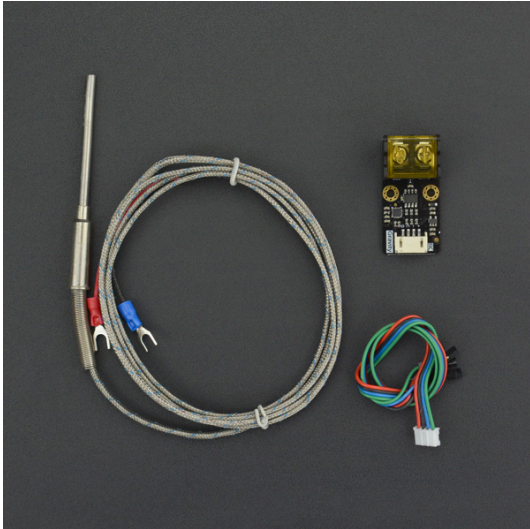


SKU:DFR0558 (<https://www.dfrobot.com/forum/>)



(<https://www.dfrobot.com/product-1753.html>)

Introduction

PT100 is suitable for most of the temperature measurement below 400°C, but usually the temperature of the household natural gas stove can reach over 800°C, and the temperature of the pottery kiln or high-power electric furnace can be more than 1000°C. The K-type thermocouple are commonly used in such ultra-high temperature scenes.

The digital K-type high temperature sensor consists of a signal amplification conversion module and a sheathed K-type thermocouple probe. When the K-type thermocouple probe is placed near a high-temperature heat source, the probe generates a small voltage proportional to the temperature due to the thermoelectric effect. The module uses a MAX31855K dedicated chip to amplify this small voltage, convert it to digital signals, and compensate accordingly. The temperature readings can be read through Gravity I2C interface. The module can measure extremely wide temperature ranging from -270°C to 1372°C, the error from -200°C to 700°C is within $\pm 2^{\circ}\text{C}$, and the error from 700°C to 1350°C is within $\pm 4^{\circ}\text{C}$. The attached K-type thermocouple can measure up to 800 °C with error within $\pm 2.5^{\circ}\text{C}$.

Features

- 14 bit, 0.25°C digital high resolution temperature measurement
- Extremely wide temperature range
- Wide input voltage, compatible with 3.3V and 5V controllers
- Gravity I2C interface, convenient connection
- Fits any K-type thermocouple probe

Specifications

Signal Amplification Conversion Module

- Input Voltage (VCC): 3.3V~5.5V
- Probe: K Type Thermocouple
- Temperature Range: -270°C~1372°C
- Resolution: 0.25 °C
- Error: within $\pm 2^{\circ}\text{C}$ (-200°C~700°C) ~ $\pm 4^{\circ}\text{C}$ (700°C~1350°C)
- Interfaces: Gravity I2C (Logic Level 0-3.3V)
- Dimension: 44.0mm*22.0mm

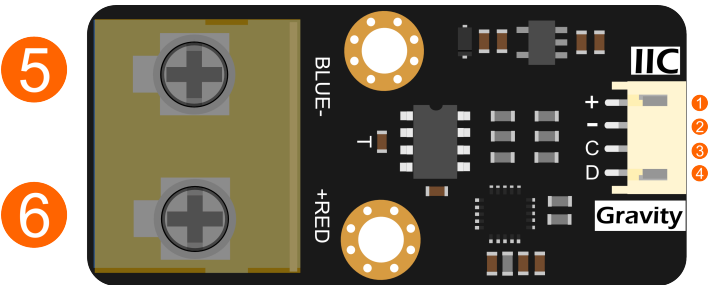
Armored K-Type Thermocouple Probe

- Temperature Range: 0 °C ~ 800 °C
- Error: $\leq \pm 2.5^{\circ}\text{C}$
- Wire Length: 1.5m
- Probe Length: 50mm
- Probe Diameter: $\Phi 4\text{mm}$
- Features: Waterproof, Corrosion Resistant (Weak Acid or Alkali Resistant, Rustproof), High Temperature Resistance

