

Assignment 4: Data-driven engineering from fleets

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MPMOB

First, I drew a circle with a radius of 15 in the middle of the video. The image width is 640 and height is 480, so I choose the midpoint of the horizontal coordinate (320). We want to make it possible to move the circle up and down depending on the speed when the vehicle accelerates, so we calculate the y coordinate by $480 - \text{int}(15 * \text{speed})$.

```
// Draw a blue circle
cv::circle(img, cv::Point(320, 480-int(15*speed)), 15, cv::Scalar(255, 0, 0)); // circle
```

In the top left corner of the image, print the speed of the vehicle.

```
std::string speedText = "Speed: " + std::to_string(speed) + " m/s"; // speed text
cv::putText(img, //target image
    speedText, //text
    cv::Point(10, 30), //top-left position
    cv::FONT_HERSHEY_DUPLEX, //typeface
    0.8, //type size
    CV_RGB(118, 185, 0), //font color
    1 //font thickness);
```

The results are displayed as follows:



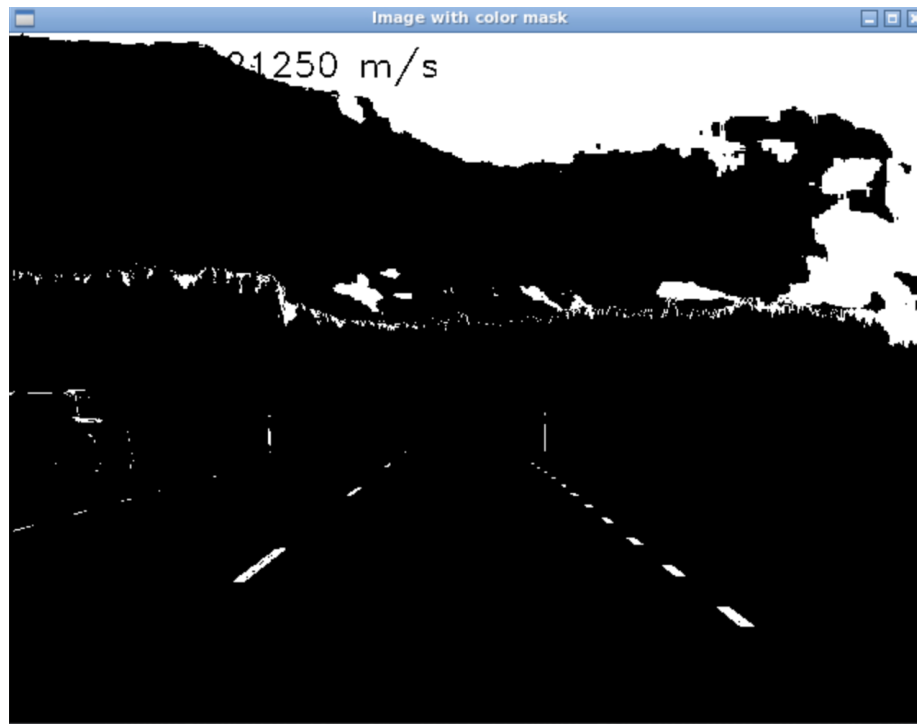
When speed up, the circle's position will move ahead on the road:



Then, I create a color filter to filter out the white road markings. When I try to detect objects by adjusting thresholds through a range of pixel values in the HSV color space, the filtering is not very effective as the white of the sky and the white of the road signs are particularly similar.

```
cv::Mat mask;  
cv::inRange(hsvImg, cv::Scalar(0, 0, 180), cv::Scalar(180, 35, 255), mask);
```

