Homework 9: Phys 5210 (Fall 2021)

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Problem 1: In atomic physics experiments such as the ones done in JILA, a cloud of interacting atoms is sometimes placed in a rotating external potential. It is convenient to study these atoms in a reference frame which rotates together with the potential where their potential energy does not depend on time. As we know the velocity of a particle at a position \mathbf{r} in this rotating reference frame is related to the velocity of the same particle in the stationary reference frame by $\mathbf{v}_0 = \mathbf{v} + \mathbf{\Omega} \times \mathbf{r}$, where $\mathbf{\Omega}$ is the constant angular velocity of rotation, \mathbf{v} is the velocity of the particle in the rotating reference frame and \mathbf{v}_0 is the velocity in the stationary reference frame. The Lagrange function in the rotating reference frame of a system of particles, each with mass \mathbf{m} , labelled by the index $j = 1, 2, \ldots, N$, is then given by

$$\mathcal{L} = \sum_{j=1}^{N} \frac{mv_{0j}^{2}}{2} - U(\mathbf{r}) = \sum_{j=1}^{N} \left(\frac{mv_{j}^{2}}{2} + m\mathbf{v}_{j} \cdot (\mathbf{\Omega} \times \mathbf{r}_{j}) + \frac{m(\mathbf{\Omega} \times \mathbf{r}_{j})^{2}}{2} \right) - U(\mathbf{r})$$
(1.1)

Find the Hamiltonian of this system in the rotating reference frame.

Solution.

Given the Lagrange function (1.1), the canonical momenta are

$$\mathbf{p}_{j} = \frac{\partial \mathcal{L}}{\partial \mathbf{v}_{j}} = m\mathbf{v}_{j} + m(\mathbf{\Omega} \times \mathbf{r}_{j}) \Rightarrow \mathbf{v}_{j} = \frac{\mathbf{p}_{j}}{m} - \mathbf{\Omega} \times \mathbf{r}_{j}$$
(1.2)

where $\mathbf{v}_j = \dot{\mathbf{r}}_j$. Then we can write the Hamiltonian as

$$\mathcal{H} = \sum_{j=1}^{N} \mathbf{p}_{j} \cdot \mathbf{v}_{j} - \mathcal{L}$$

$$= \sum_{j=1}^{N} \left[\frac{p_{j}^{2}}{m} - \mathbf{p}_{j} \cdot (\mathbf{\Omega} \times \mathbf{r}_{j}) - (\mathbf{p}_{j} - m\mathbf{\Omega} \times \mathbf{r}_{j}) \cdot (\mathbf{\Omega} \times \mathbf{r}_{j}) - \frac{m}{2} (\mathbf{\Omega} \times \mathbf{r}_{j})^{2} \right] + U(\mathbf{r})$$

$$= \sum_{j=1}^{N} \left[\frac{p_{j}^{2}}{2m} - \mathbf{p}_{j} \cdot (\mathbf{\Omega} \times \mathbf{r}_{j}) \right] + U(\mathbf{r})$$

$$(1.3)$$

Problem 2: Inspired by *Goldstein*, Chapter 8, Problem 35. Consider a system with this Lagrangian

 $\mathcal{L} = \frac{m}{2} (\dot{x}^2 - \omega^2 x^2) e^{2\gamma t} \tag{2.1}$

where $\gamma > 0, \omega \neq 0, m > 0$.

- (a) Write down the Euler-Lagrange equation and solve it with arbitrary initial conditions at t = 0.
- (b) Find the Hamiltonian, write down the Hamilton equations of motion and verify that they are equivalent to the Euler-Lagrange equation.
- (c) For arbitrary initial conditions such as in part (a), how do the position x, the momentum p, and the Hamiltonian \mathcal{H} of this system behave as $t \to \infty$?

Solution.

