

# Normalizing flows (could)

• NFs as a compression (coding) method

	high compression $\Rightarrow$ small codes	good reconstruction $\hat{x} = g(f(x)) \approx x$	accurate distribution $\hat{p}(x) \sim p^*(x)$
AE	$\dim(z)$ hyperparameter	😊 (minimize loss)	😞 ( $p_E(z) = f_{\#} p^*(x)$ unknown)
GAN	—    —	😞 (no encoder)	😊 (minimize loss)
AE with latent distrib. (*)	—    —	😞 $\leftarrow$ trade-off $\rightarrow$ 😞	😊
NF	😞 $\dim(z) = \dim(x)$	😊 $\hat{x} = g(f(x)) = x$ (invertible network)	😊 (minimize loss)

3 goals of coding:

$$z = f(x) \quad \hat{x} = g(z)$$

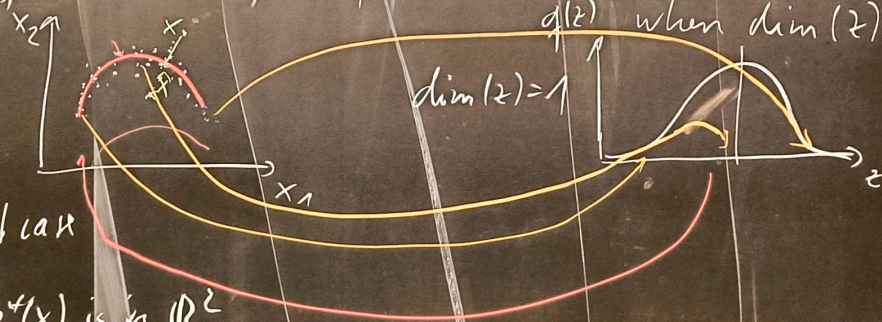
$$z \sim p(z|x) \quad \hat{x} \sim p(x|z)$$

(\*) AE with controlled latent distribution:

- VAE
- InfoVAE
- invertible GAN

in AE: even if we know  $q(z) = p_E(z)$ ,  $\hat{p}(x) = p^*(x)$  is generally impossible  
 when  $\dim(z) < \dim(x)$

example: banana distribution  
 $\dim(x) = 2$



- imperfect reconstruction

$|\hat{x} - x| \approx$  noise in the best case

- imperfect generation

$\hat{p}(x)$  is on centerline,  $p^*(x)$  is in  $\mathbb{R}^2$

- change in VAE:  $\mathbb{E}[\hat{p}(\hat{x}|z=f(x))]$  is the centerline

$\hat{p}(\hat{x}|z=f(x))$  creates synthetic noise indistinguishable from true noise



## variants of NF architectures

- coupling flows
  - volume-preserving (NICE, GIN) are not universal  
(cannot change the number of modes  $\Rightarrow$  define  $q(z) = \sum T_k N(\mu_k, \Sigma_k)$  GMM)
  - affine coupling  $z_{>\vec{D}}^{(l)} = s_l(z_{\leq \vec{D}}^{(l-1)}) \cdot z_{>\vec{D}}^{(l-1)} + t_l(z_{\leq \vec{D}}^{(l-1)})$

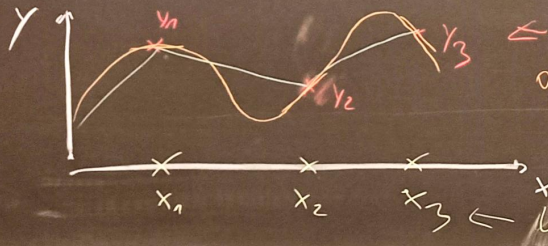
simplest universal NF models

- spline coupling:  $z_{>\vec{D}}^{(l)} = \varphi_l(z_{>\vec{D}}^{(l-1)}; z_{\leq \vec{D}}^{(l-1)})$

$\uparrow$  arbitrary function invertible in first arg.

implement  $\varphi_l$  as a spline ( $\hat{=}$  piecewise polynomial or other basis fct)

