# Tianshu Kuai

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Toronto, Canada

#### **Education**

Sep 2017 – Apr 2022

Bachelor of Applied Science in Engineering Science, University of Toronto Robotics Major, Artificial Intelligence Minor

University of Toronto Excellence Award, NSERC Undergraduate Student Research Awards, Dean's Honour List for all academic semesters

## **Experience**

May 2021 - Ongoing

**University of Toronto** | Undergraduate Researcher

Supervised by Prof. Steven Waslander, Toronto Robotics and Artificial Intelligence Lab (TRAILab)

- Undergraduate thesis on improving feature learning processes to get more robust features and more accurate bounding box refinement for 3D object detectors
- Designed and supported the development of high-performance LiDAR 3D object detection models for autonomous vehicles. PDV [1] achieved state-of-the-art multi-class 3D object detection results on Waymo Open Dataset upon publication.

July 2021 - Ongoing

**aUToronto** | Computer Vision Engineer

University of Toronto Autonomous Driving Group, SAE/GM AutoDrive Challenge

- Research on fast and lightweight 3D perception models on collected data
- · Worked on deploying real-time perception models on autonomous vehicles

May 2020 - May 2021

**Qualcomm** | Machine Learning Research Intern

Supervised by Dr. Shaojie Zhuo, Machine Learning Research Team

- Proposed several efficient deep learning models for audio processing
- Applied state-of-the-art methods for neural network compression
- Contributed to NPU software compiler pipeline development

May 2019 - Aug 2019

University of Toronto | Undergraduate Researcher

Supervised by Prof. Deepa Kundur, Department of Electrical and Computer Engineering

- Implemented machine learning models for early relapse detection in Youth Depression
- Worked on patients' data processing and imputations for missing data
- · Developed pipeline to track patients' facial expressions for behaviour analysis

#### **Publications**

2022

[1] Jordan S. K. Hu, **Tianshu Kuai**, and Steven L. Waslander, "Point Density-Aware Voxels for LiDAR 3D Object Detection," *CVPR* 2022.

· Awarded the second prize in senior design competition

# Mar 2019 | NSERC Undergraduate Student Research Awards

• Undergraduate student research awards by Natural Sciences and Engineering Research Council of Canada (NSERC)

# Feb 2019 | University of Toronto Excellence Award

• Awarded to University of Toronto undergraduate students based on research aptitude

# Sep 2017 | University of Toronto Engineering Entrance Scholarship

Scholarship for top engineering candidates pursing studies at the University of Toronto

# **Selected Projects**

#### 2021 | Real Time Audio Denoiser

- A model built using convolutional neural networks with encoder-decoder structure
- Model takes the noisy speech as input and produce a de-noised speech as the final output
- Achieved good performance on various types of signals with only 33K parameters

#### 2020 Deep Learning Based COVID-19 Diagnosis Tool

- A finetuned ResNet18 for COVID-19 diagnosis using Lung CT scan
- Finetuned U-net for labelling the infection area on raw CT scans for COVID-19 patients
- Great potential to be a commercial software product for hospitals where COVID-19 Test Kits are unavailable

#### 2019 Autonomous Ball Dispensing Mobile Machine

- Started from literature and market survey, through professional engineering decision-making tools to successfully converge to a fully autonomous ball dispensing machine prototype
- Used PIC18F4620 with MPLAB X and Arduino Nano to enable movement of its components, real-time clock, user Interface, and IR Remote Control
- · Can potentially be used for automatic delivery and dispensing in warehouses

### **Skills**

Languages | (*Proficient*) Python, C/C++, MATLAB, LaTeX - (*Working*) PostgreSQL, Bash, Java, Verilog

Tools | Git, Linux/Unix, Docker, Anaconda, Docker, AutoCAD, OpenFace, OrCAD Pspice

Libraries | PyTorch, TensorFlow, TensorFlow Lite, ONNX, ROS, NumPy OpenCV, SciPy, Scikit-learn, Pandas