

1 Factors affecting inferences on natural mortality and
2 associated environmental effects in state-space
3 age-structured assessment models

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19

20 **Abstract**

21 Treatment of natural mortality is a major consideration in assessment models and state-space
22 approaches allow estimation of temporal variation in this mortality rate as well as effects of
23 specific covariates. However, there has been no investigation of the reliability of inferences
24 made regarding natural mortality, associated covariate effects, and important assessment
25 output from state-space assessment models. We conducted a large-scale simulation study
26 that considers models fit to data simulated from operating models with alternative assump-
27 tions defined by several factors, but we focus on scenarios where there is temporal contrast
28 in fishing pressure and lower uncertainty in population observations (age composition and
29 indices of abundance). We fit estimating models to simulated observations with alternative
30 assumptions on inclusion of environmental effects, estimation of the median natural mortal-
31 ity rate, and the source of temporal variability in the population demography. Our results
32 suggest that estimation of environmental effects on natural mortality is possible and reliable
33 even when the population process error source was misspecified in some scenarios with lower
34 uncertainty in covariate observations, and higher covariate temporal variability.

35 **keywords:** state-space assessment models, time-varying natural mortality, bias, AIC

³⁶ Introduction

³⁷ State-space population models are now used widely for fisheries stock assessment in Europe,
³⁸ the United States, and Canada (Nielsen and Berg, 2014; Cadigan, 2016; Pedersen and Berg,
³⁹ 2017; Stock and Miller, 2021). Because application of these methods are considered best
⁴⁰ practice and recommended for the next generation of stock assessment models (Hoyle et al.,
⁴¹ 2022; Punt, 2023), it is expected their use will only grow globally. An appeal of state-
⁴² space models lies in their separation of sources of biological and measurement variability by
⁴³ treating latent population characteristics as statistical time series with periodic observations
⁴⁴ measured with error. Through advances in computational capacity, we can use sophisticated
⁴⁵ numerical approaches to estimate model parameters as mixed effects (Thorson and Minto,
⁴⁶ 2015; Kristensen et al., 2016).

⁴⁷ State-space stock assessment models, with non-linear functions of latent processes and nu-
⁴⁸ merous observation types with different probability distribution assumptions represent one
⁴⁹ of most complex classes of state-space models. The literature on the effects of various factors
⁵⁰ on reliability of inferences from state-space assessment models is growing (Li et al., 2024;
⁵¹ Miller et al., In reviewa). The importance of contrast in population size and fishing mortality
⁵² (F) and quality of data used to fit assessment models including the state-space variety is
⁵³ known (Magnusson and Hilborn, 2007; Miller et al., In reviewa). Furthermore, estimation
⁵⁴ of natural mortality (M), and even temporal variability in M is possible in many scenarios
⁵⁵ (Lee et al., 2011; Cadigan, 2016; Miller and Hyun, 2018; Miller et al., In reviewa).

⁵⁶ The effects of temporal variation in recruitment via undefined or explicit environmental
⁵⁷ factors have been extensively investigated in both traditional assessment models and state
⁵⁸ space models (Myers, 1998; Haltuch and Punt, 2011; Johnson et al., 2016; Miller et al., 2016).
⁵⁹ Reliability of estimating environmental and spawning biomass effects on recruitment in state-
⁶⁰ space assessment models requires a combination of strong effects, good age composition data
⁶¹ quality, contrast in the environmental covariate and lower recruitment variability (Britten

62 et al., In review; Miller et al., In reviewa).

63 A critical aspect of fisheries assessment models and their use in management is short-term
64 projections that are used to determine catch advice. While understanding drivers of re-
65 cruitment is important particularly for subsequent effects on reference points, recruitment
66 in short-term projections typically has little impact on the exploitable biomass in the first
67 few projection years. However, assumptions for M have immediate and larger effects on
68 projected biomass because they affect the abundances at older age classes at the end of the
69 data time series that constitute spawning biomass and catch (Brodziak et al., 2008; Stock
70 et al., 2021).

71 Because of the effects of M on both biological reference points and short term projections,
72 better understanding sources of variation in M would provide more accurate estimation of
73 abundance and productivity and therefore improved management. Temporal variation in M
74 is less studied than recruitment, but its importance for explaining variability in observations
75 has been demonstrated in state-space assessment models for Atlantic cod and yellowtail
76 flounder (Cadigan, 2016; Stock et al., 2021). Deriso et al. (2008) also demonstrated the
77 importance of several factors affecting M for Pacific herring.

78 Assessment models could include temporal variation in many aspects of population dynamics
79 or how observations are related to the population. For example the Woods Hole Assessment
80 Model (WHAM) can include process errors treated as random effects for transition in cohorts
81 over time (hereafter referred to as apparent survival), catchability for indices of abundance,
82 selectivity of fishing fleets or indices, movement between regions, or in M (Stock and Miller,
83 2021; Miller et al., In reviewb). However, misspecified temporal population process errors
84 could lead to biased population and stock status estimation, and, therefore, poor fisheries
85 management decisions (Legault and Palmer, 2016; Szuwalski et al., 2018). Studies of the
86 reliability of inferences regarding the presence of temporal variability in M are limited. Miller
87 et al. (In reviewa) found AIC could accurately distinguish process errors in apparent survival,

88 but not for those specifically due to M except when uncertainty in population observations
89 (indices, catch and age composition) was low and there was greater temporal variation in M .
90 In their simulation studies looking at models with multiple sources of process error, Li et al.
91 (2024) found including more sources of process error than existed in the operating model
92 was a better model-building approach than excluding them a priori.

93 Here we conduct a simulation study with operating models (OMs) varying by degree of ob-
94 servation error uncertainty, sources of process error, fishing history, temporal variation in
95 environmental covariates, and magnitude of the effect of the covariate on M . The simu-
96 lated observations from these OMs are fitted with estimating models that make alternative
97 assumptions for sources of process error, and whether median M and covariate effects are
98 estimated. We evaluate the effects of these factors on convergence of fitted models, whether
99 Akaike's information criterion (AIC) can determine the correct source of process error and
100 correct assumption about covariate effects on M , and the accuracy for estimators of relevant
101 parameters and stock size and harvest rates derived from the assessment model.

102 Methods

103 Our analyses used the Woods Hole Assessment Model (WHAM) to construct both OMs
104 and estimation models (EMs) (Miller and Stock, 2020; Stock and Miller, 2021; Miller et al.,
105 In reviewb). The WHAM package has been used extensively to configure OMs and EMs
106 for several other simulation studies (Stock et al., 2021; Legault et al., 2023; Li et al., 2024;
107 Britten et al., In review; Li et al., In reviewa) and is used to assess many commercially
108 important stocks in the Northeast U.S. (e.g., NEFSC, 2022a,b, 2024). We used version
109 1.0.6.9000, commit 77bbd94 to generate all results.

110 We completed a simulation study with 288 operating models. The factors defining the con-
111 figuration of each operating model, described in detail in subsequent sections, include source
112 of population process error (3 levels), index and catch observation uncertainty (2 levels),

113 environmental covariate uncertainty (2 levels), temporal variation in the latent environmen-
114 tal covariate (4 levels), and fishing history (2 levels). We simulated 100 data sets for each
115 operating model that included simulations of process errors.

116 For each simulated data set we fit a set of 12 EMs. The factors that distinguish the estimating
117 models, also described in detail below, include source of population process error type (3
118 levels) whether (median) M was estimated or assumed known (2 levels), and whether the
119 effect of the environmental covariate on M was estimated or not (2 levels).

120 The sources of population process error that were used in the OMs or assumed in the EMs
121 were on recruitment only (R), recruitment and apparent survival (R+S), or recruitment
122 and M (R+M). We did not use the log-normal bias-correction feature for process errors or
123 observations described by Stock and Miller (2021) for OMs and EMs (Li et al., In reviewb).

124 Simulations were all carried out on the University of Massachusetts Green High-Performance
125 Computing Cluster. Code for completing the simulations and summarizing results can be
126 found at https://github.com/timjmiller/SSRTWG/ecov_study/mortality.

127 Operating models

128 Environmental covariate

129 In the WHAM model, environmental covariates are assumed to be described as state-space
130 processes with annual observations of the true latent covariate (Miller et al., 2016; Stock
131 and Miller, 2021). In our simulations, the latent covariate is assumed to be a stationary first
132 order autoregressive (AR1) process

$$X_y | X_{y-1} \sim N \left(\mu_E (1 - \rho_E) + \rho_E X_{y-1}, (1 - \rho_E^2) \sigma_E^2 \right)$$

133 with marginal mean $\mu_E = 0$ and variance σ_E^2 . The four configurations of the latent environ-
134 mental covariate in the operating models assume one of two values for the marginal standard

¹³⁵ deviation $\sigma_E \in \{0.1, 0.5\}$ and for the autocorrelation parameter $\rho_E \in \{0, 0.5\}$.

¹³⁶ The observations of the latent environmental covariate are assumed to be unbiased and
¹³⁷ Gaussian

$$x_y | X_y \sim N(X_y, \sigma_e^2)$$

¹³⁸ The standard deviation of the environmental observations in the operating models is one of
¹³⁹ two values $\sigma_e \in \{0.1, 0.5\}$. Figure S2 provides example simulations of the latent covariate
¹⁴⁰ and observations under the alternative configurations.

¹⁴¹ Population

¹⁴² Many of the characteristics of the population biology and structure including the age classes
¹⁴³ (10 age classes (ages 1 to 10+)), time span (40 years), maturity (Figure S1, top left), growth
¹⁴⁴ (Figure S1, top right), time of spawning (1/4 of the year), and recruitment (Figure S1,
¹⁴⁵ bottom right) are identical to Miller et al. (In reviewa). The maturity at age is a logistic
¹⁴⁶ function with age at 50% maturity ($a_{50} = 2.89$) and slope = 0.88 and weight at age is
¹⁴⁷ derived from a von Beralanffy growth function where $t_0 = 0$, $L_\infty = 85$, and $k = 0.3$, and a
¹⁴⁸ length-weight relationship

$$W_a = \theta_1 L_a^{\theta_2}$$

¹⁴⁹ where $\theta_1 = e^{-12.1}$ and $\theta_2 = 3.2$.

¹⁵⁰ The general model for M in year y is a log-linear function of both covariate effects X_y and
¹⁵¹ process errors $\varepsilon_{M,y}$ and a parameter β_M that defines median M

$$\log M_y = \beta_M + \beta_E X_y + \varepsilon_{M,y}$$

¹⁵² where the process errors are modeled as random effects that may, in general, be autocorre-

153 lated normal random variables

$$\varepsilon_{M,y} | \varepsilon_{M,y-1} \sim N(\varepsilon_{M,y-1}, (1 - \rho_M^2) \sigma_M^2)$$

154 (Stock and Miller, 2021), but we assume $\rho_M = 0$ in our R+M OMs. We assume the median
155 M rate $e^{\beta_M} = 0.2$ is constant across ages. For R and R+S OMs and EMs, $\varepsilon_{M,y} = 0$. For
156 all R+M OMs, we assume the same standard deviation $\sigma_M = 0.3$, which is estimated in
157 the R+M EMs. The covariate effect is one of 3 alternative values in the operating models,
158 $\beta_E \in \{0, 0.25, 0.5\}$. The parameters defining the simulated covariate time series, size of the
159 covariate effect, and any M random effects result in a range of different levels of variation
160 in annual values (Figure S3).

161 We assumed expected recruitment each year is from a Beverton-Holt stock-recruit relation-
162 ship (SRR)

$$R_y = \frac{aSSB_{y-1}}{1 + bSSB_{y-1}}.$$

163 All biological inputs to calculations of spawning biomass per recruit (i.e., weight, maturity,
164 and M at age) are constant in the R and R+S OMs without covariate effects on M . There-
165 fore, steepness and equilibrium unfished recruitment are also constant over the time period
166 for those OMs (Miller and Brooks, 2021). As in Miller et al. (In reviewa), our assumed bio-
167 logical inputs and selectivity (defined below) with constant M result in equilibrium F that
168 reduces spawning biomass per recruit to 40% of the unfished level is $F_{40\%} = 0.348$. With
169 an assumed unfished recruitment of $R_0 = e^{10}$, setting $F_{MSY} = F_{40\%}$ results in a steepness of
170 0.69 and $a = 0.60$ and $b = 2.4 \times 10^{-5}$. For R+M OMs and all OMs with covariate effects on
171 M , steepness is not constant, but we used the same a and b parameters as other operating
172 models which equates to a steepness and R_0 at the median of the time series models for M
173 and the covariate.

174 We also used the same two fishing scenarios as Miller et al. (In reviewa) for OMs. In the first
175 scenario, the stock experiences overfishing at $2.5F_{MSY}$ for the first 20 years followed by fishing

176 at F_{MSY} for the last 20 years (denoted $2.5F_{\text{MSY}} \rightarrow F_{\text{MSY}}$). In the second scenario, the stock
177 is fished at F_{MSY} for the entire time period (40 years). The magnitude of the overfishing
178 assumptions is intended to reflect estimates of overfishing for Northeast US groundfish stocks
179 from Wiedenmann et al. (2019).