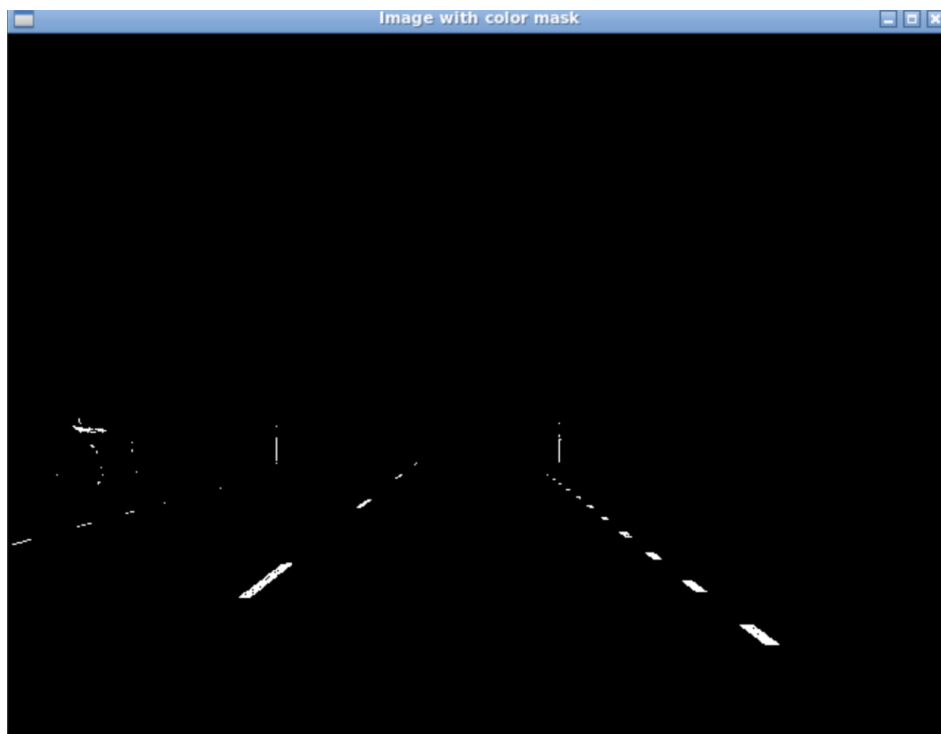
The filtering result shows as follows.



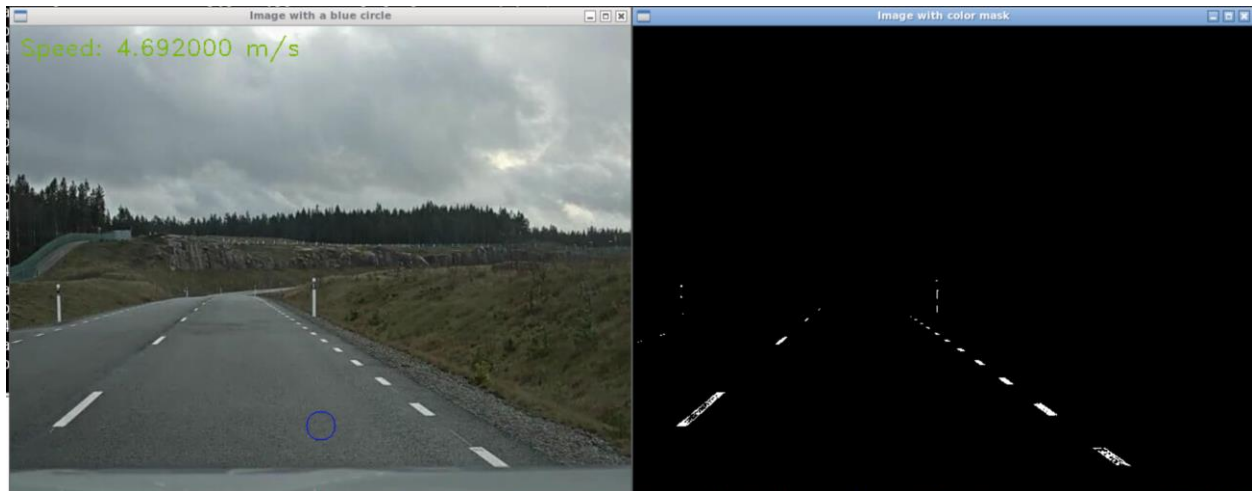
So, I added a masking layer to cover the top half of the image to improve the filtering effect.

```
cv::rectangle(img,cv::Point(0,0),cv::Point(640,260),cv::Scalar(0,0,255),-1); //new layer
```

The final result as following:



Inclusion, my final result is shown below:



Commands:

You need to run **xhost +** first

First login the docker:

```
docker login registry.git.chalmers.se
```

Then, download the reply video

```
docker run -ti --rm --init --net=host --ipc=host -v /tmp:/tmp -e DISPLAY=$DISPLAY  
registry.git.chalmers.se/ola.benderius/mms210-assignment-datareplay:rest_handler
```

Open another terminal, go into folder as this README.md file, run

```
docker build -t myapp .
```

Then run the image

```
docker run --rm -ti --init --net=host --ipc=host -v /tmp:/tmp -e DISPLAY=$DISPLAY myapp
```

Finally, you can get the results.