

FYS-2021: Assignment 2

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Abstract

This report explores key aspects of linear regression, including the use of loss functions and gradient descent for optimization. The report also highlights the application of stochastic methods in regression tasks.

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1 Problem 1: Linear Regression with Gradient Descent

1.1 1a) Loss Functions Used for Linear Regression

1.1.1 Introduction

In linear regression, the goal is to model the relationship between a dependent variable y and one or more independent variables x by fitting a linear equation to observed data. To find the best-fitting line, we minimize a loss function that measures the discrepancy between the predicted values \hat{y} and the actual values y .

Three common loss functions for linear regression are:

- **Mean Squared Error (MSE)**
- **Mean Absolute Error (MAE)**
- **Huber Loss**

1.1.2 Mean Squared Error

The most commonly used loss function is the **Mean Squared Error (MSE)** (MIT 2024). This loss function measures the average of the squared differences between the predicted values \hat{y} and the actual values y . the mathematical formula for the MSE loss function is given by:

$$L_{reg}(\hat{y}, y) = \frac{1}{N} \sum_{i=1}^N (y_i - \hat{y})^2$$

where:

- N is the number of data points
- y_i is the actual value for the i -th data point.
- \hat{y}_i is the predicted value for the i -th data point.

Derivation of the Gradient

To be able to minimize this loss function, we need to compute the gradient of L_{reg} with respect to the weight parameters ω_0 and ω_1 .

For a linear model the prediction is given by:

$$\hat{y} = \omega_0 + \omega_1 x_i$$

Where:

- ω_0 is the intercept.
- ω_1 is the slope (or weight for the feature x_i).
- x_i is the input feature.

To be able to minimize the loss, we compute the gradient of L_{reg} with respect to ω_0 and ω_1 .

Gradient with respect to ω_0 :

$$\frac{\partial L_{reg}}{\partial \omega_0} = \frac{\partial}{\partial \omega_0} \left(\frac{1}{N} \sum_{i=1}^N (y_i - (\omega_0 + \omega_1 x_i))^2 \right) \quad (1)$$

We can use the chain rule here, and note that $\omega_0 + \omega_1 x_i = \hat{y}_i$, giving us:

$$\frac{\partial L_{reg}}{\partial \omega_0} = \frac{\partial}{\partial \omega_0} \left(\frac{1}{N} \sum_{i=1}^N (y_i - \hat{y}_i)^2 \right) \quad (2)$$

Applying the chain rule $(f(g(x)))' = f'(g(x))g'(x)$:

$$\frac{\partial}{\partial \omega_0} (y_i - \hat{y}_i)^2 = 2(y_i - \hat{y}_i) \cdot \frac{\partial}{\partial \omega_0} (-\hat{y}_i) \quad (3)$$

Since $\frac{\partial \hat{y}_i}{\partial \omega_0} = 1$ (because $\hat{y}_i = \omega_0 + \omega_1 x_i$), this simplifies to:

$$\frac{\partial L_{reg}}{\partial \omega_0} = \frac{2}{N} \sum_{i=1}^N (\hat{y}_i - y_i) \quad (4)$$

Gradient with respect to ω_1 :

$$\frac{\partial L_{reg}}{\partial \omega_1} = \frac{\partial}{\partial \omega_1} \left(\frac{1}{N} \sum_{i=1}^N (y_i - (\omega_0 + \omega_1 x_i))^2 \right) \quad (5)$$

chain rule:

$$\frac{\partial}{\partial \omega_1} (y_i - \hat{y}_i)^2 = 2(y_i - \hat{y}_i) \cdot \frac{\partial}{\partial \omega_1} (-\hat{y}_i) \quad (6)$$

Since $\frac{\partial}{\partial \omega_1} \hat{y}_i = \frac{\partial}{\partial \omega_1} (\omega_0 + \omega_1 x_i) = x_i$, we get:

$$\frac{\partial L_{reg}}{\partial \omega_1} = \frac{2}{N} \sum_{i=1}^N (\hat{y}_i - y_i) x_i \quad (7)$$

To conclude, the final gradients are:

$$\frac{\partial L_{reg}}{\partial \omega_0} = \frac{2}{N} \sum_{i=1}^N (\hat{y}_i - y_i) \quad (8)$$

$$\frac{\partial L_{reg}}{\partial \omega_1} = \frac{2}{N} \sum_{i=1}^N (\hat{y}_i - y_i) x_i \quad (9)$$

The gradients are positive, and the negative sign is explicitly included in the weight update rule in programming.

1.1.3 Mean Absolute Error (MAE)

The **Mean Absolute Error (MAE)** is a commonly used loss function. It measures the average absolute differences between the actual values y_i and the predicted values \hat{y}_i .

The formula for MAE is:

$$\text{MAE} = \frac{1}{N} \sum_{i=1}^N |\hat{y}_i - y_i|$$

where:

- N is the number of data points.
- y_i is the actual value for the i -th data point.
- \hat{y}_i is the predicted value for the i -th data point.

Understanding the Gradient of MAE

In linear regression, the predicted value is given by:

$$\hat{y}_i = \omega_0 + \omega_1 x_i$$

We want to find how the MAE changes with respect to the weights ω_0 and ω_1 , which requires computing the gradient of the MAE loss function.

Gradient with respect to ω_0 :

The absolute value function is not differentiable at zero, so we use a **piecewise function** to derive the gradient:

$$\frac{d}{dx}|x| = \begin{cases} 1, & \text{if } x > 0 \\ -1, & \text{if } x < 0 \end{cases}$$

The gradient of MAE with respect to ω_0 becomes:

$$\frac{\partial L_{MAE}}{\partial \omega_0} = -\frac{1}{N} \sum_{i=1}^N \text{sign}(y_i - \hat{y}_i)$$

Where:

$$\text{sign}(y_i - \hat{y}_i) = \begin{cases} 1, & \text{if } y_i - \hat{y}_i > 0 \\ -1, & \text{if } y_i - \hat{y}_i < 0 \end{cases}$$

This means if the prediction \hat{y}_i is too low compared to y_i , we increase ω_0 , and if it's too high, we decrease ω_0 .

Gradient with respect to ω_1 :

The process for ω_1 is similar:

$$\frac{\partial L_{MAE}}{\partial \omega_1} = \frac{1}{N} \sum_{i=1}^N \text{sign}(y_i - \hat{y}_i) \cdot (-x_i)$$

Here, we adjust ω_1 (the slope) based on both the sign of the error and the value of x_i .