Applications

- Electric Oven, Electric Furnace
- High Temperature Flame, Gas
- Pottery Kiln

Board Overview



Label	Name	Description

1	VCC	Power VCC(3.3~5.5V)
2	GND	Power GND

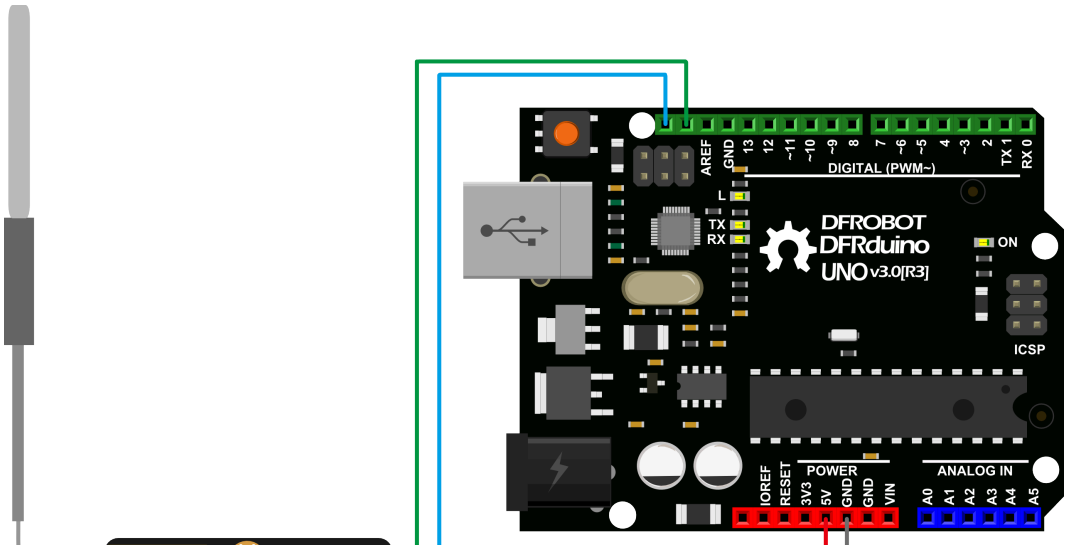
Label	Name	Description
3	SCL	I2C Clock Signal
4	SDA	I2C Data Signal
5	BLUE-	K type thermocouple negative electrode
6	RED+	K type thermocouple positive electrode

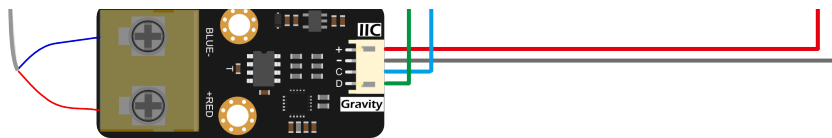
Arduino Tutorial

Requirements

- Hardware
 - DFRduino UNO R3 (<https://www.dfrobot.com/product-838.html>) (or similar) x 1
 - DFRobot Digital High Temperature Sensor (K-type) x 1
 - K-Type Thermocouple Probe x 1
 - Gravity 4P sensor wire (or Dupont wires) x 1
- Software
 - Arduino IDE (V1.0.x or V1.8.x), Click to Download Arduino IDE from Arduino® (<https://www.arduino.cc/en/software>)
 - Download and install the **DFRobot_MAX31855 Library** (https://github.com/DFRobot/DFRobot_MAX31855). How to install the library? (<https://docs.arduino.cc/software/ide-v1/tutorials/installing-libraries#.UxU8mdzF9H0>)

