dog_app

May 7, 2020

1 Convolutional Neural Networks

1.1 Project: Write an Algorithm for a Dog Identification App

In this notebook, some template code has already been provided for you, and you will need to implement additional functionality to successfully complete this project. You will not need to modify the included code beyond what is requested. Sections that begin with '(IMPLEMENTATION)' in the header indicate that the following block of code will require additional functionality which you must provide. Instructions will be provided for each section, and the specifics of the implementation are marked in the code block with a 'TODO' statement. Please be sure to read the instructions carefully!

Note: Once you have completed all of the code implementations, you need to finalize your work by exporting the Jupyter Notebook as an HTML document. Before exporting the notebook to html, all of the code cells need to have been run so that reviewers can see the final implementation and output. You can then export the notebook by using the menu above and navigating to **File -> Download as -> HTML (.html)**. Include the finished document along with this notebook as your submission.

In addition to implementing code, there will be questions that you must answer which relate to the project and your implementation. Each section where you will answer a question is preceded by a 'Question X' header. Carefully read each question and provide thorough answers in the following text boxes that begin with 'Answer:'. Your project submission will be evaluated based on your answers to each of the questions and the implementation you provide.

Note: Code and Markdown cells can be executed using the **Shift + Enter** keyboard shortcut. Markdown cells can be edited by double-clicking the cell to enter edit mode.

The rubric contains *optional* "Stand Out Suggestions" for enhancing the project beyond the minimum requirements. If you decide to pursue the "Stand Out Suggestions", you should include the code in this Jupyter notebook.

Step 0: Import Datasets

Make sure that you've downloaded the required human and dog datasets:

Note: if you are using the Udacity workspace, you *DO NOT* need to re-download these - they can be found in the /data folder as noted in the cell below.

- Download the dog dataset. Unzip the folder and place it in this project's home directory, at the location /dog_images.
- Download the human dataset. Unzip the folder and place it in the home directory, at location /lfw.

Note: If you are using a Windows machine, you are encouraged to use 7zip to extract the folder. In the code cell below, we save the file paths for both the human (LFW) dataset and dog dataset in the numpy arrays human_files and dog_files.

Step 1: Detect Humans

In this section, we use OpenCV's implementation of Haar feature-based cascade classifiers to detect human faces in images.

OpenCV provides many pre-trained face detectors, stored as XML files on github. We have downloaded one of these detectors and stored it in the haarcascades directory. In the next code cell, we demonstrate how to use this detector to find human faces in a sample image.

```
In [3]: import cv2
    import matplotlib.pyplot as plt
    %matplotlib inline

# extract pre-trained face detector
    face_cascade = cv2.CascadeClassifier('haarcascades/haarcascade_frontalface_alt.xml')

# load color (BGR) image
    img = cv2.imread(human_files[0])
    # convert BGR image to grayscale
    gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# find faces in image
    faces = face_cascade.detectMultiScale(gray)

# print number of faces detected in the image
    print('Number of faces detected:', len(faces))
```

```
# get bounding box for each detected face
for (x,y,w,h) in faces:
    # add bounding box to color image
    cv2.rectangle(img,(x,y),(x+w,y+h),(255,0,0),2)

# convert BGR image to RGB for plotting
cv_rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)

# display the image, along with bounding box
plt.imshow(cv_rgb)
plt.show()
```

Number of faces detected: 1



Before using any of the face detectors, it is standard procedure to convert the images to grayscale. The detectMultiScale function executes the classifier stored in face_cascade and takes the grayscale image as a parameter.

In the above code, faces is a numpy array of detected faces, where each row corresponds to a detected face. Each detected face is a 1D array with four entries that specifies the bounding box of the detected face. The first two entries in the array (extracted in the above code as x and y) specify the horizontal and vertical positions of the top left corner of the bounding box. The last two entries in the array (extracted here as w and h) specify the width and height of the box.

1.1.1 Write a Human Face Detector

We can use this procedure to write a function that returns True if a human face is detected in an image and False otherwise. This function, aptly named face_detector, takes a string-valued file path to an image as input and appears in the code block below.

```
In [4]: # returns "True" if face is detected in image stored at img_path
    def face_detector(img_path):
        img = cv2.imread(img_path)
        gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)
        faces = face_cascade.detectMultiScale(gray)
        return len(faces) > 0
```

1.1.2 (IMPLEMENTATION) Assess the Human Face Detector

Question 1: Use the code cell below to test the performance of the face_detector function.

