

Stat 2911 Lecture Notes

Class 17, 2016

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Parametric bootstrap (Rice 8.4,
8.9), Conditional expectation
(Rice 4.4)

Parametric Bootstrap

Set up: given a sample x_1, \dots, x_n from a dist. $F(\underline{\theta})$ we estimate $\underline{\theta}$ using $\hat{\underline{\theta}}(x_1, \dots, x_n)$.

Recipe for estimating the bias/var/MSE of $\hat{\underline{\theta}}$:

- Draw N ind. bootstrap samples of size n from $F(\hat{\underline{\theta}}(x_1, \dots, x_n))$:

$$\underline{x}^{*i} = (x_1^{*i}, \dots, x_n^{*i}) \quad i=1, \dots, N$$

- For each, compute $\hat{\underline{\theta}}^{*i} = \hat{\underline{\theta}}(\underline{x}^{*i})$
- Empirically estimate the bias/var/MSE from the sample $\hat{\underline{\theta}}^{*i} \quad i=1, 2, \dots, N$.

For example,

$$\widehat{\text{bias}}(\hat{\underline{\theta}}) = \frac{1}{N} \sum_{i=1}^N \hat{\underline{\theta}}^{*i} - \hat{\underline{\theta}}(x_1, \dots, x_n),$$

$$\widehat{\text{MSE}}(\hat{\underline{\theta}}) = \sum_{i=1}^N \left[\hat{\underline{\theta}}^{*i} - \hat{\underline{\theta}}(x_1, \dots, x_n) \right]^2 \cdot \frac{1}{N} .$$

Example. Hardy-Weinberg equilibrium;

Model: $\underline{X} = (X_1, X_2, X_3) \sim \text{multinomial}(n; (1-\theta)^2, 2\theta(1-\theta), \theta^2)$

Data: $n = 1029$ $X_1 = 342$ $X_2 = 500$ $X_3 = 187$

Goal: estimate θ , the frequency of the minor allele.

Moment estimator: $\hat{\theta} = \sqrt{\frac{X_3}{n}}$ our case $\sqrt{\frac{187}{1029}} \approx 0.4263$

MLE (also moment): $\hat{\theta} = \frac{X_2 + 2X_3}{2n}$ our case ≈ 0.4247

We found: $E_{\theta}(\hat{\theta}) = \theta$

$$E(\hat{\theta}) = \sum_{k=0}^{n-1} \sqrt{\frac{k}{n}} \binom{n}{k} (\theta^2)^k (1-\theta^2)^{n-k}$$

$$\text{MSE}(\hat{\theta}_n) = \frac{1}{2n} \theta(1-\theta)$$

$$\text{MSE}(\hat{\theta}) = 2\theta [\theta - E(\hat{\theta})]$$

We can estimate, say, the bias of $\hat{\theta}$ by:

$$\widehat{\text{bias}}(\hat{\theta}) = \sum_{k=0}^{n-1} \sqrt{\frac{k}{n}} \binom{n}{k} (\hat{\theta}^2)^k (1-\hat{\theta}^2)^{n-k} - \hat{\theta}$$

or, we can use the δ -method

and similarly, $\widehat{\text{MSE}}(\hat{\theta}) = \frac{1}{2n} \hat{\theta}(1-\hat{\theta})$.

But what if we couldn't derive the expressions above?

We can provide estimates using parametric bootstrap:

- Generate bootstrap samples $\underline{x}^{*1}, \underline{x}^{*2}, \dots, \underline{x}^{*N}$, where each \underline{x}^{*i} is sampled using the parameter estimated from the original sample $\underline{x} = (342, 500, 187)$.

That is,

$$\underline{x}^{*i} \sim \text{multinomial} \left[n=1029; p = \begin{pmatrix} 1-\tilde{\theta} \\ \tilde{\theta}^2, 2\tilde{\theta}(1-\tilde{\theta}), \tilde{\theta}^2 \end{pmatrix} \right],$$

$$\text{where } \tilde{\theta} = \sqrt{187/1029} \quad (\text{or, use } \hat{\theta} = \frac{500+2 \cdot 187}{1029})$$

- For each i , compute $\tilde{\theta}^{*i} = \sqrt{\frac{x_3^{*i}}{n}}$

$$\hat{\theta}^{*i} = \frac{x_2^{*i} + 2x_3^{*i}}{n}$$

You can now estimate, say, the bias of $\tilde{\theta}$ by

$$\overline{E(\tilde{\theta})} - \theta = \frac{1}{N} \sum_{i=1}^N \tilde{\theta}^{*i} - \tilde{\theta}$$

or $\hat{\theta}$ if $\hat{\theta}$ was used to generate the bootstrap samples

Is this estimate very sensitive to small variations in the estimated θ ?

