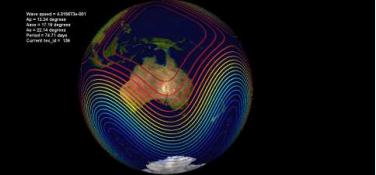


Nonlinear progressive Rossby waves

Tim Callaghan

School of Mathematics and Physics

University of Tasmania



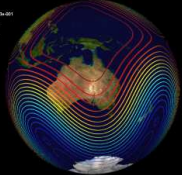
Preliminaries

- Coordinate System
- Equations of Motion
- Approximations
- Shallow Atmosphere Equations
- Volume Specification

Linearized Theory

Nonlinear Theory

Preliminaries



Coordinate System

Preliminaries

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Linearized Theory

Nonlinear Theory

Variables:

Time, t

Radial coord, r

Longitude, λ

Latitude, ϕ

Density, ρ

Pressure, p

Gravity, $\mathbf{g} = -g\mathbf{e}_r$

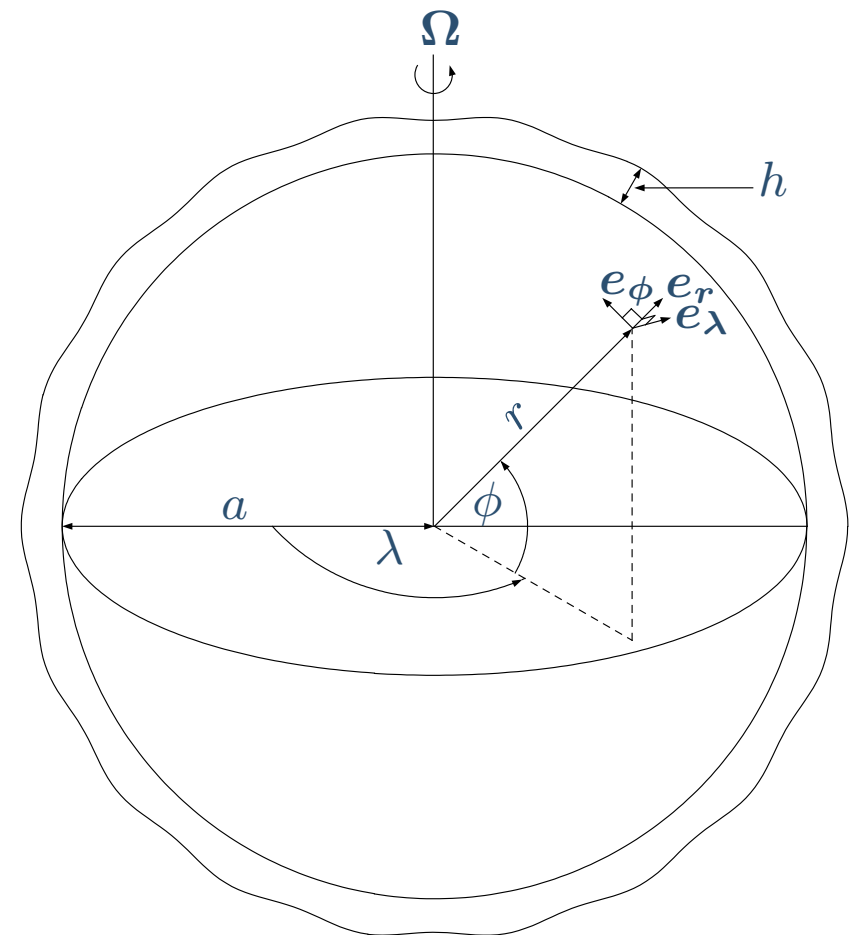
Velocity,

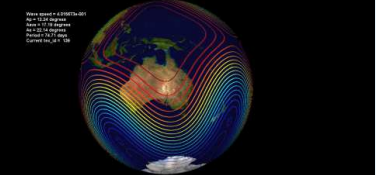
$$\mathbf{q} = u_r\mathbf{e}_r + u_\lambda\mathbf{e}_\lambda + u_\phi\mathbf{e}_\phi$$

Free-surface depth,

$$h(\lambda, \phi, t)$$

Angular velocity, Ω





Equations of Motion

Preliminaries

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Linearized Theory

Nonlinear Theory

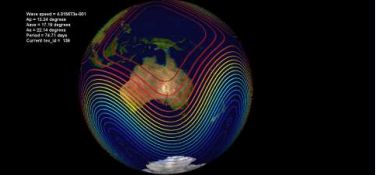
In a reference frame rotating with angular velocity Ω , conservation of mass for an incompressible inviscid fluid is expressed through the continuity equation

$$\nabla \cdot \mathbf{q} = 0 \quad (1)$$

and conservation of momentum requires the usual Euler equation

$$\frac{D\mathbf{q}}{Dt} + 2\Omega \times \mathbf{q} + \frac{1}{\rho} \nabla p = \mathbf{f}, \quad (2)$$

where \mathbf{f} is the combined effect of all body forces per unit mass.