- What percentage of the first 100 images in human_files have a detected human face?
- What percentage of the first 100 images in dog_files have a detected human face?

Ideally, we would like 100% of human images with a detected face and 0% of dog images with a detected face. You will see that our algorithm falls short of this goal, but still gives acceptable performance. We extract the file paths for the first 100 images from each of the datasets and store them in the numpy arrays human_files_short and dog_files_short.

Answer: (You can print out your results and/or write your percentages in this cell)

```
In [5]: from tqdm import tqdm
        human_files_short = human_files[:100]
        dog_files_short = dog_files[:100]
        #-#-# Do NOT modify the code above this line. #-#-#
        ## TODO: Test the performance of the face_detector algorithm
        ## on the images in human_files_short and dog_files_short.
        #intialise the detecting of face counts to 0
        human_detect_count = 0
        dog_detect_count = 0
        # counter for detecting human face
        for i in human_files_short:
            if face detector(i):
                human_detect_count += 1
        #counter for detecting dog face
        for i in dog_files_short:
            if face_detector(i):
                dog_detect_count +=1
        print("Humans face detection: {}%\nHuman face detection in dogs: {}%".format(human_detection)
```

```
Humans face detection: 98%
Human face detection in dogs: 17%
```

We suggest the face detector from OpenCV as a potential way to detect human images in your algorithm, but you are free to explore other approaches, especially approaches that make use of deep learning:). Please use the code cell below to design and test your own face detection algorithm. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

Step 2: Detect Dogs

In this section, we use a pre-trained model to detect dogs in images.

1.1.3 Obtain Pre-trained VGG-16 Model

The code cell below downloads the VGG-16 model, along with weights that have been trained on ImageNet, a very large, very popular dataset used for image classification and other vision tasks. ImageNet contains over 10 million URLs, each linking to an image containing an object from one of 1000 categories.

```
In [7]: import torch
    import torchvision.models as models

# define VGG16 model
    VGG16 = models.vgg16(pretrained=True)

# check if CUDA is available
    use_cuda = torch.cuda.is_available()

# move model to GPU if CUDA is available
    if use_cuda:
        VGG16 = VGG16.cuda()
```

Downloading: "https://download.pytorch.org/models/vgg16-397923af.pth" to /root/.torch/models/vgg100%|| 553433881/553433881 [00:05<00:00, 101903979.81it/s]

Given an image, this pre-trained VGG-16 model returns a prediction (derived from the 1000 possible categories in ImageNet) for the object that is contained in the image.

1.1.4 (IMPLEMENTATION) Making Predictions with a Pre-trained Model

In [8]: from PIL import Image

In the next code cell, you will write a function that accepts a path to an image (such as 'dogImages/train/001.Affenpinscher/Affenpinscher_00001.jpg') as input and returns the index corresponding to the ImageNet class that is predicted by the pre-trained VGG-16 model. The output should always be an integer between 0 and 999, inclusive.

Before writing the function, make sure that you take the time to learn how to appropriately pre-process tensors for pre-trained models in the PyTorch documentation.

```
import torchvision.transforms as transforms
def VGG16_predict(img_path):
    Use pre-trained VGG-16 model to obtain index corresponding to
    predicted ImageNet class for image at specified path
    Args:
        img_path: path to an image
    Returns:
        Index corresponding to VGG-16 model's prediction
    ## TODO: Complete the function.
    ## Load and pre-process an image from the given img_path
   ### PROCESSING IMAGE IN PYTORCH ###
    image = Image.open(img_path)
    #Create a transform by Resizing it to 255 and Centercrop to 224
    transform = transforms.Compose([transforms.Resize(255),transforms.CenterCrop(224),
                                     transforms.ToTensor(), transforms.Normalize(mean=[0]
                                                                                  std=[0.
    image = transform(image).float()
    image_update = image.unsqueeze(0)
    #transfer to Cuda
    image2 = image_update.cuda()
    #activate eval mode
    VGG16.eval()
    output = VGG16(image2)
    output_1 = output.cpu().data.numpy().argmax() # prediction will be index of class lo
```

```
## Return the *index* of the predicted class for that image
return output_1 # predicted class index
```

1.1.5 (IMPLEMENTATION) Write a Dog Detector

While looking at the dictionary, you will notice that the categories corresponding to dogs appear in an uninterrupted sequence and correspond to dictionary keys 151-268, inclusive, to include all categories from 'Chihuahua' to 'Mexican hairless'. Thus, in order to check to see if an image is predicted to contain a dog by the pre-trained VGG-16 model, we need only check if the pre-trained model predicts an index between 151 and 268 (inclusive).