Parametric bootstrap for Hardy-Weinberg

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If the gene frequencies are in equilibrium, the genotypes AA , Aa , aa occur with probabilities $(1 - \theta)^2$, $2\theta(1 - \theta)$, θ^2 . The maximum likelihood estimate of θ is

$$\hat{\theta} = \frac{2x_3 + x_2}{2n},$$

where $n = x_1 + x_2 + x_3$. The moment estimator is

$$\tilde{\theta} = \sqrt{\frac{x_3}{n}}$$

The observed values in the Hong Kong study were 342,500,187. First we find the values of the estimators for our particular sample.

```
> x = c(342,500,187)
> n = sum(x)
> hatth = (2*x[3]+x[2])/(2*n)      θ̂
> hatth
[1] 0.4246842
> tilth = sqrt(x[3]/n)              θ̃
> tilth
[1] 0.4262978
```

Next we obtain $N = 10,000$ bootstrap samples from a multinomial distribution with $n = 1029$ and probabilities $(1 - \hat{\theta})^2$, $2\hat{\theta}(1 - \hat{\theta})$, $\hat{\theta}^2$. Then, for each sample we obtain bootstrap estimates $\hat{\theta}^*$ and $\tilde{\theta}^*$

```
> set.seed(17)
> N = 10000
> xst = rmultinom(N, n, c((1-hatth)^2, 2*hatth*(1-hatth), hatth^2))
> thsthat = (2*xst[3,]+xst[2,]) / (2*n)
> thsttil = sqrt(xst[3,]/n)          } bootstrap estimates
                                            generating the
                                            bootstrap samples
                                            using θ̂ first.
```

We next estimate the mean, variance, bias and MSE of $\hat{\Theta}$ and $\tilde{\Theta}$ from the bootstrap samples:

```
> mean(thsthat)
[1] 0.4246392

> var(thsthat)
[1] 0.0001201425

> bootbias = mean(thsthat) - hatth
> bootbias
[1] -4.494655e-05

> mean((thsthat-hatth)^2)
[1] 0.0001201326

> mean(thsttil)
[1] 0.424283

> var(thsttil)
[1] 0.0002021445

> bootbias = mean(thsttil) - hatth
> bootbias
[1] -0.0004011775

> mean((thsttil-hatth)^2)
[1] 0.0002022852
```

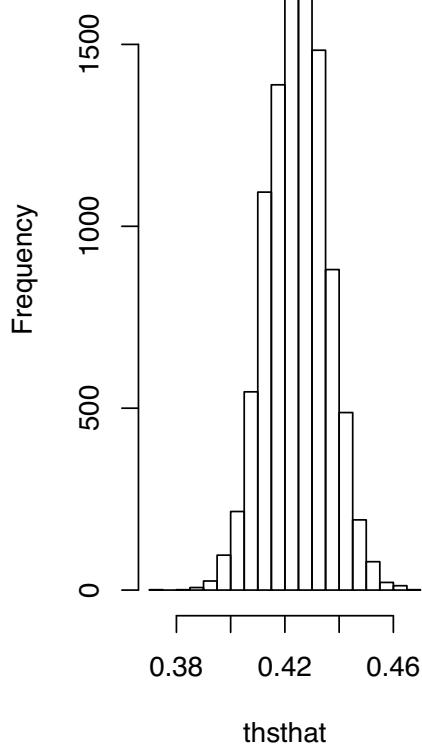
It is also instructive to view the histograms of the bootstrapped estimators:

```
> par(mfrow=c(1, 2))
> hist(thsthat)
> boxplot(thsthat, thsttil)
```

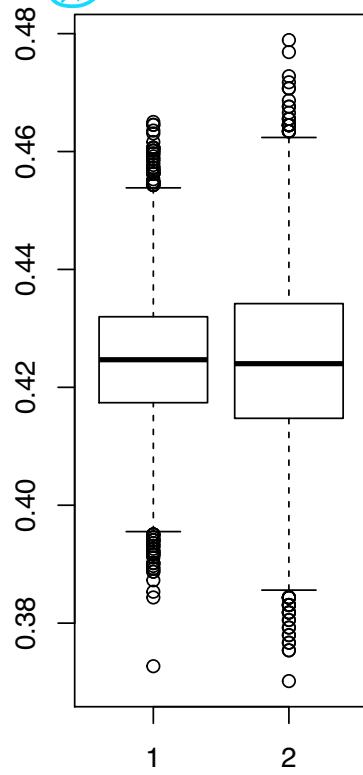
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does the shape of this histogram look familiar?

