# Coding Project [Part 5] - Numerical Integration Comparison With Existing Solutions

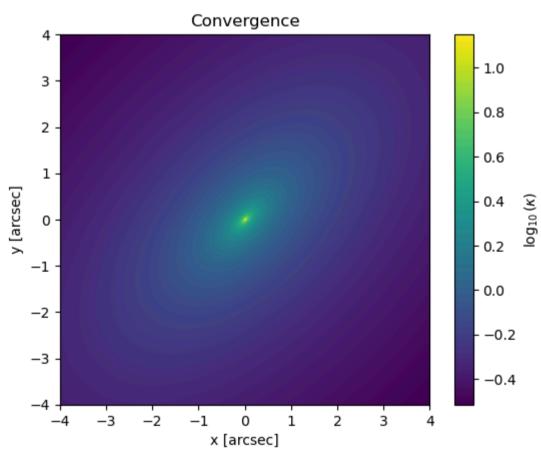
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```
import lenstronomy
import numpy as np
import matplotlib.pyplot as plt
from lenstronomy.LensModel.lens_model import LensModel
# multivariable numerical integration
from scipy.integrate import dblquad
```

### 1. Defining the Lens Model

```
In [78]: # Define the lens model - EPL + SHEAR
         lens_model = LensModel(lens_model_list=[
                                                  'EPL',
                                                 # 'SHEAR',
                                                 # 'NFW'
                                                 ])
         kwargs_lens = [
             {'theta_E': 1.8, 'e1': 0, 'e2': 0.3, 'center_x': 0, 'center_y': 0, 'gamma': 1.58}, # EPL
         # {'gamma1': 0.03, 'gamma2': 0} # shear
             # {"Rs":1, "alpha_Rs":1, "center_x":0, "center_y":0} # NFW
         x_grid, y_grid = np.linspace(-4, 4, 400), np.linspace(-4, 4, 400)
         x_coords, y_coords = np.meshgrid(x_grid, y_grid)
         kappa_on_grid = lens_model.kappa(x_coords, y_coords, kwargs_lens)
         plt.figure()
         plt.title('Convergence')
         plt.imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                    origin='lower')
         c = plt.colorbar()
         c.set_label('$\\log_{10}(\\kappa)$')
         plt.xlabel('x [arcsec]')
         plt.ylabel('y [arcsec]')
```

# Out[78]: Text(0, 0.5, 'y [arcsec]')



## 2. Numerical Integration to find the deflection angle and the lensing potential

The deflection angle  $\alpha$ , the lensing potential  $\psi$  and the convergence  $\kappa$  are related by the following equations:

$$lpha = 
abla \psi$$
  $\kappa = rac{1}{2} 
abla^2 \psi \Rightarrow 
abla lpha = 2 \kappa$ 

By taking the Fourier transform of the above equation, we get:

In [79]: def lensing\_potential\_with\_fft(x\_coords, y\_coords, kappa\_on\_grid):

# first make the grid in Fourier space
delta\_x = x\_coords[0, 1] - x\_coords[0, 0]

$$\mathcal{F}[\psi(ec{ heta})](ec{k}) = -rac{2}{k^2}\mathcal{F}[\kappa(ec{ heta})](ec{k}) \Rightarrow \psi(ec{ heta}) = -\mathcal{F}^{-1}\left[rac{2}{k^2}\mathcal{F}[\kappa(ec{ heta})](ec{k})
ight]$$

The deflection angle,  $\alpha$  and the lensing potential,  $\psi$  can be calculated from the convergence,  $\kappa$  using the following equations:

$$ec{lpha}(ec{ heta}) = rac{1}{\pi} \int \kappa(ec{ heta'}) rac{ec{ heta} - ec{ heta'}}{{|ec{ heta} - ec{ heta'}|^2}} d^2 heta'$$

$$\psi(ec{ heta}) = rac{1}{\pi} \int \kappa(ec{ heta'}) \ln |ec{ heta} - ec{ heta'}| d^2 heta'$$

Note that the deflection angle can be written as convolution of the convergence with a kernel function. The lensing potential can be written as a convolution of the convergence with a different kernel function as

$$ec{lpha}(ec{ heta}) = rac{1}{\pi} \; \kappa * \left(rac{ec{ heta}}{{|ec{ heta}|}^2}
ight)$$

$$\psi(ec{ heta}) = rac{1}{\pi} \ \kappa * \left( \ln |ec{ heta}| 
ight)$$

```
delta_y = y_coords[1, 0] - y_coords[0, 0]
                         k_x = np.fft.fftfreq(x_coords.shape[1], delta_x)
                         k_y = np.fft.fftfreq(y_coords.shape[0], delta_y)
                         k \times grid, k \times grid = np.meshgrid(k \times k \times y)
                         k_sq_grid = k_x_grid**2 + k_y_grid**2
                         k_sq_grid[0, 0] = 1 # avoid division by zero
                         # FFT of the convergence
                         kappa_fft = np.fft.fft2(kappa_on_grid)
                         # lensing potential in Fourier space
                         phi fft = -2 * kappa fft / k sq grid
                         # inverse FFT to real space
                         phi_on_grid = np.fft.ifft2(phi_fft).real
                         return phi_on_grid
                 def alpha_from_potential(phi_on_grid, x_coords, y_coords):
                         alpha_x = np.gradient(phi_on_grid, axis=1) / (x_coords[0, 1] - x_coords[0, 0])
                         alpha_y = np.gradient(phi_on_grid, axis=0) / (y_coords[1, 0] - y_coords[0, 0])
                         return alpha_x, alpha_y
In [80]: | phi = lensing_potential_with_fft(x_coords, y_coords, kappa_on_grid)
                 alpha_x, alpha_y = alpha_from_potential(phi, x_coords, y_coords)
                 fig, ax = plt.subplots(3, 2, figsize=(12, 15))
                 # Convergence
                 # ax[0, 0].set title('Our Calculation')
                 # ax[0, 1].set_title('actual')
                 ax[0, 0].imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                                                origin='lower')
                 ax[0, 1].imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                                               origin='lower')