180 We configured all R, R+S, and R+M OMs with uncorrelated random effects on recruitment
181 with standard deviation on log(recruitment) $\sigma_R = 0.5$. This same assumption was used by
182 Miller et al. (In reviewa) for R+M OMs and other OMs with fishery selectivity and index
183 catchability process errors. For R+S OMs, apparent survival process errors were uncorrelated
184 with $\sigma_{2+} = 0.3$.

185 Catch and index observations

186 We define the generation of observations of aggregate (total combined across ages) catch and
187 indices, and corresponding age composition identical to Miller et al. (In reviewa). There is a
188 single fleet operating year round for catch observations with logistic selectivity for the fleet
189 with $a_{50} = 5$ and slope = 1 (Figure S1, bottom left). Observations are generated for all 40
190 years of the model. There are two index time series intended to represent fishery-independent
191 surveys occurring in the spring (0.25 way through the year) and the fall (0.75 way through
192 the year). Catchability of both surveys are assumed to be 0.1. We assumed catch and index
193 age composition observations are generated from a logistic-normal distribution where errors
194 on the multivariate normal scale are independent. The standard deviation parameter is also
195 constant across ages.

196 Standard deviation for log-aggregate catch was 0.1. There were two levels of observation error
197 variance for aggregate indices and age composition for both indices and fleet catch. A low
198 uncertainty specification assumed standard deviation of both series of log-aggregate index
199 observations was 0.1 and the standard deviation of the logistic-normal for age composition
200 observations was 0.3. In the high uncertainty specification the standard deviation for log-

201 aggregate indices was 0.4 and that for the age composition observations was 1.5. For all
202 estimating models, the standard deviation for log-aggregate observations was assumed known
203 at the true value whereas that for the logistic-normal age composition observations was
204 estimated.

205 **Estimating models**

206 Estimating models were fit to each of 100 simulated data sets from each operating model.
207 There were three factors defining the configuration of each estimating model: 1) whether β_M
208 was estimated or assumed known, 2) whether an environmental effect β_E was estimated or
209 not, and 3) whether the process errors were assumed on recruitment only (R), recruitment
210 and survival (R+S), or recruitment and M (R+M).

211 The configuration of the process errors in the estimating models generally matched the
212 corresponding options in the operating models. For example, uncorrelated R+S was assumed
213 for both the estimating and operating model. However, R+M EMs did not assume M random
214 effects were uncorrelated (ρ_M was estimated). The environmental covariate observations
215 were included in all estimation models, whether effects on M were estimated or not, to
216 ensure comparability of AIC. All fixed effects parameters for selectivity, catchability, fully-
217 selected F , mean recruitment, initial abundance at age, and variances for logistic-normal
218 age composition distributions were estimated. Any process error variance parameters for
219 recruitment, survival, and M were also estimated. The observation error variance of the
220 environmental observations and aggregate catch and indices were all assumed known at the
221 true values.

222 **Performance measures**

223 **EM convergence**

224 We measured the frequency of convergence when fitting each EM to the simulated data
225 sets for each OM. There are various ways to assess convergence of the fit (e.g., Carvalho
226 et al., 2021), but we defined successful convergence as the Hessian of the marginal log-
227 likelihood being invertible and providing variance estimates for the fixed effects parameters as
228 recommended by Miller et al. (In reviewa). We calculated 95% confidence intervals (CIs) for
229 probability of convergence using the Clopper-Pearson exact method (Clopper and Pearson,
230 1934; Thulin, 2014).

231 **AIC for model selection**

232 We measured the frequency of correct model selection using marginal AIC. For a given
233 operating model the set of models that were considered all made the same assumptions on
234 whether or not to estimate β_M or it is assumed at the true value. For model m , the marginal
235 AIC is a function of the marginal log-likelihood maximized with respect to the fixed effects
236 in the model $\boldsymbol{\theta}$ and the number of fixed effects $n(\boldsymbol{\theta})$ estimated,

$$\text{AIC}_m = -2 [\text{argmax}_{\boldsymbol{\theta}} \log L_m(\boldsymbol{\theta}) - n(\boldsymbol{\theta})].$$

237 All model fits that successfully completed the optimization were used for this set of analyses.
238 We used all of these fits because some lack of convergence would be expected for the correct
239 behavior of more complicated models that include process errors that did not exist in the
240 operating model. For example R+M EMs fit to R OMs would be expected to estimate no
241 variance in the M random effects and the estimated variance parameter going to zero would
242 cause poor convergence.

243 **Parameter estimation**

244 All results here use OM simulations with fits that satisfied the convergence criterion described
245 above. We used this conditioning to reflect how practitioners would proceed in analyses of
246 model fits with real assessment data. That is, practitioners would ensure models converged
247 such that Hessian-based standard errors were available for all model parameter estimates.

248 We focused on statistical behavior of estimators of the covariate effect on M ($\hat{\beta}_E$), the esti-
249 mator of the median M parameter ($\hat{\beta}_M$), and estimators of terminal year M (\hat{M}), spawning
250 stock biomass ($\widehat{\text{SSB}}$), and fully-selected F (\hat{F}). In preliminary analyses we examined results
251 for the estimators of all the annual values for M , SSB and F over the whole time series,
252 but we found no appreciable differences in patterns across the various factors defining the
253 OMs and EMs. Furthermore, results for terminal year F were generally inversely related to
254 those for spawning stock biomass, and are provided in the Supplementary Materials and not
255 discussed further.

256 We calculated median errors (ME) of $\hat{\beta}_E$ and $\hat{\beta}_M$, and the Hessian-based standard error
257 estimators of these parameters ($\widehat{SE}(\hat{\beta}_E)$ and $\widehat{SE}(\hat{\beta}_M)$). We calculated the median relative
258 errors (MRE) of terminal year \hat{M} , $\widehat{\text{SSB}}$, and \hat{F} . We also calculated the root mean square
259 error (RMSE) and estimated probability of coverage of constructed 95% CIs for $\hat{\beta}_E$ and $\hat{\beta}_M$
260 for EMs that estimated these parameters. We constructed the CIs for probabilities of CI
261 coverage using the same methods as those for probabilities of convergence.

262 The true values for terminal year SSB and F vary among simulations. For the i th simulated
263 data the relative error for terminal year value θ_i provided from the fitted estimation model
264 is

$$\text{RE}_i(\theta) = \frac{\hat{\theta}_i - \theta_i}{\theta_i}$$

265 We calculated RMSE as

$$\text{RMSE}(\hat{\theta}) = \sqrt{\frac{1}{n} \sum_{i=1}^n (\hat{\theta}_i - \theta_i)^2}$$

266 For ME and MRE of estimators, we constructed 95% CIs using the binomial distribution
267 approach as in Stock and Miller (2021) and Miller et al. (In reviewa). Because of the inverse
268 relationship of the CI and the null hypothesis significance test, when the CI contains zero
269 we do not have evidence of bias from the simulation study.

270 Results

271 Miller et al. (In reviewa) found inferences are most reliable for distinguishing process error
272 sources and stock-recruit relationships in scenarios with lower observation error for indices
273 and age composition data and with temporal contrast in fishing pressure. Our expectation is
274 that inferences for covariate effects on M would require data to be at least that informative
275 and inspection of the comprehensive set of results across all OM scenarios generally confirms this
276 (See Supplemental Materials). Therefore, we restrict our attention to these OM scenarios
277 with more informative data (temporal contrast in fishing and lower population observation
278 error).

279 EM Convergence

280 In OM scenarios with contrast in fishing pressure and lower uncertainty in population observations
281 (catch, indices and age composition), R EMs generally converged with high frequency except
282 when EMs estimated covariate effects on M and the covariate uncertainty (σ_e) was high
283 (Figure S4). R+S EMs generally converged with low frequency when the OM process error
284 did not match the EM configuration. R+M EMs generally did not converge with high
285 frequency except for R+S OM scenarios with low covariate uncertainty and where the EMs assumed
286 median M as known. There was generally little effect of the treatment of median M (known
287 or estimated) on convergence for any of the other EMs. The largest impact of the size of the
288 true covariate effect (β_E) on convergence was observed for R and R+M EMs that estimated

289 covariate effects in R and R+M OMs with high uncertainty in covariate observations (σ_e) and
290 high temporal variability in the latent covariate (σ_E). There was an increase in convergence
291 frequency with increased temporal variability in the covariate for many EMs in OMs with
292 large covariate uncertainty.

293 AIC performance

294 We only present results for EMs where the median M rate parameter was estimated because
295 results differed little whether this parameter was estimated or assumed known (see Figures
296 S15 to S17). When there was temporal contrast in fishing pressure and lower uncertainty
297 in population observations, the only OM scenarios where AIC was consistently accurate for
298 both covariate effect and process error configurations were R OMs with high variability in
299 the covariate and low uncertainty in observations of the covariate (Figure S5). R+M OMs
300 with those same covariate attributes were only accurate for the covariate effect (low Type I
301 and II errors) and the incorrect process error almost always chosen was R rather than R+S.
302 We also observed high accuracy for both covariate effect and process error configurations for
303 R+S OMs where either no effect of the covariate or the strongest effect of the covariate was
304 simulated. All R and R+S OMs were accurate for process error configuration and across
305 all OMs, AIC accurately selects models without covariate effects when there are none (low
306 Type I error). See Figures S15 to S17 for full results.

307 Covariate effect estimation

308 When there was temporal contrast in fishing pressure, lower uncertainty in population ob-
309 servations, low uncertainty in environmental observations, and larger temporal contrast in
310 the simulated true environmental covariate, we observed little or no bias in estimation of
311 covariate effects ($\hat{\beta}_E$) across all EM and OM process error assumptions, both EM configura-
312 tions of median M , and all true covariate effect sizes (Figure S6, rows 3 and 4). The only

exception to this was when R EMs with median M estimated were fit to R+S OMs with those configurations. Decreasing trends in bias of $\hat{\beta}_E$ for EMs fit to many configurations of R and R+M OMs indicate that $\hat{\beta}_E$ values were closer to zero on average even when the true effect increased. For R+S OMs, EMs with the matching process error configuration showed little evidence of bias in estimating β_E across a range of covariate and covariate observation configurations. R+S and R+M EMs generally performed similarly when fitted to either R+S or R+M OMs except R+S OMs with high covariate uncertainty and low covariate variability (Figure S6, rows 5 and 6 of middle columns).

Bias of Hessian-based standard error estimation for $\hat{\beta}_E$ was also close to zero in the same OM scenarios where bias in estimation of β_E itself was close to zero (Figure S21, rows 3 and 4). However, in these high information OMs, bias of standard error estimation was observed for several EMs that did not have the matching R+S and R+M process error configuration. Estimation of standard errors was essentially unreliable for most EMs when OMs had higher uncertainty in covariate observations (Figure S21, rows 5 to 8).

Despite the reliable estimation of covariate effects and standard errors with low uncertainty in environmental observations, and larger temporal contrast in the simulated true environmental covariate, we found poor CI coverage for many EMs fitted to R+S and R+M OMs (Figure S7, rows 3 and 4). For example, R+M EMs fit to R+M OMs showed little bias in estimation of the covariate effect and standard errors, but CI coverage was negatively biased (rows 3 and 4 in right two columns of Figures S6, S7, and S21). However, there appears to be a positive correlation of the covariate and standard error estimates such that estimates less than the true value had negatively biased standard error estimates which would make CIs too small (Figure S32). CI coverage was most reliable for R+S OMs when the EMs had the matching process error configuration (Figure S7, middle 2 columns).

³³⁷ **Median natural mortality rate estimation**

³³⁸ We observed negligible bias in estimating the median M parameter (β_M) over a much wider
³³⁹ set of operating models than that for estimating the covariate effect on M . When there is
³⁴⁰ temporal contrast in fishing pressure, lower uncertainty in population observations, all EMs
³⁴¹ fit to R and R+M OMs showed little evidence of bias for $\hat{\beta}_M$ (Figure S8, left and right sets of
³⁴² columns). For R+S OMs with those conditions, only EMs with the matching process error
³⁴³ assumption showed little evidence of bias.

³⁴⁴ We also found little or no bias of Hessian-based standard error estimation for β_M in many
³⁴⁵ of the same OM scenarios where bias of $\hat{\beta}_M$ was close to zero except for some EMs with the
³⁴⁶ process error source mis-specified or where the OM simulated the strongest covariate effect
³⁴⁷ (Figure S36). Like $\hat{\beta}_M$, reliability of standard error estimation in R+S OMs required the
³⁴⁸ EMs to have the matching process error assumption.