Histogram of thsthat



which of these boxplots is of $\tilde{\theta}$ and which is of $\hat{\theta}$?



Finally, we repeat the bootstrap procedure only now we plug in $\tilde{\theta}$ instead of $\hat{\theta}$.

```
> set.seed(17)
> xst = rmultinom(N, n, c((1-tilth)^2, 2*tilth*(1-tilth),tilth^2))
> thsthat = (2*xst[3,]+xst[2,]) / (2*n)
> thsttil = sqrt(xst[3,]/n)
> mean(thsthat)

[1] 0.4261767

> var(thsthat)

[1] 0.0001189849

> mean(thsthat) - tilth

[1] -0.0001211477
```

```
> mean((thsthat-tilth)^2)
[1] 0.0001189877

> mean(thsttil)
[1] 0.4258385

> var(thsttil)
[1] 0.0002012665

> mean(thsttil) - tilth
[1] -0.0004593526

> mean((thsttil-tilth)^2)
[1] 0.0002014574
```

good agreement between the results sampled using $\hat{\phi}(\underline{x})$ and $\check{\phi}(\underline{x})$ is good news.

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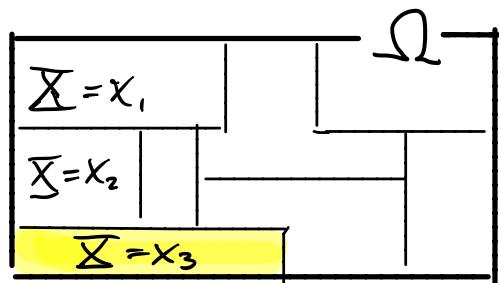
Conditional Expectation

If \bar{X} and Y are jointly distributed RVs, then if X with $P(\bar{X}=x) > 0$, we define the **conditional expectation** of Y given $\bar{X}=x$ as

$$E(Y|\bar{X}=x) = \sum_y y P(Y=y|\bar{X}=x)$$

provided $\sum_y y P(Y=y|\bar{X}=x) < \infty$ (*)

Note that if (*) holds then $E(Y|\bar{X}=x) \in \mathbb{R}$. (why?)



$E(Y|\bar{X}=x_3)$ = the weighted average of y over $\{\omega : \bar{X}(\omega) = x_3\}$

Example. Roll a fair die and let Y = outcome
 $\bar{X}=1$? even outcome?

1	3	5
2	4	6

$$\begin{array}{l} \bar{X}= \\ \bar{X}= \end{array}$$

$$\begin{array}{l} E(Y|\bar{X}=0) = \\ E(Y|\bar{X}=1) = \end{array}$$

How can we guarantee that condition(*) holds?

Claim. If $y \in L'$ then $E(Y|X=x)$ is defined and $\in \mathbb{R}$
 $\forall x$ with $P(X=x) > 0$.

Proof. We need to verify that (*) holds:

$$\begin{aligned} \sum_y |y| P(Y=y | X=x) &= \sum_y |y| \frac{P(Y=y, X=x)}{P(X=x)} \\ &\leq \frac{1}{P(X=x)} \sum_y |y| \cdot P(Y=y) < \infty \end{aligned}$$

why? why?

□

Random Sums

Let X_i be iid RVs and let N be an ind.
 N -valued RV. Define the random sum
 $T = \sum_{i=1}^N X_i$.

The RV N determines the number of summands,
or elements X_i , that are summed.

If $N=0$ then $T=0$.

Examples.

$$1) X_i \equiv 1 \text{ and } N \sim \text{Poisson}(\lambda) \Rightarrow T = \sum_{i=1}^N 1 = N$$

2) $X_i \sim \text{Bernoulli}(p)$ and $N \sim \text{Poisson}(\lambda)$

$$T = \sum_{i=1}^N X_i$$

radio-active source

$$\xrightarrow{\lambda}$$



The monitor registers an incoming particle with prob. p independently of anything else.