Conclusion The gradients derived from the MAE loss function help determine whether to increase or decrease the weights ω_0 and ω_1 to reduce the error in future predictions.

Information about the : Sign Function 2024

1.1.4 Huber Loss

The **Huber Loss** combines the advantages of both the Mean Squared Error (MSE) and the Mean Absolute Error (MAE). It is less sensitive to outliers compared to MSE and differentiable, unlike MAE, making it useful in many regression tasks. The Huber Loss behaves like MSE for small errors and like MAE for larger errors.

The Huber Loss is defined as:

$$L_{Huber}(\hat{y}, y) = \begin{cases} \frac{1}{2}(y_i - \hat{y}_i)^2, & \text{for } |y_i - \hat{y}_i| \leq \delta \\ \delta \cdot (|y_i - \hat{y}_i| - \frac{1}{2}\delta), & \text{for } |y_i - \hat{y}_i| > \delta \end{cases}$$

Where:

- y_i is the actual value,
- \hat{y}_i is the predicted value,
- δ is a threshold that controls the transition between MSE and MAE behavior.

Derivation of the Gradient for Huber Loss

As for other loss functions, the predicted value \hat{y}_i is given by:

$$\hat{y}_i = \omega_0 + \omega_1 x_i$$

Gradient with respect to ω_0 :

The gradient depends on whether $|y_i - \hat{y}_i|$ is smaller or larger than δ . For small errors (less than δ), the Huber Loss behaves like MSE, and for large errors (greater than δ), it behaves like MAE.

For the case where $|y_i - \hat{y}_i| \leq \delta$:

$$\frac{\partial L_{Huber}}{\partial \omega_0} = \frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i)$$

For the case where $|y_i - \hat{y}_i| > \delta$:

$$\frac{\partial L_{Huber}}{\partial \omega_0} = \frac{1}{N} \sum_{i=1}^N \delta \cdot \text{sign}(y_i - \hat{y}_i)$$

Thus, the gradient with respect to ω_0 is piecewise depending on the error magnitude.

Gradient with respect to ω_1 :

Similarly, for ω_1 : For small errors:

$$\frac{\partial L_{Huber}}{\partial \omega_1} = \frac{1}{N} \sum_{i=1}^N (\hat{y}_i - y_i) x_i$$

For large errors:

$$\frac{\partial L_{Huber}}{\partial \omega_1} = \frac{1}{N} \sum_{i=1}^N \delta \cdot \text{sign}(y_i - \hat{y}_i) x_i$$

1.1.5 Summary of Loss Functions

Each loss function has its advantages and drawbacks:

- **MSE** is sensitive to outliers but provides smooth gradients, making optimization straightforward.
- **MAE** is robust to outliers but provides constant gradients, which can slow down convergence.
- **Huber Loss** offers a balance between MSE and MAE, being less sensitive to outliers while maintaining differentiability.

The choice of loss function depends on the specific requirements of the problem, such as the presence of outliers and the desired robustness.

1.2 1b) Importance of Smooth Loss Functions in Gradient Descent

Smooth loss functions are preferred in gradient descent optimization because they are differentiable everywhere, providing well-defined gradients that guide the optimization process efficiently towards a global minimum (Geeks-forGeeks 2024).

Non-Differentiability Issues with MAE

The MAE loss function is not differentiable at $y_i = \hat{y}_i$ due to the absolute value function. This can lead to challenges:

- **Constant Gradient Magnitude:** The gradient magnitude does not change with the error magnitude, leading to slow convergence.
- **Optimization Stability:** Non-differentiability can cause instability in optimization algorithms that rely on gradient information.

Advantages of Smooth Loss Functions

Using a smooth loss function like MSE or Huber Loss (with appropriate δ):

- **Well-Behaved Gradients:** Differentiable loss functions provide gradients that change smoothly with the error magnitude, allowing for efficient updates.
- **Convergence Speed:** Smooth gradients enable faster convergence to the minimum.
- **Optimization Stability:** Gradient-based optimization algorithms perform better with continuous and differentiable loss surfaces.

1.3 1c) Gradient Descent Optimization Process

Gradient Descent is an iterative optimization algorithm used to minimize a loss function by adjusting the model's parameters in the opposite direction of the gradient.

1.3.1 Algorithm Steps

1. **Initialize Weights:** Start with initial weights $w_0^{(0)}, w_1^{(0)}$.
2. **Compute Predictions:** For each data point, compute $\hat{y}_i^{(k)} = w_0^{(k)} + w_1^{(k)} x_i$.
3. **Compute Loss:** Calculate the loss $L^{(k)}$ using the chosen loss function.
4. **Compute Gradients:** Compute the gradients $\frac{\partial L}{\partial w_0}$ and $\frac{\partial L}{\partial w_1}$.
5. **Update Weights:** Update the weights using:

$$w_0^{(k+1)} = w_0^{(k)} - \eta \frac{\partial L}{\partial w_0}, \quad w_1^{(k+1)} = w_1^{(k)} - \eta \frac{\partial L}{\partial w_1}$$

where η is the learning rate.

6. **Repeat:** Iterate steps 2-5 until convergence criteria are met (e.g., the change in loss is below a threshold or a maximum number of iterations is reached).

1.3.2 Learning Rate Considerations

The learning rate η controls the size of the weight updates:

- **Small η :** Leads to small updates, potentially slow convergence but more stable.
- **Large η :** Leads to large updates, faster convergence but risks overshooting the minimum or divergence.

Choosing an appropriate learning rate is critical for effective optimization.

1.4 1d) Loss Surface Visualization

To understand the behavior of the optimization process, we visualize the loss surface and the trajectory of the weights during gradient descent.

