

# Pierre-Louis TILAK

Embedded System Engineer

## Contact

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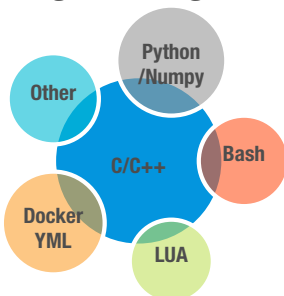
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## Languages

French : Mother tongue  
English : Fluent  
TOEIC : 925 pts  
Spanish : Academic Level

## Programming Skills



## Personal Projects

**OpenSource Cocktail Machine**  
:  
ESP8266/Raspberry Pi

### Paragliding Variometer :

Atmega328p/ Kobo  
E-reader

## Interest

**RC Models** Design and build  
RC Gliders and Airplanes

**Music** Guitar

**Sport** Paragliding, Climbing,  
Ski, MountainBike

## Summary

- Experienced Embedded System Engineer specialized in firmware development.
- Ready to manage engineering project
- Strong experience in Drone industry, perfect vision of the future of new technologies.
- Ability to design entire firmware project : Requirements, Project Organisation, Programming, Testing and Validation.
- Early employee of a fast growing startup : Autonomous, Multitask, multi-skilled, ability to adapt and be committed in any situation.
- Can-do attitude and committed to give a broad vision and a result-driven attitude to distribute the best solutions.

## Experiences

- |           |  |          |
|-----------|--|----------|
| 2015-2019 | <b>Delair (Industrial Drone Company) Developer in Autopilot team</b>   | Toulouse |
|           | Embedded System Engineer   |          |
|           | <ul style="list-style-type: none"><li>• C Programming on microcontroller (STM32) : Sensor interface, Drivers, Communication protocols.</li><li>• Control Laws for Brushless Gimbal : Kalman filtering, Brushless model control, FOC control</li><li>• Python engineering tools : GUI for experiment and log analysis ( PyQT, Matplotlib, Dash &amp; Plotly ), Scripts to communicate (TCP, Serial Port), Web request, Unitary Tests and Continuous integration (Behave)</li><li>• Implementation of Developpement Environnement : Cross-compilation toolchain (arm-gcc, make), Continuous Integration with GitLab Runners : Create docker images (build, complete test environnement with simulator) Automatic release package generation and versionning (Gitlab Pipeline, JFrog Artifactory)</li><li>• CPP Programming on embedded linux : Drone sensor configuration, Thread and IPC ( Linux Signals, SharedMemory, ZMQ, ...)</li></ul> |          |
| 2014      | <b>SCLE SFE 3 months internship</b>  | Toulouse |
|           | Test plan development : JTAG Boundary Scan (XJTAG Software)  |          |
| 2012      | <b>Polymont Subcontractor of Airbus Operating Method Writer</b>  | Toulouse |
|           | Writing operating method for maintenance on Iron-bird Airbus A330, A320 and A380   |          |

## Education

- |           |  |   |
|-----------|--|---|
| 2010-2014 | <b>Master of engineering</b>               | Institut National des Sciences Appliquées, Toulouse |
|           | Automatic Control and Electronics          |   |
| 2013      | <b>Exchange Semester 6 Months Thailand</b> | Chulanlongkorn University, Bangkok                  |

## Skills

Tools :

- Gitlab / Jira : Ticketing, Project Managment / Agile
- Docker, Gitlab Pipelines: Continuous Integration
- BDD and Unitary Tests : Behave, Gtest
- Python : Numpy / PyQt / Plotly / Sockets
- Vim, Clang, GCC Toolchain STM32 : Make/Compilation/Debugger