³⁴⁹ we found CI coverage to be unreliable for many EM-OM combinations even for OM and EM
³⁵⁰ combinations where bias in $\hat{\beta}_M$ and its standard error estimators was negligible, much like
³⁵¹ that for $\hat{\beta}_E$ (Figure S9). In the same EM OM combination we investigated above for $\hat{\beta}_E$,
³⁵² we observed an opposite negative correlation of $\hat{\beta}_M$ and its standard error estimates (Figure
³⁵³ S43), which would result in CIs being too narrow when $\hat{\beta}_M$ values are larger than average.
³⁵⁴ The exceptions to the general poor CI coverage were for all EMs fit to several R OMs with
³⁵⁵ low covariate uncertainty and covariate variability (Figure S9, first two columns) and for
³⁵⁶ R+S EMs in many R+S OMs (Figure S9, middle two columns) .

³⁵⁷ **Terminal year natural morality rate**

³⁵⁸ The EMs with either R or R+S process error configurations with median M assumed known
³⁵⁹ and covariate effects not estimated will have terminal year M correctly specified when fitted
³⁶⁰ to either R or R+S OMs with no covariate effect because M is constant in both the EM and
³⁶¹ OM at the same value. We exclude those OM-EM combinations from our results here.

362 In many of the OMs with temporal contrast in fishing pressure and lower uncertainty in
363 population observations, there was little difference in bias for terminal year M among EMs
364 whether the median M parameter (β_M) was estimated (Figure S10). However, when there
365 were differences, bias in terminal year M was closer to zero when the EM assumed β_M known,
366 as would be expected. For R OMs, all estimating models exhibited little evidence of bias
367 except when OMs simulated the largest covariate effect ($\beta_E = 0.5$). However, bias estimates
368 were at worst around 10% (Figure S10, left columns). For R+S OMs, the R+S EMs generally
369 exhibited the least evidence for bias and R+M EMs generally estimated terminal M lower
370 than the true value, particularly when observation uncertainty in the covariate was lower.
371 For R+M OMs, many of the EM configurations provided little bias in terminal \widehat{M} , but the
372 biases were generally further from zero than the results for the R OMs (Figure S10, right
373 columns).

374 Accuracy (lower RMSE) of terminal year \widehat{M} was similar for all of the EMs when fitted to
375 R+M OMs (Figure S51). For R+S OMs, accuracy was generally better for R+S EM than
376 other process error assumptions, particularly when β_E was also estimated. Accuracy for
377 R+S EMs was also generally as good as other EM process error assumptions even when the
378 OM process error type was different. As would be expected, the accuracy of terminal year
379 \widehat{M} where median M was assumed known was better than when it was estimated, when there
380 were differences.

381 Terminal year spawning stock biomass

382 In OMs with temporal contrast in fishing pressure and lower uncertainty in population
383 observations, we found little bias in estimates of terminal year SSB for all EM configurations
384 when fitted to R or R+M OMs (Figure S11). We also found little or no evidence of bias for
385 R+S OMs when the EMs assumed the correct process error configuration. We found the
386 worst bias in terminal year SSB estimation for R EMs with β_M estimated when fitted to

³⁸⁷ R+S OM_s, and R+M EM_s also had more bias than R+S EM_s in these OM_s. Like the bias
³⁸⁸ results, accuracy, as measured by RMSE, was similar for many of EM_s when fit to R and
³⁸⁹ R+M OM_s. Accuracy was generally worse (higher RMSE) when EM_s were fit to R+S OM_s,
³⁹⁰ and the worst accuracy occurred when the EM process error assumption did not match that
³⁹¹ of the OM (Figure S58).

³⁹² Discussion

³⁹³ Our simulation study demonstrated that estimation of environmental effects on M is possible
³⁹⁴ and reliable in certain scenarios even when the process error was misspecified (e.g., R and
³⁹⁵ R+S EM_s fit to R+M OM). In many of these same OM_s, frequency of convergence of fitted
³⁹⁶ models did not appear to suffer when covariate effects on M were estimated even when there
³⁹⁷ was no effect simulated. However, these scenarios are information rich in that there was
³⁹⁸ contrast in population size (due to changes in fishing pressure) and the covariate affecting
³⁹⁹ the population, and there was low uncertainty in population and covariate observations.
⁴⁰⁰ Previous research has shown that estimation of a constant M parameter requires contrast
⁴⁰¹ in time series and informative data (Lee et al., 2011), so it is no surprise that estimation
⁴⁰² of these effects also requires relatively good information via more precise observations and
⁴⁰³ higher contrast in the covariate time series.

⁴⁰⁴ Even though estimation of covariate effects was unbiased in many scenarios, AIC could only
⁴⁰⁵ reliably detect covariate effects for R and R+M OM_s with contrast in covariates and low
⁴⁰⁶ covariate uncertainty. In those scenarios where the covariate effect could be detected, CI
⁴⁰⁷ coverage for the covariate effect was often biased even when there was little or no bias in
⁴⁰⁸ the estimators of the effect and its standard error. Cadigan et al. (2024) found CI coverage
⁴⁰⁹ to be biased for SSB and F estimation in a state-space model in some scenarios, but they
⁴¹⁰ attributed the poor coverage to bias in Hessian-based standard error estimation, and their
⁴¹¹ simulations held any process error random effects constant. The coverage bias we observed,

⁴¹² at least for some OM-EM combinations, may be related to correlation of the estimators
⁴¹³ of the covariate effect and the corresponding standard error and therefore consideration of
⁴¹⁴ other methods of calculating CIs may be warranted (e.g., those based on profile likelihood
⁴¹⁵ and/or Monte Carlo sampling of the log-likelihood surface).

⁴¹⁶ Miller et al. (In reviewa) investigated R+M OMs with two levels of M process error variability
⁴¹⁷ ($\sigma_M \in \{0.1, 0.5\}$) and only found AIC able to accurately distinguish R+M process errors with
⁴¹⁸ the higher level of process error variability ($\sigma_M = 0.5$). We assumed $\sigma_M = 0.3$, intermediate
⁴¹⁹ to the values investigated by Miller et al. (In reviewa), and found process error inferences
⁴²⁰ unreliable for the source of process error, indicating that the level of variability required for
⁴²¹ detecting M process errors must be greater than $\sigma_M = 0.3$, but may still be less than 0.5. In
⁴²² our results and those by Miller et al. (In reviewa), AIC typically chose R EMs which would
⁴²³ indicate the fitted R+M EMs would estimate no variability in the M process errors. Future
⁴²⁴ studies like ours where R+M OMs are simulated with greater variability in M process errors
⁴²⁵ would better inform reliability of covariate effect inferences under such scenarios.

⁴²⁶ Deriso et al. (2008) attempted to estimate process errors as well as covariate effects with
⁴²⁷ M for Pacific herring, but similarly found no variability in M , suggesting there was too
⁴²⁸ much uncertainty in the available observations relative to the true temporal variability in
⁴²⁹ M . Given that we found covariate effect inferences using R EMs was reliable in R+M OMs
⁴³⁰ with apparently little variability in M process errors, the findings of Deriso et al. (2008) on
⁴³¹ covariate effects for Pacific herring would presumably also be robust to true low variability in
⁴³² M . However, they did not account for uncertainty in covariate observations, some of which
⁴³³ would probably have substantial uncertainty (e.g., competition and predation covariates).
⁴³⁴ We found higher covariate observation uncertainty to cause true covariate effects to be less
⁴³⁵ detectable using AIC, but we did not investigate the implications for incorrectly assuming
⁴³⁶ no covariate uncertainty for covariate inferences.

⁴³⁷ Any bias or poor accuracy for annual SSB estimation was primarily a function of whether or

not the median M parameter was estimated or known and the types of process errors, rather than the treatment of the covariate effects on M . For example, we found estimation of SSB was better when the EM had the process error correctly specified for R+S OMs. Fortunately, our results and those by Miller et al. (In reviewa) demonstrate that marginal AIC seems to be a good tool for determining whether this source of process error should be included in the model. However, the reliability of the estimation of SSB does break down in the less ideal scenarios when there is higher population observation error, and lack of contrast in fishing pressure (e.g., Figures S55 to S57).

The R+S and R+M EMs both include process error for the survival of cohorts and would be expected to perform similarly, and they did in our simulations when the OM and EM matched. However, we found that the biases using R+M EMs for R+S OMs were generally worse than using R+S EMs for R+M OMs. Additionally, there are implications for biological reference points for R+M EMs (e.g., Legault and Palmer, 2016) that are not present with R+S EMs. So, we recommend following the suggestion from Li et al. (2024) to prefer R+S EMs over R+M OMs unless strong biological evidence is present to support a particular R+M OM. Such support could be found through both biological understanding (e.g., Trijoulet et al., 2020) as well as statistical properties such as a large delta AIC for R+M compared to R+S associated with greater temporal variability in natural mortality (Miller et al., In reviewa).

The ability to accurately infer covariate effects on M in some realistic situations indicates that such investigations may be fruitful. Ability to make inferences could improve further when WHAM is extended to incorporate tagging data (Miller et al., In reviewb). Tagging data can greatly inform natural mortality estimation (Pollock et al., 1991; Hampton, 2000), and this impact on M estimation should also apply to estimation of covariate effects or unexplained temporal variation in M . Given our findings and planned future WHAM development, we expect investigations of and accounting for covariate effects on M to become more common within the fisheries stock assessment process. At the same time, it will be equally important

⁴⁶⁵ to conduct research that will improve our understanding of how best to measure the depletion
⁴⁶⁶ of stocks and determine catch advice for these stocks with covariate effects on M .

⁴⁶⁷ **Acknowledgements**

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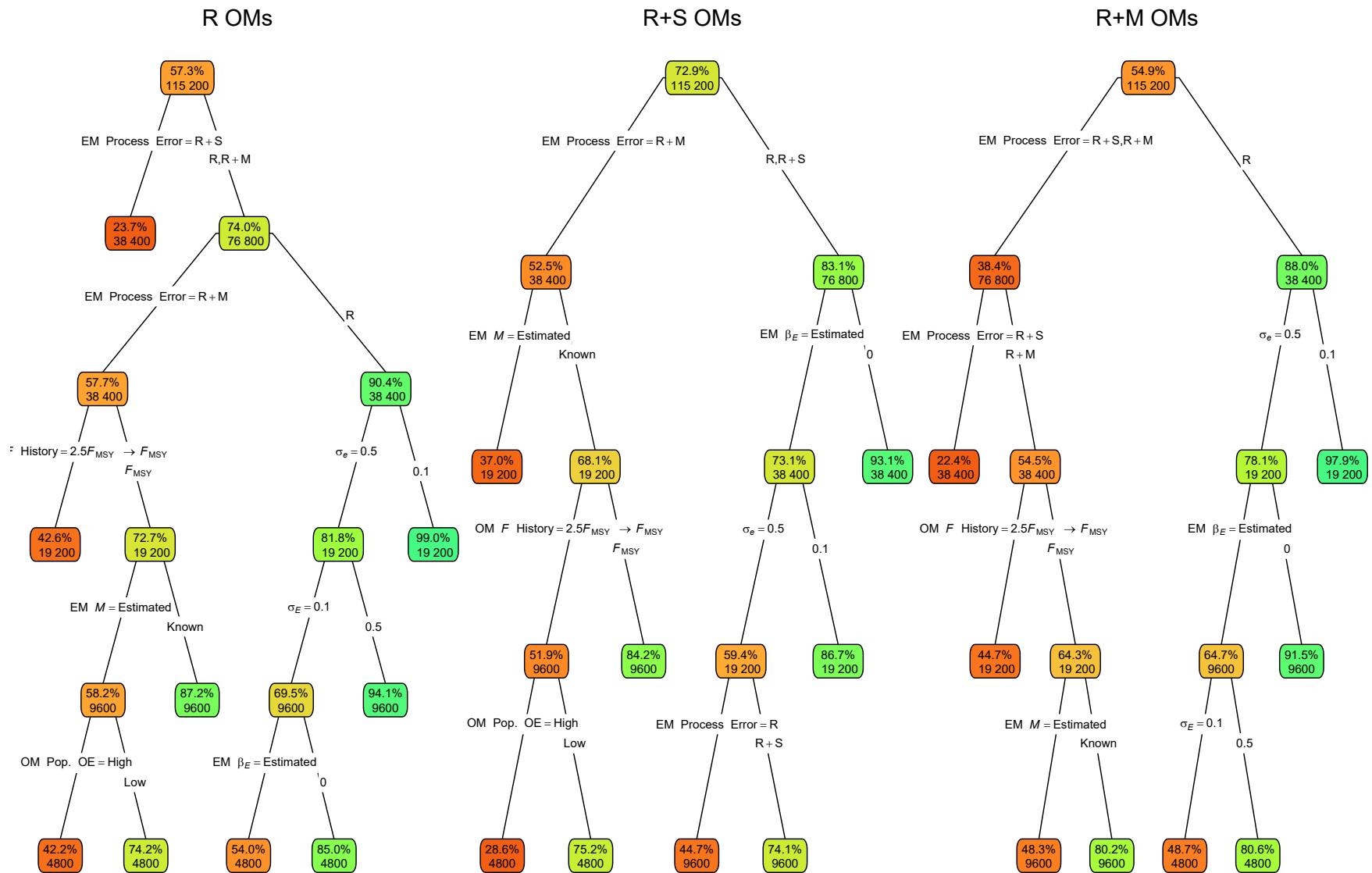


