

## **ECEN 689-605/700 Dependable Learning Systems Fall 2018**

### **Homework 1 Solution**

1. Value iteration  
5 iterations  $V(s_1)=0.4398$ ,  $V(s_2)=0.5126$ ,  $V(s_3)=0.4357$ . For all states, actions are  $a_1$  according to the policy.
2. Gauss-Seidel  
5 iterations  $V(s_1)=0.4506$ ,  $V(s_2)=0.5242$ ,  $V(s_3)=0.4483$ . For all states, actions are  $a_1$  according to the policy.
3. Dynamic programming  
 $V(s_1)=0.9357$ ,  $V(s_2)=1.0022$ ,  $V(s_3)=0.9210$ . For all states, actions are  $a_1$  according to the policy.

Due to different setup, you may get different results. But they should be close to the above. Also, the values from Gauss-Seidel should be greater than those from value iteration. Dynamic programming should obtain the largest values, as discount factor is not used.