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compute\_scores.m

```
1 function scores = compute_scores(KS, KSR, KR, alpha)
2 % inputs: KR      kernel matrix on training data
3 %         KS      kernel matrix on test data
4 %         KSR     kernel matrix on test data/training data
5 %         alpha   learnt dual vector
6 % output: scores  vector of outlier scores
7 N=length(KS);
8 scores = zeros(N,1);
9 for i=1:N
10     scores(i,1)=KS(i,i)-2*KSR(i,:)*alpha+alpha'*KR*a
11 end
```

dont use loops,  
loops get slow and  
inaccurate for huge  
amounts of data.

this can be a  
one-line-statement!  
10 / 10

hacker\_detection.m

```
1 load('stud-data.mat')
2
3 % compute kernel matrices
4 disp('computing_kernel_matrices...')
5 KR = full(Xtr'*Xtr);
6 KS = full(Xts'*Xts);
7 KSR = full(Xts'*Xtr);
8
9 % compute the alphas
10 disp('learning_one-class-SVM...')
11 C = 0.002; % adjust C
12 alpha = oneclass(KR, C);
13
14 % compute anomaly scores
15 as = compute_scores(KS, KSR, KR, alpha);
16
17 Ap = (as > 1);
18
19 predicted_attacks = find(Ap)';
20
21 hold on;
22 plot(as);
23 plot(1:length(as),1,'r-');
24
25 predicted_attacks
```

oneclass.m

```

1 function alpha = oneclass(K, C)
2 % inputs: K      N x N kernel matrix
3 %         C      regularization constant
4 % outputs: alpha N-dimensional dual solution vector
5
6 dim=length(K);
7
8 %variables for quadratic program
9 %minimize c' * x + 1/2 x' * H * x
10 %subject to A'*x = b
11 %          l <= x <= u
12 % Dimensions: c : N-column vector
13 %              H : NxN matrix
14 %              A : N-row vector
15 %              b : real number
16 %              l : N-column vector
17 %              u : N-column vector
18 %
19 %              x : N-column vector
20 %              y : Objective value
21 %ERROR: chol works not properly on very slow (close to zero) data
22 %c=diag(K)';
23 %H=-K;
24 %b=1;
25 %A=ones(dim,1);
26 %l=zeros(dim,1);
27 %u=ones(dim,1)*C;
28 %[x,y] = pr_loqo2(c, H, A, b, l, u);
29 u = x;
30
31 H=-K;
32 f=diag(K);
33 l=zeros(dim,1);
34 u=ones(dim,1)*C;
35 Aeq = ones(dim,1)';
36 beq = ones(1);
37 alpha = quadprog(H,f,[],[],Aeq,beq,l,u);

```

pr\_loqo2 and quadprog both solve minimization problems, yet we have formulated a maximization problem. -> solvers wont converge, ever (problems are concave, thus become unconstrained)

f= -diag(K)

H = 2K. we have to turn it around, because of this

10 / 20 , for correct constraints.

pr\_loqo2.m

```

1 function [x,y] = pr_loqo2(c, H, A, b, l, u)
2 %[X,Y] = PR_LOQO2(c, H, A, b, l, u)
3 %
4 %loqo solves the quadratic programming problem
5 %
6 %minimize c' * x + 1/2 x' * H * x
7 %subject to A'*x = b
8 %          l <= x <= u
9 %
10 % Dimensions: c : N-column vector
11 %              H : NxN matrix
12 %              A : N-row vector
13 %              b : real number
14 %              l : N-column vector