1.4.1 Visualization Code

```
1 import numpy as np
2 import matplotlib.pyplot as plt
3
4 # Generate synthetic data
5 np.random.seed(42)
6 N = 100
7 x = 2 * np.random.rand(N)
8 y = 4 + 3 * x + np.random.randn(N)
9
10 # Define the loss function (MSE)
11 def mse_loss(w0, w1, x, y):
12     y_pred = w0 + w1 * x
13     return np.mean((y - y_pred) ** 2)
14
15 # Create a grid of weight values
16 w0_values = np.linspace(0, 8, 100)
17 w1_values = np.linspace(0, 6, 100)
18 W0, W1 = np.meshgrid(w0_values, w1_values)
19 Loss = np.array([[mse_loss(w0, w1, x, y) for w0 in w0_values] for w1 in w1_values])
20
21 # Plot the loss surface
22 plt.figure(figsize=(10, 6))
23 CS = plt.contour(W0, W1, Loss, levels=50, cmap='viridis')
24 plt.clabel(CS, inline=1, fontsize=8)
25 plt.xlabel('w0')
26 plt.ylabel('w1')
27 plt.title('Loss Surface (MSE)')
```

Listing 1: Visualizing the Loss Surface

1.4.2 Gradient Descent Trajectory

Instead of drawing on the given loss surface image, I tried to perform gradient descent and plot the trajectory of the weights on the loss surface instead.

```
1 # Initialize weights
2 w0, w1 = 0.0, 0.0
3 learning_rate = 0.1
4 iterations = 50
5 w0_history = [w0]
6 w1_history = [w1]
7
8 # Gradient descent loop
9 for i in range(iterations):
10     y_pred = w0 + w1 * x
11     error = y_pred - y
12     grad_w0 = (2 / N) * np.sum(error)
13     grad_w1 = (2 / N) * np.sum(error * x)
14     w0 -= learning_rate * grad_w0
15     w1 -= learning_rate * grad_w1
16     w0_history.append(w0)
17     w1_history.append(w1)
18
19 # Plot the trajectory
20 plt.plot(w0_history, w1_history, 'ro-', label='Gradient Descent Path')
21 plt.legend()
22 plt.show()
```

Listing 2: Gradient Descent Trajectory

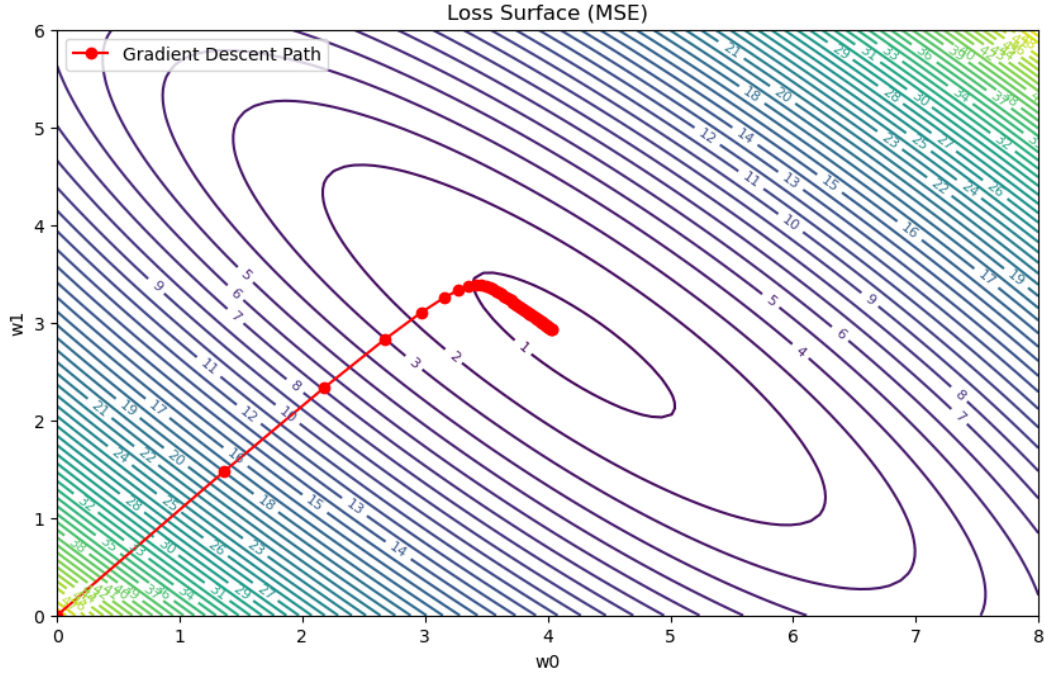


Figure 1: Loss surface visualization with gradient descent trajectory. The path shows the weights updating towards the global minimum.

1.5 1e) Trajectory Derivation

The trajectory observed in the loss surface visualization results from the iterative updates of the weights guided by the gradients.

1.5.1 Mathematical Justification

At each iteration:

$$w_j^{(k+1)} = w_j^{(k)} - \eta \frac{\partial L}{\partial w_j}$$

For MSE loss, the gradients are:

$$\frac{\partial L_{\text{MSE}}}{\partial w_0} = -\frac{2}{N} \sum_{i=1}^N (y_i - \hat{y}_i), \quad \frac{\partial L_{\text{MSE}}}{\partial w_1} = -\frac{2}{N} \sum_{i=1}^N (y_i - \hat{y}_i) x_i$$

The negative gradients point in the direction of steepest descent, and the learning rate η scales the step size. The iterative updates cause the weights to move along the path of steepest descent towards the minimum of the loss surface.

1.5.2 Connection to Visualization

In Figure 1, the red dots represent the sequence of weight values $(w_0^{(k)}, w_1^{(k)})$. The path shows how the weights are updated at each iteration, gradually approaching the point that minimizes the MSE loss.

1.6 1f) Impact of Large Learning Rate on Gradient Descent

A large learning rate can adversely affect the convergence of gradient descent.

1.6.1 Experiment with Large Learning Rate

We set a large learning rate $\eta = 1.5$ and observe the behavior.

```
1 # Initialize weights
2 w0, w1 = 0.0, 0.0
3 learning_rate = 1.5 # Large learning rate
4 iterations = 10
5 w0_history = [w0]
6 w1_history = [w1]
7
8 # Gradient descent loop
9 for i in range(iterations):
10     y_pred = w0 + w1 * x
11     error = y_pred - y
12     grad_w0 = (2 / N) * np.sum(error)
13     grad_w1 = (2 / N) * np.sum(error * x)
14     w0 -= learning_rate * grad_w0
15     w1 -= learning_rate * grad_w1
16     w0_history.append(w0)
17     w1_history.append(w1)
18
19 # Plot the trajectory
20 plt.figure(figsize=(10, 6))
21 CS = plt.contour(W0, W1, Loss, levels=50, cmap='viridis')
22 plt.clabel(CS, inline=1, fontsize=8)
23 plt.plot(w0_history, w1_history, 'ro-', label='Gradient Descent Path with Large Learning Rate')
24 plt.xlabel('w0')
25 plt.ylabel('w1')
26 plt.title('Loss Surface (MSE) with Large Learning Rate')
27 plt.legend()
28 plt.show()
```

