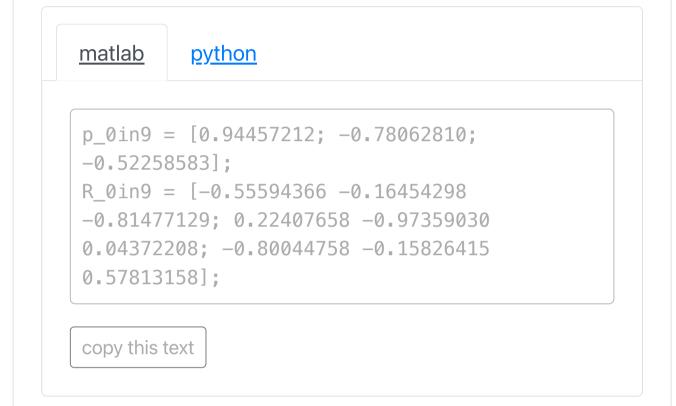
HW2.4. Find the inverse transformation

The position and orientation of frame 0 in the coordinates of frame 9 are:

$$p_{90} = egin{bmatrix} 0.94457212 \ -0.78062810 \ -0.52258583 \end{bmatrix} \qquad R_{90} = egin{bmatrix} -0.55594366 \ 0.22407658 \ -0.80044758 \end{bmatrix}$$



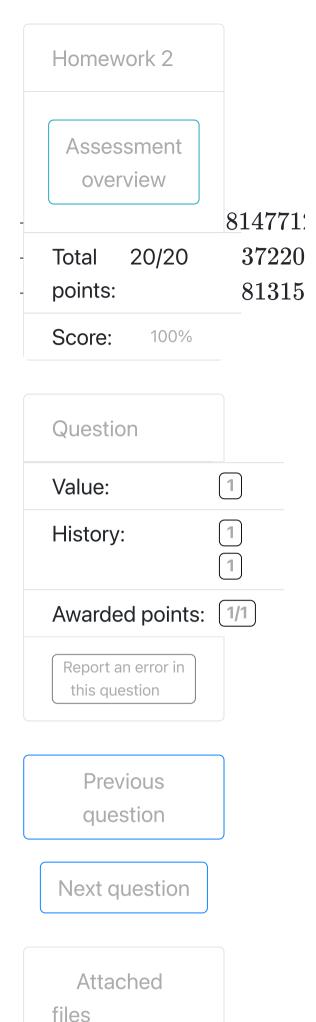
Find the position and orientation of frame 9 in the coordinates of frame 0:

Save & Grade
Single attempt

Save only

Additional attempts available with new variants

0



No attached

Attach a file

Attach text

files