Use these ideas to complete the dog_detector function below, which returns True if a dog is detected in an image (and False if not).

1.1.6 (IMPLEMENTATION) Assess the Dog Detector

Question 2: Use the code cell below to test the performance of your dog_detector function.

- What percentage of the images in human_files_short have a detected dog?
- What percentage of the images in dog_files_short have a detected dog?

```
Answer:
```

```
0.0%
```

```
detected dog in human_files: 0.0% detected dog in dog_files: 100.0%
```

We suggest VGG-16 as a potential network to detect dog images in your algorithm, but you are free to explore other pre-trained networks (such as Inception-v3, ResNet-50, etc). Please use the code cell below to test other pre-trained PyTorch models. If you decide to pursue this *optional* task, report performance on human_files_short and dog_files_short.

Step 3: Create a CNN to Classify Dog Breeds (from Scratch)

Now that we have functions for detecting humans and dogs in images, we need a way to predict breed from images. In this step, you will create a CNN that classifies dog breeds. You must create your CNN *from scratch* (so, you can't use transfer learning *yet*!), and you must attain a test accuracy of at least 10%. In Step 4 of this notebook, you will have the opportunity to use transfer learning to create a CNN that attains greatly improved accuracy.

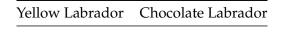
We mention that the task of assigning breed to dogs from images is considered exceptionally challenging. To see why, consider that *even a human* would have trouble distinguishing between a Brittany and a Welsh Springer Spaniel.

Brittany	Welsh Springer Spaniel	

It is not difficult to find other dog breed pairs with minimal inter-class variation (for instance, Curly-Coated Retrievers and American Water Spaniels).

Curly-Coated Retriever	American Water Spaniel

Likewise, recall that labradors come in yellow, chocolate, and black. Your vision-based algorithm will have to conquer this high intra-class variation to determine how to classify all of these different shades as the same breed.



We also mention that random chance presents an exceptionally low bar: setting aside the fact that the classes are slightly imabalanced, a random guess will provide a correct answer roughly 1 in 133 times, which corresponds to an accuracy of less than 1%.

Remember that the practice is far ahead of the theory in deep learning. Experiment with many different architectures, and trust your intuition. And, of course, have fun!

1.1.7 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dog_images/train, dog_images/valid, and dog_images/test, respectively). You may find this documentation on custom datasets to be a useful resource. If you are interested in augmenting your training and/or validation data, check out the wide variety of transforms!

```
In [12]: ### TODO: Write data loaders for training, validation, and test sets
         ## Specify appropriate transforms, and batch_sizes
         import os
         import torch
         from torchvision import datasets
         from PIL import ImageFile
         from torchvision import datasets, transforms
         ImageFile.LOAD_TRUNCATED_IMAGES = True
         # Declare the transforms for train, valid and test sets.
         transforms = {
             # RandomHorizontalFlip() & RandomRotation() to augement data in train transformation
             'train' : transforms.Compose([transforms.Resize(256),
                                           transforms.RandomResizedCrop(224),
                                           transforms.RandomHorizontalFlip(),
                                           transforms.RandomRotation(10),
                                            transforms.ToTensor(),
                                            transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                 std=[0.229, 0.224, 0.225])]),
             'valid' : transforms.Compose([transforms.Resize(256),
                                           transforms.CenterCrop(224),
                                           transforms.ToTensor(),
                                           transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                 std=[0.229, 0.224, 0.225])]),
             'test' : transforms.Compose([transforms.Resize(256),
                                          transforms.CenterCrop(224),
                                          transforms.ToTensor(),
                                          transforms.Normalize(mean=[0.485, 0.456, 0.406],
                                                                std=[0.229, 0.224, 0.225])])
         }
         # number of subprocesses to use for data loading
         num_workers = 0
         # how many samples per batch to load
         batch_size = 20
```

```
# Create image datasets (train, valid, test)
         image_datasets = {x: datasets.ImageFolder(os.path.join('/data/dog_images', x), transfor
                          for x in ['train', 'valid', 'test']}
         # Create data loaders (train, valid, test)
         data_loaders = {x: torch.utils.data.DataLoader(image_datasets[x], batch_size=batch_size
                                                       shuffle=True, num_workers = num_workers)
                        for x in ['train', 'valid', 'test']}
In [13]: from torchvision import utils
         def visualize_sample_images(inp):
             inp = inp.numpy().transpose((1, 2, 0))
             inp = inp * np.array((0.229, 0.224, 0.225)) + np.array((0.485, 0.456, 0.406))
             inp = np.clip(inp, 0, 1)
             fig = plt.figure(figsize=(60, 25))
             plt.axis('off')
             plt.imshow(inp)
             plt.pause(0.001)
In [14]: inputs, classes = next(iter(data_loaders['train']))
         # Convert the batch to a grid.
         grid = utils.make_grid(inputs, nrow=5)
         # Display!
         visualize_sample_images(grid)
```



