

# EXPECTATIONS FORMATION WITH FAT-TAILED PROCESSES: EVIDENCE AND THEORY

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NBER Behavioral Finance Meeting

April 2025

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  - **Challenge**: hard to study beliefs because rational expectations become intractable
- **This paper**: study expectations formation in the presence of “**fat**” tails
  - **Takeaway**: helps match data + parsimonious model of under & overreaction

# WHAT WE DO

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$\Rightarrow$  Allowing for **fat tails** is helpful for understanding belief formation!

## 1 Three Key Facts

Fact 1: Non-Linear Error-Revision Relationship

Fact 2: Fat Tails in the Distribution of Growth

Fact 3: Expected Growth is Non-Linear in Past Growth

## 2 Model of Expectations Formation

## 3 Additional Model Predictions

Quantitative Fit

Forecasting Experiment

Return Momentum

## 4 Conclusion

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- **Sample:** 122K observations from 2000-2023 of US and foreign firms in IBES
- **Forecasting variable:**  $g_{it} \equiv \log \text{sales}_{it} - \log \text{sales}_{it-1 \text{ year}}$ 
  - Advantages relative to EPS: larger sample + stationary
  - $g_{it}$  is adjusted for firm-specific mean and SD
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- **Forecasts:**

$$F_t g_{it+h} \equiv \log F_t \text{sales}_{it+h \text{ years}} - \log F_t \text{sales}_{it+(h-1) \text{ years}} \quad (1)$$

- $F_t$  = consensus analyst forecasts after year  $t$  FY-end announcement
- $F_t g_{it+h}$  is adjusted using same firm-specific mean and SD as  $g_{it}$
- Note: (1) ignores a Jensen's adjustment, but not quantitatively important

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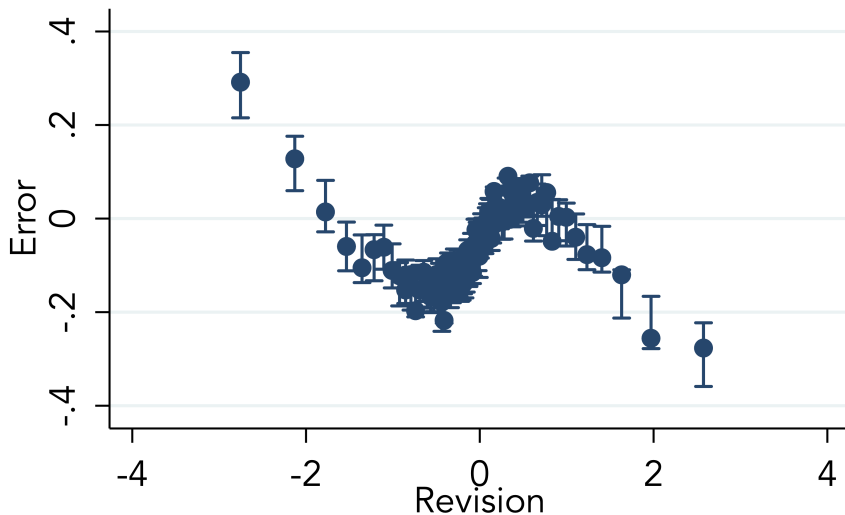
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$$\underbrace{g_{it+1} - F_t g_{it+1}}_{\text{forecast error}} = \alpha + \beta \underbrace{(F_t g_{it+1} - F_{t-1} g_{it+1})}_{\text{forecast revision}} + \epsilon_{it+1}$$