Approximations

Preliminaries

- Coordinate System
- Equations of Motion
- Approximations
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Linearized Theory

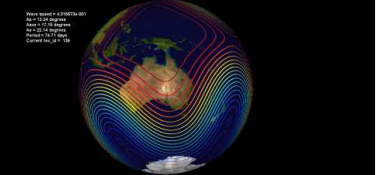
Nonlinear Theory

- Shallow atmosphere, $h(\lambda, \phi, t) \ll a$.
- Mainly tangential motion, $u_r \ll u_\lambda$ and $u_r \ll u_\phi$.
- Radial coordinate approximated by $r = a$.
- Hydrostatic balance, $p(r, \lambda, \phi, t) = p_o + \rho g(a + h(\lambda, \phi, t) - r)$.
- Only allow progressive waves, define $\eta = \lambda - ct$, where $-ct$ term merely translates any initial wave structure.
- Nondimensionalize, reference scales v_{ref} , h_{ref} and c_{ref} , leading to dimensionless parameters

$$Sr = \frac{a c_{ref}}{v_{ref}} \quad \text{Strouhal number,}$$

$$Ro = \frac{v_{ref}}{2\Omega a} \quad \text{Rossby number,}$$

$$Fr = \frac{v_{ref}}{\sqrt{gh_{ref}}} \quad \text{Froude number.}$$



Shallow Atmosphere Equations

Preliminaries

- Coordinate System
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Linearized Theory

Nonlinear Theory

The conservation equations in spherical polar component form are given by

Mass

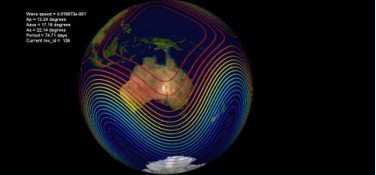
$$(u_\lambda - \text{Sr } c \cos \phi) \frac{\partial h}{\partial \eta} + u_\phi \cos \phi \frac{\partial h}{\partial \phi} + h \left[\frac{\partial u_\lambda}{\partial \eta} + \cos \phi \frac{\partial u_\phi}{\partial \phi} - u_\phi \sin \phi \right] = 0,$$

λ momentum

$$(u_\lambda - \text{Sr } c \cos \phi) \frac{\partial u_\lambda}{\partial \eta} + u_\phi \cos \phi \frac{\partial u_\lambda}{\partial \phi} - \left(\frac{\cos \phi}{\text{Ro}} + u_\lambda \right) u_\phi \sin \phi + \frac{1}{\text{Fr}^2} \frac{\partial h}{\partial \eta} = 0,$$

ϕ momentum

$$(u_\lambda - \text{Sr } c \cos \phi) \frac{\partial u_\phi}{\partial \eta} + u_\phi \cos \phi \frac{\partial u_\phi}{\partial \phi} + \left(\frac{\cos \phi}{\text{Ro}} + u_\lambda \right) u_\lambda \sin \phi + \frac{\cos \phi}{\text{Fr}^2} \frac{\partial h}{\partial \phi} = 0.$$



Volume Specification

Preliminaries

- Coordinate System
- Equations of Motion
- Approximations
- Shallow Atmosphere Equations
- Volume Specification

Linearized Theory

Nonlinear Theory

It is necessary to specify the total volume V_b of the atmosphere.

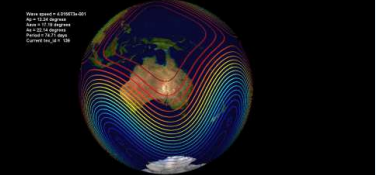
■ Define exactly κ wavelengths around a latitude circle.
The total volume of fluid is

$$V = \frac{4\kappa}{3} \int_0^{\pi/\kappa} \int_0^{\pi/2} [h^3 + 3\hat{a}^2 h + 3\hat{a} h^2] \cos \phi \, d\phi d\eta.$$

The volume specification condition is now written in the form

$$1 - \frac{V}{V_b} = 0.$$

The complete specification of a nonlinear atmospheric progressive Rossby wave in this model consists of solving all conservation equations subject to some condition defining the amplitude of the wave.



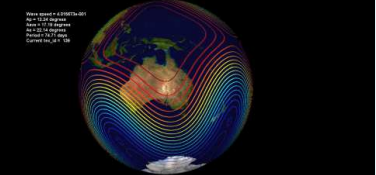
Preliminaries

Linearized Theory

- Zonal Flow and Perturbations
- Series Solution
- Generalized Eigenvalue Problem
- Model Parameters
- Comparison with R-H wavespeed

Nonlinear Theory

Linearized Theory



Zonal Flow and Perturbations

Preliminaries

Linearized Theory

● Zonal Flow and Perturbations

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Nonlinear Theory

Consider small amplitude Rossby waves as perturbations to a base Westerly zonal flow. Have zonal flow of the form

$$u_{\lambda z} = \omega \cos \phi,$$

$$u_{\phi z} = 0,$$

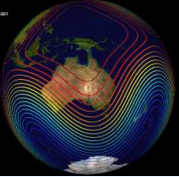
$$h_z = h_o + \frac{\omega \text{Fr}^2}{2} \left(\frac{1}{\text{Ro}} + \omega \right) \cos^2 \phi,$$

and then construct $O(\epsilon)$ perturbations

$$u_{\lambda}(\eta, \phi) = u_{\lambda z} + \epsilon \cos(\kappa \eta) \Lambda(\phi) + O(\epsilon^2),$$

$$u_{\phi}(\eta, \phi) = 0 + \epsilon \sin(\kappa \eta) \Phi(\phi) + O(\epsilon^2),$$

$$h(\eta, \phi) = h_z + \epsilon \cos(\kappa \eta) \mathcal{H}(\phi) + O(\epsilon^2).$$