                 ax[0, 0].set_xlabel('x [arcsec]')
                 ax[0, 0].set_ylabel('y [arcsec]')
                 ax[0, 1].set_xlabel('x [arcsec]')
                 ax[0, 1].set_ylabel('y [arcsec]')
                 c = ax[0, 0].figure.colorbar(ax[0, 0].images[0], ax=ax[0, 0])
                 c.set_label('$\\log_{10}(\\kappa)$')
                 c = ax[0, 1].figure.colorbar(ax[0, 1].images[0], ax=ax[0, 1])
                 c.set_label('$\\log_{10}(\\kappa)$')
                 # Deflection angles
                 lenstronomy_alpha_x, lenstronomy_alpha_y = lens_model.alpha(x_coords, y_coords, kwargs_lens)
                 ax[1, 0].set_title('Our Calculation')
                 ax[1, 1].set_title('actual')
                 ax[1, 0].imshow(np.sqrt(alpha x**2 + alpha y**2), extent=[np.min(x grid), np.max(x grid), np.min(y grid), np.max(y
                                               origin='lower')
                 ax[1, 1].imshow(np.sqrt(lenstronomy_alpha_x**2 + lenstronomy_alpha_y**2), extent=[np.min(x_grid), np.max(x_grid), np.max(x_g
                                               origin='lower')
                 ax[1, 0].set_xlabel('x [arcsec]')
                 ax[1, 0].set ylabel('y [arcsec]')
                 ax[1, 1].set_xlabel('x [arcsec]')
                 ax[1, 1].set_ylabel('y [arcsec]')
                 c = ax[1, 0].figure.colorbar(ax[1, 0].images[0], ax=ax[1, 0])
                 c.set_label('$|\\vec{\\alpha}|$')
```

```
c = ax[1, 1].figure.colorbar(ax[1, 1].images[0], ax=ax[1, 1])
 c.set_label('$|\\vec{\\alpha}|$')
 # Lensing potential
 ax[2, 0].set_title('Our Calculation')
 ax[2, 1].set_title('actual')
 ax[2, 0].imshow(phi, extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                    origin='lower')
 ax[2, 1].imshow(lens_model.potential(x_coords, y_coords, kwargs_lens), extent=[np.min(x_grid), np.max(x_grid), np.m
                    origin='lower')
 ax[2, 0].set_xlabel('x [arcsec]')
 ax[2, 0].set_ylabel('y [arcsec]')
 ax[2, 1].set_xlabel('x [arcsec]')
 ax[2, 1].set_ylabel('y [arcsec]')
 c = ax[2, 0].figure.colorbar(ax[2, 0].images[0], ax=ax[2, 0])
 c.set_label('$\\phi$')
 c = ax[2, 1].figure.colorbar(ax[2, 1].images[0], ax=ax[2, 1])
 c.set_label('$\\phi$')
                                                         1.0
                                                                                                                            1.0
    3 -
                                                                       3 -
                                                         0.8
                                                                                                                            0.8
    2 -
                                                                       2 -
                                                         0.6
                                                                                                                            0.6
    1 -
                                                                       1 -
y [arcsec]
                                                                   [arcsec]
                                                              log<sub>10</sub> (K)
                                                         - 0.4
                                                                                                                            0.4
                                                                       0 -
                                                         - 0.2
                                                                                                                            0.2
                                                                      -1 -
                                                        - 0.0
                                                                                                                            0.0
   -2
                                                                     -2
                                                         - -0.2
                                                                                                                            -0.2
   -3
                                                                     -3 ·
           -3
                            0
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                                                                                        -1
                                                                                               0
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                                                                                                          2
                                                                                                               3