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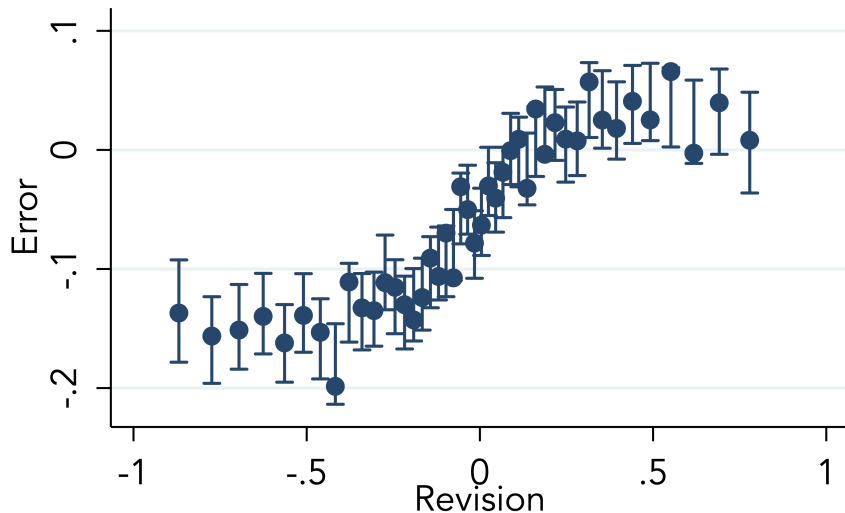
- $\beta \neq 0$  is inconsistent with rational expectations
  - Revisions are in forecasters' information set  $\Rightarrow$  should not predict errors
- $\beta > 0 \Rightarrow$  revisions do not update “enough”  $\Rightarrow$  **underreaction** Bouchaud et al. 19
- $\beta < 0 \Rightarrow$  revisions update “too much”  $\Rightarrow$  **overreaction** Bordalo et al. 19
- Now a standard way of characterizing deviations from RE across datasets

# FACT 1: NON-LINEAR ERROR-REVISION RELATIONSHIP



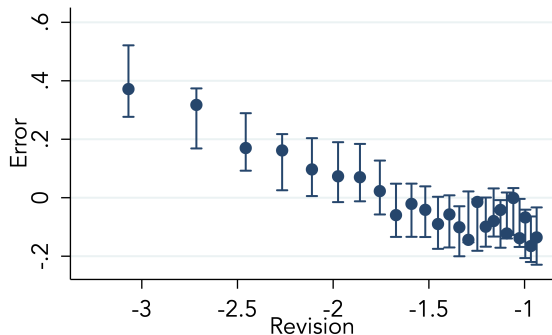
- Forecasts underreact **and** overreact within **same** variable and horizon

# UNDERREACTION IN THE BULK OF THE DISTRIBUTION...



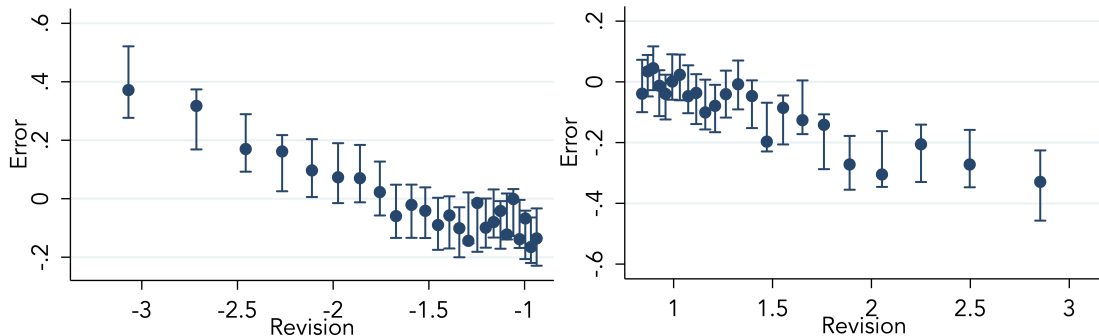
- Between **10-90%** of revisions, error-revision slope is **positive** Bouchaud et al. 19

## ... BUT OVERREACTION IN THE TAILS!



- Between **0-10%** of revisions, error-revision slope is **negative**

## ... BUT OVERREACTION IN THE TAILS!



- Between **0-10%** and **90-100%** of revisions, error-revision slope is **negative**



- ① Not driven by within-firm adjustment: holds with **raw growth**
- ② Does not reflect omitted Jensen's term: holds with **percent growth**
- ③ Does not arise because of aggregate **time-varying volatility**
- ④ Not driven by aggregation: present in **individual** forecasts
- ⑤ Does not reflect sample: similar for both US and foreign firms