Fig. 1. Classification trees indicating primary factors determining convergence as defined by providing Hessian-based standard errors for R, R+S, and R+M OMs. Nodes denote percent convergence (top) and number of fits (bottom) for the corresponding subset. Lower or higher convergence rates are indicated by more red or green polygons, respectively

⁵⁹⁵ Supplemental Materials

Table 1. For each OM process error source (columns), percent reduction in deviance for logistic regression models fit to indicators of convergence (providing Hessian-based standard errors) with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	0.86	<0.01	0.24
OM Obs. Error	0.56	0.03	0.26
OM σ_e	0.66	2.99	0.93
OM σ_E	0.53	2.22	0.62
OM ρ_E	<0.01	0.02	<0.01
OM β_E	0.02	<0.01	<0.01
EM Process Error	24.53	9.33	23.06
EM β_E assumption	0.16	2.96	0.51
EM M Assumption	0.18	2.83	0.40
All factors	28.92	22.67	27.34
+ All Two Way	36.15	33.54	34.03
+ All Three Way	37.95	36.58	35.57

Table 2. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the median natural mortality rate parameter with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	4.03	16.52	6.51
OM Obs. Error	2.74	0.54	0.64
OM σ_e	0.01	<0.01	0.01
OM σ_E	0.18	0.02	0.15
OM ρ_E	0.07	0.05	<0.01
OM β_E	0.37	0.04	0.10
EM Process Error	2.31	11.99	2.65
EM β_E assumption	2.83	7.20	3.25
All factors	12.14	33.71	12.81
+ All Two Way	21.74	46.46	19.84
+ All Three Way	26.38	49.41	22.24

Table 3. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the standard error of the MLE for median natural mortality rate with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	0.55	12.91	3.65
OM Obs. Error	0.98	0.01	0.07
OM σ_e	<0.01	0.03	0.11
OM σ_E	0.13	0.03	0.19
OM ρ_E	<0.01	0.02	<0.01
OM β_E	0.12	0.07	0.23
EM Process Error	3.16	8.79	6.83
EM β_E assumption	0.18	8.96	3.81
All factors	5.32	28.39	14.71
+ All Two Way	11.80	44.67	22.70
+ All Three Way	17.83	51.54	29.46

Table 4. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the covariate effect on natural mortality (β_E) with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	0.03	0.06	0.02
OM Obs. Error	<0.01	0.06	0.02
OM σ_e	0.04	0.08	0.06
OM σ_E	<0.01	0.02	0.01
OM ρ_E	<0.01	0.01	<0.01
OM β_E	0.05	<0.01	<0.01
EM Process Error	0.01	0.06	0.01
EM M assumption	0.02	0.02	<0.01
All factors	0.18	0.37	0.14
+ All Two Way	0.50	1.11	0.35
+ All Three Way	1.38	1.88	0.66

Table 5. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the terminal year SSB with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
Convergence	0.02	0.13	<0.01
OM F history	2.08	2.74	1.75
OM Obs. Error	1.09	0.18	1.19
$OM\sigma_e$	0.01	<0.01	<0.01
$OM\sigma_E$	<0.01	<0.01	<0.01
$OM\rho_E$	<0.01	<0.01	<0.01
OM β_E	<0.01	0.01	<0.01
EM Process Error	0.52	1.05	0.57
$EM\beta_E$ assumption	<0.01	0.05	0.01
EM M assumption	1.76	2.12	1.51
All factors	5.97	6.58	5.21
+ All Two Way	12.81	13.00	11.97
+ All Three Way	16.41	15.57	15.73

Table 6. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the median natural mortality rate parameter with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	<0.01	<0.01	<0.01
OM Obs. Error	<0.01	<0.01	<0.01
OM σ_e	<0.01	<0.01	<0.01
OM σ_E	<0.01	<0.01	<0.01
OM ρ_E	<0.01	<0.01	<0.01
OM β_E	<0.01	<0.01	0.01
EM Convergence	<0.01	0.01	0.01
EM Process Error	<0.01	0.01	0.01
EM β_E assumption	<0.01	<0.01	<0.01
All factors	0.02	0.02	0.05
+ All Two Way	0.15	0.15	0.24
+ All Three Way	0.57	0.54	0.73

Table 7. For each OM process error source (columns), percent reduction in deviance for linear regression models fit to errors in estimation measured by Eq. ?? for the covariate effect on natural mortality (β_E) with each OM and EM factor (rows) included individually, combined, and with second and third order interactions.

Factor	R	R+S	R+M
OM F history	<0.01	0.01	<0.01
OM Obs. Error	<0.01	<0.01	<0.01
OM σ_e	<0.01	<0.01	<0.01
OM σ_E	<0.01	<0.01	<0.01
OM ρ_E	<0.01	<0.01	<0.01
OM β_E	<0.01	0.01	<0.01
EM Convergence	<0.01	<0.01	<0.01
EM Process Error	<0.01	0.01	0.01
EM M assumption	<0.01	<0.01	<0.01
All factors	0.02	0.03	0.03
+ All Two Way	0.16	0.20	0.18
+ All Three Way	0.58	0.73	0.59

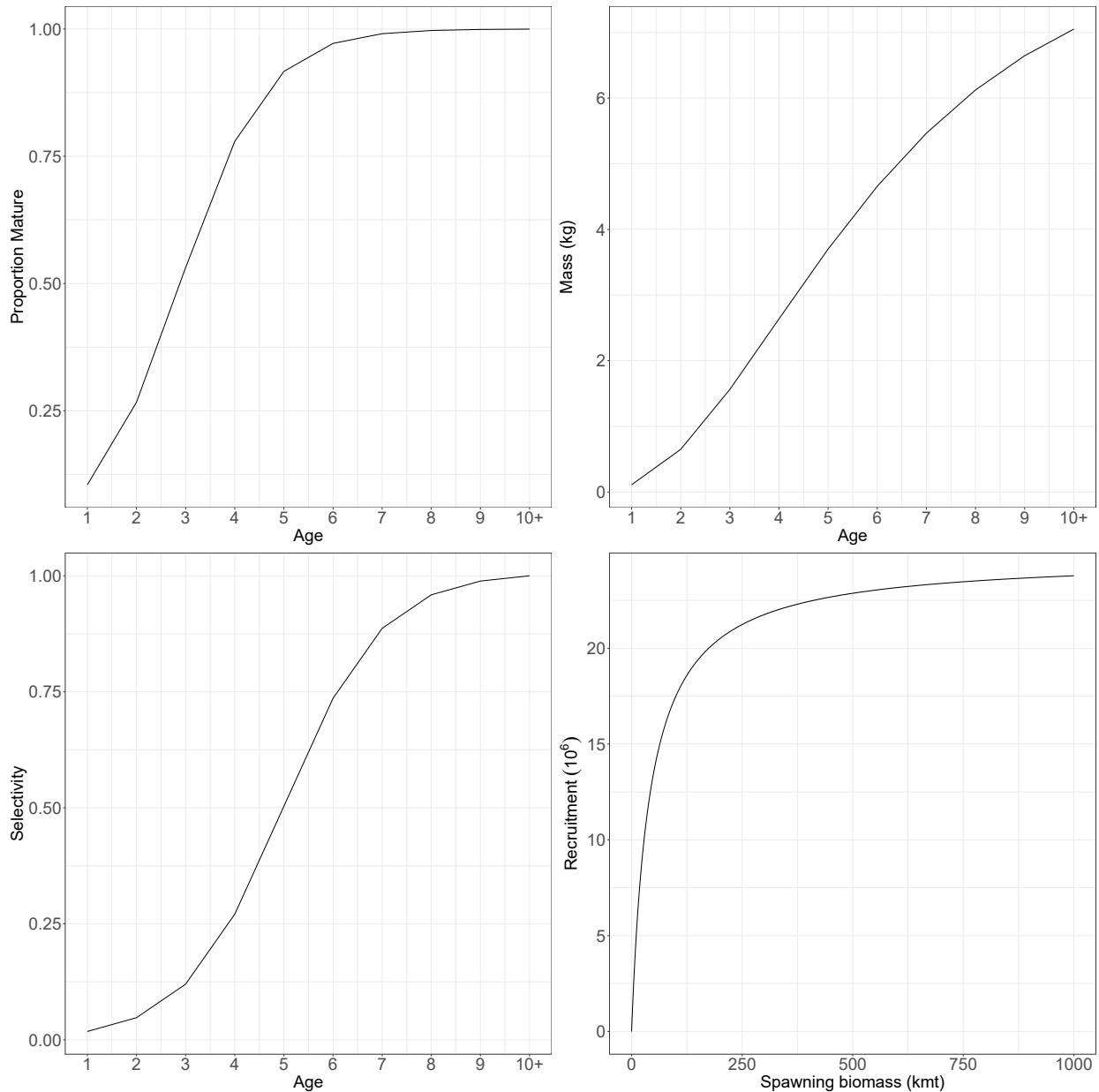


Fig. S1. The proportion mature at age, weight at age, fleet and index selectivity at age, and Beverton-Holt stock-recruit relationship assumed for the population in all operating models. For operating models with random effects on fleet selectivity, this represents the selectivity at the mean of the random effects.

Fig. S2. Example simulations of environmental covariate latent processes and observations with different levels of observation error, and different assumptions about variability of the latent process.