Series Solution

Preliminaries

Linearized Theory

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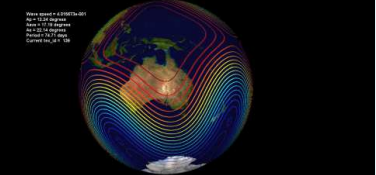
Nonlinear Theory

- Derive a linearized system of equations for the $O(\epsilon)$ corrections.
- Impose specific symmetry conditions.
- Solve using Fourier series of the form

$$\Lambda(\phi) = \sum_{n=1}^N P_{\kappa,n} \cos((2n-1)\phi),$$

$$\Phi(\phi) = \sum_{n=1}^N Q_{\kappa,n} \sin(2n\phi),$$

$$\mathcal{H}(\phi) = \sum_{n=1}^N H_{\kappa,n} (-1)^n [\cos(2n\phi) + \cos(2(n-1)\phi)].$$



Generalized Eigenvalue Problem

Preliminaries

Linearized Theory

- Zonal Flow and Perturbations
- Series Solution
- Generalized Eigenvalue Problem
- Model Parameters
- Comparison with R-H wavespeed

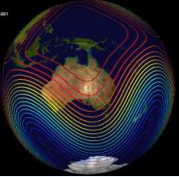
Nonlinear Theory

- Use orthogonality to integrate the equations (Galerkin method).
- Derive a generalized eigenvalue problem of the form

$$Ax = cBx.$$

- A and B are matrices corresponding to the left and right-hand sides of each of the algebraic equations obtained from orthogonality.
- The eigenvalue c is precisely the wavespeed for the progressive Rossby wave.
- Vector x is the eigenvector of unknown linearized coefficients, which is defined as

$$x = [H_{\kappa,1}, \dots, H_{\kappa,N}, P_{\kappa,1}, \dots, P_{\kappa,N}, Q_{\kappa,1}, \dots, Q_{\kappa,N}]^T.$$



Model Parameters

Preliminaries

Linearized Theory

- Zonal Flow and Perturbations
- Series Solution
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- Model Parameters
- Comparison with R-H wavespeed

Nonlinear Theory

We use parameters that closely approximate those of the Earth.

$$a = 6.37122 \times 10^6 \text{ m}$$

$$\Omega = \frac{2\pi}{24 \times 3600} \approx 7.272 \times 10^{-5} \text{ s}^{-1}$$

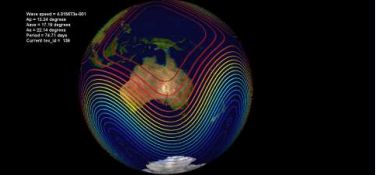
$$g = 9.80616 \text{ m s}^{-2}$$

$$v_{ref} = 40 \text{ m s}^{-1}$$

$$h_{ref} = 8.0 \times 10^3 \text{ m}$$

$$c_{ref} = \frac{\Omega}{30} \approx 2.4241 \times 10^{-6} \text{ s}^{-1}$$

Thus: $\text{Sr} \approx 3.8611 \times 10^{-1}$, $\text{Fr} \approx 1.4281 \times 10^{-1}$ and $\text{Ro} \approx 4.3166 \times 10^{-2}$



