

Advanced Machine Learning Subsidiary Notes

Lecture 12: Convexity

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1 Keywords

- Convex sets, convex functions, Jensen's inequality

2 Main Points

2.1 Convex Sets

- We are familiar geometrically with convex regions
- To define convexity we need to define an intermediate point $\mathbf{z} = a\mathbf{x} + (1 - a)\mathbf{y}$
 - we requires $a \in [0, 1]$ (i.e. x is in the interval between 0 and 1) for \mathbf{z} to be between \mathbf{x} and \mathbf{y}
 - to define convexity we only need to have addition and scalar multiplication
- We can the define convexity in a very general way: a set \mathcal{S} is convex if for every pair of points $\mathbf{x}, \mathbf{y} \in \mathcal{S}$ and for every possible $a \in [0, 1]$ then $\mathbf{z} = a\mathbf{x} + (1 - a)\mathbf{y} \in \mathcal{S}$
- We can apply convexity to sets of complicated objects
- For example the set of positive semi-definite matrices forms a convex set
 - This follows from the fact the sum of two positive semi-definite matrices is also positive semi-definite and if we multiply a positive semi-definite matrix by a positive number then the matrix is still positive semi-definite

2.2 Convex Functions

- We can define a function, $f(\mathbf{x})$, to be a *convex function* if for all pairs of points in the domain of the function and all $a \in [0, 1]$

$$f(a\mathbf{x} + (1 - a)\mathbf{y}) \leq af(\mathbf{x}) + (1 - a)f(\mathbf{y})$$

- This means that the function sits on or below the linear chord connecting any two points in the domain of the function
- The epigraph of a function is the area that lies on or above the functions
 - The epigraph of a convex function forms a convex region
 - If the epigraph of a function forms a convex region then the function is convex
- We can define *convex-down* or *concave* functions by inverting the constraint

$$f(a\mathbf{x} + (1 - a)\mathbf{y}) \geq af(\mathbf{x}) + (1 - a)f(\mathbf{y})$$

- for clarity I will sometimes refer to "convex" functions as *convex-up* functions

- convex-down functions have similar (but opposite) properties to convex up functions

- A function where for every pair of points and for any a such that $0 < a < 1$ (i.e. a lies strictly between 0 and 1) then if

$$f(a\mathbf{x} + (1-a)\mathbf{y}) < af(\mathbf{x}) + (1-a)f(\mathbf{y})$$

then function is said to be *strictly convex*

- Linear functions $f(\mathbf{x}) = a\mathbf{x} + c$ are both convex-up and convex-down functions
 - For a function to be a strictly convex function it cannot have a linear section
- Convex functions lie on or above their tangent plane
 - The tangent plane to a function $f(\mathbf{x})$ at a point \mathbf{x}_0 is the plane orthogonal to the gradient, $\nabla f(\mathbf{x}_0)$ that goes through the point \mathbf{x}_0
- A necessary and sufficient condition for a function to be convex is that its second derivative is non-negative or for multi-dimensional functions the Hessian is positive semi-definite
 - If the second derivative is positive (i.e. always greater than 0) or the Hessian is positive definite then the function is strictly positive

- Examples

- Convex-up Functions

- * $f(x) = x^2$ is strictly convex since $f''(x) = 2 > 0$
- * $f(x) = x^{-2}$ is strictly convex since $f''(x) = 2x^{-4} > 0$
- * $f(x) = x^4$ is convex since $f''(x) = 12x^2 \geq 0$
- * $f(x) = e^{cx}$ is strictly convex for all c as $f''(x) = c^2 e^{cx} > 0$
- * $f(\mathbf{x}) = \|\mathbf{x}\|^2$ is strictly convex since $\mathbf{H}(\mathbf{x}) = \mathbf{I} \succ 0$
- * $f(x) = |x|$ is convex since for $a \in [0, 1]$ we have $|ax + (1-a)y| \leq a|x| + (1-a)|y|$ with equality only when $xy \geq 0$