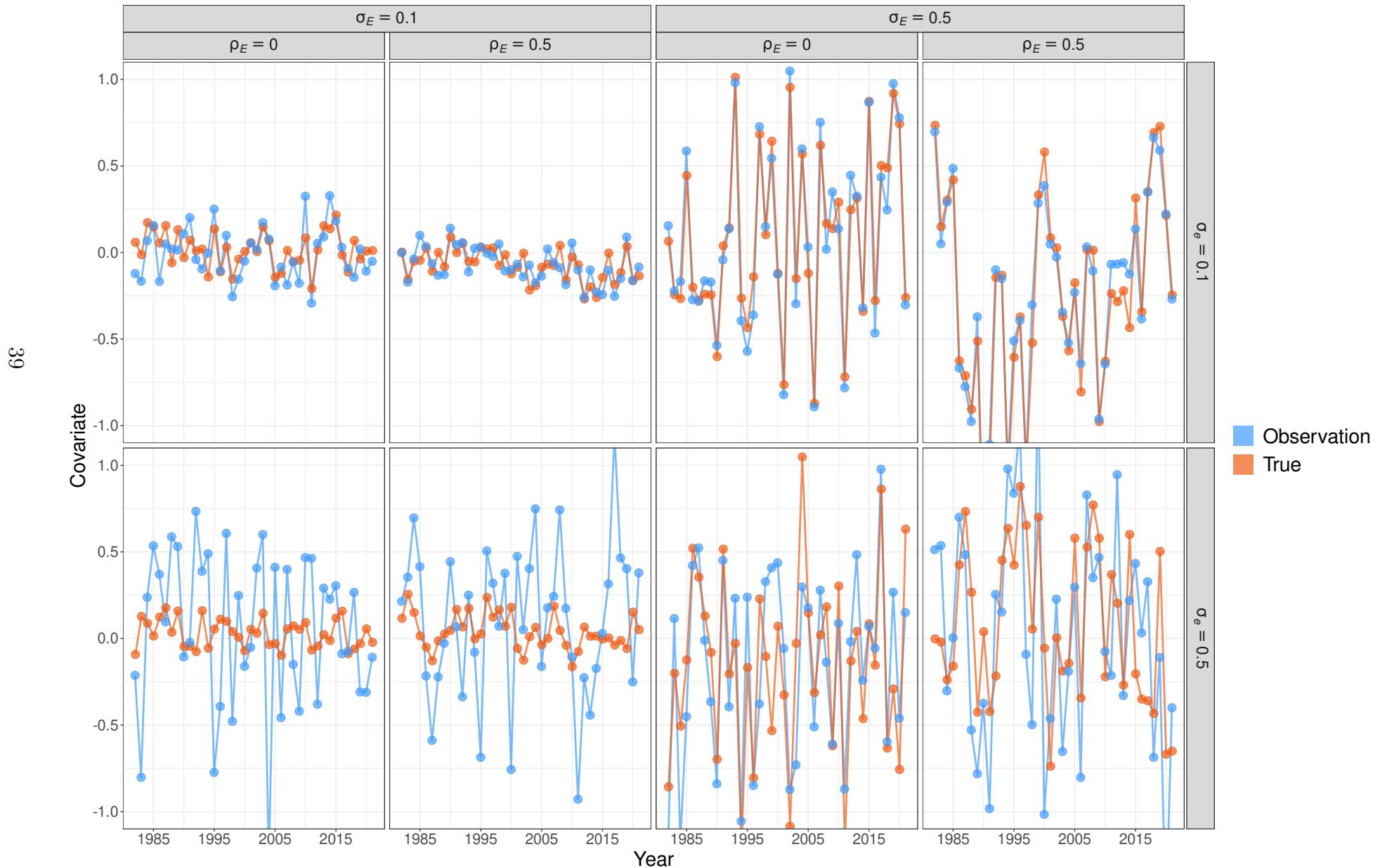
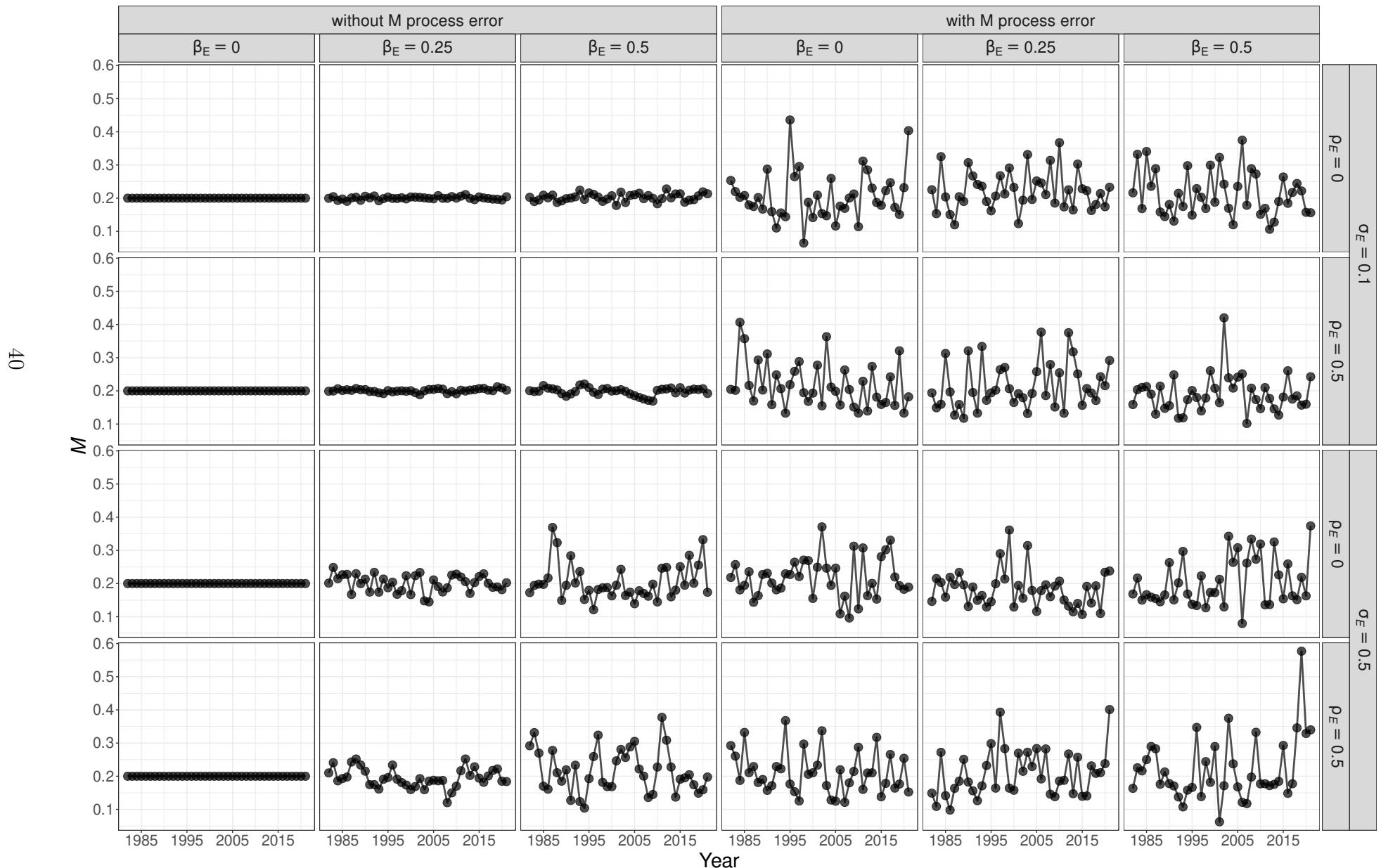
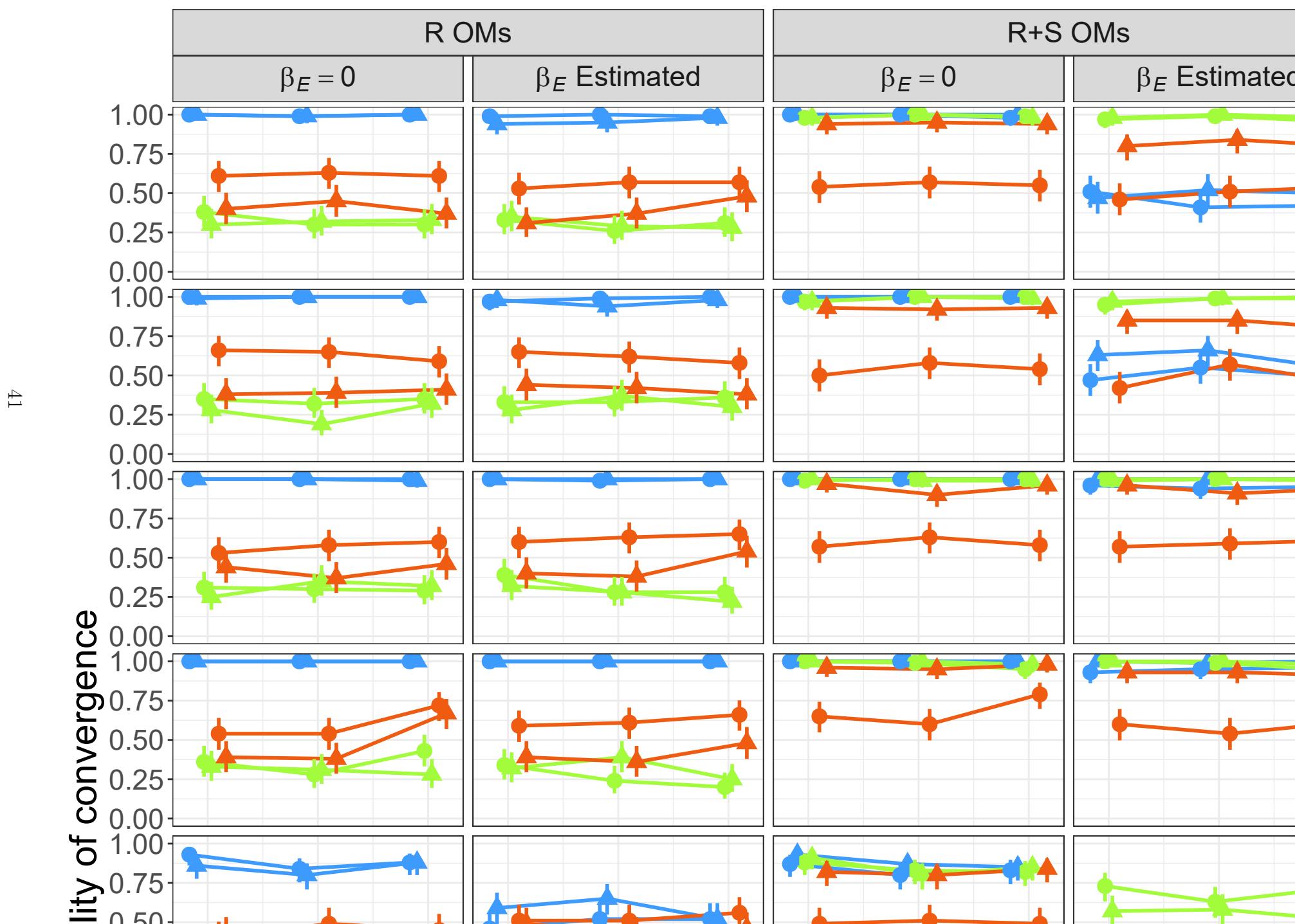


Fig. S3. Example simulations of annual natural mortality rates that may be a function of a temporally varying environmental covariate and autoregressive random effects.





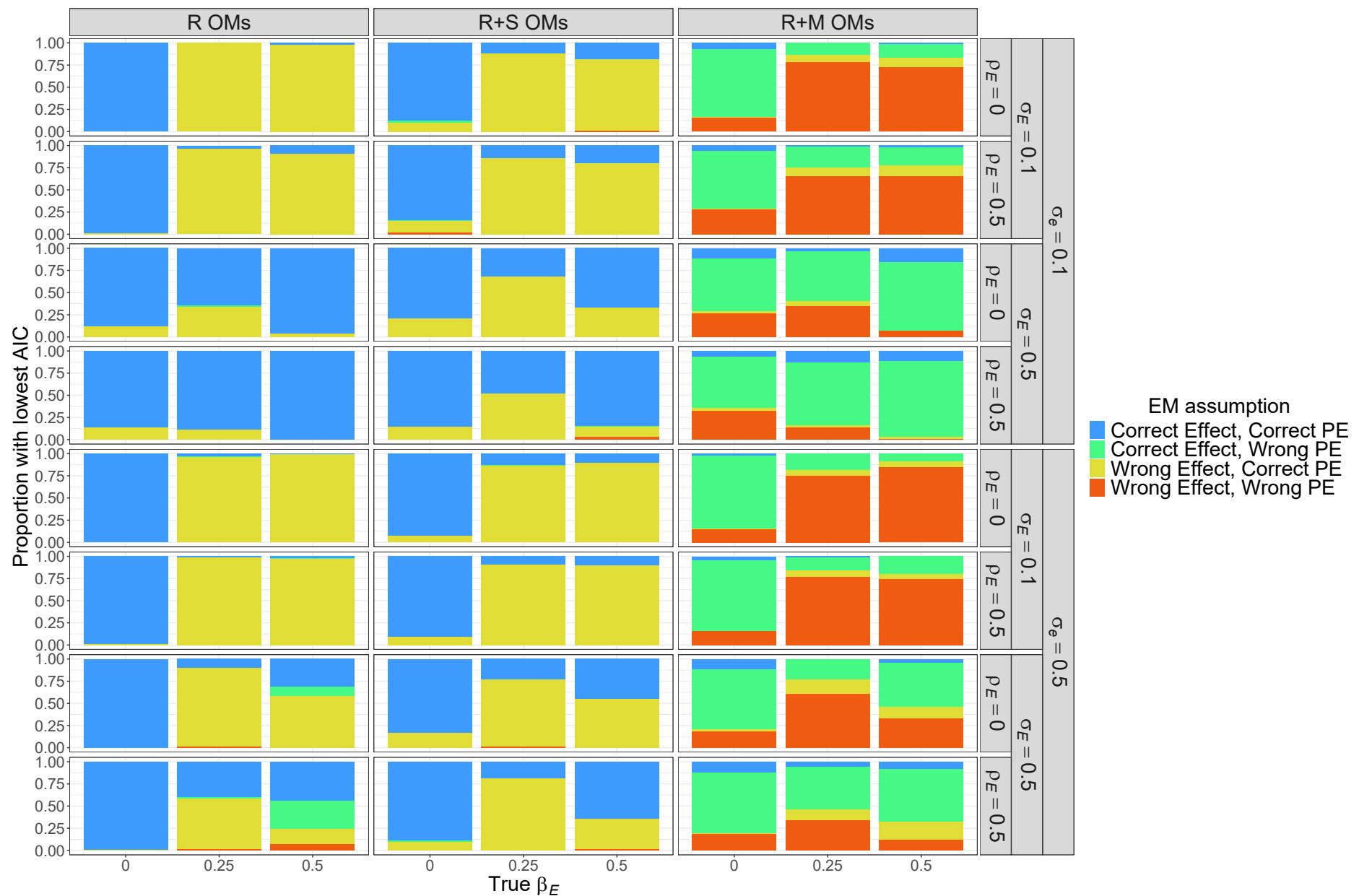


Fig. S5. For each OM, the proportion of simulated data sets where the EM type (treatment of environmental covariate effect and assumed process error type) had the lowest AIC. All OMs had low observation error for fish population observations and temporal contrast in fishing pressure. All EMs estimated median natural mortality rate.

