

Ques 1 - Difference between BFS / DFS. Write application of both.

BFS

It stands for Breadth first search
uses queue

Data structure for finding the shortest path
in level-wise

BFS can be used to find the
shortest path, it uses to find single source
shortest path in unweighted graph.

BFS is better when target is
closer from the source

It considers all the neighbor, so it is
not suitable for decision tree used
in puzzle games

BFS is slower

Time complexity is $O(V+E)$

Application :- of BFS

- To detect cycles in graph
- Path finding
- Topological sorting

Ques - Which data structure to implement and why?

BFS uses the queue data structure to traverse a graph in a breadthward motion and uses a queue to remember to get the next vertex to start a search. When a dead end occurs in any iteration the queue follows the queue concept the vertex that can be discovered first will be explored first

DFS uses the stack data structure to traverse a graph in depthward motion and uses stack to remember to get the next vertex to start a search. When a dead end occurs in any iteration

DFS

It stands for Depth first search
it uses stack.

It also finds the shortest path in
depth-wise search

In DFS, we might traverse through
more edges to reach a destination
vertex from source

DFS is better when target is far
from the source

It consider more suitable for decision
tree.

DFS is faster

It time complexity is also $O(V+E)$

Application:- BFS

- GPS Navigation system
- Broadcasting
- Peer to Peer networking



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Ques - what do you meant by sparse and dense graphs? which representation is better for sparse and dense graphs?

A dense graph is a graph in which the number of edges is close to the maximal number of edges. The every pair of vertices is connected maximum. The opposite, a graph with only a few edges by one edge. The opposite, the distinction between sparse and dense graph is more vague and depends on the context.

The graph density of simple graph is defined to be the ratio of numbers of edges $|E|$ with respect to the maximum possible edge.

$$D = \frac{|E|}{\binom{|V|}{2}} = \frac{2|E|}{|V|(|V|-1)}$$

Ques - Heap data structures can be used to implement priority queue? Name two graph algorithms where you need to use Priority queue and why?

Binary heap is a Binary data structure. A priority queue can be implemented using an array, a linked list, a heap data structure. Among these data structures, heap data structure provides an efficient implementation of priority queue.

Hence, we used heap for implementation of priority queue.

By inserting an element into the priority queue and delete element from queue, find Max/min and Extract Max/min from the Priority Queue.

The graph algorithm uses the priority queue.

Dijkstra's shortest path algorithm

Prim's algorithm

heap sort algorithm



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To detect the cycle in BFS and DFS?

In case of DFS :.. back edge concept will be used to find out cycles in the graph. If there exist back edge in the graph then it contain a cycle.

In case of BFS : just traverse the graph and if any vertex find its adjacent vertex with flag zero then that graph contains a cycle.

Ques - what do you mean by disjoint set data structure? Explain 3 operations along with example which can be performed on disjoint set

The disjoint set data structure is also known as union - find data structure and myself find set. It is also data structure that contains a collection of disjoint or non-overlapping sets. The disjoint set means that when the set is partitioned into the disjoint subsets. The various operation can be performed on the disjoint subset. In case, we add new set we can merge in set, whether the two element are in the same set or not efficiently.

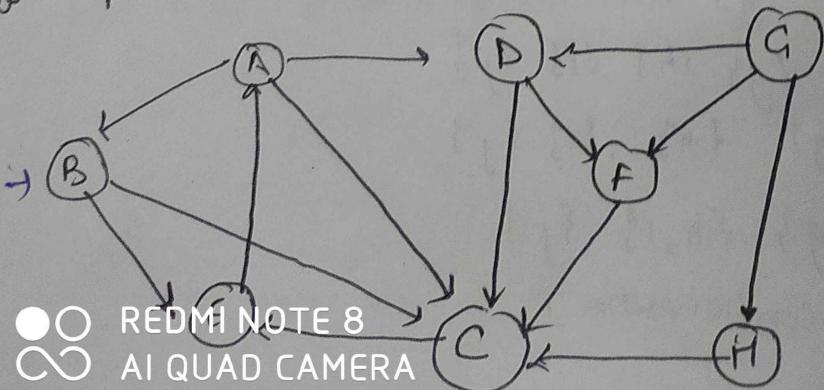
operation on disjoint set

CREATE-SET(x) - Create a new set with one element $\{x\}$.

