Machine learning 2 Exercise sheet 9

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1 Hidden Markov Models

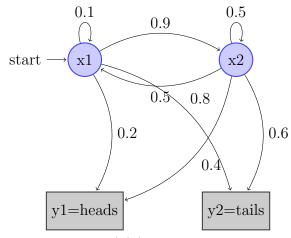
Let $A_{i,j}$ the transition matrix between hidden states x_i and x_j . $B_{i,j}$ is the probability, beeing in state i to overserve y_j . The following matrices A and B describe two hidden states and two possible observations.

$$A = \begin{pmatrix} 0.1 & 0.9 \\ 0.5 & 0.5 \end{pmatrix}$$

$$B = \begin{pmatrix} 0.2 & 0.8 \\ 0.4 & 0.6 \end{pmatrix}$$

1.1 a. Draw the graph of the model

The Hidden-Markov-chain for A and B looks like the following4



Because of $\pi = (1|0)$ all state-sequences start with the initial state x_1 .

1.2 b.

We interpret the above as a model for an experiment with two hidden (unfair) coins and two visible coins. Describe such an experiment which can be modelled by the Markov model given above. Here, heads should correspond to the first indices in A, B, π , heads to the second.

A man is standing behind an curtain and is throwing two unfair coins, just one each time. The guy in front of the curtain just get the observation wheter he sees heads or tails.

1.3 c.

Given the bayes rule:

$$P(x|y_1 = tails, y_2 = tails) = \frac{P(y_1 = tails, y_2 = tails|x)P(x)}{P(y_1 = tails, y_2 = tails)}$$
(1)

Because of the statistical independence, we can write

$$P(y_1 = tail, y_2 = tail | x_1, x_2) = \pi_1 \cdot P(y_1 | x_1) \cdot P(x_1) \cdot P(y_2 | x_2) \cdot P(x_2)$$
(2)

All possible sequences with length 2 (with two transitions) are

State transitions

$$P(x)$$
 $P(y_1 = tails, y_2 = tails | x)$

 1
 $[x_1] \rightarrow x_1 \rightarrow x_1$
 $P(x_1, x_1, x_1) = 1 \cdot 0.1 \cdot 0.1 = 0.01$
 $0.1 \cdot 0.4 \cdot 0.1 \cdot 0.4 = 0.0016$

 2
 $[x_1] \rightarrow x_1 \rightarrow x_2$
 $P(x_1, x_1, x_2) = 1 \cdot 0.1 \cdot 0.9 = 0.09$
 $0.1 \cdot 0.4 \cdot 0.9 \cdot 0.6 = 0.0216$

 3
 $[x_1] \rightarrow x_2 \rightarrow x_1$
 $P(x_1, x_2, x_1) = 1 \cdot 0.9 \cdot 0.5 = 0.45$
 $0.9 \cdot 0.6 \cdot 0.5 \cdot 0.4 = 0.108$

 4
 $[x_1] \rightarrow x_2 \rightarrow x_2$
 $P(x_1, x_2, x_2) = 1 \cdot 0.9 \cdot 0.5 = 0.45$
 $0.9 \cdot 0.6 \cdot 0.5 \cdot 0.6 = 0.162$

$$P(y_1, y_2) = \sum_{x} P(y_1, y_2 | x) P(x)$$
(3)

$$= \sum_{x} P(y_1 = tails, y_2 = tails|x)P(x)$$
(4)

$$= 0.0016 \cdot 0.01 + 0.0216 \cdot 0.09 + 0.0108 \cdot 0.45 + 0.162 \cdot 0.45 \tag{5}$$

$$=0.07972$$
 (6)

The result for $P(x|y_1 = tails, y_2 = tails)$ follows as State-sequence $P(x|y_1 = tails, y_2 = tails)$

1
$$x = x_1, x_1$$
 $\frac{0.0016 \cdot 0.01}{0.07972} = 0.002007025$
2 $x = x_1, x_2$ $\frac{0.0216 \cdot 0.09}{0.07972} = 0.024385349$
3 $x = x_2, x_1$ $\frac{0.108 \cdot 0.45}{0.07972} = 0.609633718$
4 $x = x_2, x_2$ $\frac{0.0162 \cdot 0.45}{0.07972} = 0.091445058$