# Tianshu Kuai

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Toronto, Canada

#### Education

Sep 2022 – Dec 2023

Master of Science in Applied Computing, University of Toronto

**AI Concentration** 

cGPA: 4.00 / 4.00

Sep 2017 – Apr 2022

Bachelor of Applied Science in Engineering Science, University of Toronto

Robotics Major, Artificial Intelligence Minor

Major GPA: 3.80 / 4.00, cGPA: 3.73 / 4.00

University of Toronto Excellence Award, NSERC Undergraduate Student Research Awards, Dean's

Honour List

# **Experience**

May 2023 - Apr 2024

Samsung AI Center Toronto | Research Intern

Supervised by Dr. Alex Levinshtein, Samsung AI Center Toronto

Research on diffusion model based real-world image restoration and enhancement

May 2022 - Ongoing

University of Toronto | 3D Computer Vision Researcher

Supervised by Prof. Igor Gilitschenski, Toronto Intelligent Systems Lab (TISL)

- Currently working on 3D scene representation and manipulation
- Proposed a template-free method [3] for building animatable 3D models for arbitrary types of articulated and deformable objects from a collection of monocular videos, which allows users to animate reconstructed objects in 3D for content creation

May 2021 - Apr 2023

**University of Toronto** | Computer Vision Researcher

Supervised by Prof. Steven L. Waslander, Toronto Robotics and Artificial Intelligence Lab (TRAILab)

- Currently working on self-supervised LiDAR semantic segmentation for autonomous driving, and contributed to the development of a novel method [2] that outperforms state-of-the-art 2D-to-3D representation learning frameworks
- Designed and supported the development of high-performance LiDAR 3D object detection models for autonomous vehicles. PDV [1] achieved state-of-the-art multi-class 3D object detection results on Waymo Open Dataset upon publication
- Undergraduate thesis on improving feature learning processes to get more robust features and more accurate bounding box refinement for 3D object detectors

July 2021 - June 2022

**aUToronto** | Computer Vision Engineer

University of Toronto Autonomous Driving Group, SAE/GM AutoDrive Challenge

- Research on fast and lightweight 3D perception models on collected data
- · Worked on deploying real-time perception models on autonomous vehicles

May 2020 - May 2021

Qualcomm | Machine Learning Research Intern

Supervised by Dr. Shaojie Zhuo, Machine Learning Research Team

- Proposed several efficient deep learning models for audio processing
- Applied state-of-the-art methods for neural network compression
- Contributed to NPU software compiler pipeline development

2023

- [3] **T. Kuai**, A. Karthikeyan, Y. Kant, A. Mirzaei, and I. Gilitschenski, "CAMM: Building Category-Agnostic and Animatable 3D Models from Monocular Videos," *CVPRW* 2023.
- [2] A. Mahmoud, J. S. K. Hu, **T. Kuai**, A. Harakeh, L. Paull, and S. L. Waslander, "Self-Supervised Image-to-Point Distillation via Semantically Tolerant Contrastive Loss," *CVPR* 2023.

2022

[1] J. S. K. Hu, **T. Kuai**, and S. L. Waslander, "Point Density-Aware Voxels for LiDAR 3D Object Detection," *CVPR* 2022.

## **Academic Service**

Reviewer | CVPR 2023, WACV 2024, ECCV 2024

## **Honors**

#### Jan 2020

# **University of Toronto Engineering Competition**

• Awarded the second prize in the senior design competition

## Mar 2019

# **NSERC Undergraduate Student Research Award**

• Undergraduate student research award from Natural Sciences and Engineering Research Council of Canada (NSERC)

#### Feb 2019

## **University of Toronto Excellence Award**

Awarded to University of Toronto undergraduate students based on research aptitude

## Sep 2017

# **University of Toronto Engineering Entrance Scholarship**

Scholarship for top engineering candidates pursuing studies at the University of Toronto

# **Selected Projects**

#### 2021

#### **Real Time Audio Denoiser**

- A model built using convolutional neural networks with an encoder-decoder structure
- The model takes the noisy speech as input and produces a de-noised speech as the output
- Achieved good performance on various types of signals with only around 33k parameters

#### 2020

# Deep Learning Based COVID-19 Diagnosis Tool

- A finetuned ResNet-18 for COVID-19 diagnosis using Lung CT scan
- Finetuned U-Net for labelling the infection area on raw CT scans for COVID-19 patients
- Great potential to be a commercial software product for hospitals where COVID-19 testing kits are unavailable

## 2019

## **Autonomous Ball Dispensing Mobile Machine**

- Started from literature and market survey, through professional engineering decision-making tools to successfully converge to a fully autonomous ball dispensing machine prototype
- Used PIC18F4620 with MPLAB X and Arduino Nano to enable movement of its components, real-time clock, user Interface, and IR Remote Control
- Can potentially be used for automatic delivery and dispensing in warehouses