Assignment 1 Part 1

```
1.
A: p = 2i_A + (-2)j_A
B: p = 3i_B + 0.5j_B
C: p = -4i_C + 3j_C
2.
1
   0 0 0
0 2 0 0
0 0 3 0
0 0 0 1
3.
modelMatrix.setAsIdentity();
 modelMatrix *= Translate(1,1,1);
 modelMatrix *= Scale(1,1,2);
4.
[0.5 \ 2.5 \ 2]^T
5.
   1
                                 1 2
                                                            2
      0 0 2
                         0 0
                                               0
                                                  0
                                                                           0 0
                                                                                   1 2
                                            c: 0 = 0.5 = 0
                                 0 3
                                                                                      3
   0 0 0 3
                         0 1
                                                            3.5
                                                                           0 1
A:
                        -1 0
                                 0 0
                                               -1 0
                                                                          -2 	 0
                                                                                      0
     0 1
              0
                                                        0
                                                                                   0
                                                            -1
                             0 0 1
   0 0 0 1
                                                     0 0
                                                                               0
                                                                                   0 1
                         0
                                                0
                                                            1
                                                                           0
For arbitrary tilted line y = mx + b
                    \cos\theta -\sin\theta
                                   0
                                          1
                                              0
                                                   0
                                                          \cos\theta
                                                                  sin\theta
                                                                         0
M =
       0 \quad 1 \quad b \quad * \quad sin\theta
                            cos\theta
                                    0 * 0
                                              -1 \quad 0 \quad * \quad -\sin\theta
                                                                  cos\theta
                                                                         0 *
       \begin{bmatrix} 0 & 0 & 1 \\ 0 & & \end{bmatrix}
                              0
                                    1
                                               0
                                                   1
                                                            0
                                                                         1
                      0
                                                                    0
     0
    1 - b
 0
```

* Scale(1,-1,1) *

RotateX($-\theta$) * Translate(0,-

For arbitrary tilted line y = x - 1 and $\theta = 45$

RotateX(θ)

In OpenGL Shader code:

M = Translate(0,b,0) *

b,0)

```
modelMatrix.setAsIdentity();
modelMatrix *= Translate(0,b,0);
modelMatrix *= RotateX(\theta);
modelMatrix *= Scale(1,-1,1);
modelMatrix *= RotateX(-\theta);
modelMatrix *= Translate(0,-b,0);
```

For arbitrary tilted line y = x - 1 and $\theta = 45$

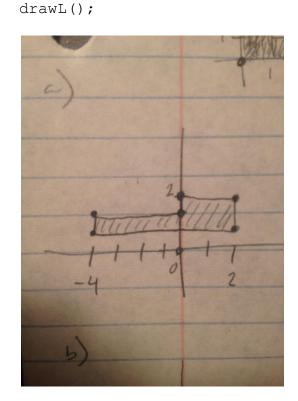
$$\mathsf{M} = \begin{matrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{matrix}$$

For arbitrary tilted line y = x - 1

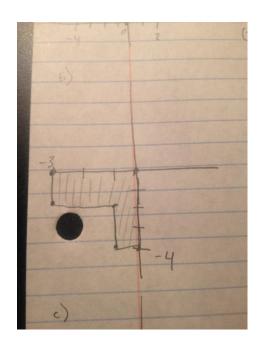
In OpenGL Shader code:

```
modelMatrix.setAsIdentity();
modelMatrix *= Translate(0,-1,0);
modelMatrix *= RotateX(45);
modelMatrix *= Scale(1,-1,1);
modelMatrix *= RotateX(-45);
modelMatrix *= Translate(0,1,0);
```

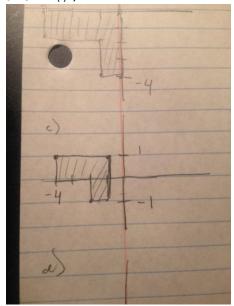
7. a)L' = ABCL modelMatrix *= Scale(2,1,1); modelMatrix *= Translate(1,1,0); modelMatrix *= RotateZ(90);



```
b) L' = CADL
modelMatrix = matrixStack.pop();
matrixStack.push(modelMatrix); //saves for part c
modelMatrix *= RotateZ(90);
modelMatrix *= Scale(2,1,1);
modelMatrix *= Scale(-1,1,1);
drawL();
```



```
c) L' = CBDL
modelMatrix = matrixStack.pop();
matrixStack.push(modelMatrix); //saves for part d
modelMatrix *= RotateZ(90);
modelMatrix *= Translate(1,1,0);
modelMatrix *= Scale(-1,1,1);
drawL();
```



```
d) L' = DCCADL
modelMatrix = matrixStack.pop();
modelMatrix *= Scale(-1,1,1);
modelMatrix *= RotateZ(90);
modelMatrix *= RotateZ(90);
```

```
modelMatrix *= Scale(2,1,1);
modelMatrix *= Scale(-1,1,1);
drawL();
```