- Convex-down Functions

1. $f(x) = -x^2$ is strictly convex-down since $f''(x) = -2 < 0$
2. $f(x) = \sqrt{x}$ (for $x > 0$) is strictly convex-down since $f''(x) = -x^{-3/2}/4 < 0$
3. $f(x) = \log(x)$ is strictly convex-down since $f''(x) = -1/x^2 < 0$

- A function $f(\mathbf{x})$ that is constrained to a convex domain ($\mathbf{x} \in \mathcal{S}$, where \mathcal{S} is a convex set) is convex in that domain if for all pairs $\mathbf{x}, \mathbf{y} \in \mathcal{S}$ and all $a \in [0, 1]$ we have

$$f(a\mathbf{x} + (1-a)\mathbf{y}) \leq af(\mathbf{x}) + (1-a)f(\mathbf{y})$$

- This is just a more precise definition of a convex function
- Note that by limiting the domain of a function some non-convex functions may be convex over that domain
 - * e.g. $\cos(x)$ is convex in the interval $[-\pi/2, 3\pi/3]$
- A convex function constrained to lie in a convex set will still be convex
- Any combination of linear constraints will form a convex set
- Therefore convex functions restricted to satisfy linear constraints will be convex
- The minimum of a convex function will form a convex set
 - There can be no local minima
 - For a strictly convex function the minimum will be unique

- The sum of convex functions will be convex
- **Linear regression**
 - The loss function of linear regression is convex

$$L(\mathbf{w}) = \|\mathbf{X}\mathbf{w} - \mathbf{y}\|^2$$

- * The Hessian is $\mathbf{X}^T\mathbf{X}$ which is positive semi-definite which is a sufficient condition for $L(\mathbf{w})$ to be convex
- Both the L_2 regulariser and the L_1 regulariser are convex
- The L_2 regulariser is strictly convex so there will be a unique solution
- Many machine learning algorithms are chosen because they involve minimising a convex function leading to a unique minimum

2.3 Jensen's Inequality

- For any convex-up function, if \mathbf{x} is a random variable then

$$\mathbb{E}[f(\mathbf{x})] \geq f(\mathbb{E}[\mathbf{x}])$$

- $\mathbb{E}[\dots]$ denotes the expectation

- For any convex-down function

$$\mathbb{E}[f(\mathbf{x})] \leq f(\mathbb{E}[\mathbf{x}])$$

- These are known as *Jensen's Inequality*

- **Proof**

- We can prove this starting from the fact that $f(\mathbf{x})$ lies above the tangent plane at any point

$$f(\mathbf{x}) \geq f(\mathbf{x}^*) + (\mathbf{x} - \mathbf{x}^*)^T \nabla f(\mathbf{x}^*)$$

- This has to be true at the point $\mathbf{x}^* = \mathbb{E}[\mathbf{x}]$

$$f(\mathbf{x}) \geq f(\mathbb{E}[\mathbf{x}]) + (\mathbf{x} - \mathbb{E}[\mathbf{x}])^T \nabla f(\mathbb{E}[\mathbf{x}])$$

- Taking expectations of both sides of the equation

$$\mathbb{E}[f(\mathbf{x})] \geq f(\mathbb{E}[\mathbf{x}]) + (\mathbb{E}[\mathbf{x}] - \mathbb{E}[\mathbf{x}])^T \nabla f(\mathbb{E}[\mathbf{x}]) = f(\mathbb{E}[\mathbf{x}]) \quad \square$$