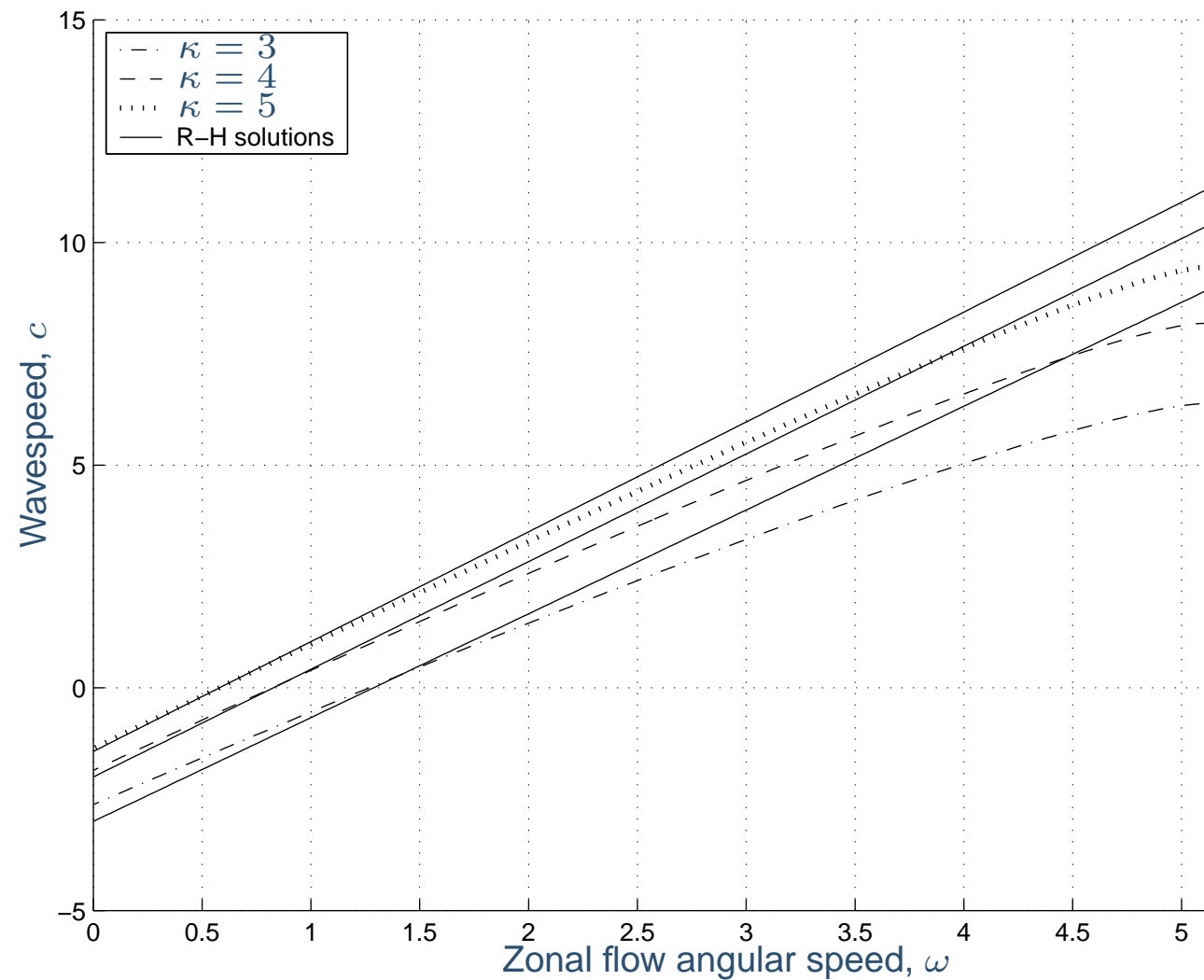
Comparison with R-H wavespeed

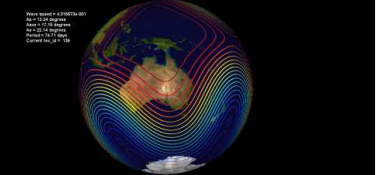
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Nonlinear Theory





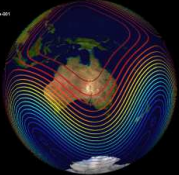
Preliminaries

Linearized Theory

Nonlinear Theory

- Series Solution
- Amplitude Forcing and Measurement
- Solution Process
- Results for $\kappa = 4$,
 $\omega = 1.25$
- F-S contours, $\kappa = 4$,
 $\omega = 1.25$
- Results for $\kappa = 4$,
 $\omega = 1.0$
- F-S contours (end Branch 4),
 $\kappa = 4, \omega = 1.0$
- F-S contours (end Branch 5),
 $\kappa = 4, \omega = 1.0$
- Velocity (end Branch 5),
 $\kappa = 4, \omega = 1.0$

Nonlinear Theory



Series Solution

Seek solutions of the full nonlinear problem using Fourier series of the form

$$u_{\lambda}(\eta, \phi) = \omega \cos \phi + \sum_{m=1}^M \sum_{n=1}^N P_{m,n} \cos(\kappa m \eta) \cos((2n-1)\phi),$$

$$u_{\phi}(\eta, \phi) = \sum_{m=1}^M \sum_{n=1}^N Q_{m,n} \sin(\kappa m \eta) \sin(2n\phi)$$

$$h(\eta, \phi) = \sum_{n=0}^N H_{0,n} \cos(2n\phi),$$

$$+ \sum_{m=1}^{M-1} \sum_{n=1}^N H_{m,n} \cos(\kappa m \eta) (-1)^n [\cos(2n\phi) + \cos(2(n-1)\phi)].$$

Preliminaries

Linearized Theory

Nonlinear Theory

● Series Solution

● Amplitude Forcing and Measurement

● Solution Process

● Results for $\kappa = 4$,
 $\omega = 1.25$

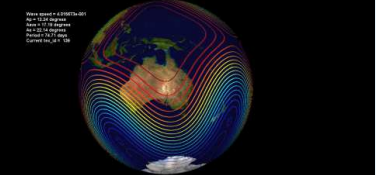
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● Results for $\kappa = 4$,
 $\omega = 1.0$

● F-S contours (end Branch 4),
 $\kappa = 4, \omega = 1.0$

● F-S contours (end Branch 5),
 $\kappa = 4, \omega = 1.0$

● Velocity (end Branch 5),
 $\kappa = 4, \omega = 1.0$



Amplitude Forcing and Measurement

Preliminaries

Linearized Theory

Nonlinear Theory

● Series Solution

● Amplitude Forcing and Measurement

● Solution Process

● Results for $\kappa = 4$,

$$\omega = 1.25$$

● F-S contours, $\kappa = 4$,

$$\omega = 1.25$$

● Results for $\kappa = 4$,

$$\omega = 1.0$$

● F-S contours (end Branch 4),

$$\kappa = 4, \omega = 1.0$$

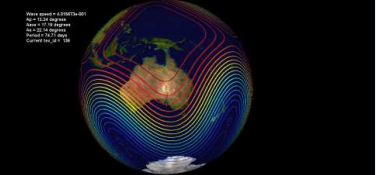
● F-S contours (end Branch 5),

$$\kappa = 4, \omega = 1.0$$

● Velocity (end Branch 5),

$$\kappa = 4, \omega = 1.0$$

- Force amplitude \mathcal{A} through either $H_{1,1}$ or c .
- In this context, progressive Rossby waves are perturbations from a base Westerly zonal flow, for which the height contours are simply circles of constant ϕ . The unperturbed free-surface height contours at $\phi = \pm\pi/4$ are taken here as the base level, against which Rossby wave amplitudes are measured.
- Define the equatorial, polar and average amplitudes as \mathcal{A}_e , \mathcal{A}_p and \mathcal{A}_{ave} respectively.