Listing 3: Gradient Descent with Large Learning Rate

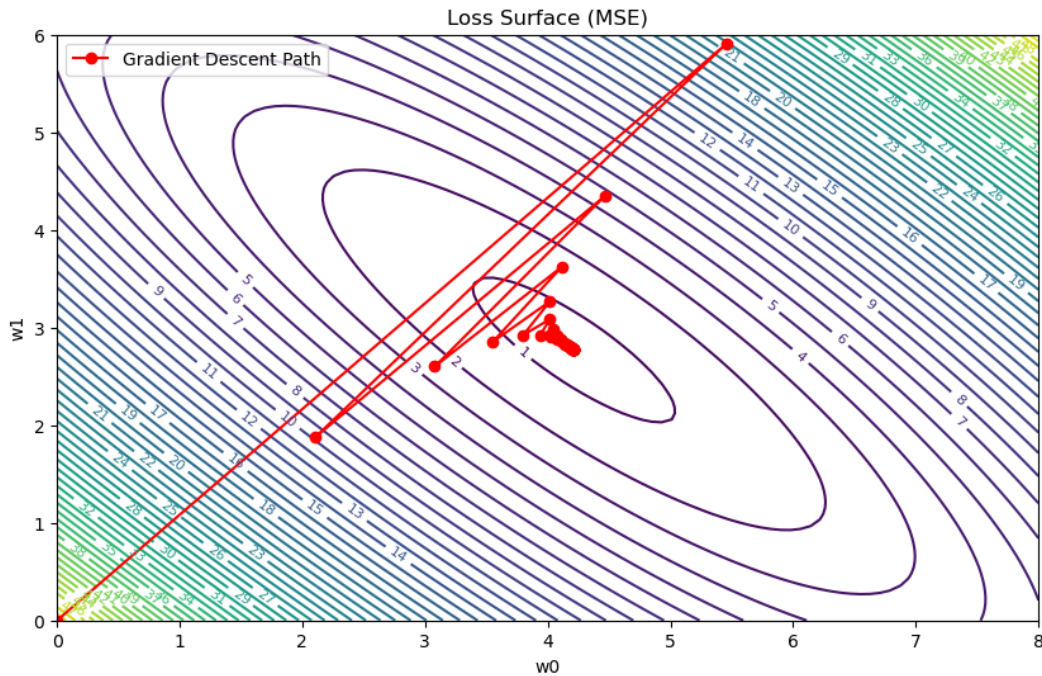


Figure 2: Gradient descent trajectory with a large learning rate. The path shows oscillations and divergence from the minimum.

1.6.2 Analysis

With a large learning rate, the weight updates become too large, causing the weights to overshoot the minimum and potentially diverge. The trajectory exhibits oscillations and fails to converge to the optimal weights.

1.6.3 Conclusion

Choosing an appropriate learning rate is crucial. If the learning rate is too large, the optimization may not converge. One way of checking this is by plotting it as I have in this report.

1.7 1g) Local Minima and Solutions

In some optimization problems, the weights can get stuck in local minima, represented by the orange star on the loss surface. This happens because the optimization algorithm follows the gradients, and in non-convex loss functions, it might settle in a local minimum rather than finding the global minimum.

Suggested Strategy: Momentum

One strategy to solve this problem is by using **momentum**. Momentum helps the optimization process avoid getting stuck by allowing it to "build speed" in directions where the gradient consistently points, making it easier to escape local minima. In simple terms, momentum gives the optimization a "push" based on its previous steps, which prevents it from settling in local dips on the loss surface.

Example: heavy ball

$$w_{t+1} = w_t - \alpha \nabla E(w_t) + \beta(w_t - w_{t-1})$$

Momentum

$(w_t - w_{t-1})$ is the variation at the previous step

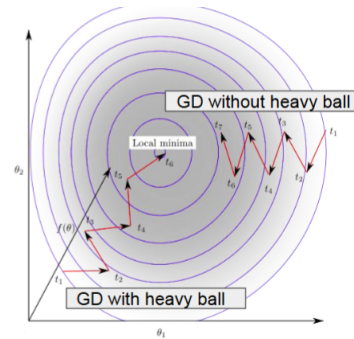


Figure 3: Example from lecture on Optimization and Gradient Descent (Benjamin Ricaud 2024)

Alternative Strategy: Adaptive Learning Rates

Another approach is to use **adaptive learning rates**. This technique adjusts the learning rate during the optimization process. For example, if the algorithm detects that it's moving slowly or getting stuck, it can increase the learning rate to make bigger steps, helping it escape local minima. On the other hand, it can reduce the learning rate when getting closer to the optimal solution to ensure more precise updates.

Summary

Both momentum and adaptive learning rates are effective ways to avoid the issue of local minima, ensuring that the optimization continues toward finding the global minimum.

1.8 Conclusion

In this problem, we explored linear regression using different loss functions and gradient descent optimization. We:

- Derived gradients for MSE, MAE, and Huber Loss.
- Discussed the importance of smooth loss functions.
- Demonstrated gradient descent optimization and the impact of learning rate.
- Showed understanding of strategies for circumventing local minima.

This analysis highlights the significance of choosing appropriate loss functions and hyperparameters to ensure efficient and effective optimization in linear regression tasks.

2 Problem 2: Classifying Data

2.1 2a) Data Overview and Visualization

2.1.1 Data Description

The dataset consists of **3600 samples** with a single feature and a class label. The samples are divided into two classes:

- **Class 0 (C0):** Contains **1600 samples** generated from a *Gamma distribution* with a known shape parameter $\alpha = 2$ and an unknown scale parameter β .
- **Class 1 (C1):** Contains **2000 samples** generated from a *Gaussian distribution* with unknown mean μ and standard deviation σ .

The objective is to develop a Bayes classifier to distinguish between these two classes based on the feature values.