                      -1
                                                                              -3
                        x [arcsec]
                                                                                           x [arcsec]
                    Our Calculation
                                                                                            actual
                                                                       4
                                                         35
                                                                                                                            3.0
    3 -
                                                                       3 ·
                                                         30
    2 -
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                                                                                                                            2.5
                                                         - 25
    1 ·
                                                                       1 -
y [arcsec]
                                                                   y [arcsec]
                                                                                                                            2.0
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                                                                                                                            1.5
                                                                      -1 -
   ^{-1}
                                                        - 10
                                                                                                                           - 1.0
   -2
                                                                     -2
                                                         - 5
   -3
                                                                     -3
                                                                                                                            0.5
                      -1
           -3
                -2
                            0
                                             3
                                                                             -3
                                                                                   -2
                                                                                        -1
                                                                                               0
                                                                                                     1
                                                                                                               3
                        x [arcsec]
                                                                                           x [arcsec]
                    Our Calculation
                                                                                            actual
    4
                                                                       4
                                                         20
                                                                                                                            12
    3
                                                                       3 -
    2
                                                                       2 -
    1
y [arcsec]
    0
                                                                       0 -
                                                                      -2
   -2
                                                          -60
   -3
                                                                      -3
                            0
                                             3
                                                   4
                                                                                                          2
                                                                                                               3
                                                                                                                     4
                        x [arcsec]
                                                                                           x [arcsec]
```

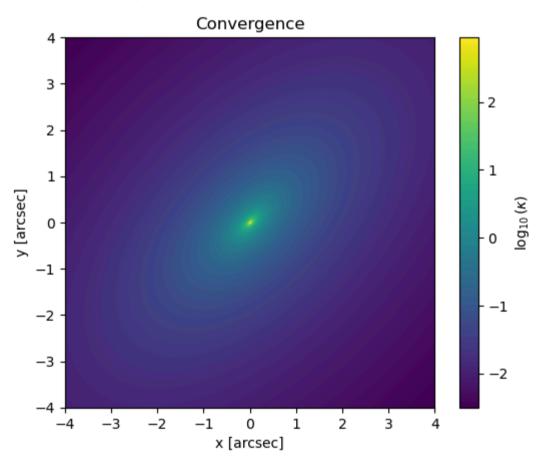
We see deviations from the analytical solution at the edges of the grid. This is due to the fact that the numerical integration is not able to capture the behaviour of the function at the edges of the grid. The EPL power law is slowly varying and does not die out fast enough

before reaching the edges of the grid.