Connection Diagram





Read Temperature

- Connect the probe and Arduino to the module according to the connection diagram. The I2C address is fixed to 0x10.
- Install DFRobot_MAX31855 library.
- Open Arduino IDE, upload the following sample code to the Arduino UNO.
- Open the serial monitor of Arduino IDE.

```

/#!/
 * file ReadTemp.ino
 *
 * Connect MAX31855 to arduino via I2C interface,then download this example
 * @n open serial monitor to check the temperature.
 *
 * Copyright [DFRobot](https://www.dfrobot.com), 2016
 * Copyright GNU Lesser General Public License
 *
 * version V0.1
 * date 2018-3-6
 */

#include <DFRobot_MAX31855.h>

DFRobot_MAX31855 max31855;

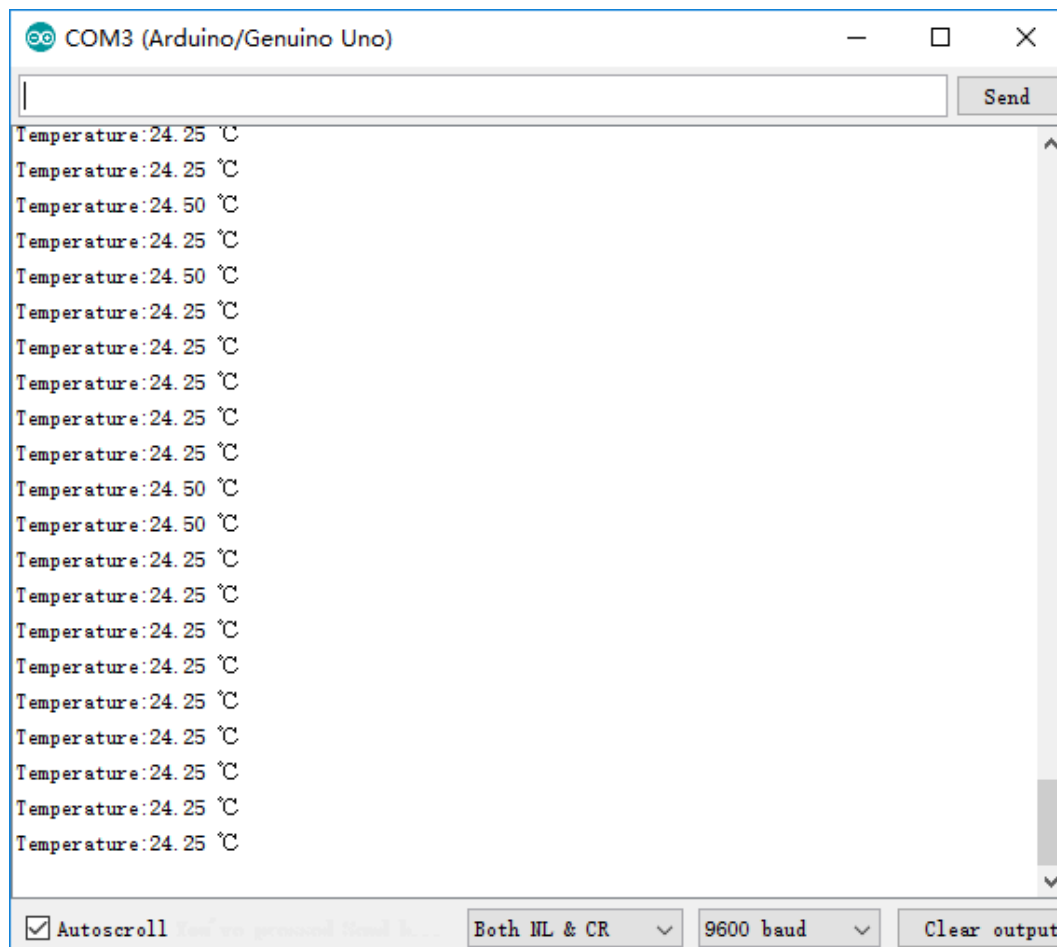
void setup(){
  /*Set baudrate*/
  Serial.begin(9600);
}

void loop(){
  int stat;
  /*Detect I2C device*/
  stat = max31855.scan();
  if(!stat){
    Serial.println("No I2C devices!");
  }
  else{
    /*Read Celsius*/
    float temp = max31855.readCelsius();
    Serial.print("Temperature:");
    Serial.print(temp);
    Serial.println(" °C");
  }
  delay(1000);
}

```

Results

- Arduino prints current temperature every one second.

