

Stat 2911 Lecture Notes

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Uri Keich

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Sydney

Prediction, MGFs, moments and
derivatives of the MGF (Rice 4.4,
4.5)

Prediction (of unobserved, not necessarily future events)

Suppose X and y are jointly distributed RVs.

The prediction problem is to minimize the error, finds:

$$\underset{g: \mathbb{R} \rightarrow \mathbb{R}}{\operatorname{argmin}} E[Y - g(X)]^2.$$

$$E\{[Y - g(X)]^2\} = E\{E([Y - g(X)]^2 | X)\}$$

$$\underbrace{E([Y - g(X)]^2 | X)}_W \geq \underbrace{V(Y|X)}_{U} \text{ with } "=" \text{ iff } g(X) = E(Y|X)$$

Claim. If $W, U \in L'$ and $W \geq U$, then

$$E(W) \geq E(U) \text{ with } "=" \text{ iff } P(W=U)=1.$$

$$\Rightarrow E\{[Y - g(X)]^2\} = E\{E([Y - g(X)]^2 | X)\} = E(W) \\ \geq E(U) = E[V(Y|X)]$$

with " $=$ " iff $W=U$ a.s. $\Leftrightarrow g(X) = E(Y|X)$ a.s.

Cor. The optimal MSE predictor of y given X is $E(Y|X)$ and the MSE in this case is $E[V(Y|X)]$.

Note: if y is ind. of X then $E(Y|X) =$ (same as when we don't know X), and $MSE = V(Y)$ (why?)

Example. Z and W are standard bivariate normal with parameter / correlation coefficient $\rho \in (-1, 1)$.

Recall: $Z|W=w \sim N(\rho w, 1-\rho^2)$

$$\Rightarrow E(Z|W=w) =$$

$$\Rightarrow E(Z|W) =$$

$\Rightarrow \rho \cdot W$ minimizes $E[(Z-g(W))^2]$ among all functions g .

Notably, the best MSE predictor of Z given W is linear in W . Again, this is a property of the multivariate normal dist. and is not the case generally.

$$\begin{aligned} \text{MSE} &= E[(Z-\rho W)^2] \\ &= E(Z^2) - 2\rho E(ZW) + \rho^2 E(W^2) \\ &= 1 - \rho^2 \end{aligned}$$

Compare this with $V(Z|W) =$

$$\Rightarrow E[V(Z|W)] =$$

(invariant of W ,
again, a property
of the normal)

If $\rho=0$, then $E(Z|W) =$

$$= E(Z) \quad (Z, W \text{ are ind.})$$

$$\text{MSE} = V(Z)$$

As $|\rho| \uparrow 1$, $\text{MSE} \downarrow 0$.

Claim. If $w, u \in L'$ and $w \geq u$, then

$$E(w) \geq E(u) \text{ with } "=" \text{ iff } P(w=u)=1.$$

Proof.

Let $\bar{X} = w - u$, then $\bar{X} \geq 0$.

$$(\text{intuitively}) \Rightarrow E(\bar{X}) > 0 \quad (\text{tricky if not jointly discrete/cont.})$$

Fact: if $\bar{X} \geq 0$ $E(\bar{X}) = \int_0^\infty (1 - F_{\bar{X}}(x)) dx$ (proved for \bar{X} disc./cont.)

$$\Rightarrow E(w) - E(u) = E(\bar{X}) \geq 0.$$

If $w=u$ a.s. then $\bar{X}=w-u=0$ a.s. so $\forall x \geq 0$

$$1 \geq F_{\bar{X}}(x) = P(\bar{X} \leq x) \geq P(\bar{X}=0) = 1$$

$$(\text{?}) \Rightarrow E(\bar{X}) = 0$$

$$\Rightarrow E(w) = E(u).$$

Conversely, if $E(w) = E(u)$ then

$$0 = E(\bar{X}) = \int_0^\infty (1 - F_{\bar{X}}(x)) dx \Rightarrow 1 - F_{\bar{X}}(x) = 0 \quad \forall x > 0$$

Since $\bar{X} \geq 0$, $F_{\bar{X}}(x) = 0 \quad \forall x < 0$ so $F_{\bar{X}}(x) = \begin{cases} 0 & x < 0 \\ 1 & x \geq 0 \end{cases}$
 $(F \text{ is right cont.})$

$$\Rightarrow \bar{X} = 0 \text{ a.s.} \Rightarrow w = u \text{ a.s.}$$

Moment Generating Function (MGF)

Let \bar{X} be a RV, then $y = e^{t\bar{X}} \geq 0$, so Ey is well-defined, albeit it can be $+\infty$.

The **MGF** of the RV \bar{X} is defined as

$$M(t) = Ee^{t\bar{X}} \quad \text{if } t \text{ for which the RHS} < \infty$$

$$M(0) = Ee^{0 \cdot \bar{X}} =$$

so the MGF is always finite for $t=0$.

