Remotely Connected Electric Field Generator for Particle Separation in a Fluid

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Abstract

This document details the design and implementation of a remotely connected electric field generator. The goal of this design is to provide an easy interface for manipulating the output voltage and frequency of a circuit remotely in order to generate an electric field. This electric field, when applied to a fluid over a long period of time will cause particles in the fluid to separate. The hardware and software components used to accomplish the aforementioned goal are described in detail.

1 Introduction

New research has shown that certain particles may be separated from fluids through dielectrophoresis. This process involves applying an electric field to a fluid. The field may be manipulated in order to attract or repel certain particles. The particles the electric field will attract or repel depends on characteristics of the electric filed which may be controlled by varying the voltage and frequency of the electronics driving the field.

This technology has many useful applications in health care

2 Project Definition

In our implementation, an electric field is applied to two metal plates. by varying the voltage and frequency applied to these plates, the properties of the electric field can be changed.

Our job is to construct a system containing an electronic circuit capable of providing the necessary voltages and frequencies required to drive a pair of metal plates. This system must enable the circuit to be controllable through the use of a web interface. In addition, a small form factor must be maintained.

The system must be able to generate up to a 60 V peak-peak sine wave with user-controlled variable frequency from 10 kHz to 1 MHz.

3 Deliverables

There are four items which must be constructed for this project:

For the analog circuit components, functionality of the circuit will be tested using an oscilloscope to verify the requirements have been satisfied. This method can also be used to ensure the output signal contains minimal amounts of noise and distortion.

The construction of this device is the first phase of the project. After the completion of this component, the device will be used to experiment with particle separation in various fluid types. These experiments constitute the remainder of the project. For these experiments our advisor at Minetronix, John Pritchard, will be the main source of guidance and testable material.

4 Constraints

Constraints on this project fall within the size, voltage, and portability domains.

The size requirements of this project are directly related to the portability of the final design. The design requirements specify this system must be easily and quickly moved around from one workstation to another. The maximal allowed size is approximately the size of a backpack with smaller sizes being more desirable but not explicitly required. With the electronics currently being used, these requirements will easily be met.

The other constraint that we might meet would arise from the power supply. We require a 60V power supply to feed into the amplifier portion of the circuit. This means that the device will most likely be attached to a power brick that requires being plugged in. This leads to the need to be within easy reach of a wall plugin, which should not be a problem in most, if not all, testing environments.

The system requirements call for several different systems to run or power our devices. The first requirement would be a connection to a computer to be able to interact and use the web interface on the raspberry pi that runs the device. Without a computer to interact with you will have no practical means to change the device's function. The next requirement is a connection to the raspberry pi itself. The third system requirement is a standard wall outlet to plug the device into. The finished product will require a amplifier circuit from 3.3V AC to 60V AC which is most easily handled by regulating the usual 120V sine wave.

5 System Analysis

A user will interface with this system though the web interface. The interface will allow the user to choose the values for Voltage and Frequency. Once the user enters these values update scripts will run on the Raspberry pi. These scripts will cause the appropriate values to be set in the Minigen and Digital potentiometers. This will cause the output of the circuit to change to the requested values.

6 Block Diagrams

standard non-inverting amplifier circuit Detail Description

7 Functional Decomposition

There are four large blocks in our system. They include the Web Interface, Raspberry Pi, Minigen Signal Generator, and Amplifier Circuit. The project will be described in terms of these pieces.

The web interface will be created using an Apache web server. We will be able to use the Raspberry Pi to host the web server. The web server will need to display an interface which will allow the user to set the voltage and frequency. A simple interactive interface can be created with cgi scripts hosted by the webserver. In addition to hosting the web server the Raspberry pi can be used to regulate the voltage and frequency output by the system. The SPI interface of the raspberry pi will be used to communicate with the Minigen which controls the frequency and digital potentiometers which regulate the voltage.

The Minigen produces a frequency which is a function of the values contained in its frequency registers. These values can be modified though SPI communications with the Minigen. We will use the Raspberry Pi for these communications.

The Raspberry pi also controls the resistance of several digital potentiometers. These potentiometers regulate the gain of an amplifier circuit. The power from the amplifier will need to come from a voltage source which will supply at least 60 Vpp.

7.1 Web Server

The primary function of the webserver will be to communicate with the Raspberry Pi. This will be the primary method of control utilized by the user. The web pages displayed by the server will have the ability to control the voltage and frequency output from the circuit. A simple web interface might look something like the following.

Figure 2: Web Interface

This could be accomplished by running an apache web server on the Raspberry Pi. The web server would need to display this page. When the user clicks update, the server could execute a cgi script which would perform the update functions.

7.2 Raspberry Pi

The Raspberry Pi will act as the bridge between the user and the circuit. The Pi will host a webserver which the user can interact

with. Based on what the user indicates in this interaction, the Pi will update the state of the GPIO pins. The GPIO pins connect to a circuit causing the output to change based on their state.