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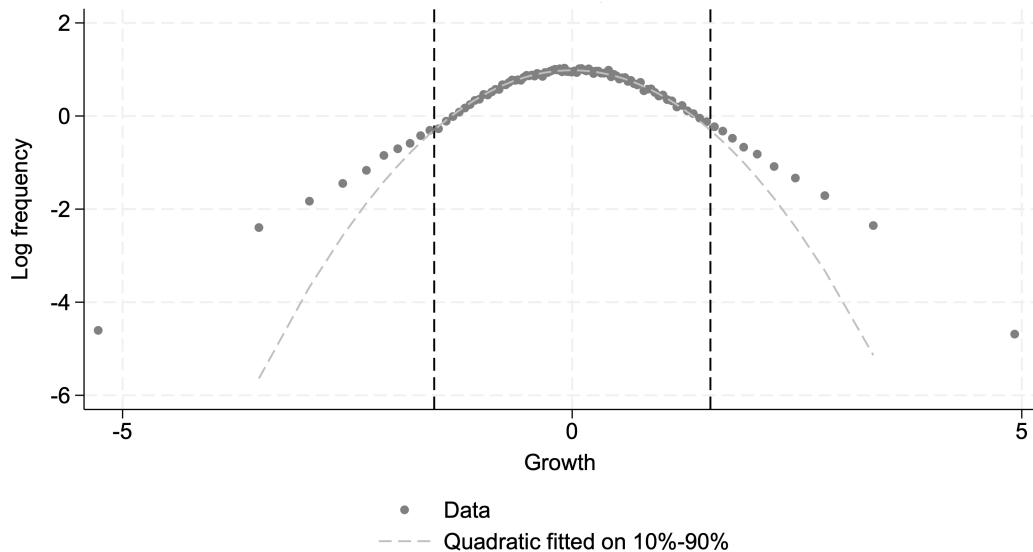
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# TAILS OF $g_{it}$ ARE FATTER THAN GAUSSIAN