MERGE-SETS(x, y) = merge into one set the set that contains element x and the set that contain element y (x and y are in different sets).

FIND-SET(x) - return the representation or a pointer to the representation of the set that contain

Ques - run BFS and DFS on graph :-



BFS child parent

A	H D F C E A B
	A G A H C E A

path $\rightarrow A \rightarrow H \rightarrow C \rightarrow E \rightarrow A \rightarrow B$

DFS

G
D
H
F
C
E
A
B

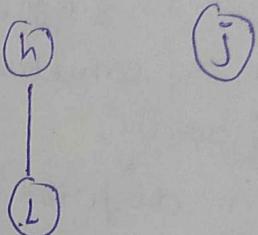
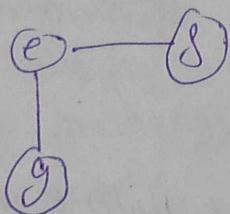
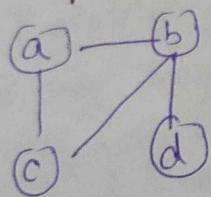
Nodes visited

G
F
C
E
A
B

Stack

Path $\rightarrow G \rightarrow F \rightarrow C \rightarrow E \rightarrow A \rightarrow B$

Ques 7) find out no. of connected component and vertices in each component using disjoint set data structure



$$V = \{a, b, c, d, e, f, g, h, i, j\}$$

$$E = \{a, b\}, \{a, c\}, \{b, c\}, \{b, d\}, \{e, f\}, \{e, g\}, \{h, i\}, \{j\}$$

(a,b)	$\{a, b\} \cap \{c\} = \emptyset$, $\{a, b\} \cap \{d\} = \emptyset$, $\{a, b\} \cap \{e, f, g\} = \emptyset$, $\{a, b\} \cap \{h, i, j\} = \emptyset$
(a,c)	$\{a, b, c\} \cap \{d\} = \emptyset$, $\{a, b, c\} \cap \{e, f, g\} = \emptyset$, $\{a, b, c\} \cap \{h, i, j\} = \emptyset$
(b,c)	$\{a, b, c\} \cap \{d\} = \emptyset$, $\{a, b, c\} \cap \{e, f, g\} = \emptyset$, $\{a, b, c\} \cap \{h, i, j\} = \emptyset$
(b,d)	$\{a, b, d\} \cap \{e, f, g\} = \emptyset$, $\{a, b, d\} \cap \{h, i, j\} = \emptyset$
(e,f)	$\{e, f\} \cap \{a, b, c, d\} = \emptyset$, $\{e, f\} \cap \{g\} = \emptyset$, $\{e, f\} \cap \{h, i, j\} = \emptyset$
(e,g)	$\{e, g\} \cap \{a, b, c, d\} = \emptyset$, $\{e, g\} \cap \{f\} = \emptyset$, $\{e, g\} \cap \{h, i, j\} = \emptyset$
(h,i)	$\{h, i\} \cap \{a, b, c, d\} = \emptyset$, $\{h, i\} \cap \{f, g\} = \emptyset$, $\{h, i\} \cap \{j\} = \emptyset$

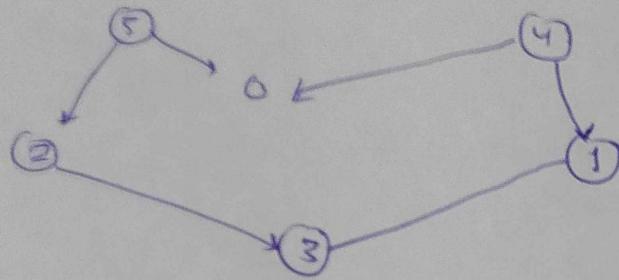
No. of connected component = 3



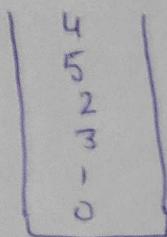
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Q10-8 Apply topological sort & DFS on graph having vertices
From 0 to 5

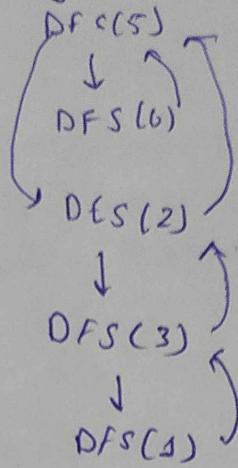


DFS



Stack
 $0 \rightarrow 5 \rightarrow 2 \rightarrow 3 \rightarrow 1 \rightarrow 0$

Applying Topological Sort



$DFS(4)$
↓
Not possible

Q11- Differentiate between Min heap and Max heap.