#### 3. Try again with a steeper power law

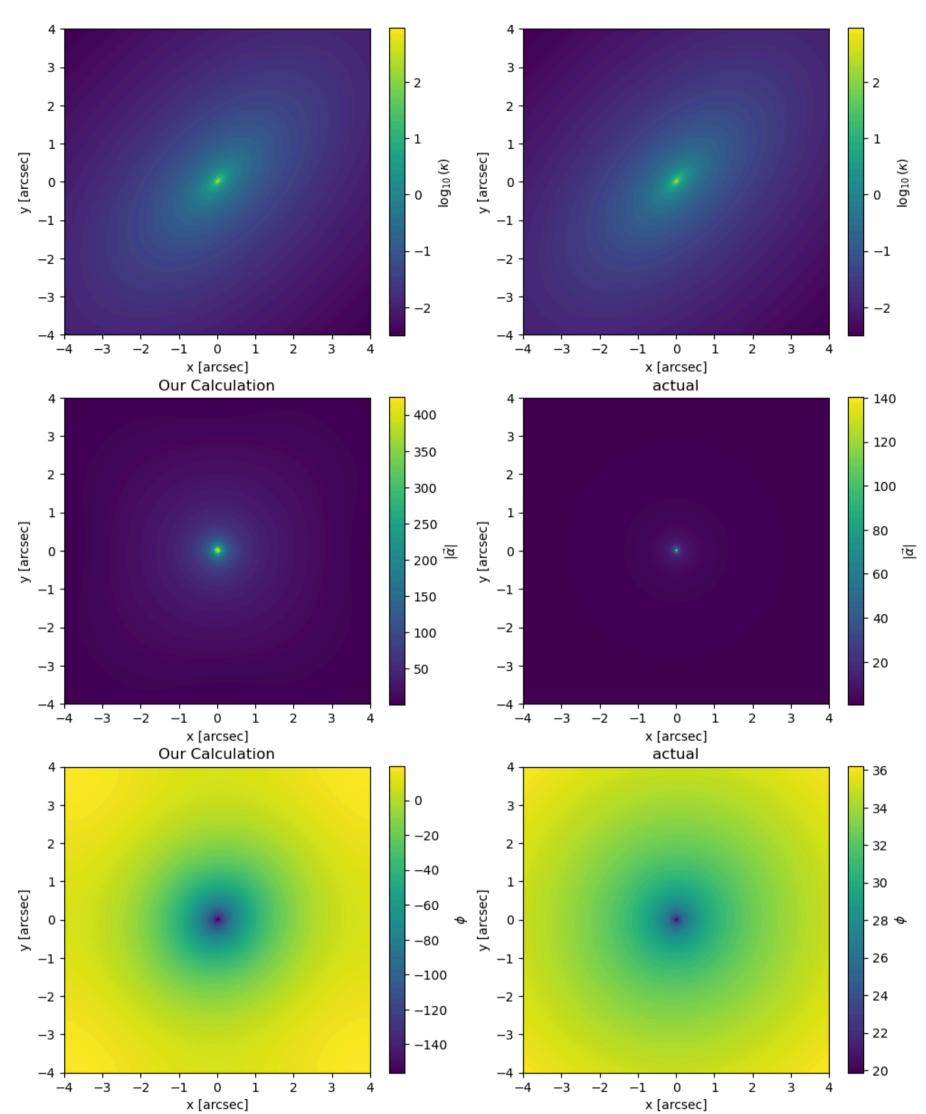
```
In [81]: # Define the lens model - EPL + SHEAR
         lens_model = LensModel(lens_model_list=[
                                                   'EPL',
                                                  # 'SHEAR',
                                                  # 'NFW'
                                                  ])
         kwargs_lens = [
             {'theta_E': 1.8, 'e1': 0, 'e2': 0.3, 'center_x': 0, 'center_y': 0, 'gamma': 2.9}, # EPL
            {'gamma1': 0.03, 'gamma2': 0} # shear
             # {"Rs":1, "alpha_Rs":1, "center_x":0, "center_y":0} # NFW
         x_{grid}, y_{grid} = np.linspace(-4, 4, 400), <math>np.linspace(-4, 4, 400)
         x_coords, y_coords = np.meshgrid(x_grid, y_grid)
         kappa_on_grid = lens_model.kappa(x_coords, y_coords, kwargs_lens)
         plt.figure()
         plt.title('Convergence')
         plt.imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                     origin='lower')
         c = plt.colorbar()
         c.set_label('$\\log_{10}(\\kappa)$')
         plt.xlabel('x [arcsec]')
         plt.ylabel('y [arcsec]')
```

#### Out[81]: Text(0, 0.5, 'y [arcsec]')



```
In [83]: phi = lensing_potential_with_fft(x_coords, y_coords, kappa_on_grid)
         alpha_x, alpha_y = alpha_from_potential(phi, x_coords, y_coords)
         fig, ax = plt.subplots(3, 2, figsize=(12, 15))
         # Convergence
         # ax[0, 0].set_title('Our Calculation')
         # ax[0, 1].set_title('actual')
         ax[0, 0].imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                         origin='lower')
         ax[0, 1].imshow(np.log10(kappa_on_grid), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                         origin='lower')
         ax[0, 0].set_xlabel('x [arcsec]')
         ax[0, 0].set_ylabel('y [arcsec]')
         ax[0, 1].set_xlabel('x [arcsec]')
         ax[0, 1].set_ylabel('y [arcsec]')
         c = ax[0, 0].figure.colorbar(ax[0, 0].images[0], ax=ax[0, 0])
