

Week 6 — Linear Transformations ★

Definition and Notation

Definition: A function $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a **linear transformation** if it satisfies:

1. **Additivity:** $T(u + v) = T(u) + T(v)$ for all $u, v \in \mathbb{R}^n$
2. **Homogeneity:** $T(cu) = cT(u)$ for all $u \in \mathbb{R}^n, c \in \mathbb{R}$

These two conditions together give the **combined linearity** property:

$$T(au + bv) = aT(u) + bT(v) \quad \text{for all } u, v, \text{ and scalars } a, b$$

More generally: $T(c_1u_1 + c_2u_2 + \dots + c_ku_k) = c_1T(u_1) + c_2T(u_2) + \dots + c_kT(u_k)$

Domain and Codomain:

- The domain of $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is \mathbb{R}^n (inputs are n -dimensional vectors)
- The codomain is \mathbb{R}^m (outputs are m -dimensional vectors)

Watch Out (Week 6 Quiz Problem 2):

- " $T(v) = w$ makes sense, so w must be in \mathbb{R}^n " \rightarrow **FALSE** — w must be in \mathbb{R}^m (the codomain)
- " $T(v) = w$ makes sense, so v must be in \mathbb{R}^m " \rightarrow **FALSE** — v must be in \mathbb{R}^n (the domain)
- The matrix of T has **m rows and n columns** \rightarrow **TRUE** (m = codomain dimension, n = domain dimension)

$T(0) = 0$ Always

Theorem: For any linear transformation T , $T(0) = 0$.

Proof sketch: $T(0) = T(0 \cdot v) = 0 \cdot T(v) = 0$ for any v .

Exam Pattern: If $T(v) \neq 0$ for some v , T might still be linear (only 0 maps to 0 necessarily). But if $T(0) \neq 0$, then T is definitely NOT linear.

Computing T of a Linear Combination from Known Outputs

If you know T on specific vectors, you can compute T on any linear combination of those vectors **without knowing the matrix**.

Method: Express the input as a linear combination of the known vectors, then apply linearity.

Week 6 Quiz Problem 1

$T: \mathbb{R}^4 \rightarrow \mathbb{R}^2$ with:

- $T([0, 1, -9, 8]^T) = [1, -5]^T$
- $T([9, 1, 0, -2]^T) = [5, -9]^T$

Find $T([54, 11, -45, 28]^T)$.

Step 1: Recognize $[54, 11, -45, 28]^T = 5 \cdot [0, 1, -9, 8]^T + 6 \cdot [9, 1, 0, -2]^T$ (Check: $5 \cdot 0 + 6 \cdot 9 = 54 \checkmark$, $5 \cdot 1 + 6 \cdot 1 = 11 \checkmark$, $5 \cdot (-9) + 6 \cdot 0 = -45 \checkmark$, $5 \cdot 8 + 6 \cdot (-2) = 28 \checkmark$)

Step 2: Apply linearity: $T([54, 11, -45, 28]^T) = 5 \cdot T([0, 1, -9, 8]^T) + 6 \cdot T([9, 1, 0, -2]^T) = 5 \cdot [1, -5]^T + 6 \cdot [5, -9]^T = [5, -25]^T + [30, -54]^T = [35, -79]^T \leftarrow \text{answer B}$

Find $T([0, 0, 0, 0]^T)$: $\rightarrow T(0) = 0 \rightarrow [0, 0]^T \leftarrow \text{answer C}$

The Matrix of a Linear Transformation

Theorem: Every linear transformation $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$ can be represented as matrix multiplication: $T(x) = Ax$ for some $m \times n$ matrix A .

How to find A: The j -th column of A equals $T(e_j)$, where e_j is the j -th standard basis vector.

$$A = [T(e_1) \mid T(e_2) \mid \dots \mid T(e_n)]$$

Exam Pattern (Week 6 Quiz Problem 2): "If we know T on all standard basis vectors of \mathbb{R}^n , we can figure out T on any vector" \rightarrow **TRUE** (each column of the matrix comes from $T(e_j)$)

Why this works: Any $x = x_1e_1 + x_2e_2 + \dots + x_n e_n$, so by linearity: $T(x) = x_1T(e_1) + x_2T(e_2) + \dots + x_nT(e_n) = A \cdot x$

Kernel and Image

Definition: The **kernel** of T (= null space of A) is: $\ker(T) = \{v \in \mathbb{R}^n \mid T(v) = 0\} = \text{null}(A)$

Definition: The **image** of T (= column space of A) is: $\text{im}(T) = \{T(v) \mid v \in \mathbb{R}^n\} = \text{col}(A)$

- $\ker(T)$ is a subspace of the **domain** (\mathbb{R}^n)
- $\text{im}(T)$ is a subspace of the **codomain** (\mathbb{R}^m)

Derivative as a Linear Transformation

Theorem: The derivative $d/dx: P_3 \rightarrow P_2$ is a linear transformation.

$$d/dx(a_0 + a_1x + a_2x^2 + a_3x^3) = a_1 + 2a_2x + 3a_3x^2$$

Why linear:

- $d/dx(f + g) = f' + g'$ \checkmark (sum rule)
- $d/dx(cf) = cf'$ \checkmark (constant multiple rule)

Second derivative $d^2/dx^2: P_3 \rightarrow P_1$ (Week 6 Quiz Problem 3): $d^2/dx^2(a_0 + a_1x + a_2x^2 + a_3x^3) = 2a_2 + 6a_3x$

The image (range) of d^2/dx^2 is all polynomials of degree ≤ 1 , i.e., **P_1** . Answer: A (P_1 , not P_2 or P_0)

Reasoning: Taking the second derivative reduces degree by 2.

- Starting space: P_3 (degree ≤ 3)
- After one derivative: P_2 (degree ≤ 2)
- After two derivatives: **P_1** (degree ≤ 1)

Summary: Key Facts about $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Domain:	\mathbb{R}^n	(inputs live here)
Codomain:	\mathbb{R}^m	(outputs live here)

Matrix A:	$m \times n$	(m rows = codomain dim, n cols = domain dim)
$T(0) = 0$:	ALWAYS	
$\ker(T)$:	subspace of \mathbb{R}^n (= $\text{null}(A)$)	
$\text{im}(T)$:	subspace of \mathbb{R}^m (= $\text{col}(A)$)	

Linearity combo rule: $T(c_1v_1 + c_2v_2 + \dots + c_kv_k) = c_1T(v_1) + \dots + c_kT(v_k)$

This is the most-tested skill: given T on a few vectors, find T on a linear combination.

Worked Practice

Setup: $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ is linear, with $T(e_1) = [1, 2]^T$, $T(e_2) = [0, -1]^T$, $T(e_3) = [3, 4]^T$.

Find the matrix A:

$$A = [T(e_1) \mid T(e_2) \mid T(e_3)] = \begin{bmatrix} 1 & 0 & 3 \\ 2 & -1 & 4 \end{bmatrix}$$

Compute $T([2, -1, 3]^T)$: Method 1 (matrix mult): $A \cdot [2, -1, 3]^T = [1 \cdot 2 + 0 \cdot (-1) + 3 \cdot 3, 2 \cdot 2 + (-1) \cdot (-1) + 4 \cdot 3]^T = [11, 17]^T$

Method 2 (linearity): $2T(e_1) - T(e_2) + 3T(e_3) = 2[1, 2]^T - [0, -1]^T + 3[3, 4]^T = [11, 17]^T \checkmark$