```

```

15 | %                u : N-column vector
16 | %
17 | %                x : N-column vector
18 | %                y : Objective value
19 | %
20 | %for a documentation see R. Vanderbei, LOQO: an Interior Point Code
21 | %                for Quadratic Programming
22 | margin = 0.05;
23 | bound  = 100;
24 | sigfig_max = 8;
25 | counter_max = 50;
26 | [m, n] = size(A);
27 | H_x    = H;
28 | H_diag = diag(H);
29 | b_plus_1 = 1;
30 | c_plus_1 = norm(c) + 1;
31 | one_x = -ones(n,1);
32 | one_y = -ones(m,1);
33 |
34 | for i = 1:n
35 |     H_x(i,i) = H_diag(i) + 1;
36 | end;
37 |
38 | eig(H_x)
39 |
40 | H_y = eye(m);
41 | c_x = c;
42 | c_y = 0;
43 | R = chol(H_x);
44 | H_Ac = R \ ([A; c_x'] / R)';
45 |
46 | H_A = H_Ac(:,1:m);
47 | H_c = H_Ac(:,(m+1):(m+1));
48 |
49 | A_H_A = A * H_A; A_H_c = A * H_c;
50 | H_y_tmp = (A_H_A + H_y); y = H_y_tmp \ (c_y + A_H_c);
51 | x = H_A * y - H_c; g = max(abs(x - l), bound);
52 | z = max(abs(x), bound); t = max(abs(u - x), bound);
53 | s = max(abs(x), bound); mu = (z' * g + s' * t) / (2 * n);
54 | sigfig = 0; counter = 0; alfa = 1;
55 | while ((sigfig < sigfig_max) * (counter < counter_max)),
56 |     counter = counter + 1; H_dot_x = H * x;
57 |     rho = - A * x + b; nu = l - x + g; tau = u - x - t;
58 |     sigma = c - A' * y - z + s + H_dot_x;
59 |     gamma_z = - z; gamma_s = - s;
60 |     x_dot_H_dot_x = x' * H_dot_x;
61 |     primal_infeasibility = norm([tau; nu]) / b_plus_1;
62 |     dual_infeasibility = norm([sigma]) / c_plus_1;
63 |     primal_obj = c' * x + 0.5 * x_dot_H_dot_x;
64 |     dual_obj = - 0.5 * x_dot_H_dot_x + l' * z - u' * s + b'*y; %%%
65 |     old_sigfig = sigfig;
66 |     sigfig = max(-log10(abs(primal_obj - dual_obj)/(abs(primal_obj) + 1)), 0);
67 |     hat_nu = nu + g .* gamma_z ./ z; hat_tau = tau - t .* gamma_s ./ s;
68 |     d = z ./ g + s ./ t;
69 |     for i = 1:n H_x(i,i) = H_diag(i) + d(i); end;
70 |     H_y = 0; c_x = sigma - z .* hat_nu ./ g - s .* hat_tau ./ t;
71 |     c_y = rho; R = chol(H_x); H_Ac = R \ ([A; c_x'] / R)';

```

```

72 H_A = H_Ac(:,1:m); H_c = H_Ac(:,(m+1):(m+1));
73 A_H_A = A * H_A; A_H_c = A * H_c; H_y_tmp = (A_H_A + H_y);
74 delta_y = H_y_tmp \ (c_y + A_H_c); delta_x = H_A * delta_y - H_c;
75 delta_s = s .* (delta_x - hat_tau) ./ t;
76 delta_z = z .* (hat_nu - delta_x) ./ g;
77 delta_g = g .* (gamma_z - delta_z) ./ z;
78 delta_t = t .* (gamma_s - delta_s) ./ s;
79 gamma_z = mu ./ g - z - delta_z .* delta_g ./ g;
80 gamma_s = mu ./ t - s - delta_s .* delta_t ./ t;
81 hat_nu = nu + g .* gamma_z ./ z;
82 hat_tau = tau - t .* gamma_s ./ s;
83 c_x = sigma - z .* hat_nu ./ g - s .* hat_tau ./ t;
84 c_y = rho; H_Ac = R \ ([A; c_x'] / R)';
85 H_A = H_Ac(:,1:m); H_c = H_Ac(:,(m+1):(m+1));
86 A_H_A = A * H_A; A_H_c = A * H_c;
87 H_y_tmp = (A_H_A + H_y); delta_y = H_y_tmp \ (c_y + A_H_c);
88 delta_x = H_A * delta_y - H_c; delta_s = s .* (delta_x - hat_tau) ./ t;
89 delta_z = z .* (hat_nu - delta_x) ./ g;
90 delta_g = g .* (gamma_z - delta_z) ./ z;
91 delta_t = t .* (gamma_s - delta_s) ./ s;
92 alfa = - 0.95 / min([delta_g ./ g; delta_t ./ t;
93                     delta_z ./ z; delta_s ./ s; -1]);
94 mu = (z' * g + s' * t) / (2 * n);
95 mu = mu * ((alfa - 1) / (alfa + 10))^2;
96 x = x + delta_x * alfa; g = g + delta_g * alfa;
97 t = t + delta_t * alfa; y = y + delta_y * alfa;
98 z = z + delta_z * alfa; s = s + delta_s * alfa;
99 end