Solution Process

Preliminaries

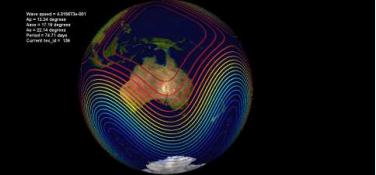
Linearized Theory

Nonlinear Theory

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- Solution Process

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 $\kappa = 4, \omega = 1.0$
- Velocity (end Branch 5),
 $\kappa = 4, \omega = 1.0$

- Solve using Collocation. We evaluate the three governing dynamical equations at every point of the collocation mesh to give a vector of residuals. In addition, the volume specification equation is evaluated and appended to this vector.
- Residual equations are solved using a multi-dimensional Newton method.
- Linearized solutions are used to initialise the Newton method when the amplitude is small.
- Once a nonlinear solution has been found, the amplitude is slowly increased and bootstrapping is used to trace out the wavespeed versus amplitude curve incrementally.



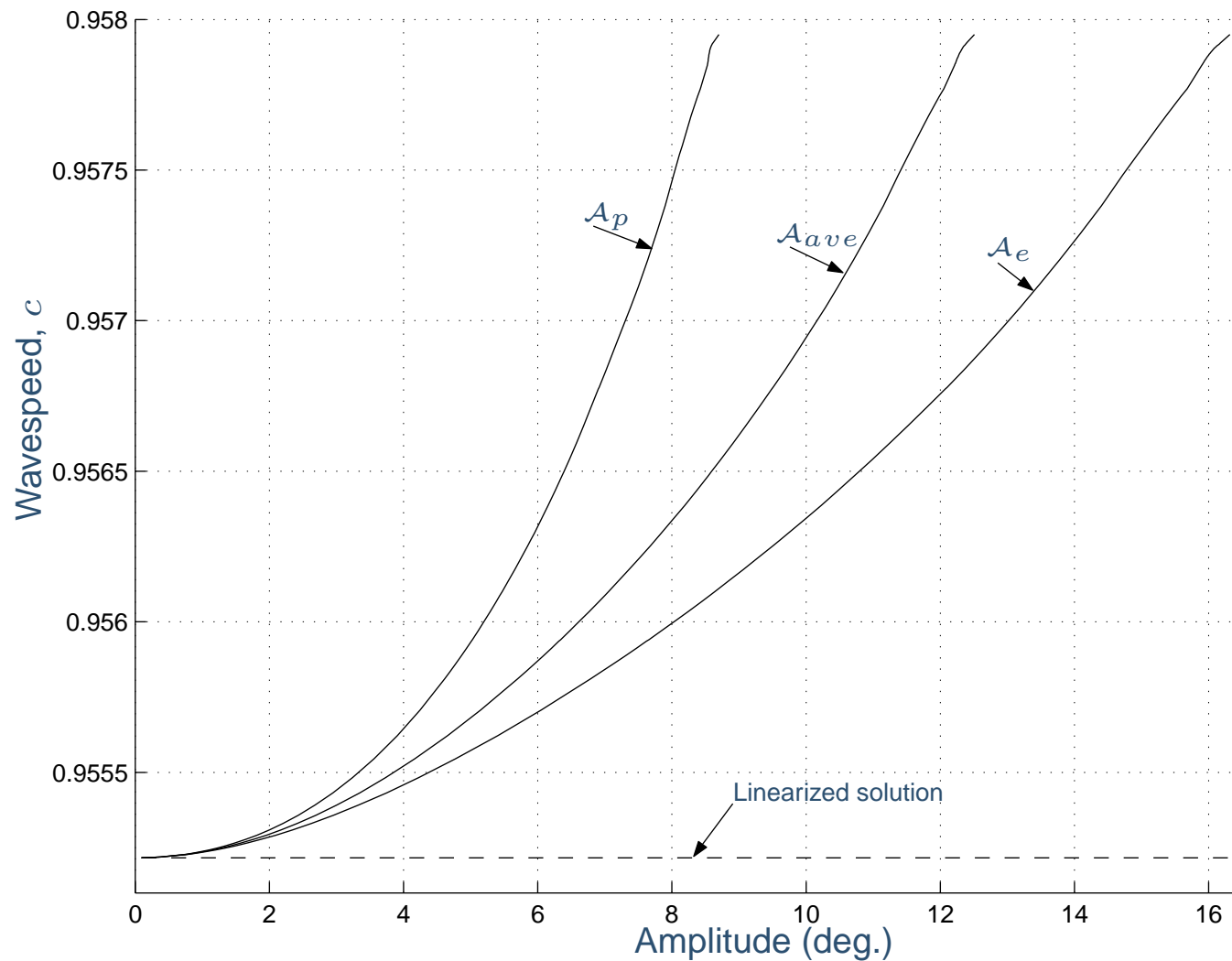
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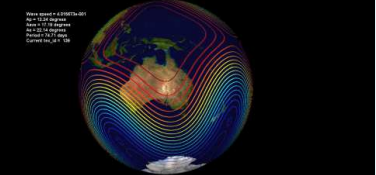
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- Velocity (end Branch 5), $\kappa = 4, \omega = 1.0$