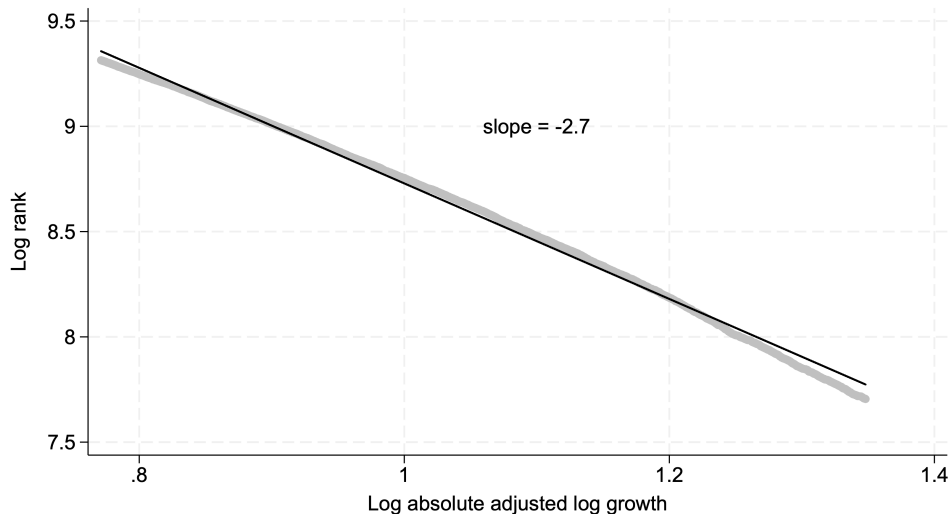


# TAIL BEHAVIOR IN TOP DECILES IS APPROXIMATELY A POWER LAW

Power Law :  $\log P(|g_{it}| > x) = -\nu \log x + \text{constant}$

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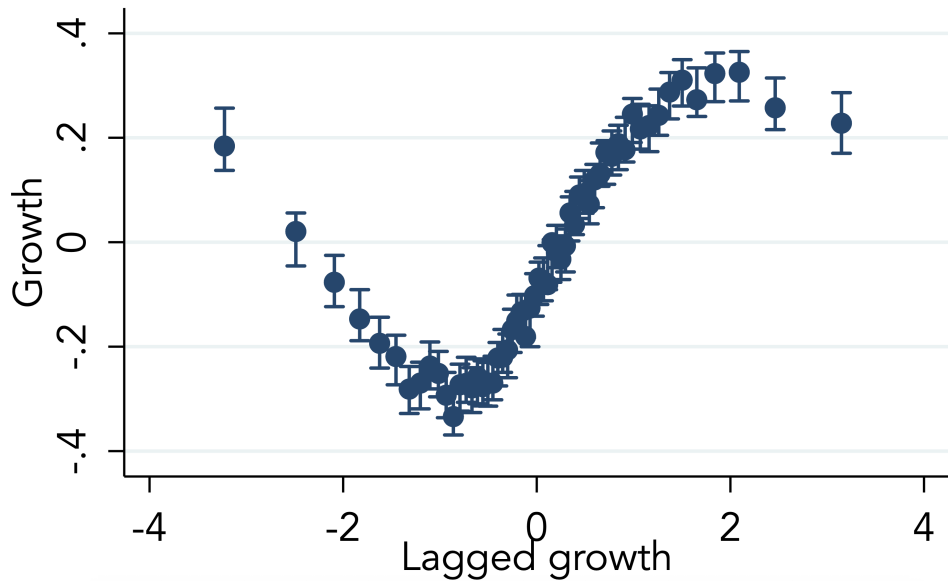
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### FACT 3: $E(g_{it}|g_{it-1})$ IS NON-LINEAR



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$$g_{t+1} = g_{t+1}^* + \sigma_\epsilon \epsilon_{t+1} \quad \epsilon_t \sim f(\cdot)$$

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- $g_t$  is a combination of persistent & transitory processes Bansal-Yaron 04, Lettau-Wachter 07
  - $g_t^*$  = **unobservable** persistent latent state
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- Remarks:
  - If  $\epsilon_t$  was Gaussian, rational expectation would be the Kalman filter
  - **Key**: tail parameter in  $u_t$  smaller than  $\epsilon_t$ , otherwise inconsistent with Fact 3

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- In bulk of distribution,  $g_t \approx \text{Gaussian} \Rightarrow \log h(g_t) \approx -\frac{g_t^2}{2\sigma_g^2} + \text{constant}$
- **Intuition**: moderate values of  $g_t$  likely reflect  $g_t^* \Rightarrow$  likely persistent

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- Overreaction in tails + unbiased on average  $\Rightarrow$  some underreaction  $\Rightarrow$  **Fact 1**
- Note: forecasts overreact to **weak** + underreact to **strong** signals Augenblick et al. 24
  - $V(g_{t+1}|g_t)$  is **higher** than  $V(g_t)$  in bulk and **lower** in tails

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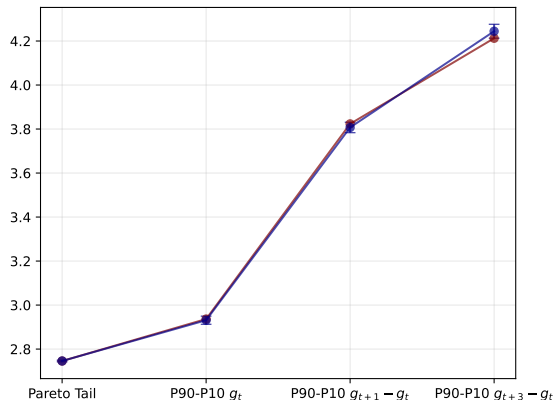
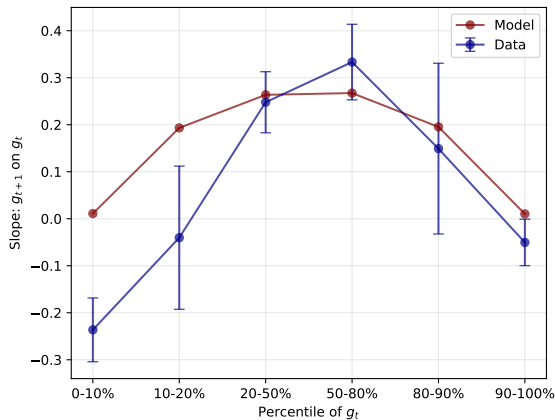
Return Momentum