Question 3: Describe your chosen procedure for preprocessing the data. - How does your code resize the images (by cropping, stretching, etc)? What size did you pick for the input tensor, and why? - Did you decide to augment the dataset? If so, how (through translations, flips, rotations, etc)? If not, why not?

Answer:

Resizing to 256px before cropping to 224 x 224 px. Reducing the size of the images could increase processing time (Taking reference from vgg16)

Yes, augumented the dataset to add more training variations by horizontal flipping and slight rotation

1.1.8 (IMPLEMENTATION) Model Architecture

Create a CNN to classify dog breed. Use the template in the code cell below.

```
super(Net, self).__init__()
        ## Define layers of a CNN
        self.conv1 = nn.Conv2d(3, 32, 3)
        self.conv2 = nn.Conv2d(32, 64, 3)
        self.conv3 = nn.Conv2d(64, 128, 3)
        self.conv4 = nn.Conv2d(128, 256, 3)
        self.conv5 = nn.Conv2d(256, 512, 3)
        self.fc1 = nn.Linear(512 * 6 * 6, 1024)
        self.fc2 = nn.Linear(1024, 133)
        self.max_pool = nn.MaxPool2d(2, 2,ceil_mode=True)
        self.dropout = nn.Dropout(0.25)
    def forward(self, x):
        ## Define forward behavior
        x = F.relu(self.conv1(x))
        x = self.max_pool(x)
        x = F.relu(self.conv2(x))
        x = self.max_pool(x)
        x = F.relu(self.conv3(x))
        x = self.max_pool(x)
        x = F.relu(self.conv4(x))
        x = self.max_pool(x)
        x = F.relu(self.conv5(x))
        x = self.max_pool(x)
        x = x.view(-1, 512 * 6 * 6)
        x = self.dropout(x)
        x = self.fc1(x)
        return x
#-#-# You so NOT have to modify the code below this line. #-#-#
# instantiate the CNN
model_scratch = Net()
print(model_scratch)
# move tensors to GPU if CUDA is available
if use_cuda:
    model_scratch.cuda()
```

def __init__(self):

```
Net(
    (conv1): Conv2d(3, 32, kernel_size=(3, 3), stride=(1, 1))
    (conv2): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1))
    (conv3): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1))
    (conv4): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1))
    (conv5): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1))
    (fc1): Linear(in_features=18432, out_features=1024, bias=True)
    (fc2): Linear(in_features=1024, out_features=133, bias=True)
    (max_pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=True)
    (dropout): Dropout(p=0.25)
)
```

Question 4: Outline the steps you took to get to your final CNN architecture and your reasoning at each step.

Answer:

First input layer has shape (224, 224, 3) while the last layer have 133 output classes.