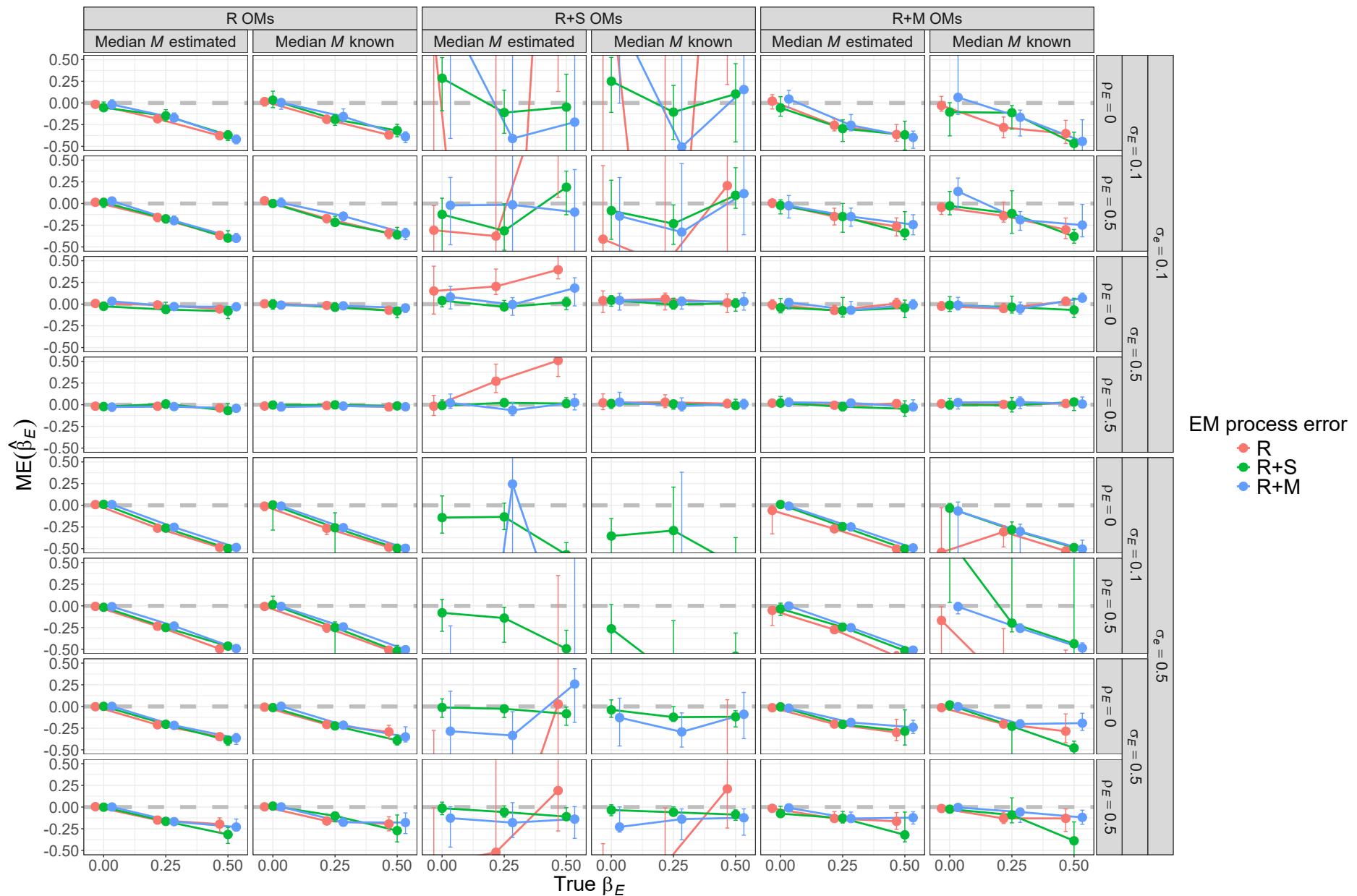


Fig. S6. Median error (ME) of estimates of environmental effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (β_M known or estimated). All OMs had low observation error and contrast in fishing mortality. Vertical lines represent 95% confidence intervals.

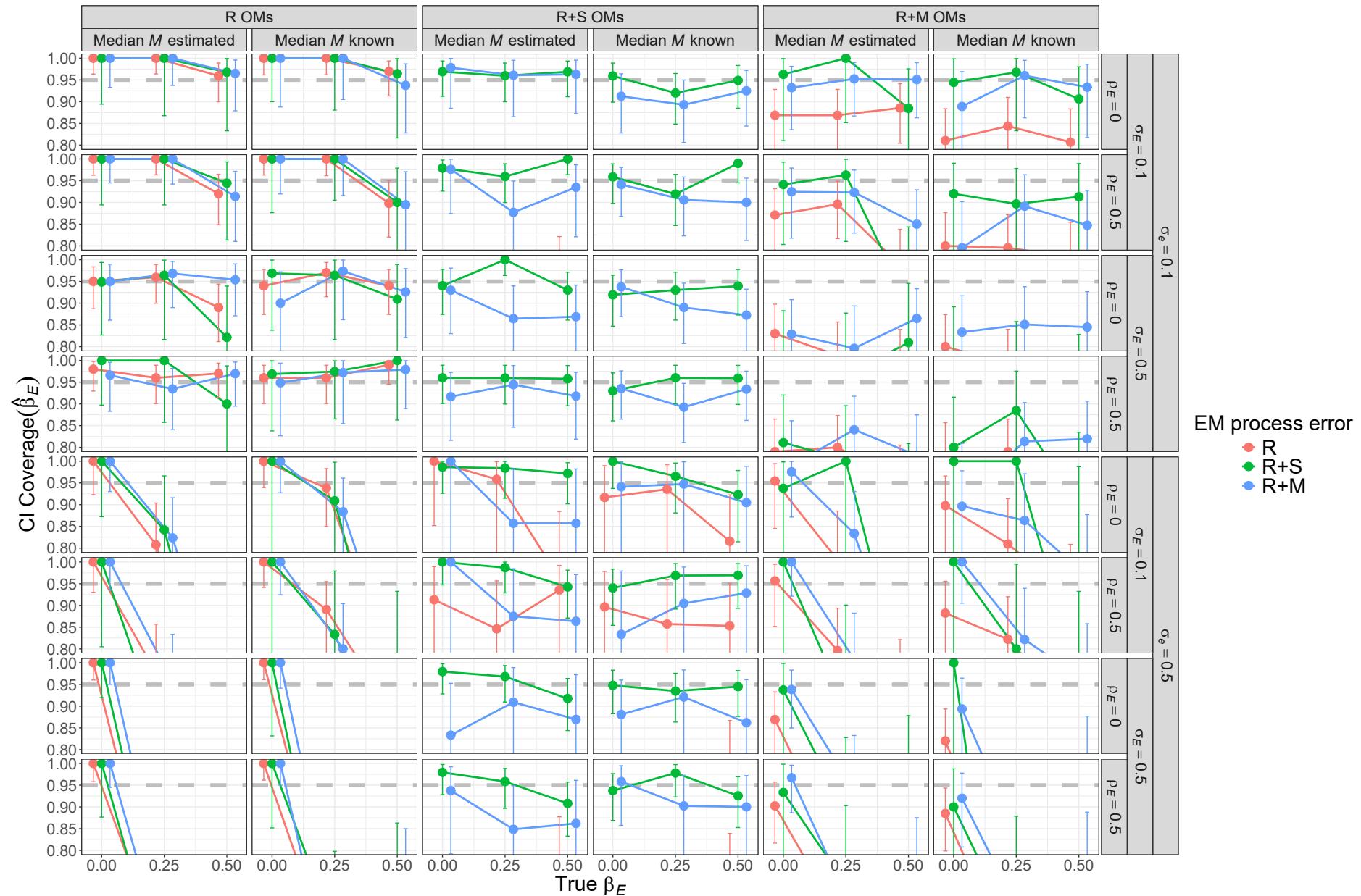


Fig. S7. Probability of 95% confidence interval for β_E containing the true value for EMs with alternative process error assumptions and treatment of median natural mortality (β_M known or estimated). All OMs had low observation error and contrast in fishing mortality. Vertical lines represent 95% confidence intervals.

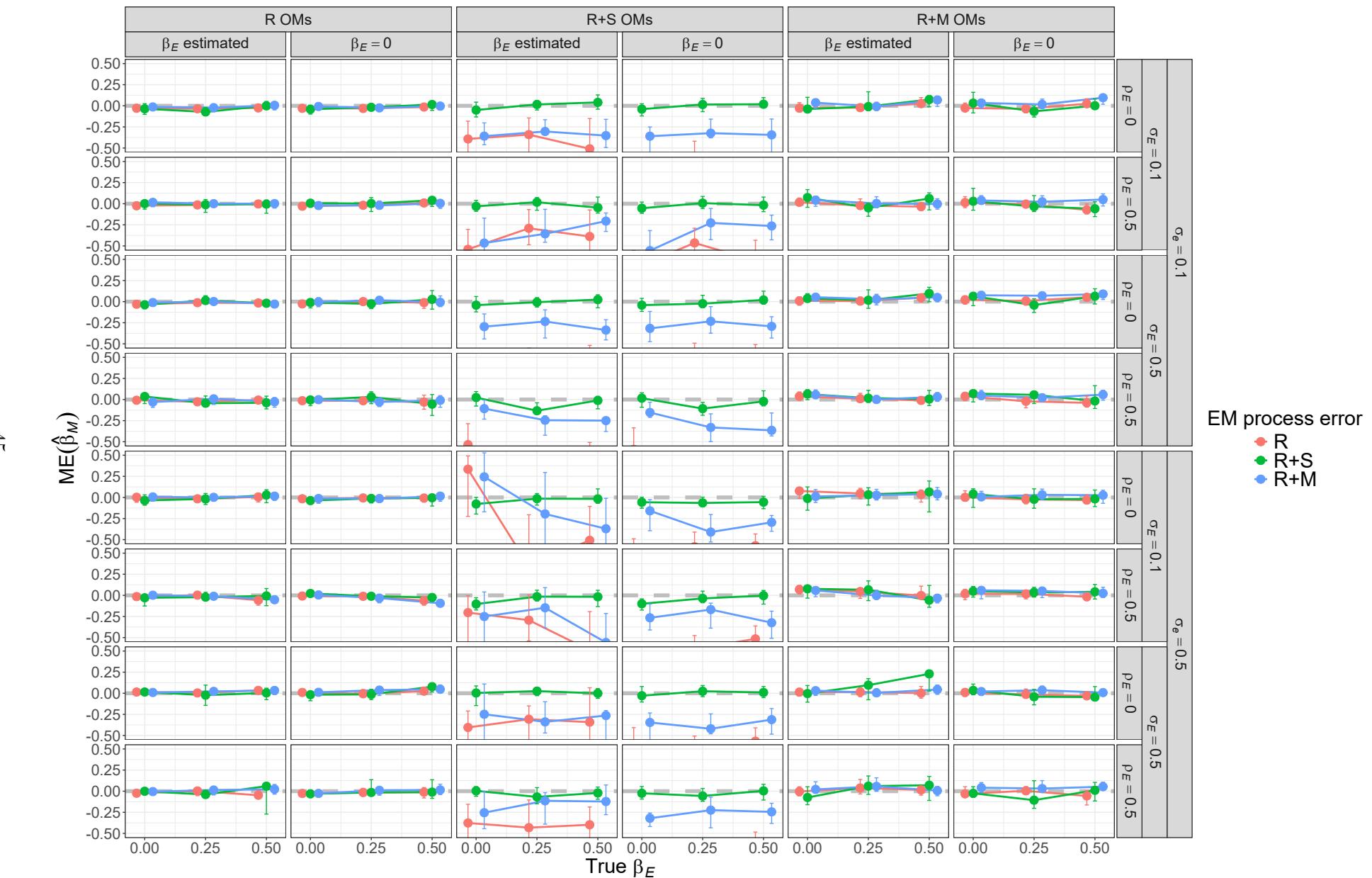


Fig. S8. Median error (ME) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). All OMs had low observation error and contrast in fishing mortality. Vertical lines represent 95% confidence intervals.