## 4 Conclusion

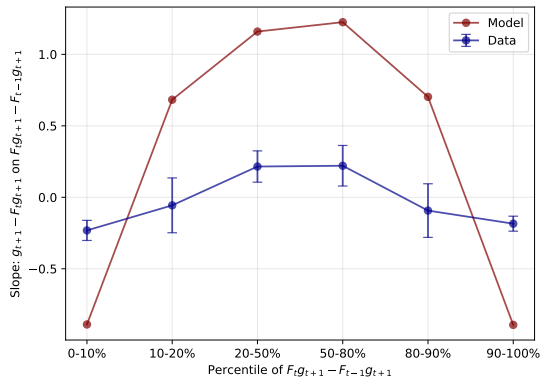
- Estimate DGP parameters using SMM by matching [Facts 2](#) and [3](#)
  - Assume  $\epsilon \sim t$ -distribution with  $\nu$  degrees of freedom

# MODEL FIT: DGP

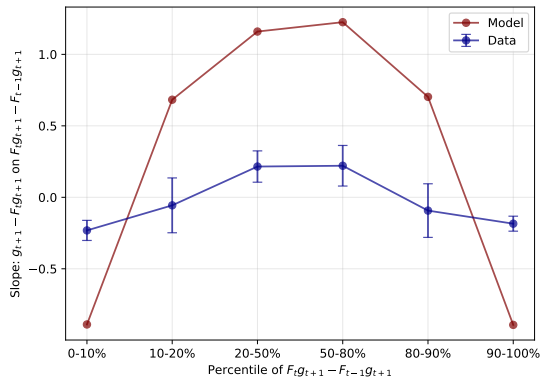
- Estimate DGP parameters using SMM by matching [Facts 2](#) and [3](#)
  - Assume  $\epsilon \sim t$ -distribution with  $\nu$  degrees of freedom
- Parameter estimates:  $\rho = 0.53$ ,  $\nu = 2.53$ ,  $\sigma_u = 0.63$ ,  $\sigma_\epsilon = 1.33$



# MODEL FIT: BELIEFS



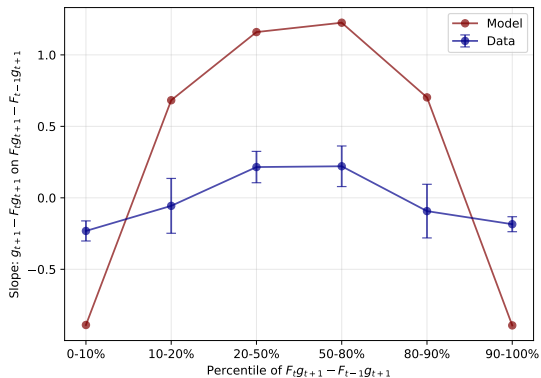
# MODEL FIT: BELIEFS



- Given DGP, model generates Fact 1 **qualitatively**, but not **quantitatively**



# MODEL FIT: BELIEFS

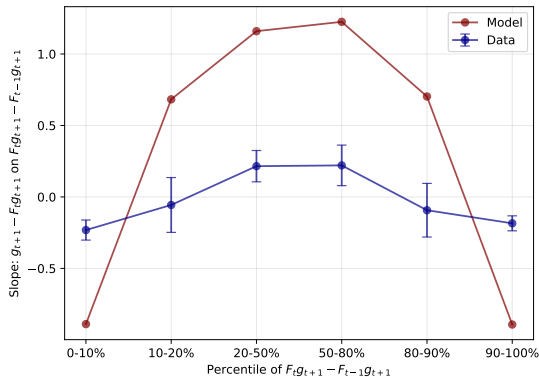


- Allow **anchoring** to RE:  $F_t^\lambda g_{t+h} = \lambda F_t g_{t+h} + \underbrace{(1 - \lambda) E_t g_{t+h}}_{\text{particle filtering}}$