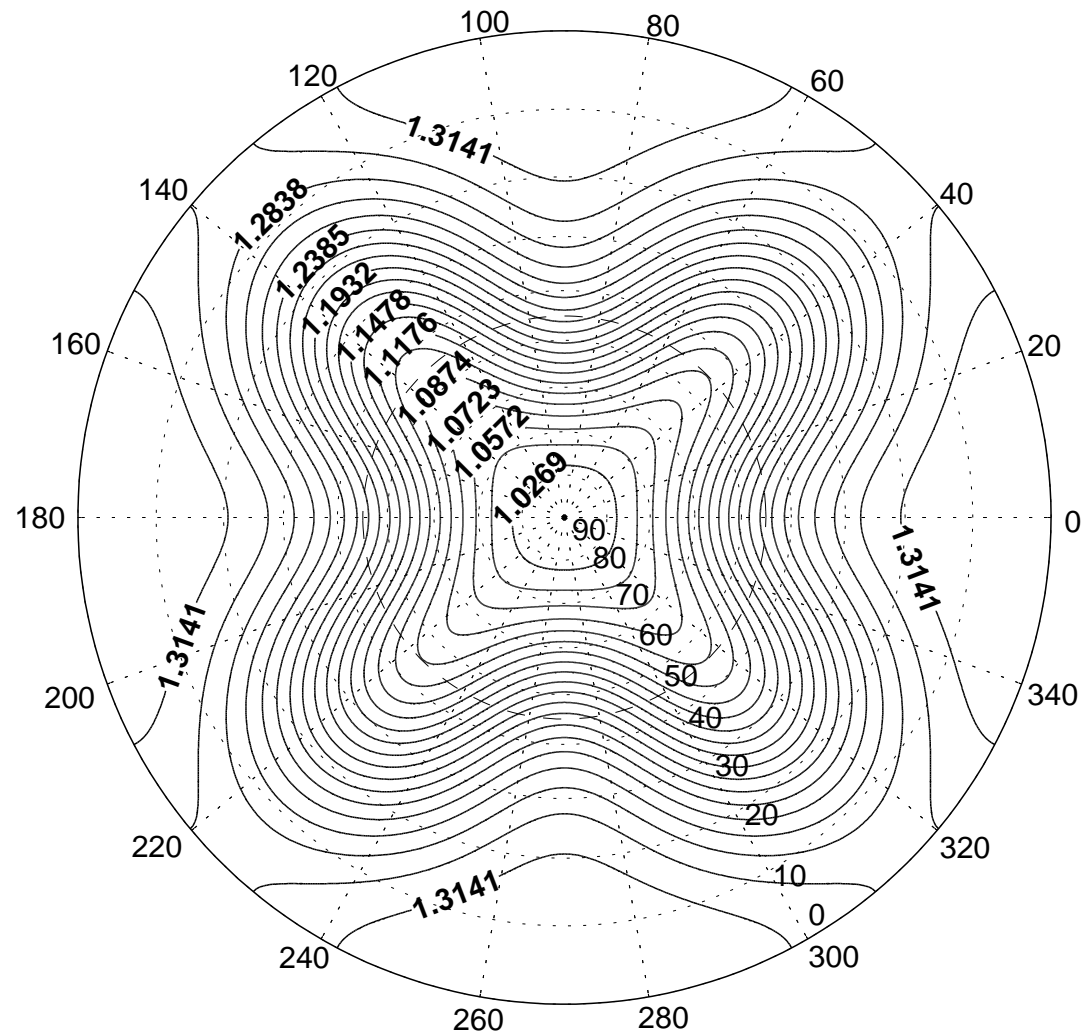
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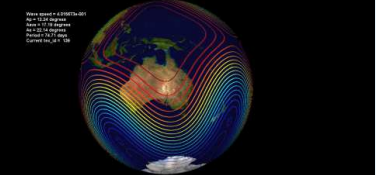
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Linearized Theory

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- Velocity (end Branch 5), $\kappa = 4$, $\omega = 1.0$





