Tianshu Kuai

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■ Toronto, Canada

Education

Sep 2017 – Apr 2022

Bachelor of Applied Science in Engineering Science, University of Toronto

Robotics Major, Artificial Intelligence Minor

Major GPA: 3.77 / 4.00, cGPA: 3.73 / 4.00

University of Toronto Excellence Award, NSERC Undergraduate Student Research Awards, Dean's

Honour List for all academic semesters

Experience

May 2021 - Ongoing

University of Toronto | Undergraduate Researcher

Supervised by Prof. Steven Waslander, Toronto Robotics and Artificial Intelligence Lab (TRAILab)

- Undergraduate thesis on improving feature learning processes to get more robust features and more accurate bounding box refinement for 3D object detectors
- Designed and supported the development of high-performance LiDAR 3D object detection models for autonomous vehicles. PDV [1] achieved state-of-the-art multi-class 3D object detection results on Waymo Open Dataset upon publication.

July 2021 - Ongoing

aUToronto | Computer Vision Engineer

University of Toronto Autonomous Driving Group, SAE/GM AutoDrive Challenge

- Research on fast and lightweight 3D perception models on collected data
- · Worked on deploying real-time perception models on autonomous vehicles

May 2020 - May 2021

Qualcomm | Machine Learning Research Intern

Supervised by Dr. Shaojie Zhuo, Machine Learning Research Team

- Proposed several efficient deep learning models for audio processing
- Applied state-of-the-art methods for neural network compression
- Contributed to NPU software compiler pipeline development

May 2019 - Aug 2019

University of Toronto | Undergraduate Researcher

Supervised by Prof. Deepa Kundur, Department of Electrical and Computer Engineering

- Implemented machine learning models for early relapse detection in Youth Depression
- Worked on patients' data processing and imputations for missing data
- Developed pipeline to track patients' facial expressions for behaviour analysis

Publications

2022

[1] Jordan S. K. Hu, **Tianshu Kuai**, and Steven L. Waslander, "Point Density-Aware Voxels for LiDAR 3D Object Detection," *CVPR* 2022.

· Awarded the second prize in senior design competition

Mar 2019 | NSERC Undergraduate Student Research Awards

• Undergraduate student research awards by Natural Sciences and Engineering Research Council of Canada (NSERC)

Feb 2019 | University of Toronto Excellence Award

• Awarded to University of Toronto undergraduate students based on research aptitude

Sep 2017 | University of Toronto Engineering Entrance Scholarship

Scholarship for top engineering candidates pursing studies at the University of Toronto

Selected Projects

2021 | Real Time Audio Denoiser

- A model built using convolutional neural networks with encoder-decoder structure
- Model takes the noisy speech as input and produce a de-noised speech as the final output
- Achieved good performance on various types of signals with only 33K parameters

2020 Deep Learning Based COVID-19 Diagnosis Tool

- A finetuned ResNet18 for COVID-19 diagnosis using Lung CT scan
- Finetuned U-net for labelling the infection area on raw CT scans for COVID-19 patients
- Great potential to be a commercial software product for hospitals where COVID-19 Test Kits are unavailable

2019 Autonomous Ball Dispensing Mobile Machine

- Started from literature and market survey, through professional engineering decision-making tools to successfully converge to a fully autonomous ball dispensing machine prototype
- Used PIC18F4620 with MPLAB X and Arduino Nano to enable movement of its components, real-time clock, user Interface, and IR Remote Control
- · Can potentially be used for automatic delivery and dispensing in warehouses

Skills

Languages | (*Proficient*) Python, C/C++, MATLAB, LaTeX - (*Working*) PostgreSQL, Bash, Java, Verilog

Tools | Git, Linux/Unix, Docker, Anaconda, Docker, AutoCAD, OpenFace, OrCAD Pspice

Libraries | PyTorch, TensorFlow, TensorFlow Lite, ONNX, ROS, NumPy OpenCV, SciPy, Scikit-learn, Pandas