(a) From the Euler-Lagrange equation for x,

$$\frac{d}{dt} \left[m\dot{x}e^{2\gamma t} \right] = -m\omega^2 x e^{2\gamma t} \Rightarrow \ddot{x} + 2\gamma \dot{x} + \omega^2 x = 0 \tag{2.2}$$

A guess to the solution of this differential equation is $x=Ce^{i\Omega t}$ for some Ω . Plugging back yields

$$-\Omega^2 + 2i\gamma\Omega + \omega^2 = 0 \Rightarrow \Omega_{\pm} = i\gamma \pm \sqrt{\omega^2 - \gamma^2}$$
 (2.3)

Since there are two solutions to Ω , the general solution for is spanned by a linear combination

$$x(t) = C_1 e^{i\Omega_+ t} + C_2 e^{i\Omega_- t} = e^{-\gamma t} \left[C_1 e^{i\sqrt{\omega^2 - \gamma^2} t} + C_2 e^{-i\sqrt{\omega^2 - \gamma^2} t} \right]$$
 (2.4)

where C_1, C_2 are some constants dependent on initial conditions. The physical solution is the real part of this

$$x(t) = e^{-\gamma t} \left[C_1 \cos\left(\sqrt{\omega^2 - \gamma^2}t\right) + C_2 \sin\left(\sqrt{\omega^2 - \gamma^2}t\right) \right]$$
 (2.5)

Thus, given arbitrary conditions $x(0) = x_0$ and $\dot{x}(0) = v_0$, we can write the real constants C_1, C_2 as

$$C_1 = x_0$$
 and $C_2 = \frac{v_0 + \gamma x_0}{\sqrt{\omega^2 - \gamma^2}}$ (2.6)

Then the final form of the solution, given initial conditions, is

$$x(t) = e^{-\gamma t} \left[x_0 \cos\left(\sqrt{\omega^2 - \gamma^2}t\right) + \frac{v_0 + \gamma x_0}{\sqrt{\omega^2 - \gamma^2}} \sin\left(\sqrt{\omega^2 - \gamma^2}t\right) \right]$$
 (2.7)

(b) From (2.1), the canonical momentum is

$$p = \frac{\partial \mathcal{L}}{\partial \dot{x}} = m\dot{x}e^{2\gamma t} \tag{2.8}$$

Then we can write the Hamiltonian as

$$\mathcal{H} = p\dot{x} - \mathcal{L} = \frac{p^2}{m}e^{-2\gamma t} - \frac{m}{2}\left(\frac{p}{m}e^{-2\gamma t}\right)^2e^{2\gamma t} + \frac{1}{2}m\omega^2x^2e^{2\gamma t} = \frac{p^2}{2m}e^{-2\gamma t} + \frac{1}{2}m\omega^2x^2e^{2\gamma t} \quad (2.9)$$

The Hamiltonian equation of motion is thus

$$\dot{x} = \frac{\partial \mathcal{H}}{\partial p} = \frac{p}{m} e^{-2\gamma t} \tag{2.10a}$$

$$\dot{p} = -\frac{\partial \mathcal{H}}{\partial x} = -m\omega^2 x e^{2\gamma t} \tag{2.10b}$$

Taking the time derivative of (2.10a) one more time and substituting in (2.10b), we get

$$\ddot{x} = \frac{\dot{p}}{m}e^{-2\gamma t} - 2\gamma \frac{p}{m}e^{-2\gamma t} = -\omega^2 x - 2\gamma \dot{x} \Rightarrow \ddot{x} + 2\gamma \dot{x} + \omega^2 x = 0$$
 (2.11)

This is the same differential equation obtained from the Euler-Lagrange equation. Thus, the Hamiltonian equation of motion is equivalent to that in the Lagrangian formulation.

(c) From (2.7), $x \to 0$ as $t \to \infty$. Also, the velocity is

$$\dot{x}(t) = -\gamma x(t) + e^{-\gamma t} \left[-x_0 \sqrt{\omega^2 - \gamma^2} \cos\left(\sqrt{\omega^2 - \gamma^2} t\right) + (v_0 + \gamma x_0) \cos\left(\sqrt{\omega^2 - \gamma^2} t\right) \right]$$
(2.12)

Thus, the mechanical momentum $p_{\text{mech}} = m\dot{x} \to 0$ as $t \to \infty$. However, the canonical momentum $p = p_{\text{mech}}e^{2\gamma t} \sim e^{\gamma t} \to \infty$ as $t \to \infty$. Also, since $x(t) = e^{-\gamma t}f(t)$ and $p(t) = e^{\gamma t}g(t)$ where f, g are bounded functions, from (2.9), we can conclude that \mathcal{H} is bounded. So \mathcal{H} doesn't blow up where $t \to \infty$.