Računalniška grafika

projekcije

kako imenujemo matriko, katere inverz je transponirana matrika sama?

katere linearne transformacije poznamo?

katero transformacijo izkoristimo za prehod iz levosučnega v desnosučni koordinatni sistem?

ali je zrcaljenje toga transformacija?

kako v homogenih koordinatah predstavimo vektor in kako točko?

kako iz homogenih koordinat preidemo v nehomogene koordinate?

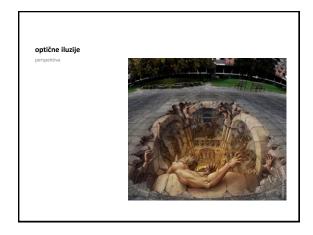
kako pridobimo nasprotno operacijo za vrtenje?

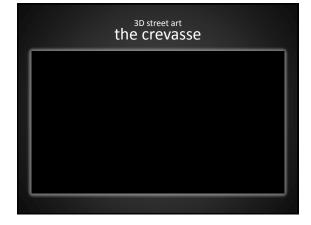
kako izvedemo vrtenje okrog poljubne točke?

kakšen mora biti vrstni red matrik pri veriženju transformacij?

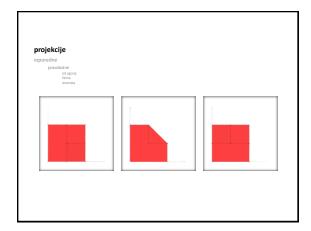
OPTIČNE ILUZIJE

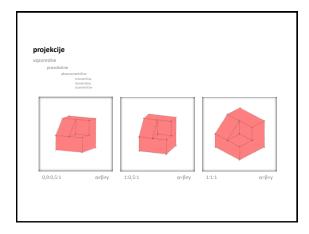
KONCEPTI?