2.1.2 Data Loading and Exploration

```

1 # Step 1: Load and Explore the Data
2 import numpy as np
3 import pandas as pd
4
5 data = pd.read_csv('data/data_problem2.csv', delimiter=',', header=None)
6 data = data.T.reset_index(drop=True)
7 data.columns = ['Feature', 'Class']
8
9 # General Information
10 print(data.info())
11 print(data.describe())
12 print(data.head())
13
14 # Class Counts
15 class_counts = data['Class'].value_counts()
16 print("\nClass Counts:")
17 print(class_counts)

```

Listing 4: Loading and Exploring the Data

[caption=Output]	min	-3.310259	0.000000
<class 'pandas.core.frame.DataFrame'>	25%	3.710522	0.000000
RangeIndex: 3600 entries, 0 to 3599	50%	9.091724	1.000000
Data columns (total 2 columns):	75%	13.729211	1.000000
# Column Non-Null Count Dtype	max	25.673673	1.000000

0 Feature 3600 non-null float64	Feature	Class	
1 Class 3600 non-null float64	0 8.903629	1.0	
	1 9.946774	1.0	
dtypes: float64(2)	2 14.458392	1.0	
memory usage: 56.4 KB	3 9.664572	1.0	
None	4 14.412270	1.0	
	...		
	Class		
count 3600.000000 3600.000000	1.0 2000		
mean 9.118580 0.555556	0.0 1600		
std 5.747397 0.496973			

We first load the data using `pandas` and assign appropriate column names. The dataset contains two columns: `Feature` and `Class`. By inspecting the data, we confirm that there are 1600 samples from Class 0 and 2000 samples from Class 1.

2.1.3 Feature and Label Separation

```
1 # Features and Labels
2 X = data['Feature'].values
3 y = data['Class'].values
```

Listing 5: Separating Features and Labels

We separate the feature values and class labels for further processing.

2.1.4 Data Visualization

```
1 # Step 2: Plot Histograms
2 import matplotlib.pyplot as plt
3 import seaborn as sns
4
5 plt.figure(figsize=(10, 6))
6 sns.histplot(data=data, x='Feature', hue='Class', bins=30, kde=True, element='step', stat='
    density')
7 plt.title('Histogram of Feature Values by Class')
8 plt.xlabel('Feature Value')
9 plt.ylabel('Density')
10 plt.show()
```

Listing 6: Plotting Histograms

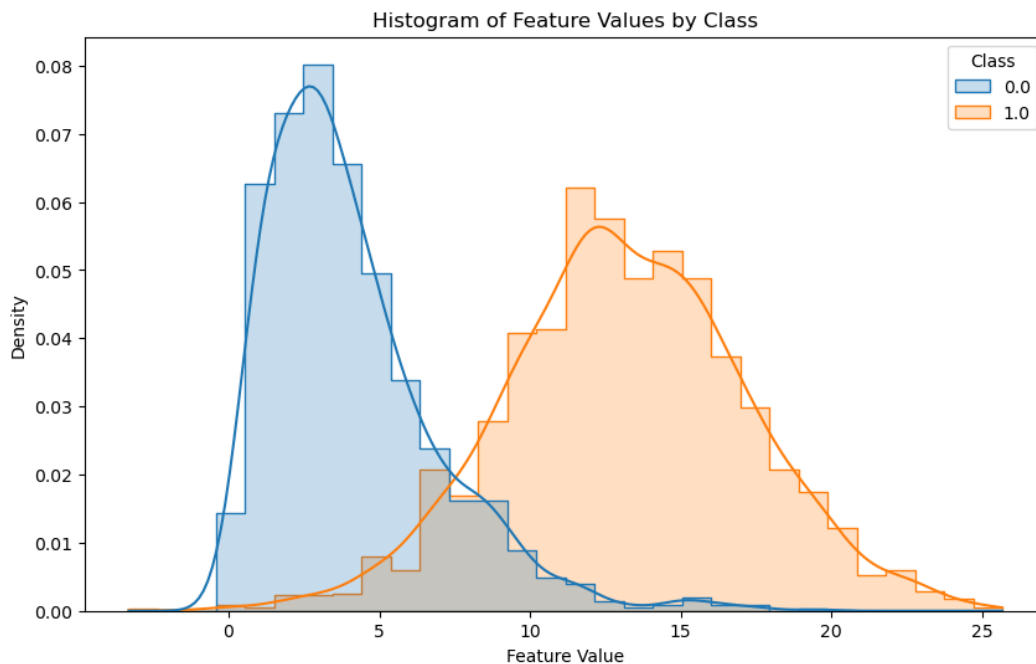


Figure 4: Histogram of feature values for Class 0 and Class 1.

The histogram in Figure 4 shows the distribution of feature values for both classes. Class 0 has a distribution skewed towards lower feature values, consistent with a Gamma distribution, while Class 1 has a distribution centered around a higher mean, consistent with a Gaussian distribution. There is some overlap between the two distributions, which may lead to misclassifications.

2.2 2b) Maximum Likelihood Estimations

To develop the Bayes classifier, we need to estimate the parameters of the underlying distributions for each class using Maximum Likelihood Estimation (MLE).

We are tasked with deriving the maximum likelihood estimates (MLE) for the parameters of two distributions: β for the Gamma distribution (Class 0) and μ, σ^2 for the Gaussian distribution (Class 1).

Gamma Distribution (Class 0)

The Gamma distribution's probability density function (PDF) is defined as:

$$f(x; \alpha, \beta) = \frac{x^{\alpha-1} e^{-x/\beta}}{\beta^\alpha \Gamma(\alpha)} \quad (10)$$

Given that $\alpha = 2$, we aim to find the MLE for the scale parameter β .