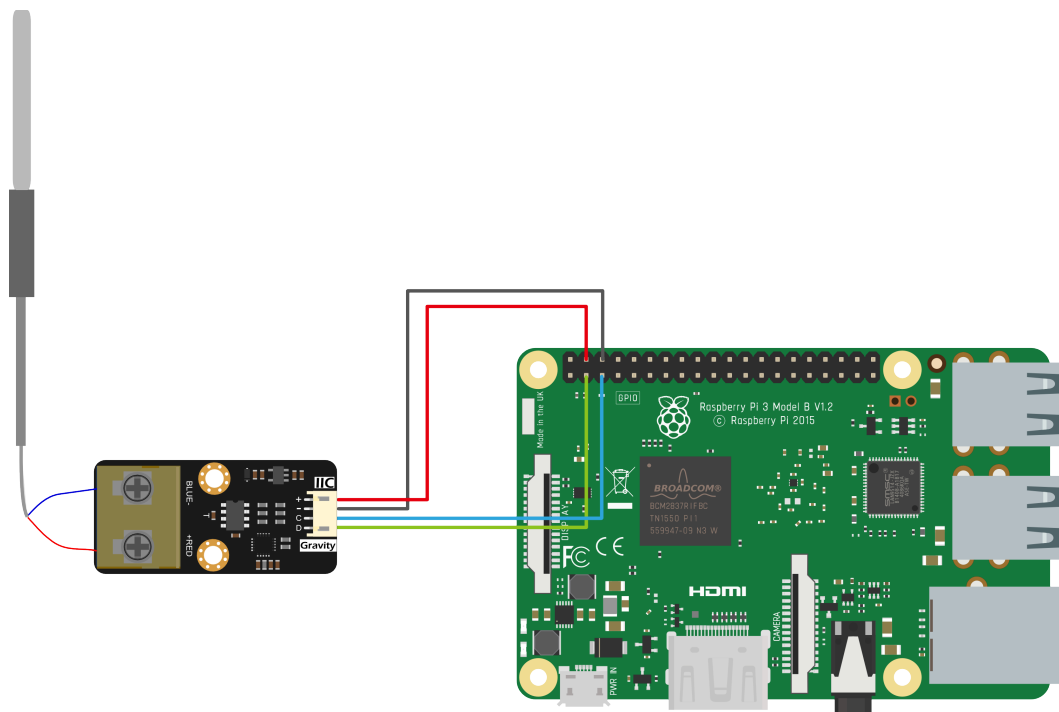


Raspberry Pi Tutorial

Requirements

- **Hardware**
 - Raspberry Pi 3 Model B (<https://www.dfrobot.com/product-1419.html>) (or similar) x 1
 - DFRobot Digital High Temperature Sensor (K-type) x 1
 - K-Type Thermocouple Probe x 1
 - Gravity 4P sensor wire (or Dupont wires) x 1
- **Software**
 - Download and install the **DFRobot_MAX31855 RaspberryPi library** (https://github.com/DFRobot/DFRobot_MAX31855/tree/master/RaspberryPi)
 - RASPBIAN (<https://www.raspberrypi.com/software/>)

Connection Diagram



Installation

1.Start the I2C interface of the Raspberry Pi. If it is already open, skip this step. Open Terminal, type the following command, and press Enter:

```
pi@raspberrypi:~ $ sudo raspi-config
```

Then use the up and down keys to select "5 Interfacing Options" -> "P5 I2C" and press Enter to confirm "YES". Reboot the Raspberry Pi.

2.Installing Python libraries and git (networking required). If it is already installed, skip this step. In the Terminal, type the following commands, and press Enter:

```
pi@raspberrypi:~ $ sudo apt-get update
pi@raspberrypi:~ $ sudo pip install wiringpi
```

3.Download the driver library and run it. In Terminal, type the following commands, and press Enter:

```
pi@raspberrypi:~ $ git clone https://github.com/DFRobot/DFRobot_MAX31855.git
pi@raspberrypi:~ $ cd ~/DFRobot_MAX31855/RaspberryPi
pi@raspberrypi:~/DFRobot_MAX31855/RaspberryPi $ python DFRobot_MAX31855.py
```