(input): (shape: 224, 224, 3) (conv1): Conv2d(3, 32, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1)) with ReLU activation (shape: 112, 112, 3) (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False) (shape: 56, 56, 3) (conv2): Conv2d(32, 64, kernel_size=(3, 3), stride=(2, 2), padding=(1, 1)) with ReLU activation (shape: 28, 28, 3) (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False) (shape: 14, 14, 3) (conv3): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1)) with ReLU activation (shape: 14, 14, 3) (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False) (shape: 7, 7, 3) (dropout): Dropout(p=0.25) (fc1): Linear(in_features=6272, out_features=512, bias=True) (dropout): Dropout(p=0.25) (fc2): Linear(in_features=512, out_features=133, bias=True)

Convolution layers are used to extract features from an input image. The more convolutional layers there are, the more complex patterns in color and shape a model can detect. But to keep things simple only 3 convolution layers are used in the model. Maxpooling is added to downsample by a factor of 2 after each convolution layers. 25% dropout added before each fully-connected layer to prevent overfitting. Last fully-connected layer will produce the final output_size (133 dimension) which predicts the different classes of breeds.

1.1.9 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_scratch, and the optimizer as optimizer_scratch below.

```
In [16]: import torch.optim as optim
    ### TODO: select loss function
    criterion_scratch = nn.CrossEntropyLoss()

### TODO: select optimizer
    optimizer_scratch = optim.SGD(model_scratch.parameters(), lr=0.01)
```

1.1.10 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_scratch.pt'.

```
In [17]: def train(n_epochs, loaders, model, optimizer, criterion, use_cuda, save_path):
             """returns trained model"""
             # initialize tracker for minimum validation loss
             valid_loss_min = np.Inf
             for epoch in range(1, n_epochs+1):
                 # initialize variables to monitor training and validation loss
                 train_loss = 0.0
                 valid_loss = 0.0
                 ##################
                 # train the model #
                 ###################
                 model.train()
                 for batch_idx, (data, target) in enumerate(loaders['train']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## find the loss and update the model parameters accordingly
                     ## record the average training loss, using something like
                     \#\# train_loss = train_loss + ((1 / (batch_idx + 1)) * (loss.data - train_loss)
                     # clear the gradients of all optimized variables, initialize weights to zer
                     optimizer.zero_grad()
                     # forward pass
                     output = model(data)
                     # calculate batch loss
                     loss = criterion(output, target)
                     # backward pass
                     loss.backward()
                     # parameter update
                     optimizer.step()
                     # update training loss
                     train_loss += loss.item() * data.size(0)
                 ########################
                 # validate the model #
                 ######################
                 model.eval()
                 for batch_idx, (data, target) in enumerate(loaders['valid']):
                     # move to GPU
                     if use_cuda:
                         data, target = data.cuda(), target.cuda()
                     ## update the average validation loss
```

```
output = model(data)
                     # batch loss
                     loss = criterion(output, target)
                     # update validation loss
                     valid_loss += loss.item() * data.size(0)
                 # calculate average losses
                 train_loss = train_loss/len(loaders['train'].dataset)
                 valid_loss = valid_loss/len(loaders['valid'].dataset)
                 # print training/validation statistics
                 print('Epoch: {} \tTraining Loss: {:.6f} \tValidation Loss: {:.6f}'.format(
                     epoch,
                     train_loss,
                     valid loss
                     ))
                 ## TODO: save the model if validation loss has decreased
                 if valid_loss <= valid_loss_min:</pre>
                     print('Validation loss decreased ({:.6f} --> {:.6f}).
                                                                              Saving model...'.
                          format(valid_loss_min, valid_loss))
                     torch.save(model.state_dict(), save_path)
                     valid_loss_min = valid_loss
             # return trained model
             return model
         # train the model
         model_scratch = train(20, data_loaders, model_scratch, optimizer_scratch,
                               criterion_scratch, use_cuda, 'model_scratch.pt')
         # load the model that got the best validation accuracy
         model_scratch.load_state_dict(torch.load('model_scratch.pt'))
Epoch: 1
                 Training Loss: 5.566193
                                                 Validation Loss: 5.031805
Validation loss decreased (inf --> 5.031805).
                                                 Saving model...
                Training Loss: 4.976583
Epoch: 2
                                                 Validation Loss: 4.816987
Validation loss decreased (5.031805 --> 4.816987).
                                                      Saving model...
                Training Loss: 4.855926
                                                 Validation Loss: 4.737646
Validation loss decreased (4.816987 --> 4.737646).
                                                      Saving model...
Epoch: 4
                 Training Loss: 4.758092
                                                 Validation Loss: 4.553135
Validation loss decreased (4.737646 --> 4.553135).
                                                      Saving model...
Epoch: 5
                Training Loss: 4.642450
                                                 Validation Loss: 4.512341
Validation loss decreased (4.553135 --> 4.512341).
                                                      Saving model...
                 Training Loss: 4.580968
                                                 Validation Loss: 4.479118
Epoch: 6
Validation loss decreased (4.512341 --> 4.479118). Saving model...
```

