

Lab09-Approximation Algorithm

CS214-Algorithm and Complexity, Xiaofeng Gao, Spring 2019.

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1. **Solution.** The following is process of solution.

a. The basic idea of a greedy algorithm is starting with an arbitrary center, and in each round, add the 'farthest' vertex to the center set until there are totally k centers.

Algorithm 1: Greedy approximation.

Input: an complete undirected graph with nonnegative edge $G(V, E)$.

Output: minimal $\max_v \{cost(v, S)\}$.

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1 S  $\leftarrow \{c_1\}$ ;  $c_1$  is an arbitrary center we choose at first .
2 for  $v \in V - S$  do
3   if  $|S| \leq k$  then
4     Find the farthest vertex  $v_i$  to center set.
5     S  $\leftarrow S \cup \{c_i\}$ .
6 return S.
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b. Let's consider a set S and two vertices v_g and v_{opt} , The optimal choice is to choose v_{opt} but we choose the v_g by greedy algorithm. In this case, we can use an illustration to describe this question, then we can construct the following relation:

$$\begin{cases} cost(v_g, S) = \max\{s_1, s\} = s_{m1}; \\ cost(v_{opt}, S) = \max\{s_2, s\} = s_{m2}; \end{cases}$$

According to the triangle inequality:

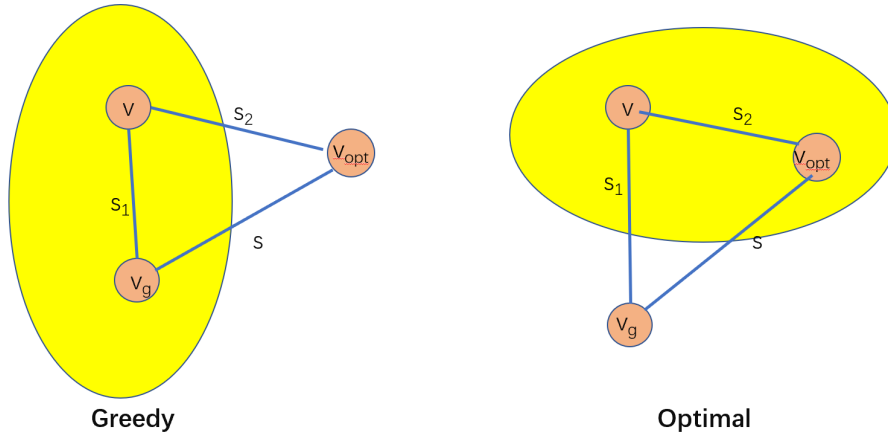


Figure 1: The flow of two nodes is 1

$cost(v_g, S) = \max\{s_1, s\} = s_{m1} \leq s_2 + s \leq 2 * \max\{s_2, s\} = 2cost(v_{opt}, S);$
 then $cost(v_g, S) \leq 2cost(v_{opt}, S)$, so $\frac{cost(v_g, S)}{cost(v_{opt}, S)} \leq 2$.

□

2. **Solution.** The following is the process of proof.

proof: In this case, we can use a vertex \mathbf{v} which belongs to \mathbf{R} , set $\mathbf{R}-\mathbf{v}$ and set \mathbf{S} , the goal is to find minimum cost tree, we can use an illustration to describe this question:

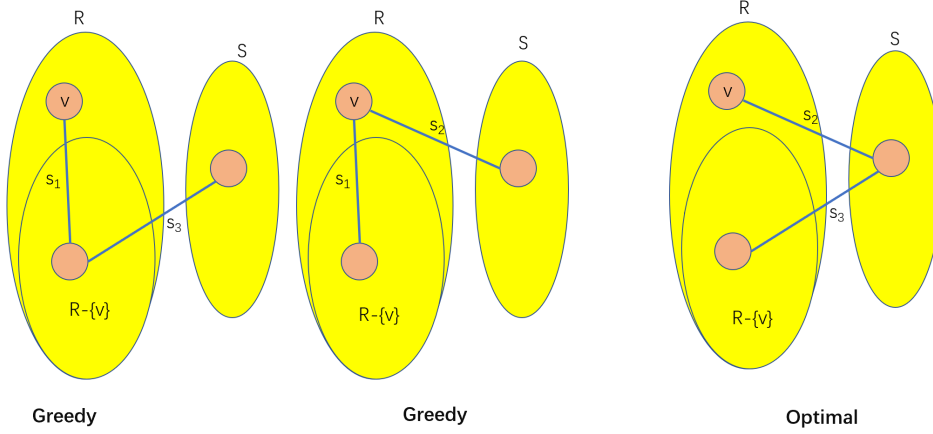


Figure 2: The flow of two nodes is 1

we consider the a vertex \mathbf{v} in \mathbf{R} , according to approximation, we know vertex \mathbf{v} must connect to one vertex in $\mathbf{R}-\mathbf{v}$, but in optimal answer, we know \mathbf{v} can connect to one vertex in \mathbf{S} , so, we can construct to the following relation by illustration above.

$$\begin{cases} c_g = s_1 + \min\{s_2, s_3\}; \\ c_{opt} = s_2 + s_3; \end{cases}$$

According to the triangle inequality: $c_g = s_1 + \min\{s_2, s_3\} \leq 2(s_2 + s_3) \leq 2c_{opt}$; For all vertices in \mathbf{R} , we have same relation, so $C_g \leq 2C_{opt}$, then $\frac{C_g}{C_{opt}} \leq 2$. □

3. Minimum Weighted Vertex Cover:

a. Denote: we assume C is a cover vertex set, In graph $G(V, E)$, for each vertex $v \in V$, if $v \in C$, $x(v) = 1$ (vertex v in vertex cover set), if $v \notin C$, $x(v) = 0$ (vertex v not in vertex cover set). at least one vertex is in vertex cover set for every edge: $x(v_j) + x(v_i) \geq 1$;

integer linear program:

$$\begin{cases} \sum_{v_i \in V} c_i x(v_i); \\ x(v_j) + x(v_i) \geq 1; \\ x(v_i), x(v_j) = 0, 1; \\ i \in \{1, 2 \dots n\} \end{cases}$$

b. proof: As we know, the following is an approximation algorithm with value $m_{LP}(G)$, we assume: m^*LP is the best solution for linear program. Then $m^*(LP) \leq m^*(G)$;

In solution **a**, we know $x(v_j) + x(v_i) \geq 1$;

so there must have one vertex which $x(v) \geq \frac{1}{2}$; $\{v_i, v_j\} \geq \frac{1}{2}$;

$$m^*(LP) = \sum_{v_i \in V} c_i x(v_i) \geq \sum_{v_i \in V \text{ and } x(v) \geq \frac{1}{2}} c_i x(v_i) \geq \sum_{v_i \in V \text{ and } x(v) \geq \frac{1}{2}} \frac{1}{2} * c_i = \frac{1}{2} m_{LP}(G)$$

Then, $\Rightarrow \frac{1}{2} m_{LP}(G) \leq m^*(G)$;

So, $\Rightarrow m_{LP}(G) / m^*(G) \leq 2$.

4. Give the corresponding $(I, sol, m, goal)$ for **Metric k -center** and **Minimum Weighted Vertex Cover** respectively. **Metric k -center**($I, sol, m, goal$) :
- $I = \{G(V, E) | G \text{ is a graph}\}$; poly time decidable.
- $sol = \{U \subseteq V | \text{arbitrary select a vertex as center, add the 'farthest' vertex to the center set until there are totally } k \text{ centers.}\}$
- $m = \text{farthest distance } v \text{ to } k\text{-center set } U; v \notin U;$
- $goal = \min\{m\};$
- Minimum Weighted Vertex Cover** ($I, sol, m, goal$):
- $I = \{G(V, E) | G \text{ is a graph}\}$; poly time decidable.
- $sol = U \subseteq V | \forall (v, u) \in E (v \in U \text{ or } u \in U).$
- $m = \sum_{v \in V} c(v)x(v). v \in V, x(v) = 1; v \notin V, x(v) = 0; c(v) \text{ is the cost of vertex } v.$
- $goal = \min\{m\}$

Remark: You need to include your .pdf and .tex files in your uploaded .zip file.