- Using Jensen's Inequality

- Consider the strictly convex function $f(\mathbf{x}) = x^2$ by Jensen's inequality

$$\mathbb{E}[x^2] \geq \mathbb{E}[x]^2$$

$$* \text{ or } \mathbb{E}[x^2] - \mathbb{E}[x]^2 \geq 0$$

- the left-hand side is the variance so we see variances are non-negative
- because $f(\mathbf{x}) = x^2$ is strictly convex we only get equality where \mathbf{x} doesn't vary at all
- Consider the Kullback-Liebler (KL) divergence defined for discrete probability distributions defined over the same range as

$$\mathcal{KL}(f\|g) = - \sum_i f_i \log\left(\frac{g_i}{f_i}\right)$$

- * This is often used to measure how different distributions are from each other
- * Note if $g_i = f_i$ then $\mathcal{KL}(f\|g) = 0$ since $\log(1) = 0$
- * Now we can use Jensen's inequality to show that $\mathcal{KL}(f\|g) \geq 0$

$$\begin{aligned}\mathcal{KL}(f\|g) &= -\sum_i f_i \log\left(\frac{g_i}{f_i}\right) = -\mathbb{E}_f\left[\log\left(\frac{g_i}{f_i}\right)\right] \\ &\geq -\log\left(\mathbb{E}_f\left[\frac{g_i}{f_i}\right]\right) \\ &= -\log\left(\sum_i f_i \frac{g_i}{f_i}\right) = -\log\left(\sum_i g_i\right) = -\log(1) = 0\end{aligned}$$

- Here we are assuming we have random variable that take values $X_i = g_i/f_i$ that occur with probability f_i
- The KL-divergence is therefore equal to $\mathbb{E}[-\log(X_i)]$
- Since $-\log(x)$ is convex up we have by Jensen's inequality that the KL-divergences is greater than or equal to $-\log(\mathbb{E}[X_i]) = -\log(\sum_i f_i X_i)$
- But $X_i = g_i/f_i$ so the KL-divergence is greater than $-\log(\sum_i g_i)$
- But g_i is a probability so $\sum_i g_i = 1$ giving us our result
- * This is known as the Gibbs' inequality after the mathematical physicist, J. Willard Gibbs, (founder of modern statistical mechanics) who first proved it
- * We often use KL-divergences when we want to choose the parameters of one probability distribution so that it approximates a second probability distribution

3 Exercises

3.1 Positive quadrant

- Prove that the set of vectors with non-negative elements form a convex set

3.2 Inverse of Convex Functions

1. Use the chain rule to compute the second derivative of $f(g(x))$
2. If $g(x) = f^{-1}(x)$ show that the second derivative of $f(g(x))$ vanishes
3. Use these results to derive an identity for the second derivative of $f^{-1}(x)$
4. Derive a condition for $f^{-1}(x)$ to be a convex-down function given that $f(x)$ is convex-up
5. Use this to show
 - (a) \sqrt{x} is a convex-down function
 - (b) $\log(x)$ is a convex-down function

3.3 Cumulant Generating Function

- Here is something a bit harder (which you don't need to know)
- The cumulant generating function of a probability distribution $p(x)$ is defined as

$$G(\lambda) = \log\left(\mathbb{E}\left[e^{\lambda x}\right]\right)$$

– the expectation is over the random variable x drawn from $p(x)$

- It is called the cumulant generating function because if we take the n^{th} derivative and set λ to zero we obtain the n^{th} cumulant (i.e. $\kappa_n = G^{(n)}(0)$)
- The first cumulant is the mean, the second the variance while the third and fourth are proportional to the skewness and kurtosis
- Cumulant generating functions appear a lot when you work with probabilities, but go beyond this course
- Nevertheless let's show they are convex
 1. Find the second derivative
 2. Show that if $p(x)$ is a probability distribution then $q(x) = p(x) e^{\lambda x} / \mathbb{E}[e^{\lambda x}]$ is also a probability distribution
 3. Hence show that the cumulant generating function is convex
- See answers