```

#### test\_ocsvm.m

```

1 function [ ] = test_ocsvm( predicted_attacks )
2
3 load( 'full-data.mat' )
4 At = (Yts' > 0.5);
5 true_attacks = find(At)';
6 missing_attacks = setdiff(true_attacks, predicted_attacks)
7 false_positives = setdiff(predicted_attacks, true_attacks)
8
9 end

```

*Machine learning 2*  
Exercise sheet 5

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40 + 20 + 10 = 70

# 1 One-class-SVM: Theory

(a) Derive the dual program for the one-class SVM.

**Primal form**

The primal form of the one-class SVM has the following form:

$$\min_{\boldsymbol{\mu}, r, \boldsymbol{\xi}} r^2 + C \sum_{i=1}^N \xi_i$$

such that

$$\begin{aligned} \|\phi(x_i) - \boldsymbol{\mu}\|^2 &\leq r^2 + \xi_i \\ \xi_i &\geq 0 \end{aligned}$$

for  $i = 1, \dots, n$ . Using Lagrange multipliers gives us the unconstrained form:

$$\min_{\boldsymbol{\mu}, r, \boldsymbol{\xi}} \max_{\boldsymbol{\alpha}, \boldsymbol{\beta} \geq 0} \underbrace{\left\{ r^2 + C \sum_{i=1}^N \xi_i + \sum_{i=1}^N \alpha_i (\|\phi(x_i) - \boldsymbol{\mu}\|^2 - r^2 - \xi_i) - \sum_{i=1}^N \beta_i \xi_i \right\}}_{L(\boldsymbol{\mu}, r, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta})}$$

The dual optimization problem is now given by

$$\max_{\boldsymbol{\alpha}, \boldsymbol{\beta} \geq 0} g(\boldsymbol{\alpha}, \boldsymbol{\beta})$$

with  $g$  being defined by

$$g(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \min_{\boldsymbol{\mu}, r, \boldsymbol{\xi}} L(\boldsymbol{\mu}, r, \boldsymbol{\xi}, \boldsymbol{\alpha}, \boldsymbol{\beta}) \quad (1)$$

To compute the minimum of  $L$  w.r.t.  $\boldsymbol{\mu}, r$  and  $\boldsymbol{\xi}$  we take the partial derivative and set it afterwards to zero.

$$\begin{aligned} \nabla_{\boldsymbol{\mu}} L &= \nabla_{\boldsymbol{\mu}} \left( \sum_{i=1}^N \alpha_i (\phi(x_i) - \boldsymbol{\mu})^T (\phi(x_i) - \boldsymbol{\mu}) \right) \\ &= \sum_{i=1}^N \alpha_i (2\boldsymbol{\mu} - 2\phi(x_i)) \end{aligned} \quad (2)$$

$$\frac{\partial L}{\partial r} = 2r - 2 \sum_{i=1}^N \alpha_i r \quad (3)$$

$$\frac{\partial L}{\partial \xi_j} = C - \alpha_j - \beta_j \quad (4)$$

Setting equations (2),(3) and (4) to 0 we obtain

$$\boldsymbol{\mu} \sum_{i=1}^N \alpha_i = \sum_{i=1}^N \alpha_i \phi(x_i) \quad (5)$$