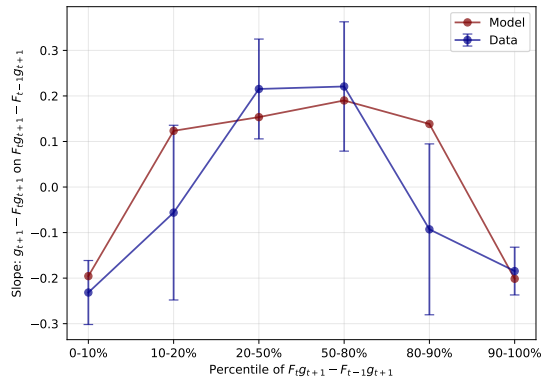
Fuster et al. 10, Gabaix 19

# MODEL FIT: BELIEFS

Kalman Filter:  $\lambda = 1$



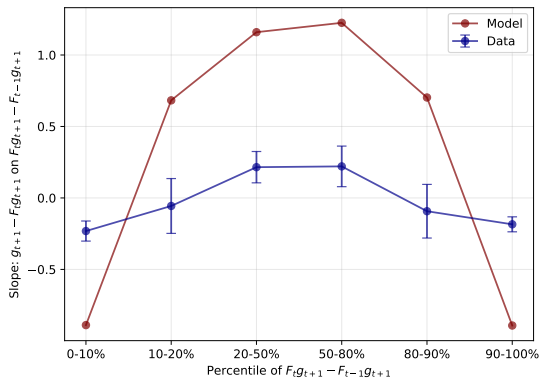
Estimated  $\lambda = 0.29$



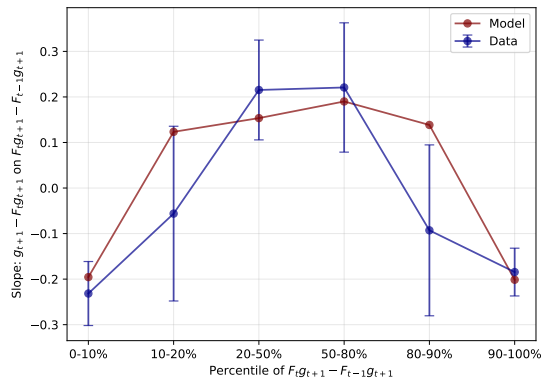
- Allow **anchoring** to RE:  $F_t^\lambda g_{t+h} = \lambda F_t g_{t+h} + (1 - \lambda) E_t g_{t+h}$  Fuster et al. 10, Gabaix 19
- $\lambda = 0.29 \Rightarrow$  replicate **Fact 1**

# MODEL FIT: BELIEFS

Kalman Filter:  $\lambda = 1$



Estimated  $\lambda = 0.29$



- Allow **anchoring** to RE:  $F_t^\lambda g_{t+h} = \lambda F_t g_{t+h} + (1 - \lambda) E_t g_{t+h}$  Fuster et al. 10, Gabaix 19
- $\lambda = 0.29 \Rightarrow$  replicate **Fact 1**, but accuracy loss is small: **0.1%** of MSE

## 1 Three Key Facts

Fact 1: Non-Linear Error-Revision Relationship

Fact 2: Fat Tails in the Distribution of Growth

Fact 3: Expected Growth is Non-Linear in Past Growth

## 2 Model of Expectations Formation

## 3 Additional Model Predictions

Quantitative Fit

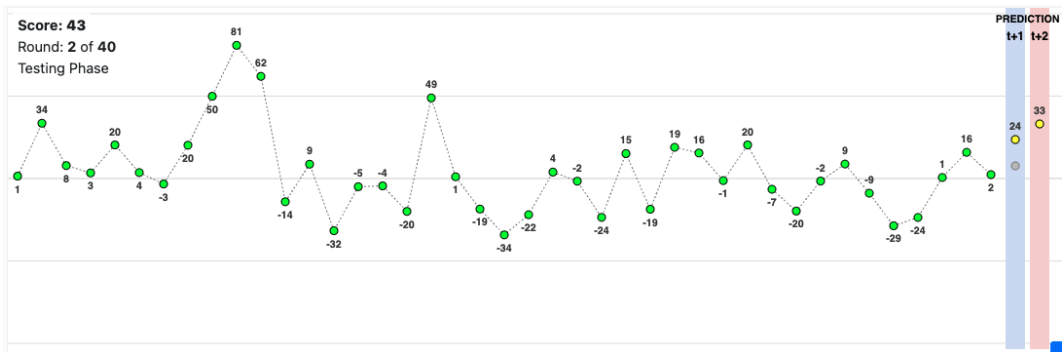
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# EXPERIMENTAL DESIGN