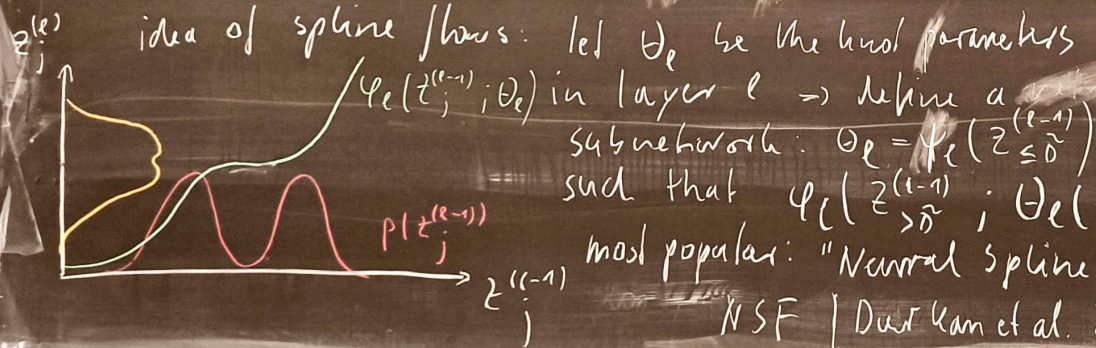
spline: parameters at "knots"  $y = \varphi(x)$  1-1



$y_1, y_2, y_3 \leftarrow$  knot values  
 optional:  $y'_i$  derivatives at knots ("Hermite spline")

spline: give knot parameters, interpolate to arbitrary  $x$  with an analytic rule (typically locally  $\Rightarrow$  only knot near the query  $x$  are relevant)

idea of spline flows: let  $\theta_\ell$  be the knot parameters



$\varphi_\ell(z_j^{(e-1)}; \theta_\ell)$  in layer  $\ell \rightarrow$  define a

subnetwork:  $\theta_\ell = \varphi_\ell(z \leq \tilde{0}^{(e-1)})$

such that  $\varphi_\ell(z > \tilde{0}^{(e-1)}; \theta_\ell(z \leq \tilde{0}^{(e-1)}))$

most popular: "Neural Spline Flow"

NSF [Durkan et al. 2019]

is invertible in

rational quadratic splines

$$\begin{aligned}
 & \left[ \begin{array}{l} \text{neighbor knots} \\ s = \frac{z - z_k}{z_{k+1} - z_k} \end{array} \right] \\
 & \left[ \frac{a_k s^2 + b_k s}{d_k s^2 + e_k s + f_k} + c_k \right]
 \end{aligned}$$



- other proposed NFs: inverse autoregressive flows, - iResNets, MADE  
more complicated than coupling flows, but not better (according to our experiments)
- state-of-the-art in terms of generative quality: diffusion models
- brand new: free-form-flows (merge between NFs and AEs) } later

conditional NFs: learn conditional prob. densities  $p(X | Y=y)$  (instead of  $p(x)$ )

- example:  $Y \hat{=}$  observations,  $X \hat{=}$  hidden system properties / states (e.g. class labels)

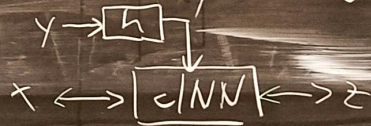
setting:  $TS = \{ (x_i, y_i) \}_{i=1}^N$   $y_i$  arbitrary condition,  $x_i \in \mathbb{R}^D$

use TS to learn  $\hat{p}(X|Y) \approx p^*(X|Y)$

- easy to do using coupling flows: each layer implements a triangular map

$$z^{(e)} = \begin{pmatrix} f_{e1}(z_1^{(e-1)}) \\ f_{e2}(z_2^{(e-1)}, z_1^{(e-1)}) \\ \vdots \\ f_{ed}(z_d^{(e-1)}, \dots, z_1^{(e-1)}) \end{pmatrix} = f_e(z^{(e-1)}) \quad \text{unconditional}$$

$$z^{(e)} = \begin{pmatrix} f_{e1}(z_1^{(e-1)}, y) \\ f_{e2}(z_2^{(e-1)}, z_1^{(e-1)}, y) \\ \vdots \\ f_{ed}(z_d^{(e-1)}, \dots, z_1^{(e-1)}, y) \end{pmatrix} = f_e(z^{(e-1)}, y) \quad \begin{array}{l} \text{conditional on } y, \text{ but} \\ \text{still triangular in } z^{(e-1)} \end{array}$$



$\Rightarrow$  implement  $S_e(z_{\leq d}^{(e-1)}, y), t_e(z_{\leq d}^{(e-1)}, y)$   
 variant: when  $y$  is complicated (e.g. image) train feature detector  $h(y) \Rightarrow S_e(z_{\leq d}^{(e-1)}, h(y)), t_e(z_{\leq d}^{(e-1)}, h(y))$