forward pass

```
Epoch: 7
                 Training Loss: 4.568019
                                                 Validation Loss: 4.456455
Validation loss decreased (4.479118 --> 4.456455).
                                                      Saving model...
                 Training Loss: 4.510890
                                                 Validation Loss: 4.412300
Epoch: 8
Validation loss decreased (4.456455 --> 4.412300).
                                                       Saving model...
                 Training Loss: 4.494479
Epoch: 9
                                                 Validation Loss: 4.316257
Validation loss decreased (4.412300 --> 4.316257).
                                                       Saving model...
Epoch: 10
                  Training Loss: 4.465570
                                                  Validation Loss: 4.287399
Validation loss decreased (4.316257 --> 4.287399).
                                                       Saving model...
                  Training Loss: 4.438796
Epoch: 11
                                                  Validation Loss: 4.243660
Validation loss decreased (4.287399 --> 4.243660).
                                                       Saving model...
                  Training Loss: 4.373902
                                                  Validation Loss: 4.247626
Epoch: 12
                  Training Loss: 4.344232
                                                  Validation Loss: 4.229075
Epoch: 13
Validation loss decreased (4.243660 --> 4.229075).
                                                       Saving model...
                                                  Validation Loss: 4.198115
                  Training Loss: 4.284812
Epoch: 14
Validation loss decreased (4.229075 --> 4.198115).
                                                       Saving model...
                  Training Loss: 4.255675
                                                  Validation Loss: 4.094622
Epoch: 15
Validation loss decreased (4.198115 --> 4.094622).
                                                       Saving model...
                  Training Loss: 4.196409
                                                  Validation Loss: 4.073539
Epoch: 16
Validation loss decreased (4.094622 \rightarrow 4.073539).
                                                       Saving model...
Epoch: 17
                  Training Loss: 4.173815
                                                  Validation Loss: 4.043166
Validation loss decreased (4.073539 \longrightarrow 4.043166).
                                                       Saving model...
Epoch: 18
                  Training Loss: 4.099463
                                                  Validation Loss: 4.041133
Validation loss decreased (4.043166 --> 4.041133).
                                                      Saving model...
                  Training Loss: 4.088770
                                                  Validation Loss: 3.951870
Epoch: 19
Validation loss decreased (4.041133 --> 3.951870).
                                                      Saving model...
Epoch: 20
                  Training Loss: 4.042433
                                                  Validation Loss: 3.911743
Validation loss decreased (3.951870 --> 3.911743).
                                                      Saving model...
```

1.1.11 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 10%.

```
In [18]: def test(loaders, model, criterion, use_cuda):
    # monitor test loss and accuracy
    test_loss = 0.
    correct = 0.
    total = 0.

model.eval()
    for batch_idx, (data, target) in enumerate(loaders['test']):
        # move to GPU
        if use_cuda:
            data, target = data.cuda(), target.cuda()
        # forward pass: compute predicted outputs by passing inputs to the model output = model(data)
```

```
# calculate the loss
                 loss = criterion(output, target)
                 # update average test loss
                 test_loss = test_loss + ((1 / (batch_idx + 1)) * (loss.data - test_loss))
                 # convert output probabilities to predicted class
                 pred = output.data.max(1, keepdim=True)[1]
                 # compare predictions to true label
                 correct += np.sum(np.squeeze(pred.eq(target.data.view_as(pred))).cpu().numpy())
                 total += data.size(0)
             print('Test Loss: {:.6f}\n'.format(test_loss))
             print('\nTest Accuracy: %2d%% (%2d/%2d)' % (
                 100. * correct / total, correct, total))
         # call test function
         test(data_loaders, model_scratch, criterion_scratch, use_cuda)
Test Loss: 3.853810
Test Accuracy: 10% (90/836)
```

Step 4: Create a CNN to Classify Dog Breeds (using Transfer Learning)

You will now use transfer learning to create a CNN that can identify dog breed from images. Your CNN must attain at least 60% accuracy on the test set.