Step 1: Likelihood Function

For n_0 independent samples $x_0^1, \dots, x_0^{n_0}$ from Class 0, the likelihood function is:

$$L(\beta) = \prod_{j=1}^{n_0} \frac{(x_0^j)^{\alpha-1} e^{-x_0^j/\beta}}{\beta^\alpha} \quad (11)$$

Substituting $\alpha = 2$ into the equation:

$$= \prod_{j=1}^{n_0} \frac{x_0^j e^{-x_0^j/\beta}}{\beta^2} \quad (12)$$

Taking the natural logarithm of the likelihood function to get the log-likelihood:

$$\log L(\beta) = \sum_{j=1}^{n_0} \left(\log x_0^j - 2 \log \beta - \frac{x_0^j}{\beta} \right) \quad (13)$$

Simplifying gives:

$$= \sum_{j=1}^{n_0} \log x_0^j - n_0 \log \beta - \frac{1}{\beta} \sum_{j=1}^{n_0} x_0^j \quad (14)$$

Step 2: Taking the Derivative

To find the MLE, we take the derivative of the log-likelihood with respect to β and set it to zero:

$$\frac{d}{d\beta} \log L(\beta) = \frac{-n_0}{\beta} + \frac{1}{\beta^2} \sum_{j=1}^{n_0} x_0^j = 0 \quad (15)$$

Multiplying through by β^2 :

$$-n_0\beta + \sum_{j=1}^{n_0} x_0^j = 0 \quad (16)$$

Solving for β :

$$\hat{\beta} = \frac{1}{n_0} \sum_{j=1}^{n_0} x_0^j \quad (17)$$

Gaussian Distribution (Class 1)

The PDF for the Gaussian distribution is:

$$f(x; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right) \quad (18)$$

The likelihood function for n_1 independent samples $x_1^1, \dots, x_1^{n_1}$ is:

$$L(\mu, \sigma^2) = \prod_{j=1}^{n_1} \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x_1^j - \mu)^2}{2\sigma^2}\right) \quad (19)$$

Taking the log-likelihood:

$$\log L(\mu, \sigma^2) = -\frac{n_1}{2} \log(2\pi\sigma^2) - \frac{1}{2\sigma^2} \sum_{j=1}^{n_1} (x_1^j - \mu)^2 \quad (20)$$

Step 2: Deriving with Respect to μ

We now take the partial derivative of the log-likelihood with respect to μ :

$$\frac{\partial}{\partial \mu} \log L(\mu, \sigma^2) = \frac{1}{\sigma^2} \sum_{j=1}^{n_1} (x_1^j - \mu) = 0 \quad (21)$$

Solving for μ :

$$\hat{\mu} = \frac{1}{n_1} \sum_{j=1}^{n_1} x_1^j \quad (22)$$

Step 3: Deriving with Respect to σ^2

Next, we derive with respect to σ^2 :

$$\frac{\partial}{\partial \sigma^2} \log L(\mu, \sigma^2) = -\frac{n_1}{2\sigma^2} + \frac{1}{2\sigma^4} \sum_{j=1}^{n_1} (x_1^j - \mu)^2 = 0 \quad (23)$$

Multiplying through by $2\sigma^4$:

$$-n_1\sigma^2 + \sum_{j=1}^{n_1} (x_1^j - \mu)^2 = 0 \quad (24)$$

Solving for σ^2 :

$$\hat{\sigma}^2 = \frac{1}{n_1} \sum_{j=1}^{n_1} (x_1^j - \hat{\mu})^2 \quad (25)$$

Summary of Results

The MLE for the parameters are as follows:

$$\hat{\beta} = \frac{1}{n_0} \sum_{j=1}^{n_0} x_0^j, \quad (26)$$

$$\hat{\mu} = \frac{1}{n_1} \sum_{j=1}^{n_1} x_1^j, \quad (27)$$

$$\hat{\sigma}^2 = \frac{1}{n_1} \sum_{j=1}^{n_1} (x_1^j - \hat{\mu})^2 \quad (28)$$

2.2.1 Parameter Estimation Using Code

```
1 # Step 4: Estimate Parameters
2
3 # Gamma distribution for Class 0
4 alpha = 2 # Given shape parameter
5 X_train_c0 = X_train[y_train == 0]
6 n0 = len(X_train_c0)
7 beta_hat = np.mean(X_train_c0) / alpha # Estimate beta
8 print(f"Estimated beta for Class 0 (Gamma): {beta_hat}")
9
10 # Gaussian distribution for Class 1
11 X_train_c1 = X_train[y_train == 1]
12 n1 = len(X_train_c1)
13 mu_hat = np.mean(X_train_c1) # Estimate mu
14 sigma_squared_hat = np.var(X_train_c1, ddof=0) # Estimate sigma^2
15 sigma_hat = np.sqrt(sigma_squared_hat) # Estimate sigma
16 print(f"Estimated mu for Class 1 (Gaussian): {mu_hat}")
17 print(f"Estimated sigma for Class 1 (Gaussian): {sigma_hat}")
18
19 # Step 5: Define PDFs
20 def gamma_pdf(x, alpha, beta):
21     # Since alpha = 2, Gamma(alpha) = 1
22     x = np.maximum(x, 1e-10) # Ensure x > 0
23     coef = 1 / (beta ** alpha) # Simplified coefficient
24     pdf = coef * x ** (alpha - 1) * np.exp(-x / beta)
25     return pdf
26
27 def gaussian_pdf(x, mu, sigma):
28     coef = 1 / (sigma * np.sqrt(2 * np.pi))
29     exponent = -0.5 * ((x - mu) / sigma) ** 2
30     pdf = coef * np.exp(exponent)
31     return pdf
32
33
34 # Step 6: Implement Classifier
35 prior_c0 = np.mean(y_train == 0)
36 prior_c1 = np.mean(y_train == 1)
37 print(f"\nClass Prior for Class 0: {prior_c0}")
38 print(f"Class Prior for Class 1: {prior_c1}")
```

Listing 7: Estimating Parameters Using MLE

Results:

Estimated beta for Class 0 (Gamma): 2.0491
Estimated mu for Class 1 (Gaussian): 13.1380
Estimated sigma for Class 1 (Gaussian): 4.0571

2.3 2c) Bayes Classifier Implementation

The Bayes classifier was implemented using maximum likelihood estimation and prior probabilities (KDnuggets 2024).