The Raspberry pi is capable of producing square waves by turning the GPIO pins on and off rapidly. We can use this functionality to produce a wave of the frequency indicated by the user. The GPIO pins can also be used to set the voltage by communicating with the circuit how much the output waveform should be amplified. The downside to this approach is the analog circuit component will need to be more complex. The analog circuit needs to output a sine wave. With this approach we would need to integrate the square wave produced by the GPIO pin.

There exist alternatives to using the GPIO pins to generate a signal with a given frequency. We could instead use the GPIO pins on the raspberry pi to communicate with a small signal generator, such as sparkfun.com s Minigen. This would make programming the Raspberry pi more complex, but could lead to higher quality waveforms. Producing a sine wave using the Minigen signal generator is likely to to produce fewer distortions compared to integrating a square wave produced by the RPIs GPIO pin twice.

7.3 Minigen

The minigen outputs a waveform from -3.3V to 3.3V, this will be the starting point before going into the amplifier circuit. The minigen communicates over SPI, which the raspberry pi has dedicated modules for. The minigen is controlled by setting five registers, two for frequency, two for phase shift and one as a control. We have no need for phase shifting, but will be communicating with the frequency and control registers. By having two frequency registers, we are able to send data to reg0, then tell the control reg to use reg0, this allows for a nicer gradient, because the frequency wont change until the entire register is written. The control register also allows for changing between sine, square and triangle, although this doesnt interest us at the moment, it may be nice to experiment with later on. Finally, the bottom half of the control register allows us to switch between writing to the top half, bottom or whole frequency register, giving us the ability to accurately dial in small changes to the register, or large changes, or just rewrite the entire frequency. Due to the small chip size, it will be able to fit into a case with the raspberry pi, allowing for a small footprint, a requirement we need to meet.

7.4 Amplifier Circuit

Takes input from the Minigen signal generator. Based on this input the circuit will manage the voltage and frequency of the output.

The Minigen will generate the signal applied to the input of the analog circuit. We only need a method of producing the correct voltage. One way we could accomplish this is to communicate to the circuit what the voltage should be using the GPIO pins on the PI to control a digital potentiometer. Like the minigen, we would use SPI to communicate with this component. Such a circuit might look like the following with one of R1, R2 being a digital potentiometer.

Figure 3: Voltage chooser circuit

The project requires that we generate signals which range from 1 to 60 vpp. The output of the digital potentiometer has 128 steps. This Translates into our ability to set 128 different gains on our amplifier. We will need multiple stages of amplifier to go between 1 and 60 Vpp. The most prominent reason for this is due to the gain bandwidth of the op-amps. We will not be able to have a large gain while still producing a frequency of 1Mhz.

One problem we foresee with the digital potentiometer is that it cannot handle a large amount of power. This may force us to come up with different amplifier configurations, or use the digital potentiometer in a different way. Another way we could possibly use this device is as an attenuator at the input to the amplifier.

Another problem which might arise with the digital potentiometer is the capacitance of the wiper. We dont have any context for understanding how much this will affect the output signal. According to some preliminary calculations, we have determined that the capacitance will not present a large problem.

8 Cost Considerations

The overall cost of our project will not be very much money. We do not know the exact op-amps other electronic components we will be using, but the costs will be minimal for those parts. The main cost of the project will come in the cost for the Rasperry Pi 2 and/or the Minigen from sparkfun.com if we end up using that. The Raspberry Pi 2 package is \$99.95 and the Minigen is \$29.95. Thinking conservatively and assuming we need both the Raspberry Pi 2 and the Minigen, the cost of the major hardware will be \$129.90. We then need to add in the cost of a resistor kit, a capacitor kit, and a handful of op-amps so that we safely budget for any parts we might need and extras for anything we break or that is defective. On sparkfun.com they have a resistor kit for \$7.95 and this would have any resistors we would need

10 Appendix

10.1 Graphical Comprehension Aides

and then some. As far as capacitor kits they only have very large kits or small kits with random values of capacitance. It may be cheaper to buy individual capacitors from sparkfun.com for \$0.25 each. Figuring 20 capacitors giving plenty needed and some extras would add \$5.00. Each of the op amps are \$0.95 on sparkfun.com and we will budget for 10 of them to again make sure we have plenty of resources available to use if needed. This would add \$9.50 to the cost of materials and would be the last component we need. Adding all the parts together gives a rough estimate of \$152.35 which is way below the maximum allotted funds of \$1,000 we are allowed to use according to the initial problem description.