4 Answers

4.1 Positive quadrant

- Let \mathcal{P} be the set of vectors with non-negative elements
- If $\mathbf{x} \in \mathcal{P}$ then if $c \geq 0$ we have $\mathbf{v} = c\mathbf{x} \in \mathcal{P}$ since each element of \mathbf{v} will be non-negative (i.e. $v_i = cx_i \geq 0$)
- Also for any two vectors $\mathbf{x}, \mathbf{y} \in \mathcal{P}$ clearly $\mathbf{w} = \mathbf{x} + \mathbf{y} \in \mathcal{P}$ since $w_i = x_i + y_i$
- Thus for any two vectors $\mathbf{x}, \mathbf{y} \in \mathcal{P}$ and any $a \in \{0, 1\}$ the vector $\mathbf{z} = a\mathbf{x} + (1-a)\mathbf{y}$ will be in \mathcal{P}

4.2 Inverse of Convex Functions

1. Taking derivatives

$$\frac{d^2 f(g(x))}{dx^2} = \frac{df'(g(x)) g'(x)}{dx} = f''(g(x)) (g'(x))^2 + f'(g(x)) g''(x)$$

2. If $g(x) = f^{-1}(x)$ then $f(g(x)) = x$ and the second derivative vanishes
3. Using 1. and 2. we find (writing $f^{-1}(x)$ as $g(x)$)

$$g''(x) = -\frac{f''(g(x)) (g'(x))^2}{f'(g(x))}$$

4. If $f(x)$ is convex then $f''(y) \geq 0$ for any y (including $y = f^{-1}(x)$) also $(g'(x))^2 \geq 0$ so for the inverse of $f(x)$ to be convex down we require $f'(f^{-1}(x)) > 0$
5. Use this to show

- (a) Let $f(x) = x^2$, so that $f''(x) = 2 > 0$ and $f'(y) = y$ which is non-negative if $y \geq 0$, but $f^{-1}(x) = \sqrt{x} > 0$ so $f'(f^{-1}(x)) \geq 0$ and consequently \sqrt{x} is convex-down
- (b) Let $f(x) = \exp(x)$, so that $f''(x) = \exp(x) > 0$. But $f'(y) = \exp(y) > 0$ for all y so $f'(f^{-1}(x)) > 0$ which is sufficient to show $f^{-1}(x) = \log(x)$ is a convex-down function

4.3 Cumulant Generating Function

1. If $G(\lambda) = \log(\mathbb{E}[e^{\lambda x}])$ then

$$G'(\lambda) = \frac{\mathbb{E}[x e^{\lambda x}]}{\mathbb{E}[e^{\lambda x}]}$$

and

$$G''(\lambda) = \frac{\mathbb{E}[x^2 e^{\lambda x}]}{\mathbb{E}[e^{\lambda x}]} - \frac{\mathbb{E}[x e^{\lambda x}]^2}{\mathbb{E}[e^{\lambda x}]^2}$$

2.
 - Now if $p(x)$ is a probability distribution it will be non-negative for all x and sum or integrate to 1
 - But then $q(x) = p(x) e^{\lambda x} / \mathbb{E}[e^{\lambda x}]$ will be non-negative as $e^{\lambda x} > 0$ and $\mathbb{E}[e^{\lambda x}] > 0$ (the expectation of positive quantities will be positive)

- But

$$\int q(x) dx = \frac{1}{\mathbb{E}[e^{\lambda x}]} \int p(x) e^{\lambda x} dx = \frac{\mathbb{E}[e^{\lambda x}]}{\mathbb{E}[e^{\lambda x}]} = 1$$

- So $q(x)$ is non-negative and normalised so is a well defined probability distribution

3. Using the result of 1. and 2

$$G''(\lambda) = \frac{\mathbb{E}_p[x^2 e^{\lambda x}]}{\mathbb{E}_p[e^{\lambda x}]} - \frac{\mathbb{E}_p[x e^{\lambda x}]^2}{\mathbb{E}_p[e^{\lambda x}]^2} = \mathbb{E}_g[x^2] - \mathbb{E}_g[x]^2 \geq 0$$

- since variances are non-negative