         c.set_label('$\\log_{10}(\\kappa)$')
         c = ax[0, 1].figure.colorbar(ax[0, 1].images[0], ax=ax[0, 1])
         c.set_label('$\\log_{10}(\\kappa)$')
         # Deflection angles
         lenstronomy_alpha_x, lenstronomy_alpha_y = lens_model.alpha(x_coords, y_coords, kwargs_lens)
```

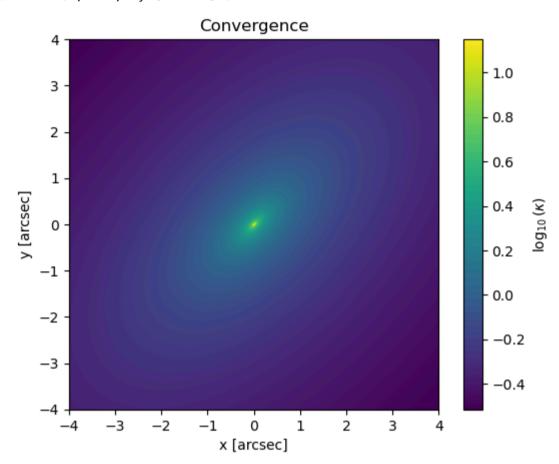
```
ax[1, 0].set_title('Our Calculation')
ax[1, 1].set_title('actual')
ax[1, 0].imshow(np.sqrt(alpha_x**2 + alpha_y**2), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid))
                                        origin='lower')
ax[1, 1].imshow(np.sqrt(lenstronomy_alpha_x**2 + lenstronomy_alpha_y**2), extent=[np.min(x_grid), np.max(x_grid), np.max(x_g
                                        origin='lower')
ax[1, 0].set_xlabel('x [arcsec]')
ax[1, 0].set_ylabel('y [arcsec]')
ax[1, 1].set_xlabel('x [arcsec]')
ax[1, 1].set_ylabel('y [arcsec]')
c = ax[1, 0].figure.colorbar(ax[1, 0].images[0], ax=ax[1, 0])
c.set_label('$|\\vec{\\alpha}|$')
c = ax[1, 1].figure.colorbar(ax[1, 1].images[0], ax=ax[1, 1])
c.set_label('$|\\vec{\\alpha}|$')
# Lensing potential
ax[2, 0].set_title('Our Calculation')
ax[2, 1].set_title('actual')
ax[2, 0].imshow(phi, extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                                        origin='lower')
ax[2, 1].imshow(lens_model.potential(x_coords, y_coords, kwargs_lens), extent=[np.min(x_grid), np.max(x_grid), np.m
                                        origin='lower')
ax[2, 0].set_xlabel('x [arcsec]')
ax[2, 0].set_ylabel('y [arcsec]')
ax[2, 1].set_xlabel('x [arcsec]')
ax[2, 1].set_ylabel('y [arcsec]')
c = ax[2, 0].figure.colorbar(ax[2, 0].images[0], ax=ax[2, 0])
c.set_label('$\\phi$')
c = ax[2, 1].figure.colorbar(ax[2, 1].images[0], ax=ax[2, 1])
c.set_label('$\\phi$')
```



We see that slowly it is converging to the analytical solution. The steeper power law dies out faster and hence the numerical integration is able to capture the behaviour of the function at the edges of the grid.

