

# Summer 9

## Applications of Gaussian elimination

- ① Solving linear system
- ② finding the rank of a matrix
- ③ inverting a matrix
- ④ extracting a basis from a system of generators

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② If  $A, B \in M_{m,n}(K)$

if  $A \sim B$ , then  $\text{rank } A = \text{rank } B$

So  $\text{If } A \in M_{m,n}(K) \Rightarrow$

$$\Rightarrow \text{rank } A = \text{rank} (\text{column}(A)) =$$

= # non-zero rows in the column  
form

9.1. Compute by applying elementary transformations  
the rank of the matrix

$$A = \begin{pmatrix} 0 & 2 & 3 \\ 2 & 4 & 3 \\ 1 & 1 & 1 \\ 2 & 2 & n \end{pmatrix} \xrightarrow{\substack{L_3 \leftrightarrow L_1}} \begin{pmatrix} 1 & 1 & 1 \\ 2 & 4 & 3 \\ 0 & 2 & 3 \\ 2 & 2 & n \end{pmatrix}$$

$$\begin{array}{l} \widetilde{L_2} = 2L_1 \\ L_4 = 2L_1 \end{array} \quad \begin{pmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 2 & 3 \\ 0 & 0 & 2 \end{pmatrix} \quad \begin{array}{l} \widetilde{L_3} = L_2 \\ L_3 = L_2 \end{array} \quad \begin{pmatrix} 1 & 1 & 1 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\begin{array}{l} \widetilde{L_3} = \\ L_2 - \frac{1}{2}L_1 \\ L_1 - \frac{1}{2}L_4 \end{array} \quad \begin{pmatrix} 1 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix} \quad \begin{array}{l} \widetilde{L_1} = \frac{1}{2}L_2 \\ L_1 = \frac{1}{2}L_4 \end{array} \quad \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{pmatrix} \Rightarrow \text{rank } A = 3$$

3)

$$\begin{pmatrix} \beta & 1 & 3 & 4 \\ 1 & \lambda & 3 & 3 \\ 2 & 3\lambda & 4 & 4 \end{pmatrix} \quad \alpha, \beta \in \mathbb{R}$$

$$\tilde{L_1} \hookrightarrow \begin{pmatrix} 1 & \lambda & 3 & 3 \\ \beta & 1 & 3 & 4 \\ 2 & 3\lambda & 4 & 4 \end{pmatrix} \quad \begin{array}{l} \tilde{L_2} = \beta L_1 \\ L_3 = 2 L_1 \end{array}$$

$$\begin{pmatrix} 1 & \lambda & 3 & 3 \\ 0 & 1 - \beta & 3 + 3\beta & 4 - 3\beta \\ 0 & \lambda & -2 & 1 \end{pmatrix} \quad \begin{array}{l} \tilde{L_2} \hookrightarrow L_3 \end{array}$$

$$\begin{pmatrix} 1 & \alpha & 3.3 \\ 0 & 1 & -2 \\ 0 & 1-\beta & 3-3\beta & 4-3\beta \end{pmatrix}$$

if  $\alpha = 0 \Rightarrow$

$$B \sim \begin{pmatrix} 1 & 0 & 3 & 3 \\ 0 & 0 & -2 & 1 \\ 0 & 1 & 3-3\beta & 4-3\beta \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & 3 & 3 \\ 0 & 1 & 3-3\beta & 4-3\beta \\ 0 & 0 & -2 & 1 \end{pmatrix}$$

if  $\lambda \neq 0$ :

$$B \sim \begin{pmatrix} 1 & 0 & 3 & 3 \\ 0 & \lambda & -2 & 1 \\ 0 & 1-\beta\lambda & 3-3\beta & 4-3\beta \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & \lambda & 3 & 3 \\ 0 & 1 & -2/\lambda & 1/\lambda \\ 0 & 0 & 1 & d \end{pmatrix}$$

$$D = \left( 3 - 3\beta - \frac{1-\beta}{\lambda} \right)^2 \frac{1}{\lambda}$$

$$f^* = u - 3\beta \quad \dots$$

$$\text{Rank}_2(f) = 2 \quad \text{if f.f.} \quad P = \emptyset = \emptyset$$

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$$\left\{ \begin{array}{l} 3x - 3 + \beta + 2 - 2\beta = 0 \\ 4x - 3 + \beta + \beta - 1 = 0 \end{array} \right.$$

$$\Leftrightarrow \left\{ \begin{array}{l} 3x - 5 + \beta = -2 \\ 4x - 2 + \beta = 1 \end{array} \right.$$

③ Inverting a matrix

$$A \in M_{m,n}(K)$$

$$\begin{pmatrix} A & | & I_m \end{pmatrix} \xrightarrow{\text{Gaussian-Jordan}} \dots \sim \begin{pmatrix} I_p & | & A^{-1} \\ 0 & | & 0 \end{pmatrix}$$