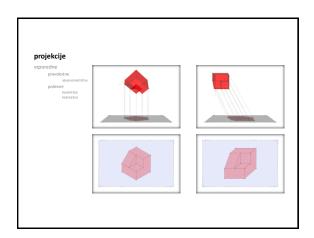


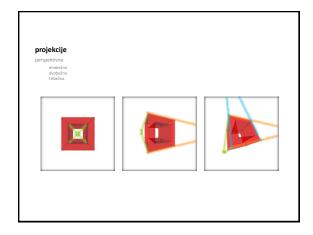


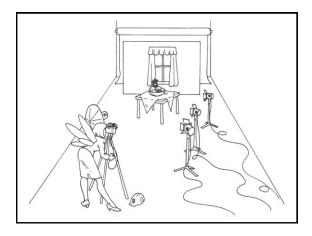
PROJEKCIJE

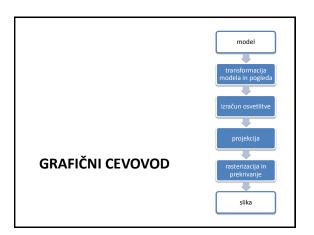


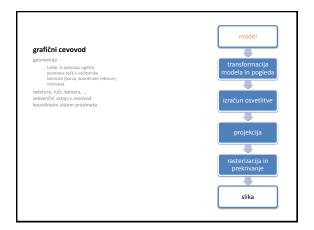


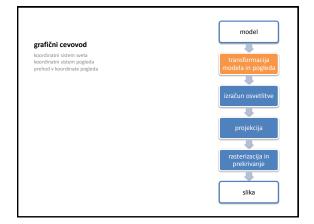


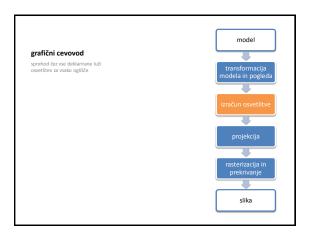


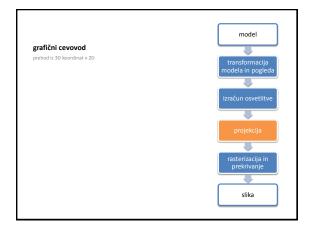


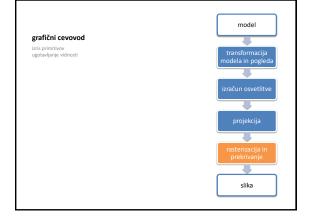




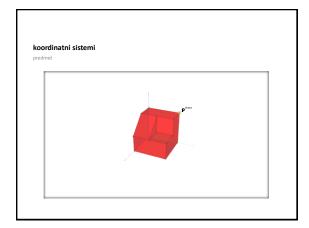


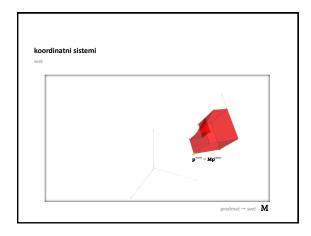


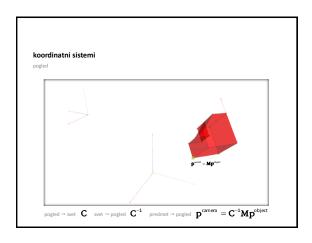


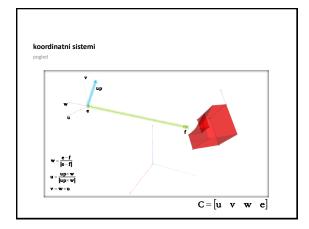


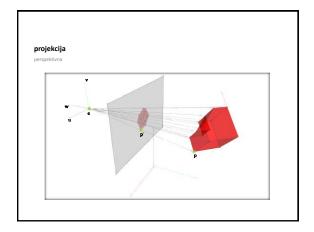
KOORDINATNI SISTEMI

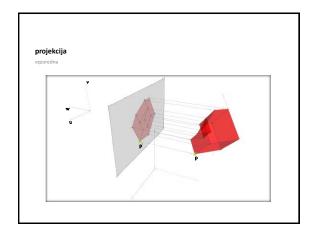




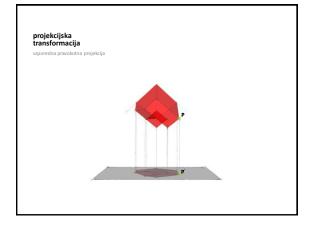


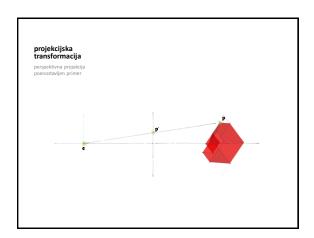


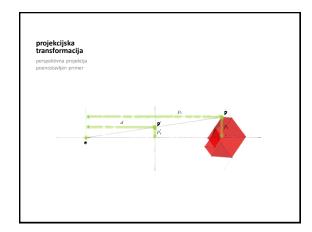


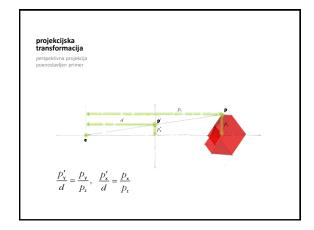


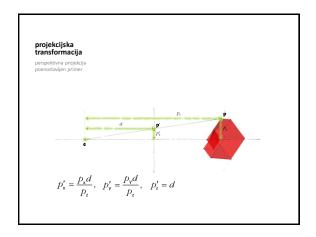
PROJEKCIJSKA TRANSFORMACIJA











projekcijska transformacija perspektivna projekcija poenostavljen primer $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1/d & 0 \end{bmatrix} \begin{bmatrix} p_x \\ p_y \\ p_z \\ p_z/d \end{bmatrix} = \begin{bmatrix} p_x d/p_z \\ p_y d/p_z \\ p_z/d \end{bmatrix} \Rightarrow \begin{bmatrix} p_x d/p_z \\ p_y d/p_z \\ d \\ 1 \end{bmatrix}$

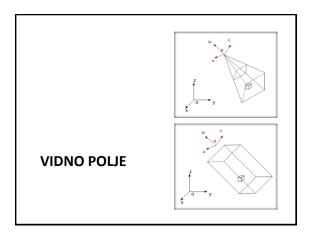
projekcijska transformacija perspektima projekcija poenostavljen primer $\begin{bmatrix} \mathbf{1} & \emptyset & \emptyset & \emptyset \\ \emptyset & \mathbf{1} & \emptyset & \emptyset \\ \emptyset & \emptyset & \mathbf{1} & \emptyset \\ \emptyset & \emptyset & -\mathbf{1}/d & \emptyset \end{bmatrix} \begin{bmatrix} p_x \\ p_y \\ p_z \\ -p_z/d \end{bmatrix} \Rightarrow \begin{bmatrix} -p_x d/p_z \\ -p_y d/p_z \\ -d \\ \mathbf{1} \end{bmatrix}$