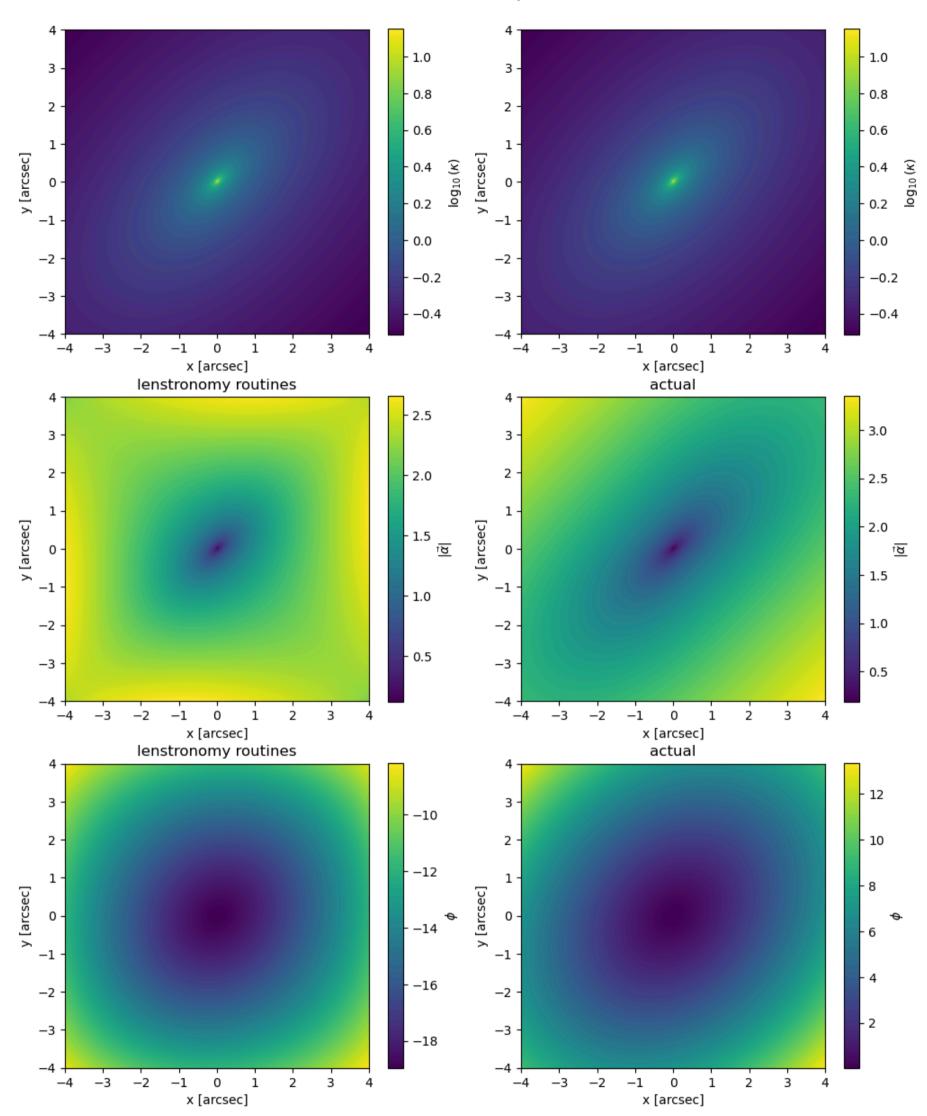
## 4. Using the built-in routines in lenstronomy

#### Out[85]: Text(0, 0.5, 'y [arcsec]')



```
In [86]: | def lensing_potential_with_fft(x_coords, y_coords, kappa_on_grid):
             # first make the grid in Fourier space
             delta_x = x_{coords}[0, 1] - x_{coords}[0, 0]
             delta_y = y_coords[1, 0] - y_coords[0, 0]
             k_x = np.fft.fftfreq(x_coords.shape[1], delta_x)
             k_y = np.fft.fftfreq(y_coords.shape[0], delta_y)
             k_x_grid, k_y_grid = np.meshgrid(k_x, k_y)
             k_{sq\_grid} = k_{x\_grid**2} + k_{y\_grid**2}
             k_sq_grid[0, 0] = 1 # avoid division by zero
             # FFT of the convergence
             kappa_fft = np.fft.fft2(kappa_on_grid)
             # lensing potential in Fourier space
             phi_fft = -2 * kappa_fft / k_sq_grid
             # inverse FFT to real space
             phi_on_grid = np.fft.ifft2(phi_fft).real
             return phi_on_grid
         def alpha_from_potential(phi_on_grid, x_coords, y_coords):
             alpha_x = np.gradient(phi_on_grid, axis=1) / (x_coords[0, 1] - x_coords[0, 0])
             alpha_y = np.gradient(phi_on_grid, axis=0) / (y_coords[1, 0] - y_coords[0, 0])
             return alpha_x, alpha_y
```

```
c = ax[0, 0].figure.colorbar(ax[0, 0].images[0], ax=ax[0, 0])
c.set_label('$\\log_{10}(\\kappa)$')
c = ax[0, 1].figure.colorbar(ax[0, 1].images[0], ax=ax[0, 1])
c.set_label('$\\log_{10}(\\kappa)$')
