Info

Name Dr.-Ing. Timo Korthals

Web Page https://www.timo-korthals.de/

Skills sensor & information fusion, robotics,

curiosity driven / reinforcement / unsupervised / deep / machine learning, embedded and high-level programming in C/C++,

ROS, embedded systems development, Python, Tensorflow, Linux

application development, Yocto, Matlab

Professional Career

01/21 - today DLR Project Agri-Gaia - An agribusiness AI ecosystem for the

agri-food industry (CES)

10/20 - today CLAAS E-Systems GmbH (CES)

Ph.D. Thesis

Affiliation Bielefeld University - Cognitronics & Sensor Systems Group

Title Deep Generative Models for Multi-Modal Perception under the

Influence of Ambiguity

At-A-Glance My work tackled the learning of acting on multi-modal data

while facilitating multi-modal deep generative models to learn multi-sensory fusion. In the context of artificial intelligence, my approach contributes to unsupervised curiosity-driven learning of active sensing for a robot fleet equipped

with visual, depth, and proximity sensors.

Academic Career

Affiliations Cognitronics & Sensor Systems Group (AG-KS)

Research Institute for Cognition and Robotics (CoR-Lab) Center for Cognitive Interaction Technology (CITEC)

Bielefeld University - Germany (UBi)

11/18 - 09/20 BMBF Project ML4Pro² Machine Learning for Production and

Products - Distributed Robot Fleet Management (CoR-Lab in

association with Miele Cie. KG)

11/17 - 02/18 BMBF Concept Elaboration for Self-Organising Machine Con-

trol Systems for Cooperating Agbot Fleets entitled Agrosystems

of the Future (CITEC)

01/17 - 12/19	DAAD PPP Grant on Learning to act on Multi-Modal Data in collaboration with the ACRV lab at the Queensland University of Technology
02/15 - $02/16$	ERASMUS+ Lecturer at Aarhus University
07/14 - 10/17	BMBF Project in the Leading Edge Cluster for Cyber-Physical Systems for Electronic Environment Detection and Mapping in Agriculture Scenarios (CoR-Lab in association with CLAAS KGaA mbH)
09/13 - $12/18$	DFG Project Mini Robot Developement (CITEC)
09/13 - $06/14$	PhD Scholarship Holder Mini Robot Developement (CITEC)

Education

03/12 - 06/13	Electrical Engineering Master - University of Paderborn Topic: Unsupervised Learning of Acoustic- and Word-Units via Hierarchical, Generative Models
03/10 - 08/10	$\mathbf{Peking}/\mathbf{China}, \mathbf{Beihang} \mathbf{University} \mathbf{of} \mathbf{Aeronautics} \& \mathbf{Astronautics}$
08/07 - 03/12	Electrical Engineering Bachelor - University of Paderborn Topic: Evaluation of Algorithms for Creating Disparity Maps on the Basis of Monucalur Video Streams

RoboCup Competitions

04/14 - 04/16	Open Challenge @Home: 2014 Germany (4 th), 2015 Germany (3 rd), 2016 Netherlands (2 nd)
08/14 - 08/16	World Cup @Home: 2014 Brasil (3 rd), 2015 China (3 rd), 2016 Germany (1 st)
03/12	Open Challenge Rescue League: 2012 Germany (3 rd)

Literature

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- Korthals, Timo, Marvin Barther, T. Schöpping, Stefan Herbrechtsmeier, and U. Rückert (2016a). Occupancy Grid Mapping with Highly Uncertain Range Sensors based on Inverse Particle Filters. In: ICINCO 2016 Proceedings of the 13th International Conference on Informatics in Control, Automation and Robotics 2.
- Korthals, Timo, Andreas Skiba, and Thilo Krause (2016). Einsatz Event-Basierter Systemarchitektur für Erntemaschinen zur Elektronischen Umfelderkennung. In: 74. Tagung LAND. TECHNIK. VDI e.V.
- Korthals, Timo, Andreas Skiba, Thilo Krause, and Thorsten Jungeblut (2016b). Evidenzkarten-basierte Sensorfusion zur Umfelderkennung und Interpretation in der Ernte. In: *Informatik in der Land-, Forst und Ernährungswirtschaft*, pp. 15–18.
- Kragh, Mikkel, Peter Christiansen, Timo Korthals, Thorsten Jungeblut, Henrik Karstoft, and Rasmus N. Jørgensen (2016). Multi-Modal Obstacle Detection and Evaluation of Occupancy Grid Mapping in Agriculture. In: *International Conference on Agricultural Engineering*. Aarhus.
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- Korthals, Timo, Mikkel Kragh, Peter Christiansen, and Ulrich Rückert (2017b). Towards Inverse Sensor Mapping in Agriculture. In: IROS 2017 Workshop on Agricultural Robotics: learning from Industry 4.0 and moving into the future. Vancouver.
- Korthals et al. (2017). MIELE Robotik-Kompetenzen im Bereich Staubsaugerroboter. In:
- Korthals, Timo, Julian Exner, Thomas Schöpping, and Marc Hesse (2018a). Path Evaluation via HMM on Semantical Occupancy Grid Maps. In: *ArXiv e-prints*. arXiv: 1805.02944 [cs.R0].
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- Korthals, Timo, Andrew Melnik, Marc Hesse, and Jürgen Leitner (2019b). Multisensory Assisted In-hand Manipulation of Objects with a Dexterous Hand. In: 2019 IEEE International Conference on Robotics and Automation Workshop on Integrating Vision and Touch for Multimodal and Cross-modal Perception, ViTac 2019, Montreal, CA, May 20-25, 2019, pp. 1-2.
- Korthals, Timo, Daniel Rudolph, Jürgen Leitner, Marc Hesse, and Ulrich Rückert (2019c). Multi-Modal Generative Models for Learning Epistemic Active Sensing. In: 2019 IEEE International Conference on Robotics and Automation, ICRA 2019, Montreal, CA, May 20-25, 2019. Montreal, Canada.
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