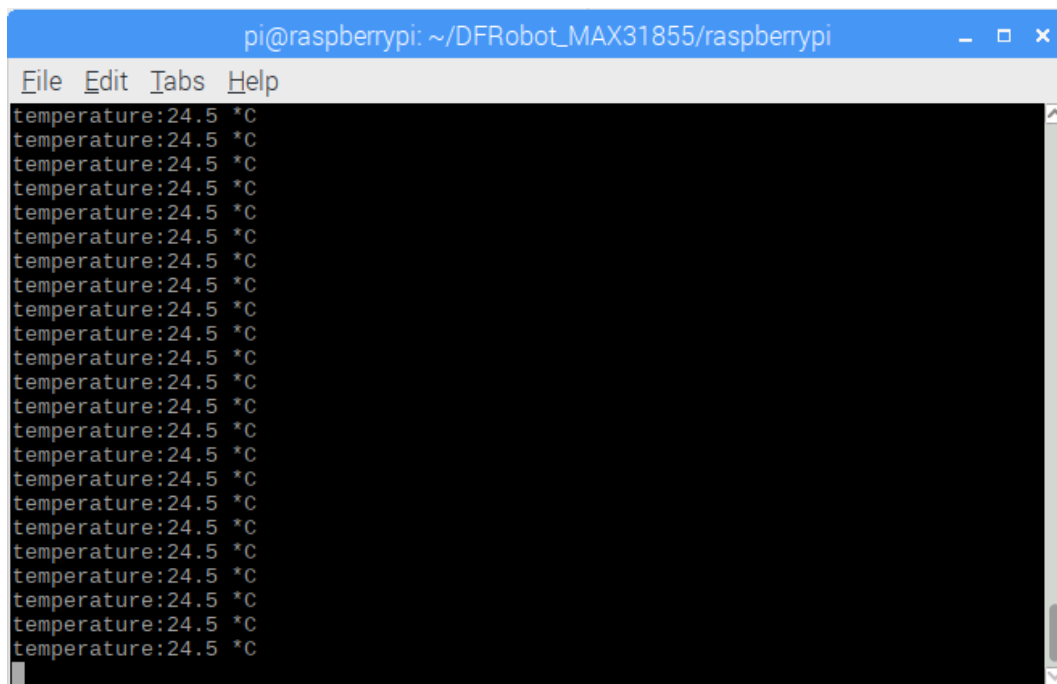
Read Temperature

- Connect the probe and RaspberryPi to the module according to the connection diagram. The I2C address is fixed to 0x10.

```
pi@raspberrypi:~/DFRobot_MAX31855/RaspberryPi/python $ cd readTemp
pi@raspberrypi:~/DFRobot_MAX31855/RaspbeeryPi/python/readTemp $ python readTemp.py
```

Results

- If the reading falls as the temperature becoming higher. Positive and negative connections of the probe may be reversed. Try to exchange them.

A screenshot of a terminal window on a Raspberry Pi. The window title is 'pi@raspberrypi: ~/DFRobot_MAX31855/raspberrypi'. The terminal shows a menu with 'File', 'Edit', 'Tabs', and 'Help'. Below the menu, there is a list of 20 lines, each displaying 'temperature:24.5 *C'. The terminal has a black background and white text. A scrollbar is visible on the right side of the terminal window.

```
pi@raspberrypi: ~/DFRobot_MAX31855/raspberrypi
File Edit Tabs Help
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
temperature:24.5 *C
```

FAQ

- **Q1.** Why my reading falls (even below zero degree) as the temperature becoming higher?
A. The positive and negative connections of the probe may be reversed. Try to exchange them.

For any questions, advice or cool ideas to share, please visit the **DFRobot Forum** (<https://www.dfrobot.com/forum/>).

More Documents

- Schematic


(https://github.com/Arduinolibrary/Gravity_I2C_High_Temperature_Sensor_K_Type/raw/master/DFR0558%20Digital%20High%20Temperature%20Sensor%20_K-Type_%20_V1.0_%20Schematic.pdf)

- Layout with Dimension

(https://github.com/Arduinolibrary/Gravity_I2C_High_Temperature_Sensor_K_Type/raw/master/DFR0558%20Digital%20High%20Temperature%20Sensor%20_K-Type_%20_V1.0_%20Layout%20with%20dimension.pdf)

- MAX31855 Datasheet

(https://github.com/Arduinolibrary/Gravity_I2C_High_Temperature_Sensor_K_Type/raw/master/MAX31855.pdf)

 Get **Gravity: I2C High Temperature Sensor (K-Type)** (<https://www.dfrobot.com/product-1753.html>) from DFRobot Store or **DFRobot Distributor**. (<https://www.dfrobot.com/distributor>)

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