$$(1 - \sum_{i=1}^N \alpha_i) r = 0 \quad (6)$$

$$C = \alpha_i + \beta_i \quad (7)$$

Assuming that we have at least 2 distinct data points, we know that  $r > 0$  holds. Thus equation (6) gives us

$$\sum_{i=1}^N \alpha_i = 1 \quad (8)$$

and thus equation (5) can be expressed by

$$\boldsymbol{\mu} = \sum_{i=1}^N \alpha_i \phi(x_i) \quad (9)$$

This equation says that one can express the optimal solution for  $\boldsymbol{\mu}$  as a linear combination of the data points in feature space. Plugging equations (7) and (9) into equation (1) gives us

$$\begin{aligned} g(\boldsymbol{\alpha}, \boldsymbol{\beta}) &= r^2 + \sum_{i=1}^N (\alpha_i + \beta_i) \xi_i + \sum_{i=1}^N \alpha_i \left( \|\phi(x_i) - \sum_{i=1}^N \alpha_i \phi(x_i)\|^2 - r^2 - \xi_i \right) - \sum_{i=1}^N \beta_i \xi_i \\ &= r^2 - r^2 \sum_{i=1}^N \alpha_i + \sum_{i=1}^N \alpha_i \left( \phi(x_i) - \sum_{j=1}^N \alpha_j \phi(x_j) \right)^T \left( \phi(x_i) - \sum_{j=1}^N \alpha_j \phi(x_j) \right) \end{aligned}$$

Using equation (8) gives us

$$g(\boldsymbol{\alpha}) = \sum_{i=1}^N \alpha_i \phi(x_i)^T \phi(x_i) - \sum_{i,j=1}^N \alpha_i \alpha_j \phi(x_i)^T \phi(x_j)$$

with the additional constraints

$$\begin{aligned} \sum_{i=1}^N \alpha_i &= 1 \\ C = \alpha_i + \beta_i &\Rightarrow 0 \leq \alpha_i \leq C \end{aligned}$$

Assuming we have a kernel function  $k$  expressing the inner product  $\phi(x)^T \phi(y) = k(x, y)$  we finally end up at the final formulation:

$$\max_{\boldsymbol{\alpha}} \left\{ \sum_{i=1}^N \alpha_i k(x_i, x_i) - \sum_{i,j=1}^N \alpha_i \alpha_j k(x_i, x_j) \right\} \quad (10)$$

subject to

well done!  
30 / 30

$$\begin{aligned} \sum_{i=1}^N \alpha_i &= 1 \\ 0 \leq \alpha_i &\leq C \text{ with } i = 1, \dots, n \end{aligned}$$

**(b) Show that the dual problem is a linearly constrained quadratic problem.**

Setting  $(\mathbf{b})_i = k(x_i, x_i)$  and  $(A)_{i,j} = -k(x_i, x_j)$  we can reformulate equation (10) in its matrix/vector notation

$$(10) = \max_{\alpha} \alpha^T A \alpha + b^T \alpha$$

Furthermore by setting  $v = 1$ ,  $\mathbf{u} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$ ,  $l_i = 0$  and  $m_i = C$  for  $i = 1, \dots, n$  we can rewrite

the constraints:

$$\sum_{i=1}^N \alpha_i = 1 \Leftrightarrow \mathbf{u}^T \boldsymbol{\alpha} = v$$