Defining the Probability Density Functions

Gamma PDF for Class 0

$$f_{C0}(x) = \frac{x^{\alpha-1}e^{-x/\beta}}{\beta^{\alpha}\Gamma(\alpha)}$$

Since $\alpha = 2$, we have $\Gamma(\alpha) = (\alpha - 1)! = 1! = 1$.

```
1 # Step 5: Define PDFs
2 def gamma_pdf(x, alpha, beta):
3     gamma_alpha = 1 # Since (2 - 1)! = 1! = 1
4     x = np.maximum(x, 1e-10) # Avoid zero or negative values
5     coef = (1 / (beta ** alpha * gamma_alpha))
6     pdf = coef * x ** (alpha - 1) * np.exp(-x / beta)
```



```
7 return pdf
```

Listing 8: Defining the Gamma PDF

Gaussian PDF for Class 1

$$f_{C1}(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

```
1 def gaussian_pdf(x, mu, sigma):
2     coef = 1 / (sigma * np.sqrt(2 * np.pi))
3     exponent = -0.5 * ((x - mu) / sigma) ** 2
4     pdf = coef * np.exp(exponent)
5     return pdf
```

Listing 9: Defining the Gaussian PDF

Calculating Class Priors

The class priors are estimated from the training data:

$$P(C0) = \frac{n_0}{n_0 + n_1}, \quad P(C1) = \frac{n_1}{n_0 + n_1}$$

```
1 # Step 6: Implement Classifier
2 prior_c0 = n0 / (n0 + n1)
3 prior_c1 = n1 / (n0 + n1)
4 print(f"\nClass Prior for Class 0: {prior_c0}")
5 print(f"Class Prior for Class 1: {prior_c1}")
```

Listing 10: Calculating Class Priors

Results:

Class Prior for Class 0: 0.4444
Class Prior for Class 1: 0.5556

2.3.1 Implementing the Bayes Classifier

The Bayes classifier assigns a sample x to the class with the highest posterior probability:

$$\text{Predict } C_i \text{ if } P(C_i|x) > P(C_j|x), \quad i \neq j$$

Using Bayes' theorem:

$$P(C_i|x) = \frac{f_{C_i}(x)P(C_i)}{f_{C0}(x)P(C0) + f_{C1}(x)P(C1)}$$

However, since the denominator is common, we can compare numerators directly.

```
1 def bayes_classifier(x, alpha, beta, mu, sigma, prior_c0, prior_c1):
2     likelihood_c0 = gamma_pdf(x, alpha, beta)
3     likelihood_c1 = gaussian_pdf(x, mu, sigma)
4     posterior_c0 = likelihood_c0 * prior_c0
5     posterior_c1 = likelihood_c1 * prior_c1
6     predictions = np.where(posterior_c0 > posterior_c1, 0, 1)
7     return predictions
```

Listing 11: Implementing the Bayes Classifier

Using Logarithms for Numerical Stability (Optional)

When dealing with very small probabilities, computing logarithms can improve numerical stability.

```
# Alternative implementation using logarithms (commented out)
def bayes_classifier_log(x, alpha, beta, mu, sigma, prior_c0, prior_c1):
    log_likelihood_c0 = np.log(gamma_pdf(x, alpha, beta) + 1e-300)
    log_likelihood_c1 = np.log(gaussian_pdf(x, mu, sigma) + 1e-300)
    log_posterior_c0 = log_likelihood_c0 + np.log(prior_c0)
    log_posterior_c1 = log_likelihood_c1 + np.log(prior_c1)
    predictions = np.where(log_posterior_c0 > log_posterior_c1, 0, 1)
    return predictions
```

Listing 12: Bayes Classifier with Logarithms

2.4 2d) Making Predictions and Evaluating the Classifier

2.4.1 Making Predictions on the Test Set

```
1 # Step 7: Make Predictions
2 X_test_reshaped = X_test.reshape(-1, 1)
3 y_pred = bayes_classifier(X_test_reshaped.flatten(), alpha, beta_hat, mu_hat, sigma_hat, prior_c0
4 , prior_c1)
```

Listing 13: Making Predictions

2.4.2 Evaluating the Classifier

```
1 # Step 8: Evaluate Classifier
2 accuracy = np.mean(y_pred == y_test)
3 print(f"\nTest Accuracy: {accuracy * 100:.2f}%")
4
5 from sklearn.metrics import confusion_matrix, classification_report
6
7 cm = confusion_matrix(y_test, y_pred)
8 print("\nConfusion Matrix:")
9 print(cm)
10
11 print("\nClassification Report:")
12 print(classification_report(y_test, y_pred))
```

Listing 14: Evaluating Classifier Performance

Results:

Test Accuracy: 91.81%

Confusion Matrix:

```
[[273  39]
 [ 20 388]]
```

Classification Report:

	precision	recall	f1-score	support
0.0	0.93	0.88	0.90	312
1.0	0.91	0.95	0.93	408
accuracy			0.92	720
macro avg	0.92	0.91	0.92	720
weighted avg	0.92	0.92	0.92	720

2.5 2e) Analyzing Misclassifications

2.5.1 Visualization of Misclassified Samples

```
1 # Step 9: Analyze Misclassifications
2 import seaborn as sns
3
4 misclassified_indices = np.where(y_pred != y_test)[0]
5 misclassified_samples = X_test[misclassified_indices]
6 correct_indices = np.where(y_pred == y_test)[0]
7 correct_samples = X_test[correct_indices]
8 correct_labels = y_test[correct_indices]
9
10 plt.figure(figsize=(12, 6))
11
12 sns.scatterplot(x=correct_samples, y=np.zeros_like(correct_samples), hue=correct_labels,
13               palette={0: 'blue', 1: 'red'}, style=correct_labels, markers={0: 'o', 1: 's'},
14               edgecolor='k', s=100, legend='full')
15
16 plt.scatter(misclassified_samples, np.zeros_like(misclassified_samples),
17           facecolors='none', edgecolors='yellow', s=150, label='Misclassified')
18
19 plt.xlabel('Feature Value')
20 plt.yticks([])
21 plt.legend(title='Class', loc='upper right')
22 plt.title('Classification Results on Test Data')
23 plt.show()
```