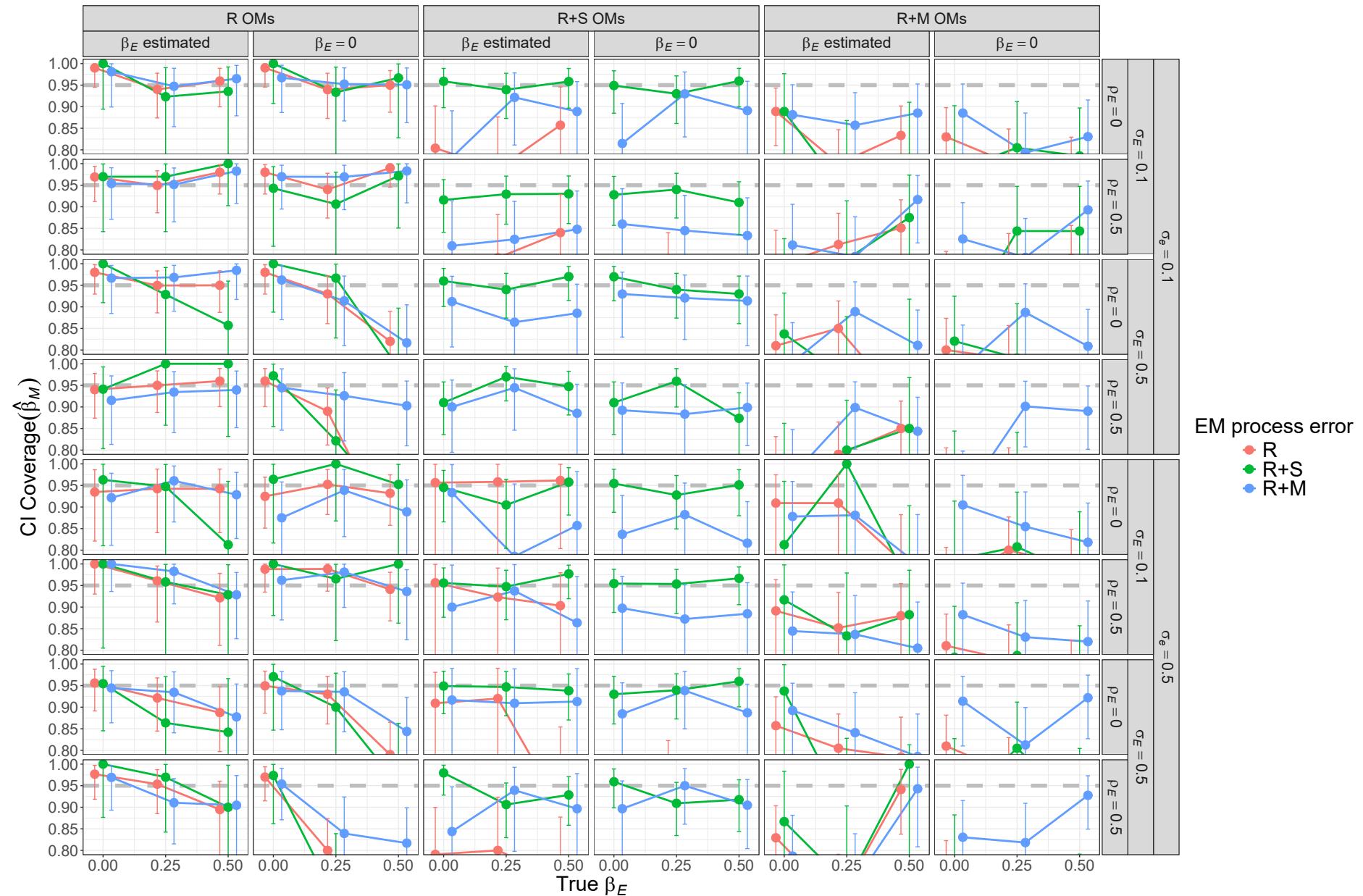


Fig. S9. Probability of 95% confidence interval for β_M containing the true value for EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). All OMs had low observation error and contrast in fishing mortality. Vertical lines represent 95% confidence intervals.

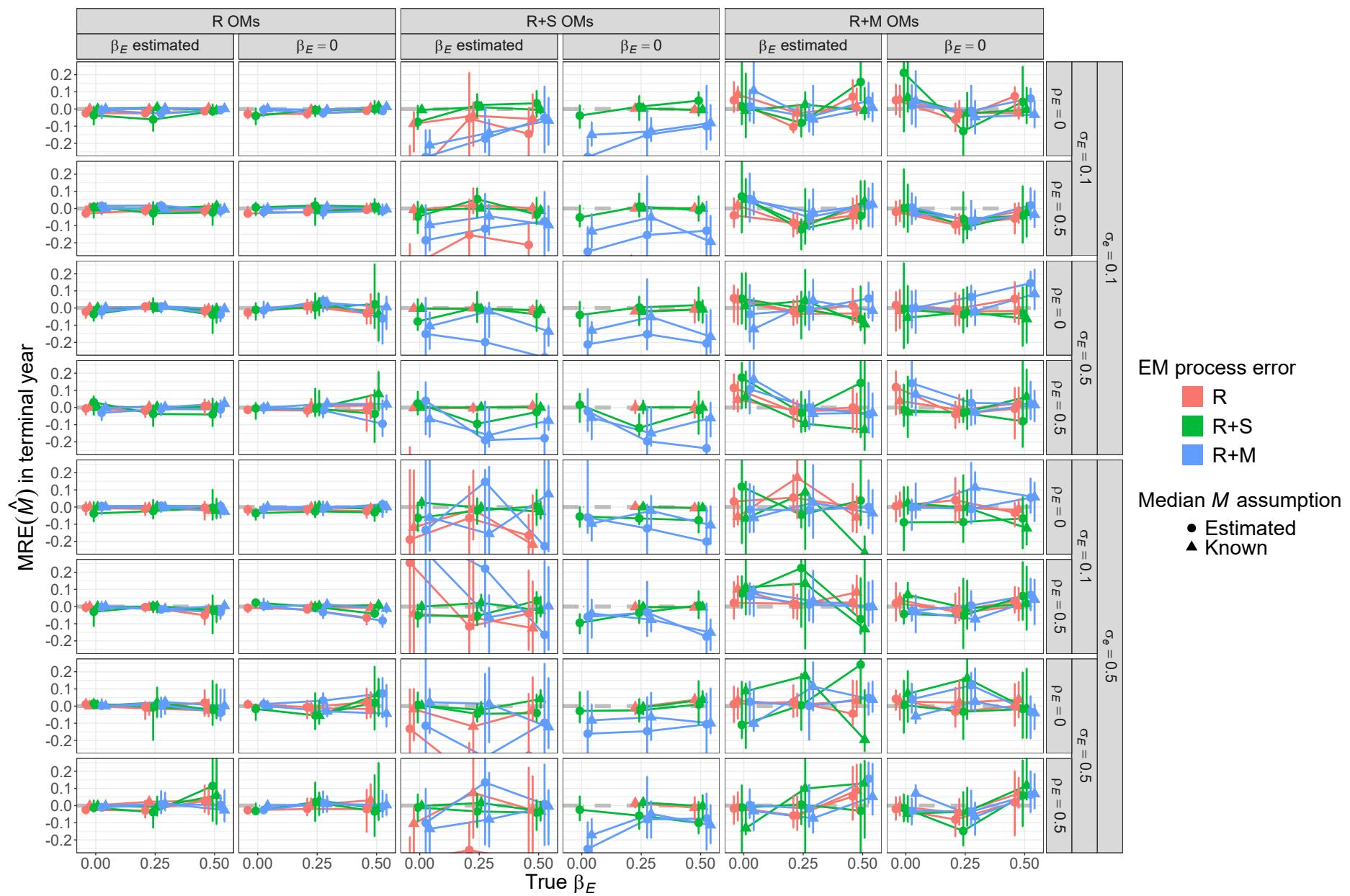


Fig. S10. Median relative error (MRE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low observation error and contrast in fishing mortality.