Min heap

In min-heap, key present at root node must be less than or equal to among keys present at all of its children.

The minimum key element is present at the root.

It uses ascending priority

The smallest element has priority with construction of min-heap.

The smallest element is the first to be popped from the heap

Max heap

1) In max-heap the key present at root must be greater than or equal to among key present at all of its children

2) The maximum key element is present at the root.

3) It uses descending priority

4) The largest element has priority, while construction of max-heap.

5) The largest element is the 1st to be popped from the heap



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ques 1 - What do you mean by minimum Spanning tree? What are the applications of MST?

Ans → Minimum spanning Tree is a subset of edges of a connected edge-weighted undirected graph that connects all the vertices together without any cycles & with minimum possible edge weighted.

Application:-

Consider n stations are to be linked using a communication network and laying of communication link b/w any two stations involved in cost. The best solution would be to extract a Subgraph formed as minimum cost Spanning tree.

i) Designing LAN

iii) suppose you want to construct highway or railroads spanning tree, then we can use the concept of MST.

iv) laying pipeline connecting offshore drilling rigs, refineries & consumer markets

ques 2 → Analyze time and space complexity of Prim, Kruskal, Dijkstra and Bellman Ford Algorithm

Time complexity of Prim's Algorithm $O(|E| \log |V|)$

Space complexity of Prim's Algorithm $O(|V|)$

Kruskal's Algorithm

Time complexity of $\mathcal{O}(|E| \log |E|)$

Space complexity $O(|V|)$

Dijkstra's Algorithm

Time complexity $O(V^2)$

Space complexity $O(V^2)$

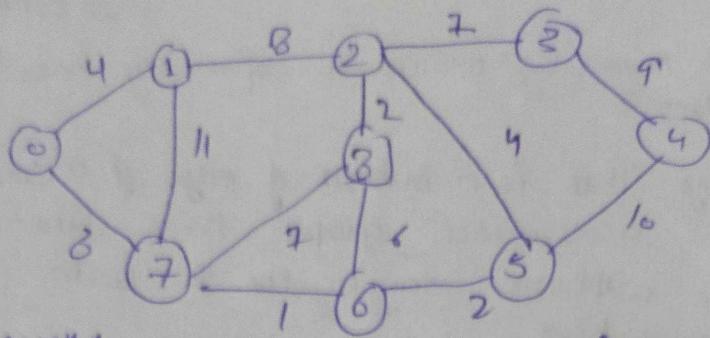
Bellman Ford's Algorithm

Time complexity $O(|V||E|)$

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Space complexity $O(|E|)$

Ques 3 → Apply Kruskal and Prim's Algorithm on given graph
compute MST and its weight

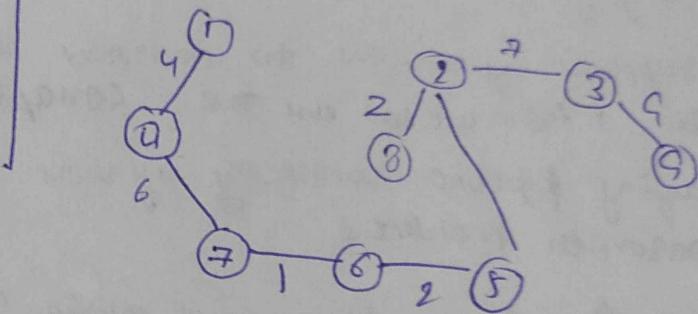


Kruskal's Algorithm

0	V W
6	7 1
5	6 2
2	8 2
0	1 4
2	5 4
6	8 6
2	3 7
2	8 7
0	7 8
1	2 8
4	3 9
4	5 10
1	7 10
3	5 14

Prim's Algorithm

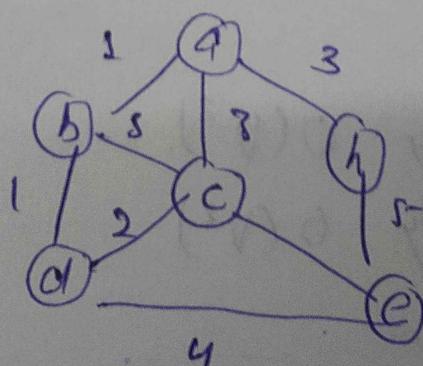
$$4 + 8 + 2 + 4 + 2 + 7 + 9 + 3 \\ = 37$$