Recall: $T \sim \text{Poisson}(\lambda p)$

$$\Rightarrow E(T) = \lambda p$$

Our goal is to be able to compute $E(T)$ directly i.e., without the need to first find the dist. of T .

Expectation is linear:

$$E\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n E(X_i) = n E(X_i)$$

$$E(T) = E\left(\sum_{i=1}^N X_i\right) \neq N E(X_i) \text{ (why?)}$$

But we will show $E(T) = E(N) E(X_i)$.

How?

Recall the total probability law:

$$P(T=s) = \sum_n P(T=s | N=n) P(N=n).$$

We will establish an analogous "total expectation law":

$$E(T) = \sum_n E(T | N=n) P(N=n).$$

Again, \bar{X}_i are iid RVs and N is an independent N -valued RV. Let $T = \sum_1^N \bar{X}_i$ and let $S_n = \sum_1^n \bar{X}_i$, so $T = S_N$.

Finally, let $\{S_n\} = T(\Omega)$, then for n with $P(N=n) > 0$ we have:

$$\begin{aligned} P(T = S_k | N=n) &= \frac{P(T = S_k, N=n)}{P(N=n)} \\ &= \frac{P\left(\sum_1^N \bar{X}_i = S_k, N=n\right)}{P(N=n)} \\ &= \frac{P\left(\sum_1^n \bar{X}_i = S_k, N=n\right)}{P(N=n)} \\ &= \frac{P\left(\sum_1^n \bar{X}_i = S_k\right) P(N=n)}{P(N=n)} \\ &= P(S_n = S_k) \end{aligned}$$

($\sum_1^n \bar{X}_i$ is ind. of N)

Claim. If $P(N=n) > 0$ then the dist. of T given that $N=n$ is the same as the (unconditional) dist. of $S_n = \sum_1^n \bar{X}_i$, and in particular $S_n(\Omega) \subset T(\Omega)$.

Proof. $P(T = S_k | N=n) = P(S_n = S_k)$

Cor. If $X_i \in L'$ then $E(T|N=n) = n E(\bar{X}_i)$ and, in particular, it is well defined and in \mathbb{R} .

Proof.

$$\sum_k^1 |S_k| P(T=S_k | N=n) = \sum_k^1 S_k P(S'_n = S_k)$$

$$\stackrel{\text{why?}}{=} E(|S'_n|) < \infty \quad \text{tricky!} \quad \stackrel{\text{why?}}{=}$$

$\Rightarrow E(T|N=n)$ is well defined. Moreover,

$$\sum_k^1 S_k P(T=S_k | N=n) = \sum_n^1 S_k P(S'_n = S_k)$$

$$\stackrel{?}{=} E\left(\sum_i^n \bar{X}_i\right)$$

$$= \sum_i^n E(\bar{X}_i)$$

$$= n E(\bar{X}_i) .$$

up to here we didn't need X_i to be identically distributed

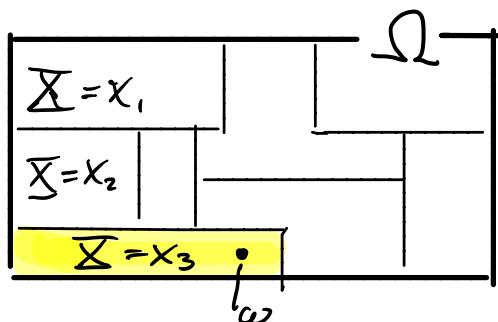
Do we need X_i to be ind. of one another?

Conditional Expectation (the RV)

Recall: If $y \in L'$ then $E(y|X=x)$ is defined if x with $P(X=x) > 0$.

Def. For $y \in L'$ we define the RV conditional expectation of y given X as

notation $\underbrace{E(y|X)}_{\text{notation}}(\omega) = E[y | X=X(\omega)]$



Suppose $\omega \in \Omega$ satisfies $X(\omega)=x_3$.
Then $E(y|X)(\omega) = E(y|X=x_3)$

Note that $E(y|X)$ is const. on the event $X=x_k$, i.e., $\forall \omega \in \{X=x_k\}$ or $X(\omega)=x_k$, $E(y|X)(\omega) = E(y|X=x_k)$. That is, both X and $E(y|X)$ are constant on the event $\{X=x_k\}$, the constant being the average of X or y on that event.