The Ultimate DSA Reviewer

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Introduction to Data Structures and Algorithms

Data Structures

- serves as containers for storing data
- efficient data storage

Features of Data Structures

1. Interface

 Set of operations and parameters that a data structure supports, accepts and return type

2. Implementation

Internal representation of a data structure

Characteristics of Data Structures

1. Correctness

Implementation should run interface accurately

2. Time Complexity

- Running / execution time should be as small as possible

3. Space Complexity

Memory usage should be as little as possible

Types of Data Structures

1. Linear Data Structures

- a. Arrays
- b. Linked Lists
- c. Stacks
- d. Queues

^{*} An interface describes what a data structure does (methods, operations, etc), while an implementation describes how the data structure does it (the way the method or operation does something)

2. Non-linear Data Structures

- a. Trees
- b. Graphs
- c. Hash Tables

Operations on Data Structures

1. Creation

- Creating a structure, first operation

2. Insertion

- Adding new data elements in the structure

3. Deletion

- Removal of a particular data element

4. Updating

- Modifying a data element

5. Searching

- Find location of a particular element

6. Sorting

- Process of arranging data in some order

7. Merging

Combining data elements from two different lists

8. Traversal

Accessing each element exactly once so it can be processed

9. Destruction

- Deletion of entire data structure

Basic Terminologies

- 1. Data set of values
- 2. Data item single unit of values
- **3. Group items** data items divided into sub items
- 4. Elementary items data items that cannot be divided
- Attribute and entity entity which contains certain attributes or properties
- 6. Entity set entities of similar attributes
- Field single elementary unit of information representing an attribute of an entity
- 8. Record collection of field values of a given entity

9. File - a collection of records of the entities in a given entity set

Algorithms

- step-by-step procedures for solving problems
- logic and sequence of operations

Characteristics of an algorithm:

- 1. Input
 - Reads the data of the given problem
- 2. Output
 - Desired result produced
- 3. Process / Definiteness
 - Each step is unambiguous (precise)
- 4. Effectiveness
 - Each step is concise and accurate
- 5. Finiteness
 - Each step is finite

Approaches for designing an algorithm

- 1. Top-down approach
 - Complicated algorithm should be divided into smaller modules
- 2. Bottom-up approach
 - Start with the basic up to the high level (complicated) modules

Analyzing an algorithm

- 1. Time Complexity
 - Amount of time taken by an algorithm to run the program completely

Execution time cases

- 1. Worst Case
 - Maximum time an operation can take
- 2. Average Case
 - Average time an operation can take

3. Best Case

 Least possible execution time an operation can take

2. Space complexity

- Amount of memory space required to run the program completely
- Depends upon the input size

Big O Notation

- Notates the time complexity of an algorithm
- Uses worst-case analysis
- Ignores constant factors, lower-order terms and adds notations if there are multiple terms

1. Constant - O(1)

- Quickest time complexity, runs immediately once executed

2. Logarithmic - O(log n)

- Reduces the input size in each step
*example, start with 1000 items, then 500, then 250, 125, so on

3. Linear - O(n)

- Time complexity depends on the input size (n)

4. Superlinear - O(n log n)

 Still individually processes each element (O(n)) but reduces it in each step (O(log n))

5. Quadratic - O(n^2)

Number of steps is equivalent to the square of the input size,
 where each element is compared with each other

6. Cubic - O(n^3)

Number of steps is equivalent to the cube of the input size

7. Exponential - O(2ⁿ)

Number of steps double as input size grows

8. Factorial - O(n!)

- Number of steps is based off the factorial of the input size

Arrays

Lists

- An ordered set of a variable number of elements to which additions and deletions may be made
- Simplest and commonly found type of data

Linear Lists

- A list which displays the relationship of physical adjacency of a finite sequence of data items or records
- Has a single successor and single predecessor

Array

- A type of linear data structure that is defined as a collection of elements with same or different data types
- Exists in both single and multiple dimensions

Array index

- Value that labels the elements in an array (ex: array[0])

Memory address

- Starting address of free memory available

Element

- Item stored in an array

Matrix / Matrices

- A mathematical object. A general matrix consists of m rows and n columns.
- Usually made from multi-dimensional arrays.

Linked List

Linked List

- A collection of nodes that together form a linear ordering
- Divided into two parts: Information and address

Types of Linked List

- 1. Singly
 - pointer is connected to the next variable
- 2. Doubly
 - pointer is connected to the next and previous variable
- 3. Circular
 - end value is connected to the start value

Stacks

- Stacks
- A fundamental data structure that operates on Last-In-First-Out (LIFO).
- Elements can only be added or removed from one end (the top)
- O(1) time complexity for insertion and deletion

Key Operations

- 1. push()
 - Adds an element on top of the stack
- 2. pop()
 - Removes and returns top element from stack
- 3. peek()/top()
 - Returns the top element without removing it
- 4. isEmpty()
 - Checks if the stack is empty
- All time complexity of all key operations is O(1)
- Overflow: Condition when a stack is full
- Underflow: Condition when trying to pop from an empty stack

Applications of Stacks

- 1. Function Calls
 - Store return addresses and local variables
- 2. Expression Evaluation
 - Evaluate arithmetic expressions
- 3. Backtracking

 Keep track of the state of a problem during backtracking algorithms

4. Undo/Redo Functionality

- Implements undo and redo functions in applications

Expression Notations and Stack Implementations Expression Notations

A. Infix

 Standard mathematical notation where operators are placed between operands (A + B * C)

B. Postfix / Reverse Polish Notation

- Operators follow their operands (A B C * +) = (A + B * C)

C. Prefix / Polish Notation

- Operators precede their operands (+ A * B C) = (A + B * C)