$$0 \leq \alpha_i \leq C \Leftrightarrow l_i \leq \alpha_i \leq m_i$$

10 / 10

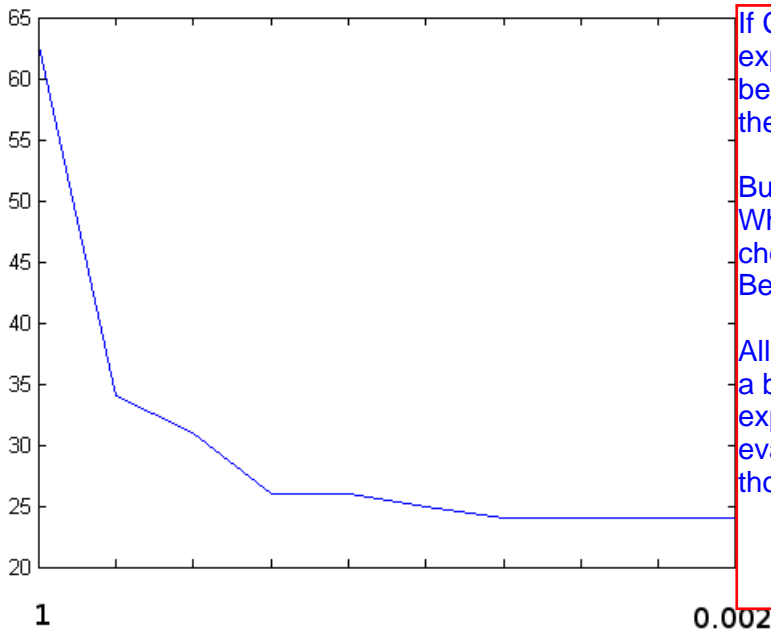
## 2 Implementation

see attached matlab implementation.

*pr\_loqo2* is running into small value (close to zero) issues. Tested with 64Bit/Win7/(Matlab 2012 b/2013a). *quadprog()* worked instead.

## 3 Result of the One-class SVM vs. hackers

With the help of the slack-variables  $\xi_i$  the One-class-SVM try to fit best on the normal data in order to find the anormal hacker activities. Using an appropriate value of  $C$  is important to distinguish hacker activities from normal ones. The following plot shows the number of hacker activities found if  $C$  ist changed, starting with  $C = 1$  and halved in each step.



If  $C = 0.002$  is interesting, maybe a bit exploration around that value would have been nice. In your plot, it is at the end of the evaluated spectrum.

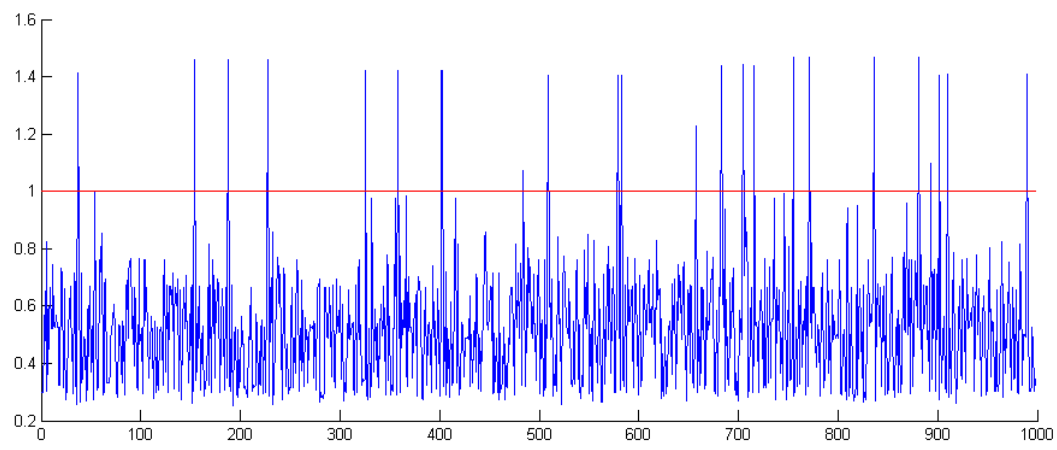
But Why is this value of  $C$  appropriate? What are your observations, how do you choose it, based on what reasoning? Because it is the last value you tried?

All in all the evaluation of this problem is a bit lacking. 10 / 30 for performing experiments. 20 points missing for no evaluation of documentation of your thought process.

Maybe an appropriate value for may  $C = 0.002$ . This value is applied to test data to find hacker activities on event-logs.



# Hacker attacks found



## Explicit position of hacker attacks

37 154 188 228 326 358 402 403 484 509 579 583 658 683 705 716 755 771 836 881 893 902 910  
990