1.1.12 (IMPLEMENTATION) Specify Data Loaders for the Dog Dataset

Use the code cell below to write three separate data loaders for the training, validation, and test datasets of dog images (located at dogImages/train, dogImages/valid, and dogImages/test, respectively).

If you like, **you are welcome to use the same data loaders from the previous step**, when you created a CNN from scratch.

1.1.13 (IMPLEMENTATION) Model Architecture

Use transfer learning to create a CNN to classify dog breed. Use the code cell below, and save your initialized model as the variable model_transfer.

```
In [20]: import torchvision.models as models
    import torch.nn as nn
```

```
## TODO: Specify model architecture
## TODO: Specify model architecture
model_transfer = models.resnet50(pretrained=True)

# Freeze parameters so we don't backprop through them
for param in model_transfer.parameters():
    param.requires_grad = False

# Replace the last fully connected layer with a Linnear layer with 133 out features
model_transfer.fc = nn.Linear(2048, 133)

if use_cuda:
    model_transfer = model_transfer.cuda()
```

Downloading: "https://download.pytorch.org/models/resnet50-19c8e357.pth" to /root/.torch/models/100%|| 102502400/102502400 [00:01<00:00, 89186154.18it/s]

Question 5: Outline the steps you took to get to your final CNN architecture and your reasoning at each step. Describe why you think the architecture is suitable for the current problem.

Answer:

For this CNN I picked ResNet50 for it good performance vs error on ImageNet classification. It contains dog breeds that have been pretrained, it seemed to be the perfect network for my hardware and accuracy requirements.

1.1.14 (IMPLEMENTATION) Specify Loss Function and Optimizer

Use the next code cell to specify a loss function and optimizer. Save the chosen loss function as criterion_transfer, and the optimizer as optimizer_transfer below.

1.1.15 (IMPLEMENTATION) Train and Validate the Model

Train and validate your model in the code cell below. Save the final model parameters at filepath 'model_transfer.pt'.

```
Epoch: 3
                Training Loss: 1.328834
                                                Validation Loss: 0.621706
Validation loss decreased (0.687194 --> 0.621706).
                                                     Saving model...
                Training Loss: 1.257801
                                                Validation Loss: 0.574082
Epoch: 4
Validation loss decreased (0.621706 --> 0.574082).
                                                     Saving model...
               Training Loss: 1.233920
Epoch: 5
                                           Validation Loss: 0.584076
Epoch: 6
                Training Loss: 1.228276
                                                Validation Loss: 0.645630
Epoch: 7
                Training Loss: 1.163031
                                                Validation Loss: 0.577747
Epoch: 8
                Training Loss: 1.166042
                                                Validation Loss: 0.548597
Validation loss decreased (0.574082 --> 0.548597).
                                                     Saving model...
Epoch: 9
                Training Loss: 1.152910
                                               Validation Loss: 0.554076
                                                Validation Loss: 0.603190
Epoch: 10
                 Training Loss: 1.128183
```

1.1.16 (IMPLEMENTATION) Test the Model

Try out your model on the test dataset of dog images. Use the code cell below to calculate and print the test loss and accuracy. Ensure that your test accuracy is greater than 60%.

```
In [ ]: test(transfer_loaders, model_transfer, criterion_transfer, use_cuda)
```

