = 2.5, tolerance = 0.0001



We can see that as step increases, the iteration number will decrease. However, the Classification and Perceptron Loss will become "deeper", and more fluctuation.

4 Problem 4

For the discrete distribution $\{p_k | k = 1, 2, \dots, N\}$, we have $\sum_k p_k = 1$. Use the definition as follows,

$$\begin{aligned} H &= - \sum_{k=1}^N p_k \log p_k \\ I &= \sum_{k=1}^N p_k - 1 \\ F &= H + \lambda I \end{aligned}$$

Applying Lagrange multipliers,

$$\begin{aligned} \nabla F &= \begin{bmatrix} \frac{\partial F}{\partial p_1} \\ \frac{\partial F}{\partial p_2} \\ \dots \\ \frac{\partial F}{\partial p_N} \\ \frac{\partial F}{\partial \lambda} \end{bmatrix} \\ &= \begin{bmatrix} -\log p_1 - 1 + \lambda \\ -\log p_2 - 1 + \lambda \\ \dots \\ -\log p_N - 1 + \lambda \\ p_1 + p_2 + \dots + p_N - 1 \end{bmatrix} \\ &= 0 \\ &\Rightarrow p_1 = p_2 = \dots = p_N = e^{1 - \log N - 1} = e^{\lambda - 1} \\ &\Rightarrow \lambda = 1 - \log N \\ &\Rightarrow p_1 = p_2 = \dots = p_N = e^{1 - \log N - 1} = \frac{1}{N} \end{aligned}$$

So the uniform distribution will maximize the entropy.