If \bar{X} is a discrete RV with pmf $\sum_i p_{\bar{X}}(x_i) = 1$ then

$$M(t) = \sum_i e^{tx_i} p_{\bar{X}}(x_i) \quad (\text{where } < \infty).$$

If \bar{X} is a cont. RV with density $f_{\bar{X}}$ then

$$M(t) = \int_{\mathbb{R}} e^{tx} f_{\bar{X}}(x) dx \quad (\text{where } < \infty).$$

Examples. i) $\bar{X} \sim \text{Pois}(\lambda)$ where $\lambda > 0$:

$$M(t) = \sum_{k=0}^{\infty} e^{tk} \underbrace{e^{-\lambda} \lambda^k}_{\lambda^k / k!}$$

$$= e^{-\lambda} \sum_{k=0}^{\infty} \underbrace{(\lambda e^t)^k}_{x^k} / k!$$

$$= e^{-\lambda} e^{\lambda e^t} = e^{\lambda(e^t - 1)} \quad \forall t \in \mathbb{R}$$

(ii) $X \sim N(0, 1)$

$$\begin{aligned}
 M(t) &= \int_{-\infty}^{\infty} e^{tx} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx \\
 &= \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(x^2 - 2tx + t^2) + t^2/2} dx \\
 &= e^{t^2/2} \int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-(x-t)^2/2} dx \\
 &= e^{t^2/2} \quad \forall t \in \mathbb{R}
 \end{aligned}$$

(iii) $X \sim \Gamma(\alpha, \lambda) \quad \alpha, \lambda > 0$

$$\begin{aligned}
 M(t) &= \int_0^{\infty} e^{tx} \frac{\lambda^{\alpha}}{\Gamma(\alpha)} x^{\alpha-1} e^{-\lambda x} dx \\
 &= \frac{\lambda^{\alpha}}{\Gamma(\alpha)} \int_0^{\infty} x^{\alpha-1} e^{-(\lambda-t)x} dx \quad \left\{ \begin{array}{ll} \text{if } t \geq \lambda \\ \text{if } t < \lambda \end{array} \right.
 \end{aligned}$$

For $t < \lambda$ we have

$$\begin{aligned}
 M(t) &= \left(\frac{\lambda}{\lambda-t}\right)^{\alpha} \int_0^{\infty} \frac{(\lambda-t)^{\alpha}}{\Gamma(\alpha)} x^{\alpha-1} e^{-(\lambda-t)x} dx \quad \nu > 0 \\
 &= \left(\frac{\lambda}{\lambda-t}\right)^{\alpha} \quad \forall t < \lambda .
 \end{aligned}$$

MGFs are useful for two reasons.

Theorem M1. If $\exists \delta > 0$ s.t. $M(t) < \infty \quad \forall t \in (-\delta, \delta)$
 Then $\forall n \in \mathbb{N} \quad M^{(n)}(0) = E(X^n)$ (and both exist).

Intuitively, it makes sense:

$$\begin{aligned} M(t) &= \frac{d}{dt} \sum_i e^{tx_i} p_{\underline{X}}(x_i) \\ &\stackrel{?}{=} \sum_i \frac{d}{dt} e^{tx_i} p_{\underline{X}}(x_i) \\ &= \sum_i x_i e^{tx_i} p_{\underline{X}}(x_i) \\ \Rightarrow M'(0) &= \sum_i x_i p_{\underline{X}}(x_i) = \end{aligned}$$

Similarly,

$$\begin{aligned} M^{(k)}(t) &= \frac{d^k}{dt^k} \int_{-\infty}^{\infty} e^{tx} f_{\underline{X}}(x) dx \\ &\stackrel{?}{=} \int_{-\infty}^{\infty} \frac{d^k}{dt^k} e^{tx} f_{\underline{X}}(x) dx \\ &= \int_{-\infty}^{\infty} x^k e^{tx} f_{\underline{X}}(x) dx \\ \Rightarrow M^{(k)}(0) &= \int_{-\infty}^{\infty} x^k f_{\underline{X}}(x) dx = \end{aligned}$$

Examples

i) $\bar{X} \sim \text{Pois}(\lambda)$

$$M(t) = e^{\lambda(e^t - 1)} \quad \forall t \in \mathbb{R}$$

$$M'(t) = M(t) \cdot \lambda e^t$$

$$\Rightarrow M'(0) = M(0) \cdot \lambda = E(\bar{X})$$

$$M''(t) = M(t)(\lambda e^t)^2 + M(t) \lambda e^t$$

$$\Rightarrow M''(0) = E(\bar{X}^2)$$

(ii) $\bar{X} \sim N(0, 1)$ $M(t) = e^{t^2/2} \quad \forall t \in \mathbb{R}$

$$M'(t) = M(t) \cdot t$$

$$\Rightarrow M'(0) = E(\bar{X})$$

$$M''(t) = M(t) \cdot t^2 + M'(t)$$

$$\Rightarrow M''(0) = E(\bar{X}^2)$$

(iii) $\bar{X} \sim \Gamma(\alpha, \lambda)$ $M(t) = \left(\frac{\lambda}{\lambda-t}\right)^\alpha = \lambda^\alpha (\lambda-t)^{-\alpha} \quad \forall t < \lambda$

$$M'(t) = \lambda^\alpha (\lambda-t)^{-\alpha-1} (-\alpha)(-1)$$

$$= \alpha \lambda^\alpha (\lambda-t)^{-(\alpha+1)} \quad t < \lambda$$

$$\Rightarrow M'(0) = \alpha \lambda^\alpha \lambda^{-\alpha-1} = \frac{\alpha}{\lambda} = E(\bar{X})$$

$$M''(t) = \alpha(\alpha+1) \lambda^\alpha (\lambda-t)^{-(\alpha+2)} \quad t < \lambda$$

$$\Rightarrow M''(0) = \frac{\alpha(\alpha+1)}{\lambda^2} = E(\bar{X}^2)$$

Theorem M2. Let F and G be CDFs and suppose $\exists \delta > 0$ s.t. $\forall t \in (-\delta, \delta)$ $M_F(t) = M_G(t) (< \infty)$. Then $F = G$.

It follows that all the moments of F and G exist and are equal. The converse is false: all the moments of F and G can exist, and be equal, yet $F \neq G$.