1.1.17 (IMPLEMENTATION) Predict Dog Breed with the Model

Write a function that takes an image path as input and returns the dog breed (Affenpinscher, Afghan hound, etc) that is predicted by your model.

```
In [ ]: ### TODO: Write a function that takes a path to an image as input
        ### and returns the dog breed that is predicted by the model.
        from torchvision import transforms
        from PIL import Image
        from PIL import ImageFile
        ImageFile.LOAD_TRUNCATED_IMAGES = True
        # list of class names by index, i.e. a name can be accessed like class_names[0]
        class_names = [item[4:].replace("_", " ") for item in transfer_loaders['train'].dataset.
        def predict_breed_transfer(img_path):
            # load the image and return the predicted breed
            img = Image.open(img_path)
            transform = transforms.Compose([transforms.Resize(224),
                                        transforms.CenterCrop(224),
                                        transforms.ToTensor(),
                                        transforms.Normalize([0.485, 0.456, 0.406],
                                                              [0.229, 0.224, 0.225])])
            img_as_tensor = transform(img)
            img_as_tensor = img_as_tensor.unsqueeze_(0)
            if use_cuda:
                img_as_tensor = img_as_tensor.cuda()
            output = model_transfer(img_as_tensor)
```



Sample Human Output

Step 5: Write your Algorithm

Write an algorithm that accepts a file path to an image and first determines whether the image contains a human, dog, or neither. Then, - if a **dog** is detected in the image, return the predicted breed. - if a **human** is detected in the image, return the resembling dog breed. - if **neither** is detected in the image, provide output that indicates an error.

You are welcome to write your own functions for detecting humans and dogs in images, but feel free to use the face_detector and human_detector functions developed above. You are required to use your CNN from Step 4 to predict dog breed.

Some sample output for our algorithm is provided below, but feel free to design your own user experience!

1.1.18 (IMPLEMENTATION) Write your Algorithm

```
In []: import matplotlib.pyplot as plt

def run_app(img_path):
    ## handle cases for a human face, dog, and neither
    img = Image.open(img_path)
    plt.imshow(img)
    plt.show()

if dog_detector(img_path) is True:
```

```
prediction = predict_breed_transfer(img_path)
    print("Dog Detected!\nIt looks like a {0}".format(prediction))
elif face_detector(img_path) > 0:
    prediction = predict_breed_transfer(img_path)
    print("Hello, human!\nIf you were a dog... You look like a {0}".format(prediction)
else:
    print("Urm... Are you an alien?")
```

Step 6: Test Your Algorithm

In this section, you will take your new algorithm for a spin! What kind of dog does the algorithm think that *you* look like? If you have a dog, does it predict your dog's breed accurately? If you have a cat, does it mistakenly think that your cat is a dog?

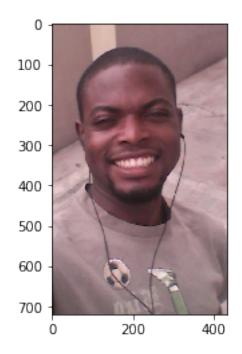
1.1.19 (IMPLEMENTATION) Test Your Algorithm on Sample Images!

Test your algorithm at least six images on your computer. Feel free to use any images you like. Use at least two human and two dog images.

Question 6: Is the output better than you expected:) ? Or worse:(? Provide at least three possible points of improvement for your algorithm.

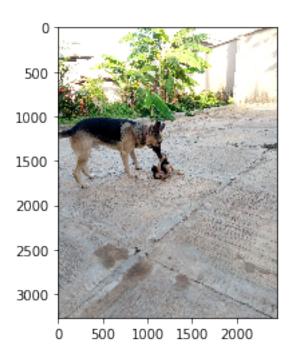
Answer: (Three possible points for improvement)

- 1) Maybe more image augmentations (flipping vertically, move left or right, etc.) might improve model accuracy
- 2) Could probably spend some more time fine tuning the learning rate
- 3) Increasing the Epochs



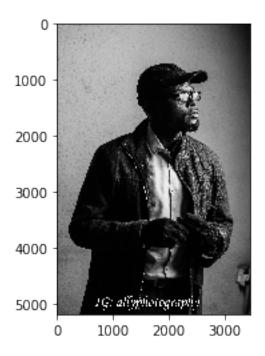
Hello, human!
If you were a dog... You look like a Italian greyhound

In [33]: run_app("IMG.jpg")



Dog Detected!
It looks like a German shepherd dog

In [36]: run_app("IMG_0249.jpg")



Urm... Are you an alien?

In [37]: run_app("IMA.jpg")



Dog Detected!
It looks like a German shepherd dog

In [39]: run_app("IMAGOjpg")



Dog Detected!
It looks like a Labrador retriever

In [40]: run_app("367E1CD1.jpg")



Hello, human!
If you were a dog... You look like a Akita

In []: