

**CS 174A: Assignment 1 (Written)**  
**Spring 2014 (Prof. M. Alex Vasilescu)**

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**Exercise 1**

$$\begin{aligned}p_A &= 2i - 2j \\p_B &= 3i + 0.5j \\p_C &= -4i + 3j\end{aligned}$$

**Exercise 2**

$$M = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

**Exercise 3**

```
modelMatrix *= Translate(1, 1, 1);  
modelMatrix *= Scale(1, 1, 2);
```

**Exercise 4**

$$[0.5 \ 2.5 \ 2]^T$$

**Exercise 5**

```
//PartA  
M =  $\begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$ 
```

//PartB

```
M= [0 0 1 2]
    [0 1 0 3]
    [-1 0 0 0]
    [0 0 0 1]
```

//PartC

```
M= [0 0 1 2]
    [0 0.5 0 3.5]
    [-1 0 0 -1]
    [0 0 0 1]
```

//PartD

```
M= [0 0 1 2]
    [0 1 0 3]
    [-2 0 0 0]
    [0 0 0 1]
```

## Exercise 6

Let line be parameterized as:  $y=m*x+b$ .

$M=Translate(0,b)*Rotate(theta)*Scale(1,-1)*Rotate(-theta)*Translate(0,-b)$

where  $theta = \arctan(m)$ .

$$M = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & b \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -b \\ 0 & 0 & 1 \end{bmatrix}$$

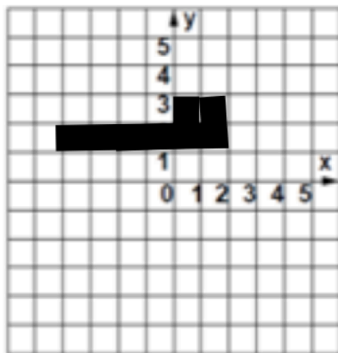
OpenGL Shader Code:

```
mat4M(1.0f);//Identity
M*=Translate(0,b,0);//AssumeusingX,Yplaneonly(2D)
M*=RotateZ(theta);
M*=Scale(1,-1,1);
M*=RotateZ(-theta);
M*=Translate(0,-b,0);
```

## Exercise 7

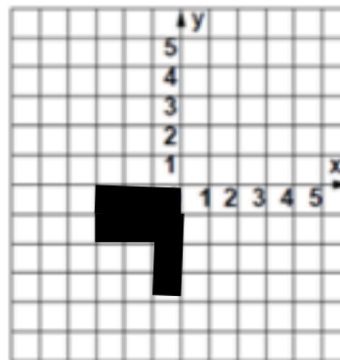
```
#define A modelMatrix *= Scale(2, 1, 1);
#define B modelMatrix *= Translate(1, 1, 0);
#define C modelMatrix *= RotateZ(90);
#define D modelMatrix *= Scale(-1, 1, 1);
#define X model_view = view_trans * model_trans;
```

a)  $L' = ABC L$



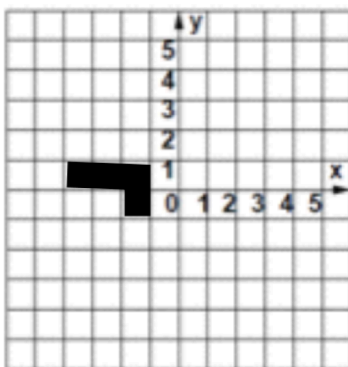
A  
B  
C  
X  
drawL();

b)  $L' = CAD L$



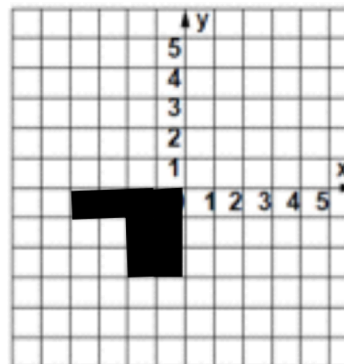
C  
A  
D  
X  
drawL();

c)  $L' = CBD L$



C  
B  
D  
X  
drawL();

d)  $L' = DCCAD L$



D  
C  
C  
A  
D  
X  
drawL();