Listing 15: Analyzing Misclassifications

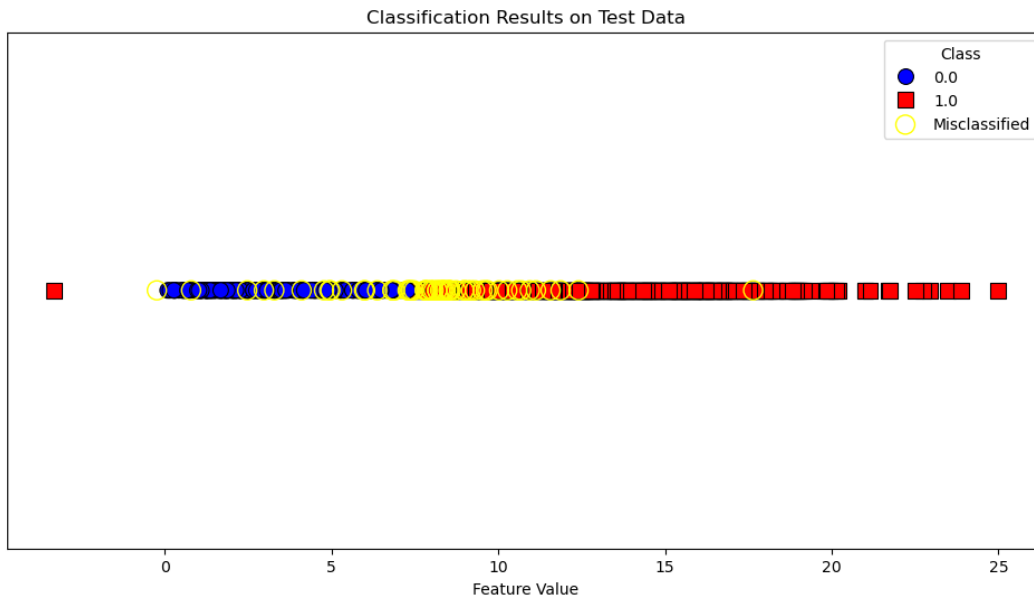


Figure 5: Visualization of correctly classified and misclassified samples on the test set.

2.5.2 Observations

From the confusion matrix and classification report, we observe:

- **Accuracy:** The classifier achieves an overall accuracy of **91.81%**.
- **Precision and Recall:**
 - **Class 0 (Gamma Distribution):**
 - * Precision: 0.93

- * Recall: 0.88
- * F1-Score: 0.90
- **Class 1 (Gaussian Distribution):**
 - * Precision: 0.91
 - * Recall: 0.95
 - * F1-Score: 0.93

2.6 2f) Discussion

2.6.1 Impact of Class Imbalance

The class priors reflect the imbalance in the training data:

$$P(C0) = 0.4444, \quad P(C1) = 0.5556$$

This imbalance can influence the classifier's predictions, potentially biasing it towards the majority class (Class 1).

2.6.2 Analysis of Misclassifications

Figure 5 shows that misclassifications primarily occur in regions where the feature distributions of the two classes overlap. Specifically:

- Some samples from **Class 0** with higher feature values are misclassified as **Class 1**.
- A few samples from **Class 1** with lower feature values are misclassified as **Class 0**.

2.6.3 Possible Improvements

To enhance the classifier's performance, especially for the minority class, we can consider:

Adjusting Class Priors

Assuming equal class priors could reduce bias towards the majority class:

$$P(C0) = 0.5, \quad P(C1) = 0.5$$

Applying Feature Transformation

Transforming the feature values (e.g., using logarithmic scaling) might improve class separability.

Visualizing Estimated PDFs

```

1 # Step 10: Additional Visualization
2 x_values = np.linspace(min(X), max(X), 1000)
3 gamma_pdf_values = gamma_pdf(x_values, alpha, beta_hat)
4 gaussian_pdf_values = gaussian_pdf(x_values, mu_hat, sigma_hat)
5
6 plt.figure(figsize=(12, 6))
7
8 sns.histplot(X_train_c0, bins=30, color='blue', alpha=0.5, stat='density', label='Class 0
   Histogram')
9 sns.histplot(X_train_c1, bins=30, color='red', alpha=0.5, stat='density', label='Class 1
   Histogram')
10
11 plt.plot(x_values, gamma_pdf_values, color='blue', label='Estimated Gamma PDF (Class 0)')
12 plt.plot(x_values, gaussian_pdf_values, color='red', label='Estimated Gaussian PDF (Class 1)')
13 # adding decision boundary
14 plt.axvline(x=(mu_hat+ beta_hat * alpha)/2, color='green', linestyle='--', label=f'Decision
   Boundary{(mu_hat+ beta_hat * alpha)/2:.2f}')
15
16 plt.xlabel('Feature Value')

```

```

17 plt.ylabel('Density')
18 plt.legend()
19 plt.title('Estimated PDFs and Histograms')
20 plt.show()

```

Listing 16: Plotting Estimated PDFs

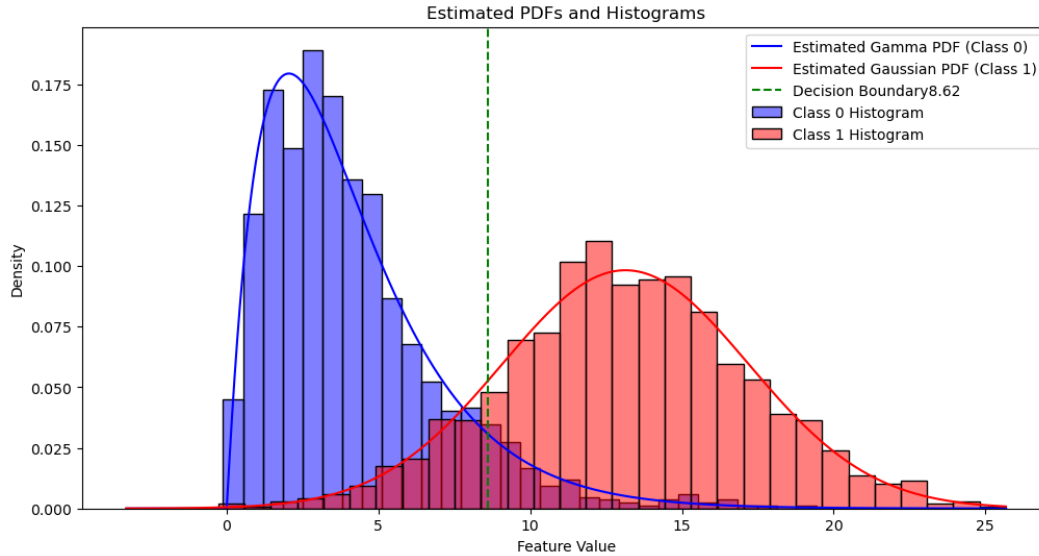


Figure 6: Estimated probability density functions overlaid on the histograms of the training data.

The plot in Figure 6 shows that the estimated PDFs fit the data distributions reasonably well. The overlap between the two distributions explains the misclassifications.

2.7 2h) Conclusion

We developed a Bayes classifier to distinguish between two classes with different underlying distributions. By estimating the parameters using MLE, we implemented the classifier and achieved a high accuracy of **91.81%**. The analysis highlights the impact of class imbalance and overlapping distributions on classifier performance. Adjusting class priors and exploring other techniques can further improve the classifier.

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