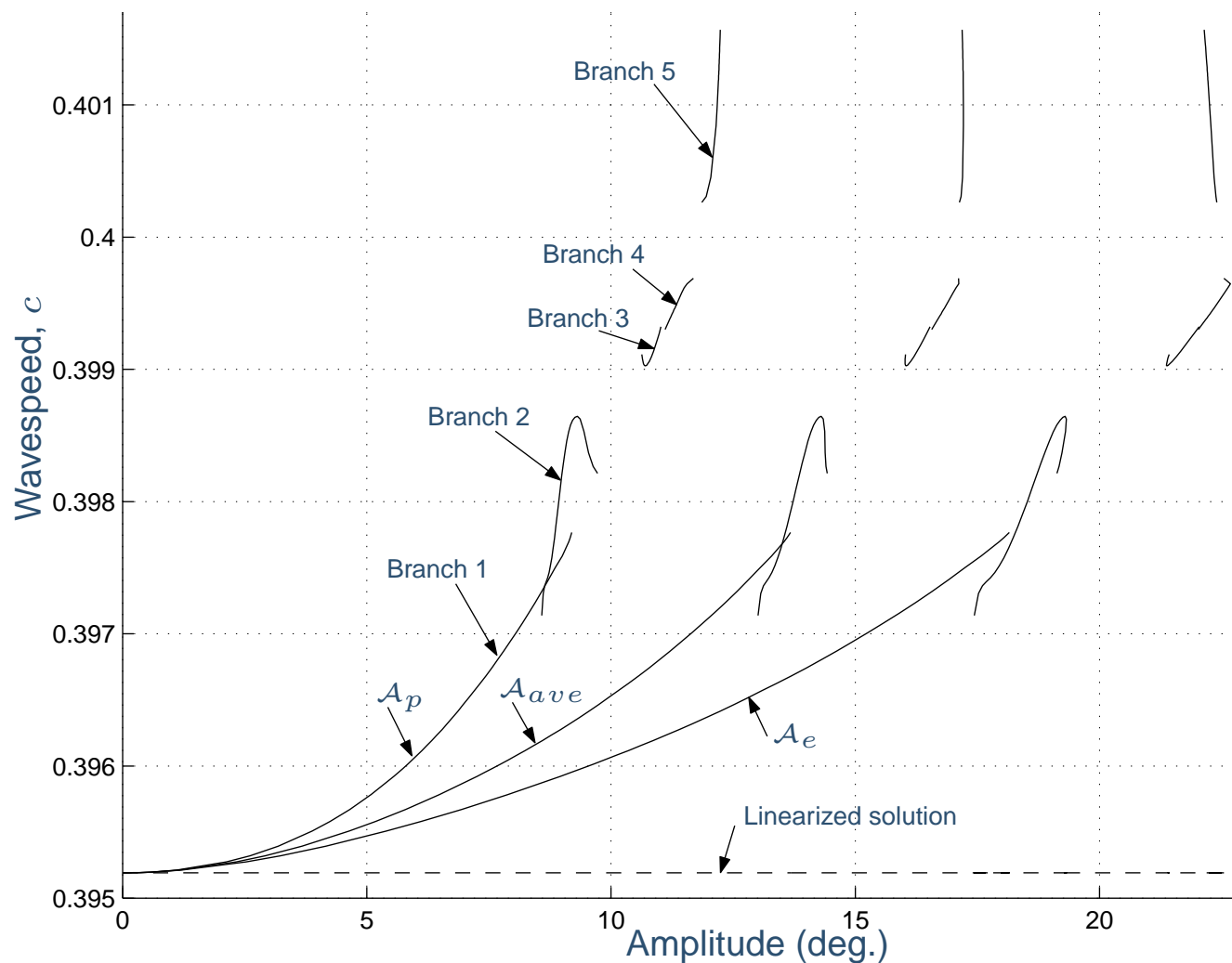
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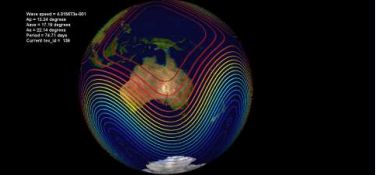
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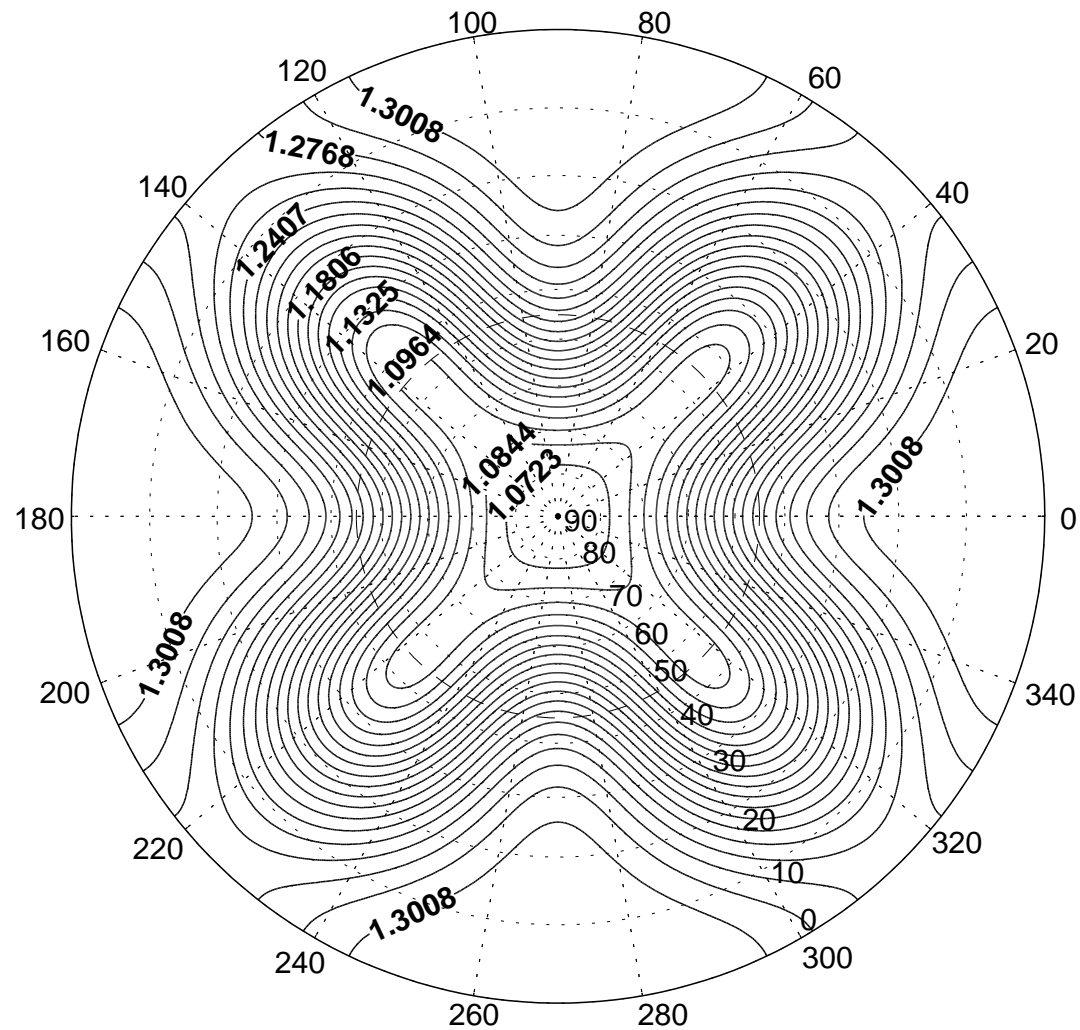
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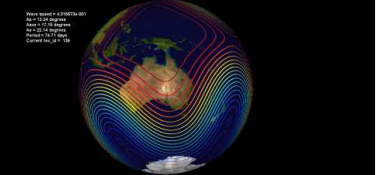
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Linearized Theory