5. Compute the inverse by direct row  
transformation

$$A = \begin{pmatrix} 1 & 4 & 2 \\ 2 & 3 & 0 \\ 3 & 0 & -1 \end{pmatrix}$$

$$\left( \begin{array}{ccc|ccc} 1 & 4 & 2 & 1 & 0 & 0 \\ 2 & 3 & 1 & 0 & 1 & 0 \\ 3 & 0 & -1 & 0 & 0 & 1 \end{array} \right)$$

$$\begin{aligned} L_2 &= 2L_1 \\ L_3 &= 3L_1 \end{aligned}$$

$$\left( \begin{array}{ccc|ccc} 1 & 4 & 2 & 1 & 0 & 0 \\ 0 & -5 & 3 & -2 & 1 & 0 \\ 0 & -12 & -4 & -3 & 0 & 1 \end{array} \right)$$

$$\begin{aligned} L_2 &= \frac{1}{5}L_2 \\ L_3 &= \frac{1}{5}L_3 \end{aligned}$$

$$\left( \begin{array}{ccc|ccc} 1 & 4 & 2 & 1 & 0 & 0 \\ 0 & 1 & \frac{3}{5} & \frac{2}{5} & -\frac{1}{5} & 0 \\ 0 & -12 & -4 & -3 & 0 & 1 \end{array} \right)$$

$$L_3 + 12L_2$$

$$\left( \begin{array}{ccc|ccc} 1 & 4 & 2 & 1 & 0 & 0 \\ 0 & 1 & \frac{3}{5} & \frac{2}{5} & -\frac{1}{5} & 0 \\ 0 & 0 & \frac{1}{5} & \frac{12}{5} & -\frac{12}{5} & 1 \end{array} \right)$$

$$L_3 \cdot 5 \quad \left( \begin{array}{ccc|cc} 1 & 4 & 2 & 1 & 0 \\ 0 & 1 & \frac{3}{8} & \frac{2}{5} & -\frac{1}{5} \\ 0 & 0 & 1 & 5 & -12 \end{array} \right) \quad \downarrow$$

$$L_2 \sim \frac{3}{5} L_3 \quad \left( \begin{array}{ccc|cc} 1 & 4 & 0 & \frac{36}{5} & -10 \\ 0 & 1 & 0 & 1 & -3 \\ 0 & 0 & 1 & 9 & -12 \end{array} \right)$$

$$L_2 \sim 6 L_2 \quad \left( \begin{array}{ccc|cc} 1 & 0 & 0 & 9 & -12 \\ 0 & 1 & 0 & 1 & -3 \\ 0 & 0 & 1 & 9 & -12 \end{array} \right)$$

$$A^{-1} = \left( \begin{array}{ccc} -3 & -4 & 2 \\ -4 & 7 & -3 \\ 5 & -12 & 5 \end{array} \right)$$

4  $V = K^m$

$v_1, \dots, v_m \in V$

then if  $\text{echelon} \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{pmatrix} = \begin{pmatrix} w_1 \\ u_{m_2} \\ \vdots \\ u_{m_2} \\ 0 \\ 0 \\ \vdots \\ 0 \end{pmatrix}$

then  $B = (u_1, \dots, u_{m_2})$  is a basis for  
 $\langle v_1, \dots, v_m \rangle$

Q. Determine the dimension of the subspaces

$S, T, S+T, S \cap T$  and find basis for all

$$S = \langle (1, 0, 4), (3, 1, 0), (1, 1, -4) \rangle$$

$$T = \langle (-3, -2, 4), (5, 2, 4), (-2, 0, -8) \rangle$$

Let  $A = \begin{pmatrix} 1 & 0 & 4 \\ 2 & 1 & 0 \\ 1 & 1 & -4 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & -2 \\ 0 & 1 & -2 \end{pmatrix}$

$$\sim \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & -2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$B_S = \{(1, 0, 4), (0, 1, -2)\}$$

$$B_T = \{ \dots \} = \begin{pmatrix} 3 & -2 & 4 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\Rightarrow \dim T=2 \Rightarrow B_T = \{(3, -2, 4), (0, 1, 2)\}$$

$$B_{S+T} = \{(1, 0, 4), (0, 1, 2), (3, -2, 4), (0, -1, 2)\}$$

$$= \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & 2 \\ -3 & -2 & 4 \\ 0 & -1 & 2 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & -2 \\ 0 & -2 & 16 \\ 0 & -1 & 2 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 0 & 4 \\ 0 & 1 & -2 \\ 0 & 0 & 16 \\ 0 & 0 & 0 \end{pmatrix}$$

$$B_{S+\bar{T}} = \{(1, 0, 4), (0, 1, -2)\}$$

$$\begin{array}{l} \dim S+\bar{T}=2 \\ \dim S=2 \\ \dim \bar{T}=2 \end{array} \quad \Rightarrow S=\bar{T}$$