Total Cost Raspberry Pi 2 Kit - \$99.95 Minigen - \$29.95 Resistors - \$7.95 Capacitors - \$5.00 Op Amps - \$9.50 Estimated Total = \$152.35

9 Timeline

Completion Date Object Description 10/1 Project Plan Create a project plan which specifies the pieces of the project. 10/15 Design Complete a detailed design of each component of our project. Assign people to work on the various pieces of the project. 11/1 Design Web Interface Design and build web interface. Outline code for Communications with Minigen and Digital Potentiometers. 11/15 Hardware Communications and Design Get communications working between Raspberry Pi, Minigen, and Digital Potentiometers. 12/1 Completion of Prototype Take final steps testing prototype. Device should be able to do everything in specification. 12/15 Presentation Present a working prototype of our project. 1/15 Begin Science Component Begin working on Research component of the project. 2/1 - 5/15 Continue Experimenting Use the project to perform some sort of research TBD

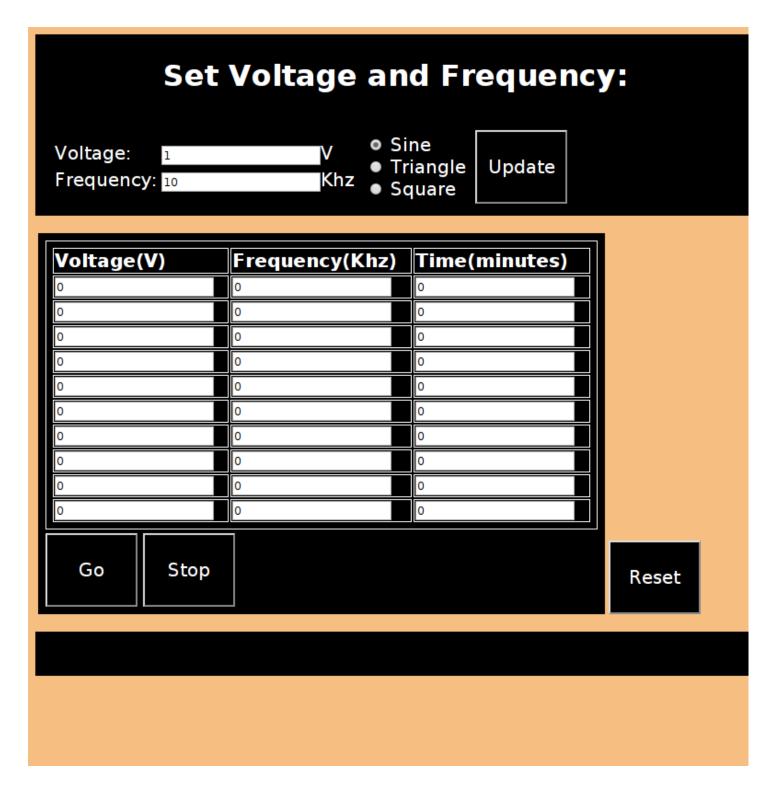


Figure 1: Web Interface

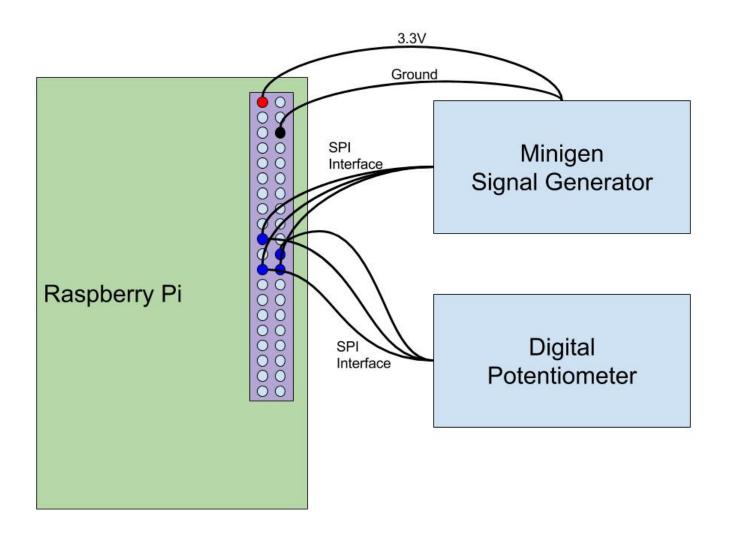


Figure 2: Raspberry Pi Connection Scheme

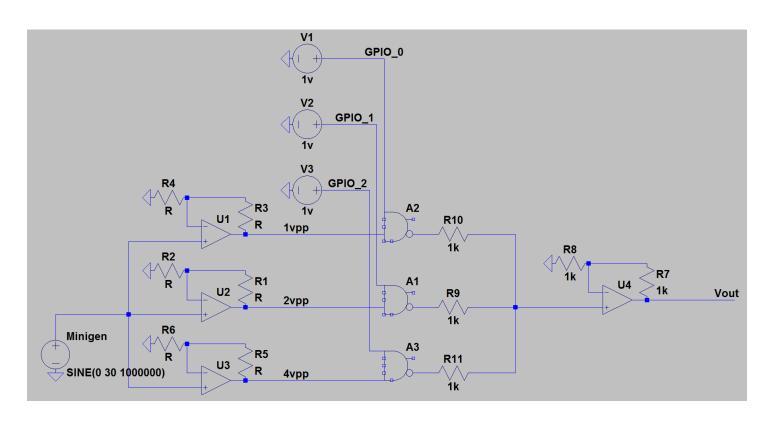


Figure 3: Voltage Control Circuit