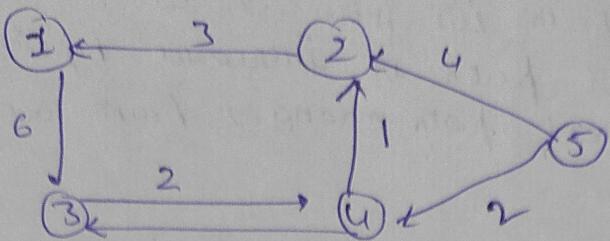
Ques 4 →

Given a directed weight graph from a source vertex 'S' to a destination vertex 'T'. You are also given the shortest path from S to T. Does the shortest path remain same in following cases:

- i) If weight of every edge is increased by 10 unit
- ii) If weight of every edge is decreased by 10 unit



all pair shortest path algorithm - Floyd Warshall on below mentioned graph. Also analyse space & time complexity of it



	1	2	3	4	5
1	0	∞	6	3	∞
2	2	0	∞	∞	∞
3	∞	∞	0	2	∞
4	∞	1	1	0	∞
5	∞	4	∞	2	0

	1	2	3	4	5
1	0	∞	6	3	0
2	2	0	8	5	∞
3	∞	∞	0	2	∞
4	∞	1	1	0	∞
5	∞	4	∞	2	0

	1	2	3	4	5
1	0	∞	6	3	∞
2	2	0	8	5	∞
3	∞	∞	0	2	∞
4	3	1	1	0	∞
5	6	4	12	2	0

Time complexity

$$\rightarrow O(|V|^3)$$

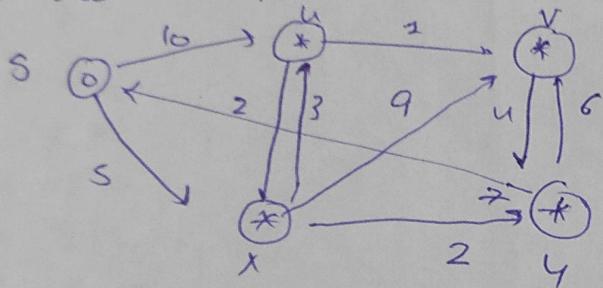
Space complexity

$$\rightarrow O(|V|^2)$$

Ans) (i) The shortest path may change. The reason is that there may be different no. of edges in different paths from 'S' to 't'.
 For ex:- Let the shortest path of weight 15 and has edges s - u - v - t.
 Let there is another path is increased by 5% and becomes 15 + 5%. weight of other path is increased by 2% & becomes 20 + 2%, so, the shortest path changes from an increased path with weight as 45.

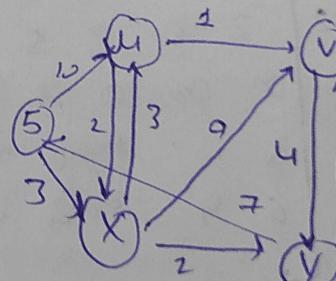
(ii) If we are multiply all edges weight by 10, the shortest path doesn't change. The reason is that weight of all path from 'S' to 't' gets multiplied by same unit one number of edges or path doesn't matter.

Ques 3 → Apply Dijkstra & Bellman Ford algorithm on graph given right side to compute shortest path to all nodes from node S.

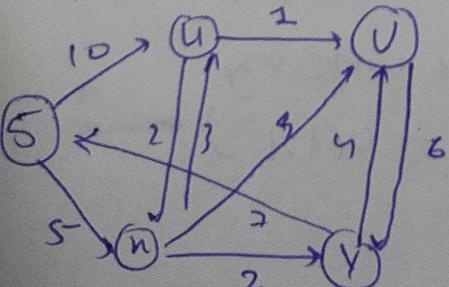


Dijkstra's Algorithm

Node	SHORTEST DIST FROM SOURCE NODE S				
U	8				
X		5			
V			9		
Y				7	



Bellman Ford Algorithm



1 st	0	∞	∞	3	∞
2 nd	0	10	11	8	10
3 rd	0	8	19	5	15
4 th	0	8	9	5	15