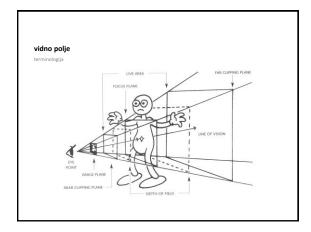


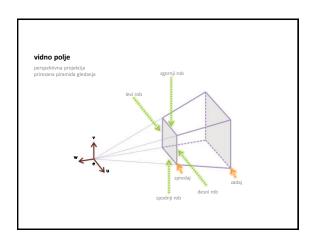


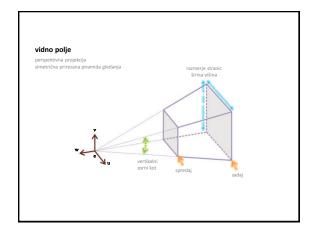


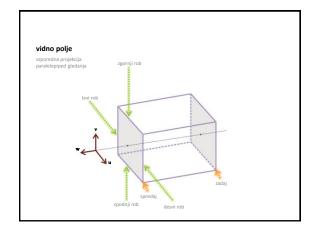


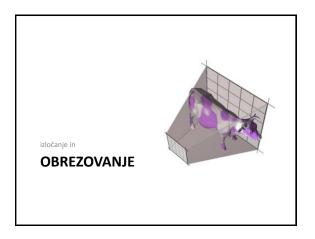


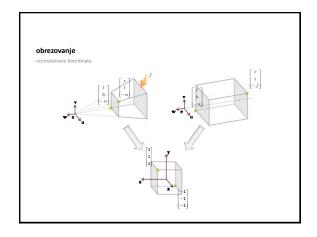












PROJEKCIJSKA MATRIKA

projekcijska matrika

perspektivna projekcija prirezana piramida gledanja

$$\mathbf{P}_{p}(l,r,t,b,n,f) = \begin{bmatrix} \frac{2*n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2*n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & -\frac{f+n}{f-n} & -\frac{2*n*f}{f-n} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

projekcijska matrika

perspektivna projekcija simetrična prirezana piramida gledanja

$$\mathbf{P}_{p}(\alpha, a, n, f) = \begin{bmatrix} \frac{1}{a - \tan \frac{\alpha}{2}} & 0 & 0 & 0 \\ 0 & \frac{1}{\tan \frac{\alpha}{2}} & 0 & 0 \\ 0 & 0 & -\frac{f + n}{f - n} & -\frac{2 * n * f}{f - n} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

projekcijska matrika

pravokotna projekcija

$$\mathbf{P}_{\mathrm{o}}(l,r,t,b,n,f) = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{l-b} & 0 & -\frac{l+b}{l-b} \\ 0 & 0 & -\frac{2}{f-n} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

projekcijska matrika

pravokotna projekcija simetrična

$$\mathbf{P}_{o}(w, h, n, f) = \begin{bmatrix} \frac{2}{w} & 0 & 0 & 0 \\ 0 & \frac{2}{h} & 0 & 0 \\ 0 & 0 & -\frac{2}{f-n} & -\frac{f+n}{f-n} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

projekcijska matrika

poševna projekcija zamik sveta z uporabo striženja pravokotna projekcija

$$\mathbf{P} = \mathbf{P}_{o}\mathbf{H}(\theta, \varphi) = \mathbf{P}_{o}\begin{bmatrix} \mathbf{1} & \mathbf{0} & \cot \theta & \mathbf{0} \\ \mathbf{0} & \mathbf{1} & \cot \varphi & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{1} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{1} \end{bmatrix}$$

matrika naprave

transformacija v koordinate naprave

$$\mathbf{D} \! \left(x_{\mathbf{0}}, x_{\mathbf{1}}, y_{\mathbf{0}}, y_{\mathbf{1}} \right) \! = \! \begin{bmatrix} \frac{x_{\mathbf{1}} - x_{\mathbf{0}}}{2} & \mathbf{0} & \mathbf{0} & \frac{x_{\mathbf{0}} + x_{\mathbf{1}}}{2} \\ \mathbf{0} & -\frac{y_{\mathbf{1}} - y_{\mathbf{0}}}{2} & \mathbf{0} & \frac{y_{\mathbf{0}} + y_{\mathbf{1}}}{2} \\ \mathbf{0} & \mathbf{0} & \frac{1}{2} & \frac{1}{2} \\ \mathbf{0} & \mathbf{0} & \mathbf{0} & \mathbf{1} \end{bmatrix}$$

transformacijska veriga

matrika modela matrika kamere projekcijska matrika matrika naprave



transformacijska veriga

matrika modela matrika kamere projekcijska matrika matrika naprave

$$\mathbf{p'} = \begin{bmatrix} p'_{\mathbf{x}} \\ p'_{\mathbf{y}} \\ p'_{\mathbf{z}} \\ w' \end{bmatrix}$$

$$\begin{array}{c} p'_{\mathbf{x}}/w', \ p'_{\mathbf{y}}/w' \\ \text{silkovni element} \end{array}$$

projekcija

vzporedne, perspektivne, taksonomija

grafični cevovod transformacija modela in pogleda, izračun osvetlitve, projekcija, rasterizacija in prekrivanje

koordinatni sistemi

predmeta, sveta, pogleda, naprave

parametri kamere očišče, koordinatni sistem pogleda, projekcijska ravnina

vidno polje perspektivna projekcija, vzporedna projekcija

projekcijska matrika perspektivna projekcija, vzporedna projekcija, normalizirane koordinate, transformacijska veriga

 $http://metal.brightcookie.com/2_draw/draw_t3/htm/draw3_2.htm$

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Akenine-Möller, Haines, Hoffman, Real-Time Rendering, 3rd Ed., ch 2,4.6

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Dunn, Parberry, 3D Math Primer for Graphics and Game Development, ch 3,9.4

Eberly, 3D Game Engine Design, ch 3.1-4

Guid, Računalniška grafika, **ch 5,6** dodatna literatura

DO PRIHODNJIČ