# Deflection angles
lenstronomy_alpha_x, lenstronomy_alpha_y = lens_model.alpha(x_coords, y_coords, kwargs_lens)
ax[1, 0].set_title('lenstronomy routines')
ax[1, 1].set_title('actual')
ax[1, 0].imshow(np.sqrt(alpha_x**2 + alpha_y**2), extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid))
                origin='lower')
ax[1, 1].imshow(np.sqrt(lenstronomy_alpha_x**2 + lenstronomy_alpha_y**2), extent=[np.min(x_grid), np.max(x_grid), n
                origin='lower')
ax[1, 0].set_xlabel('x [arcsec]')
ax[1, 0].set_ylabel('y [arcsec]')
ax[1, 1].set_xlabel('x [arcsec]')
ax[1, 1].set_ylabel('y [arcsec]')
c = ax[1, 0].figure.colorbar(ax[1, 0].images[0], ax=ax[1, 0])
c.set_label('$|\\vec{\\alpha}|$')
c = ax[1, 1].figure.colorbar(ax[1, 1].images[0], ax=ax[1, 1])
c.set_label('$|\\vec{\\alpha}|$')
# Lensing potential
ax[2, 0].set_title('lenstronomy routines')
ax[2, 1].set_title('actual')
ax[2, 0].imshow(phi, extent=[np.min(x_grid), np.max(x_grid), np.min(y_grid), np.max(y_grid)],
                origin='lower')
ax[2, 1].imshow(lens_model.potential(x_coords, y_coords, kwargs_lens), extent=[np.min(x_grid), np.max(x_grid), np.m
                origin='lower')
ax[2, 0].set_xlabel('x [arcsec]')
ax[2, 0].set_ylabel('y [arcsec]')
ax[2, 1].set_xlabel('x [arcsec]')
ax[2, 1].set_ylabel('y [arcsec]')
c = ax[2, 0].figure.colorbar(ax[2, 0].images[0], ax=ax[2, 0])
c.set_label('$\\phi$')
c = ax[2, 1].figure.colorbar(ax[2, 1].images[0], ax=ax[2, 1])
c.set_label('$\\phi$')
```



Again, there is slight deviation from the analytical solution at the edges of the grid.