Tilak Gupta

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Education

Mechatronics Engineering, University of Waterloo (87% Average)

Sep 2015 - Present

 Relevant Courses: Computer Structures and Real-Time Systems, Sensors and Instrumentation, Embedded Systems (edX)

Skills

Firmware

Embedded C/C++ | Python | Bash | FreeRTOS | Bare Metal | GNU ARM Toolchain | OpenOCD | HAL Lib. | UART, SPI, I2C, CAN | PWM | Keil MCB 1700 | uVision | CubeMX | IAR Emb. Workbench | Visual Studio

Hardware

ARM | STM32 | DMM | Oscilloscope | Power Supplies/Wave Generators | Particle Core | Arduino | IoT | Altium (Learning) | Circuit Design | Schematics | Soldering Surface Mounts | Hardware Debugging

Extracurricular Experience

Waterloo Formula Electric, Firmware Team, University of Waterloo

Jan 2017 - Present

- Setup SPI communication with SD card for logging sensor values, benchmarked R/W speeds
- Developing firmware for 2018 vehicle Data Acquisition Unit

Work Experience

Control Systems Design Assistant, MedAvail Technologies Inc.

May – Aug 2017

- Developed a bootloader capable of recovering firmware from external memory for pre-launch machine
- Designed and tested an API to transmit node firmware over CAN during node updates
- Ported code running in TI-RTOS to FreeRTOS on STM32 MCUs
- Debugged hardware issues arising from CAN and SPI using oscilloscopes and CAN analyzers

Software Engineer, BDO Solutions Ltd

Sep - Dec 2016

- Decreased web application load times by 50% by redesigning application in different software
- Increased web security by enforcing HTTPS and preventing Cross Site Scripting attacks
- Performed propensity modelling and regression analysis to predict insurance claims

Software Engineer, Broad-Connect Telecom Inc.

Jan - April 2016

- Engineered software for new web portal elements in a start-up like environment
- Increased security by developing two-factor authentication system
- Designed and wrote unit tests for applications to ensure maintainability and resiliency of code

Projects

Electric Carbon Fiber Bike (WIP, Construction Pending)

- Designed a full size carbon fiber bike frame and planned electrical propulsion system
- Planning to design a custom in-house motor control unit to control BLDC motor
- Designed a custom mono-shock rear suspension for off-road capability

LED Ambient Lighting

- Used the Particle Core to program LEDs to respond to weather and music
- Wrote firmware to transfer LED color commands using custom serial communication protocol

Quadcopter

- Built a quadcopter utilizing online resources and sourced parts (Frame, Motors, ESCs)
- Debugged hardware and firmware issues which arose during the build

Awards

- Waterloo President's Scholarship | \$2,000
- Vex Robotics: Excellence in Design | Rick Hansen Regional Winner Out of 36 teams
- Rick Hansen Science Department Award