- Design follows Afrouzi et al. 23: participants make one and two-period forecasts
- 201 participants make 40 forecasts  $\Rightarrow$  8K observations possibly scale up?
- DGPs: 1. rescaled estimated DGP, 2. Gaussian AR1 with  $\rho = 0.2$  Afrouzi et al. 23



# FAT TAILS CREATE NON-LINEAR ERROR-REVISION RELATIONSHIP

	Dependent Variable: Error	
	Estimated DGP (1)	Gaussian AR1
Revision	-0.40*** (0.02)	
Revision $\times$ Bottom 20%		
Revision $\times$ Top 20%		
Revision $\times$ Top & Bottom 20%		
Constant	✓	
Clustering by Participant	✓	
Number of Observations	7839	

# FAT TAILS CREATE NON-LINEAR ERROR-REVISION RELATIONSHIP

	Dependent Variable: Error	
	Estimated DGP (1)	Gaussian AR1 (4)
Revision	-0.40*** (0.02)	-0.44*** (0.02)
Revision $\times$ Bottom 20%		
Revision $\times$ Top 20%		
Revision $\times$ Top & Bottom 20%		
Constant	✓	✓
Clustering by Participant	✓	✓
Number of Observations	7839	5421

# FAT TAILS CREATE NON-LINEAR ERROR-REVISION RELATIONSHIP

	Dependent Variable: Error		
	Estimated DGP		Gaussian AR1
	(1)	(2)	(4)
Revision	-0.40*** (0.02)	-0.28*** (0.06)	-0.44*** (0.02)
Revision $\times$ Bottom 20%		-0.27*** (0.09)	
Revision $\times$ Top 20%		-0.11 (0.08)	
Revision $\times$ Top & Bottom 20%			
Constant	✓	✓	✓
Clustering by Participant	✓	✓	✓
Number of Observations	7839	7839	5421



# FAT TAILS CREATE NON-LINEAR ERROR-REVISION RELATIONSHIP

	Dependent Variable: Error			
	Estimated DGP			Gaussian AR1
	(1)	(2)	(3)	(4)
Revision	-0.40*** (0.02)	-0.28*** (0.06)	-0.28*** (0.06)	-0.44*** (0.02)
Revision $\times$ Bottom 20%		-0.27*** (0.09)		
Revision $\times$ Top 20%		-0.11 (0.08)		
Revision $\times$ Top & Bottom 20%			-0.18** (0.08)	
Constant	✓	✓	✓	✓
Clustering by Participant	✓	✓	✓	✓
Number of Observations	7839	7839	7839	5421

# FAT TAILS CREATE NON-LINEAR ERROR-REVISION RELATIONSHIP

	Dependent Variable: Error					
	Estimated DGP			Gaussian AR1		
	(1)	(2)	(3)	(4)	(5)	(6)
Revision	-0.40*** (0.02)	-0.28*** (0.06)	-0.28*** (0.06)	-0.44*** (0.02)	-0.42*** (0.06)	-0.42*** (0.06)
Revision $\times$ Bottom 20%		-0.27*** (0.09)			-0.12 (0.09)	
Revision $\times$ Top 20%		-0.11 (0.08)			-0.07 (0.07)	
Revision $\times$ Top & Bottom 20%			-0.18** (0.08)			-0.09 (0.07)
Constant	✓	✓	✓	✓	✓	✓
Clustering by Participant	✓	✓	✓	✓	✓	✓
Number of Observations	7839	7839	7839	5421	5421	5421