Nonlinear Theory

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- F-S contours (end Branch 5), $\kappa = 4, \omega = 1.0$
- Velocity (end Branch 5), $\kappa = 4, \omega = 1.0$





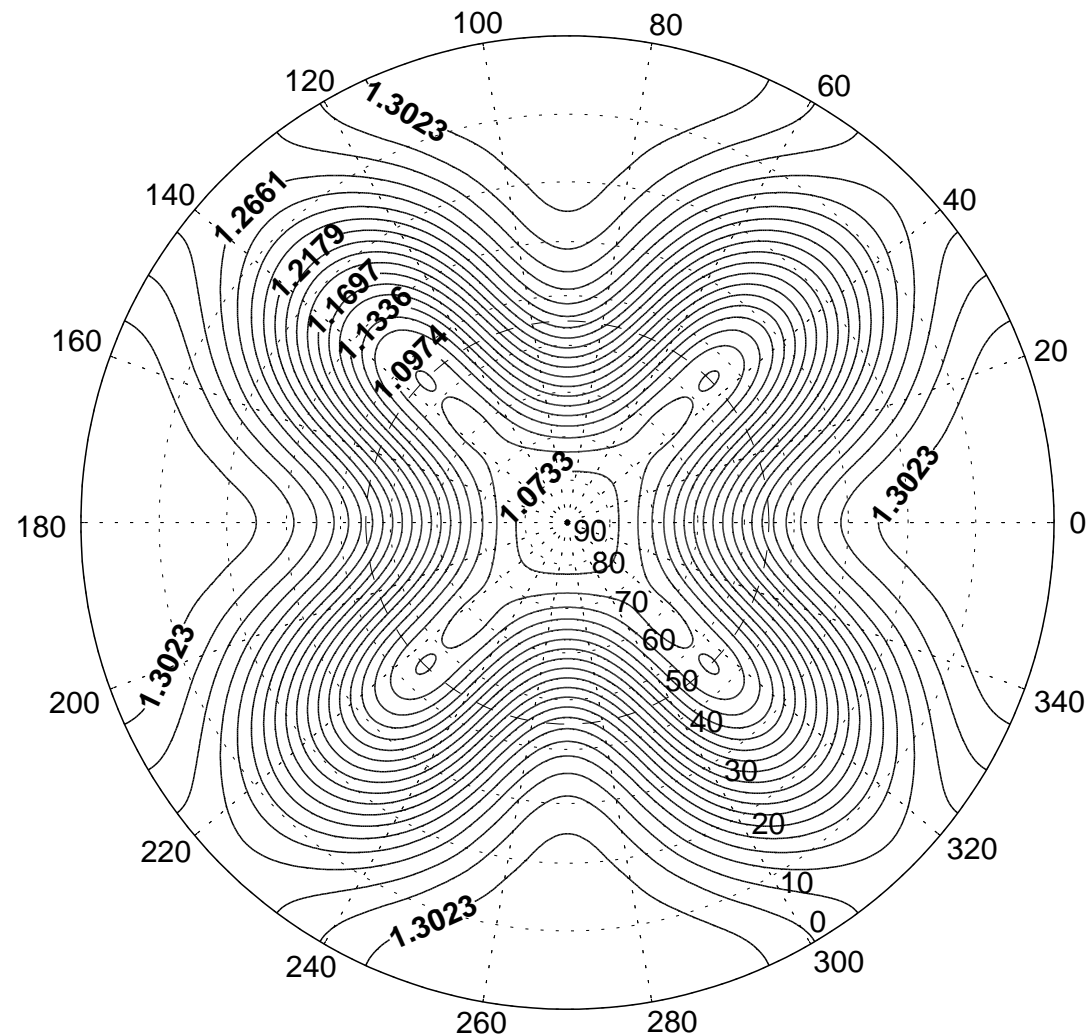
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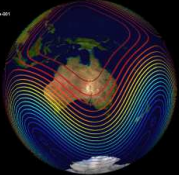
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- Velocity (end Branch 5), $\kappa = 4$, $\omega = 1.0$





Velocity (end Branch 5), $\kappa = 4$, $\omega = 1.0$

Preliminaries

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