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# POSITIVE MOMENTUM IN BULK + MEAN-REVERSION IN TAILS

- Campbell 91 + assume constant  $F_t(r_{t+k})$  & earnings growth $_t = \gamma \times g_t$

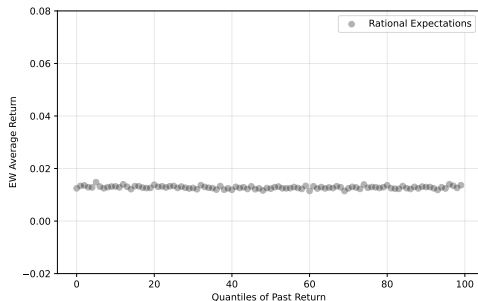
$$\Rightarrow r_{t+1} = \bar{r} + \gamma (F_{t+1} - F_t) \sum_{k=0}^{\infty} c^k g_{t+1+k}$$

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## Model

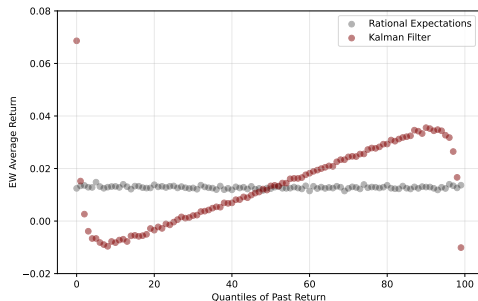


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## Model

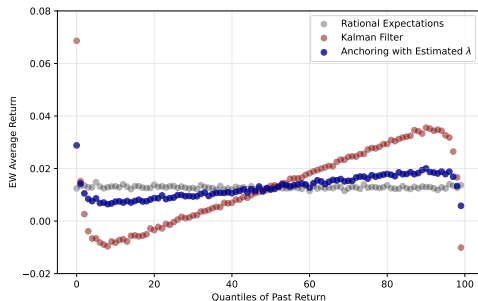


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## Model

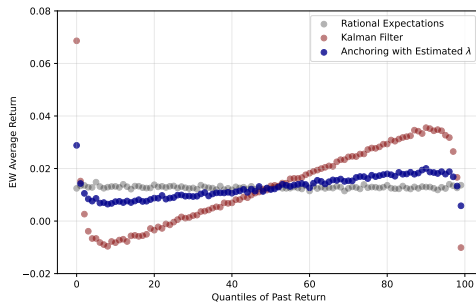


# POSITIVE MOMENTUM IN BULK + MEAN-REVERSION IN TAILS

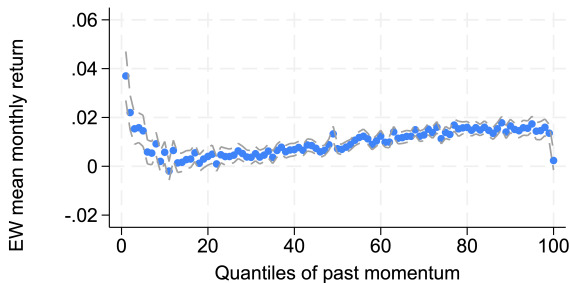
- Campbell 91 + assume constant  $F_t(r_{t+k})$  & earnings growth $_t = \gamma \times g_t$

$$\Rightarrow r_{t+1} = \bar{r} + \gamma (F_{t+1} - F_t) \sum_{k=0}^{\infty} c^k g_{t+1+k}$$

**Model**



**Data: Below Median Market Cap**





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## 4 Conclusion

- Main fact: forecast errors are **non-linear** in forecast revisions
  - Underreaction in the bulk of the distribution, overreaction in the tails
- One deviation from RE can explain this: **ignoring fat tails**
  - **Intuition**: extreme realizations are less persistent than forecasters realize
  - Provides a parsimonious model of under **and** overreaction **within a DGP**
  - Also consistent with evidence from experiments and asset prices
- Broader takeaways:
  - 1 **Non-Gaussian models of DGP** are helpful for understanding belief formation
  - 2 **Combining** experiments + surveys useful for assessing important features

# THANK YOU!

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