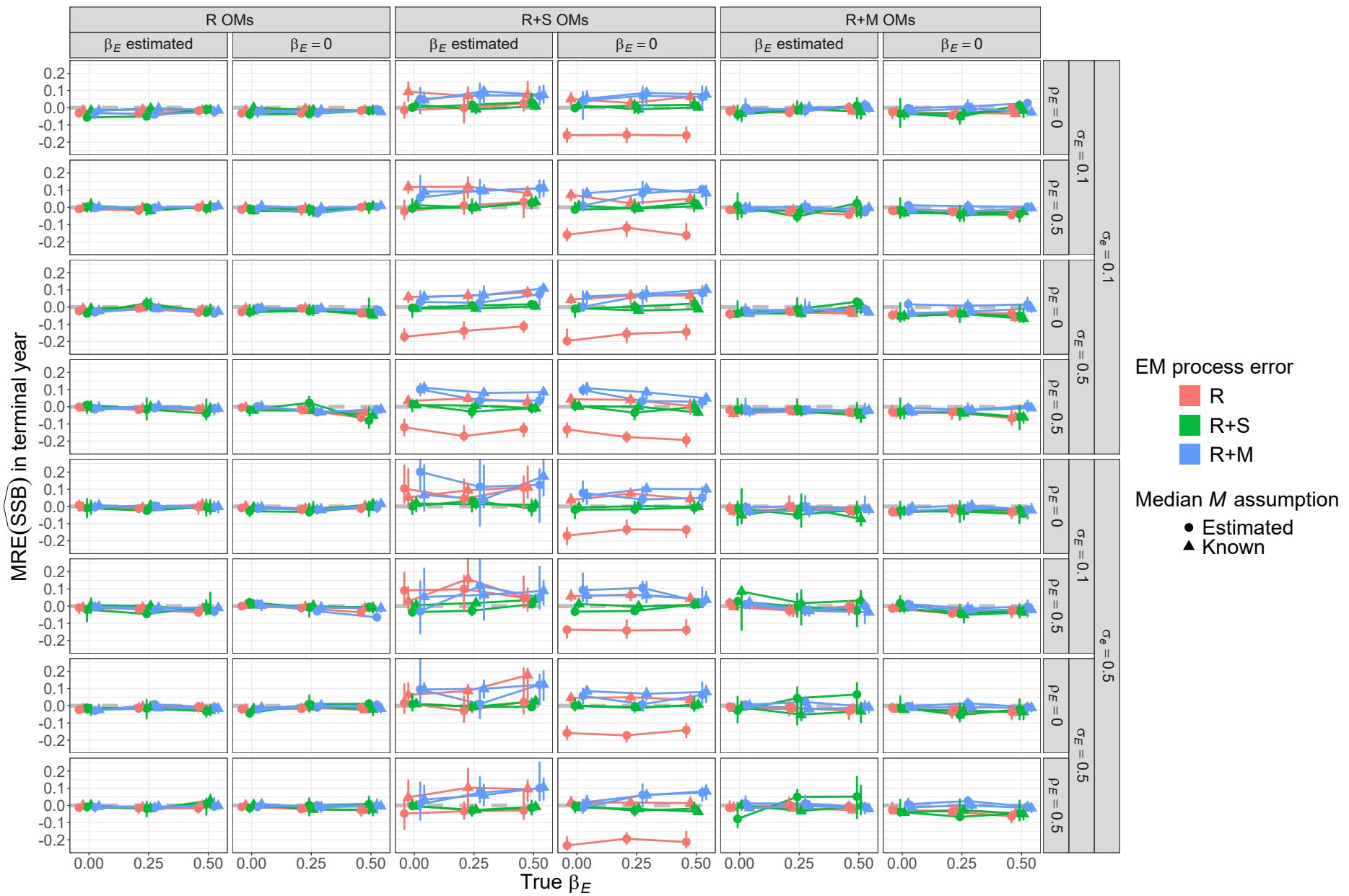
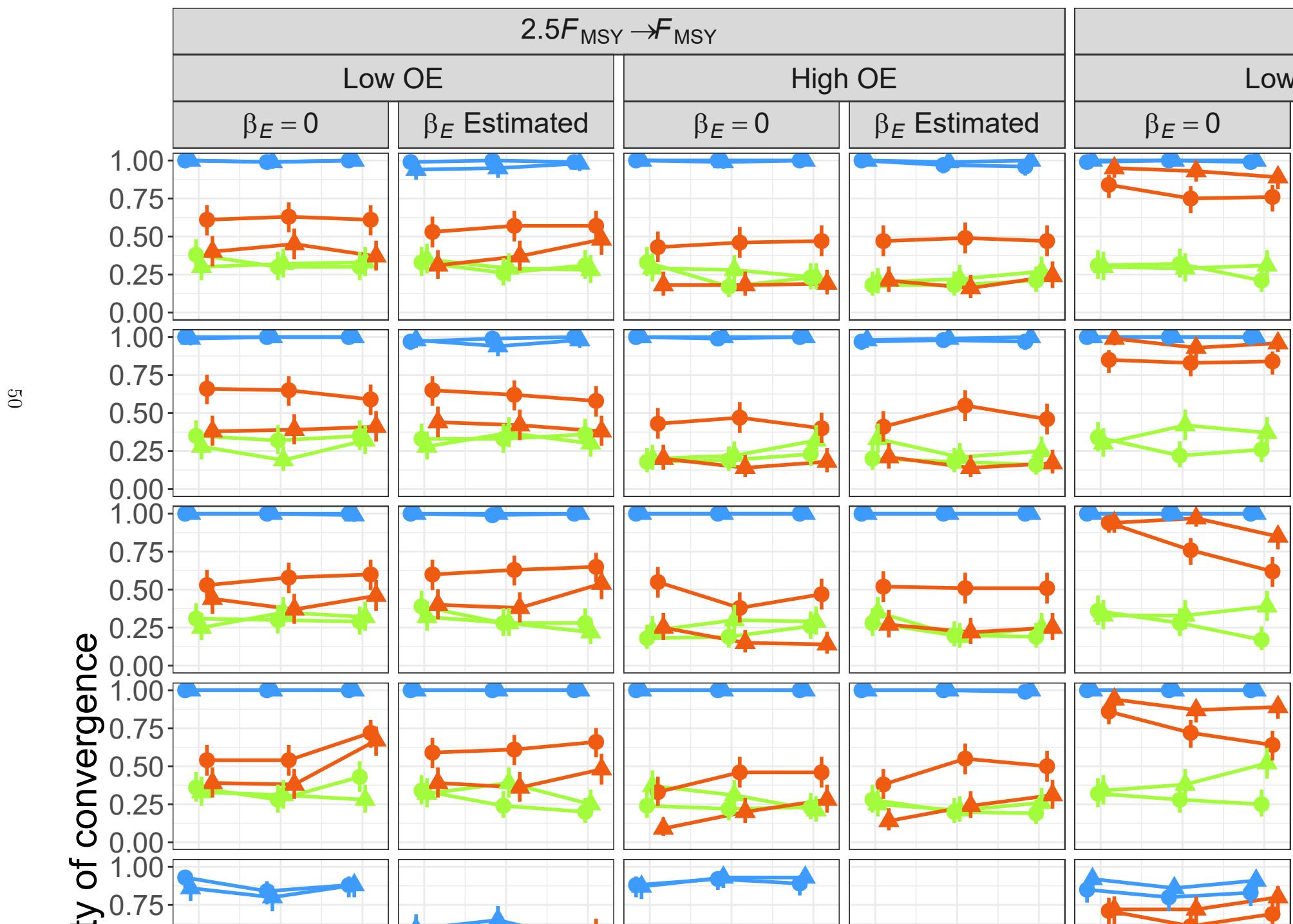
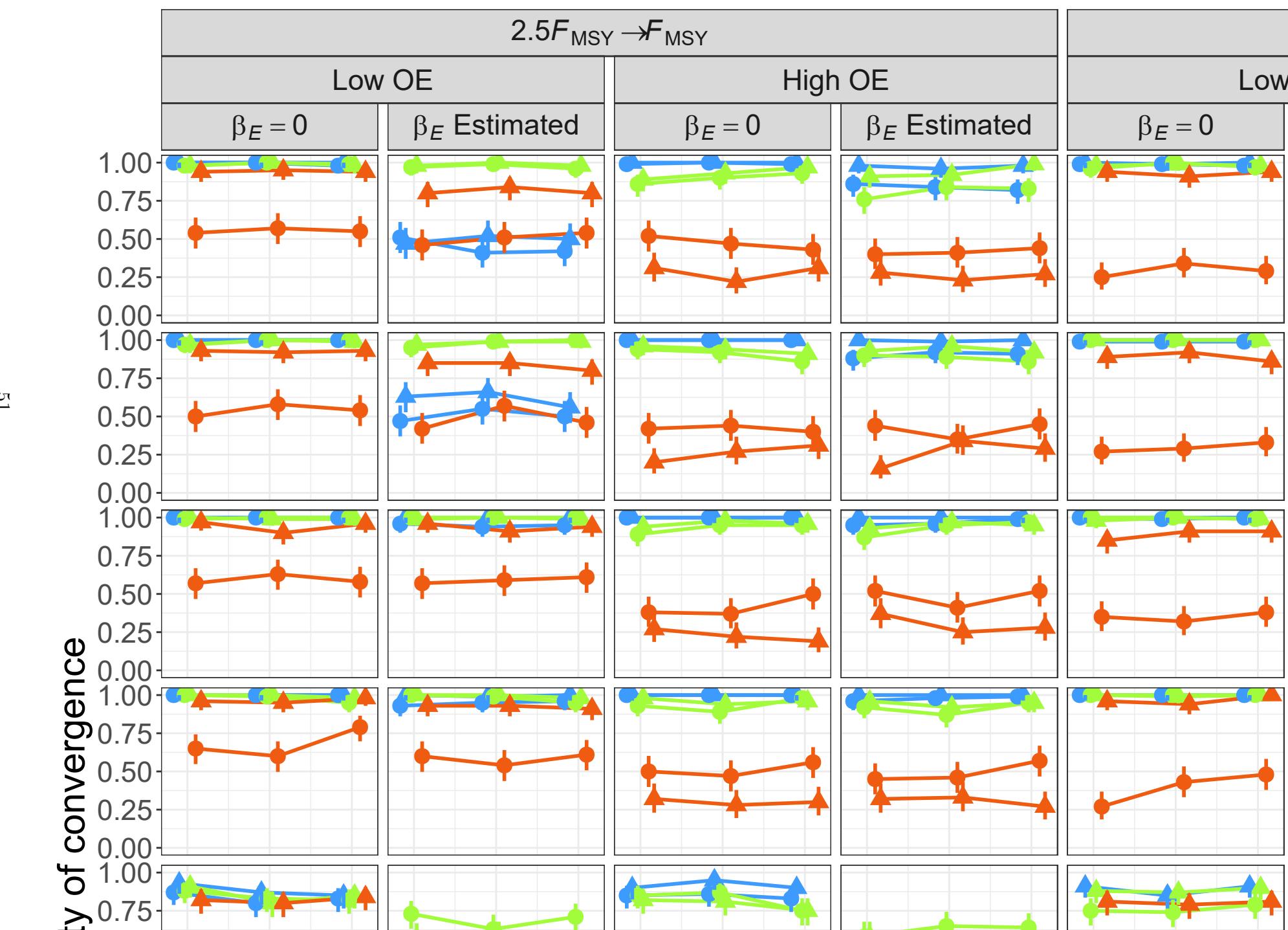
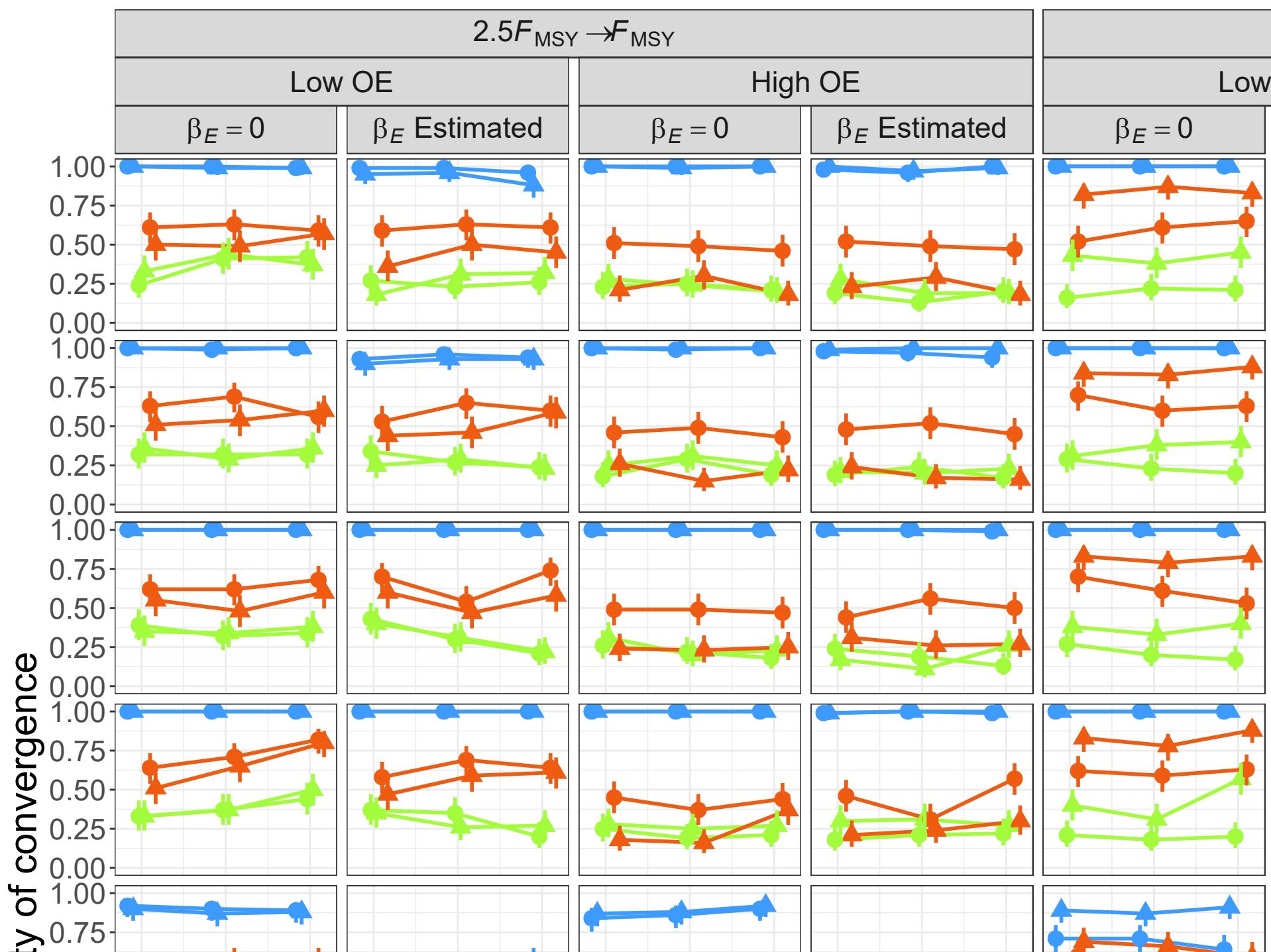


Fig. S11. Median relative error (MRE) of estimates of spawning stock biomass (SSB) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low observation error and contrast in fishing mortality.

596 **Convergence results**







₅₉₇ **AIC results**

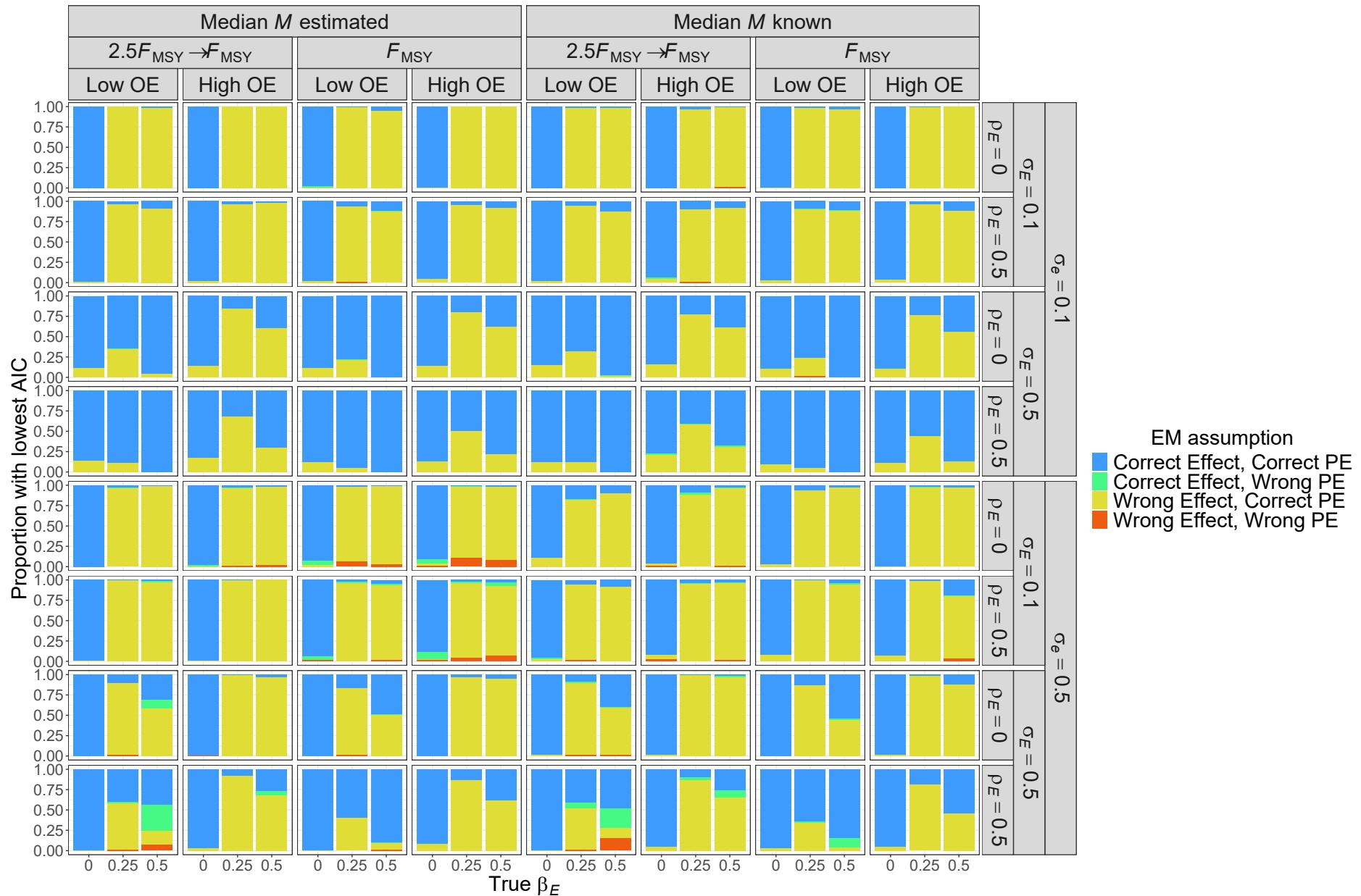


Fig. S15. Proportion of simulated data sets for R OMs where the EM type (treatment of environmental covariate and assumed process error type) had the lowest AIC.

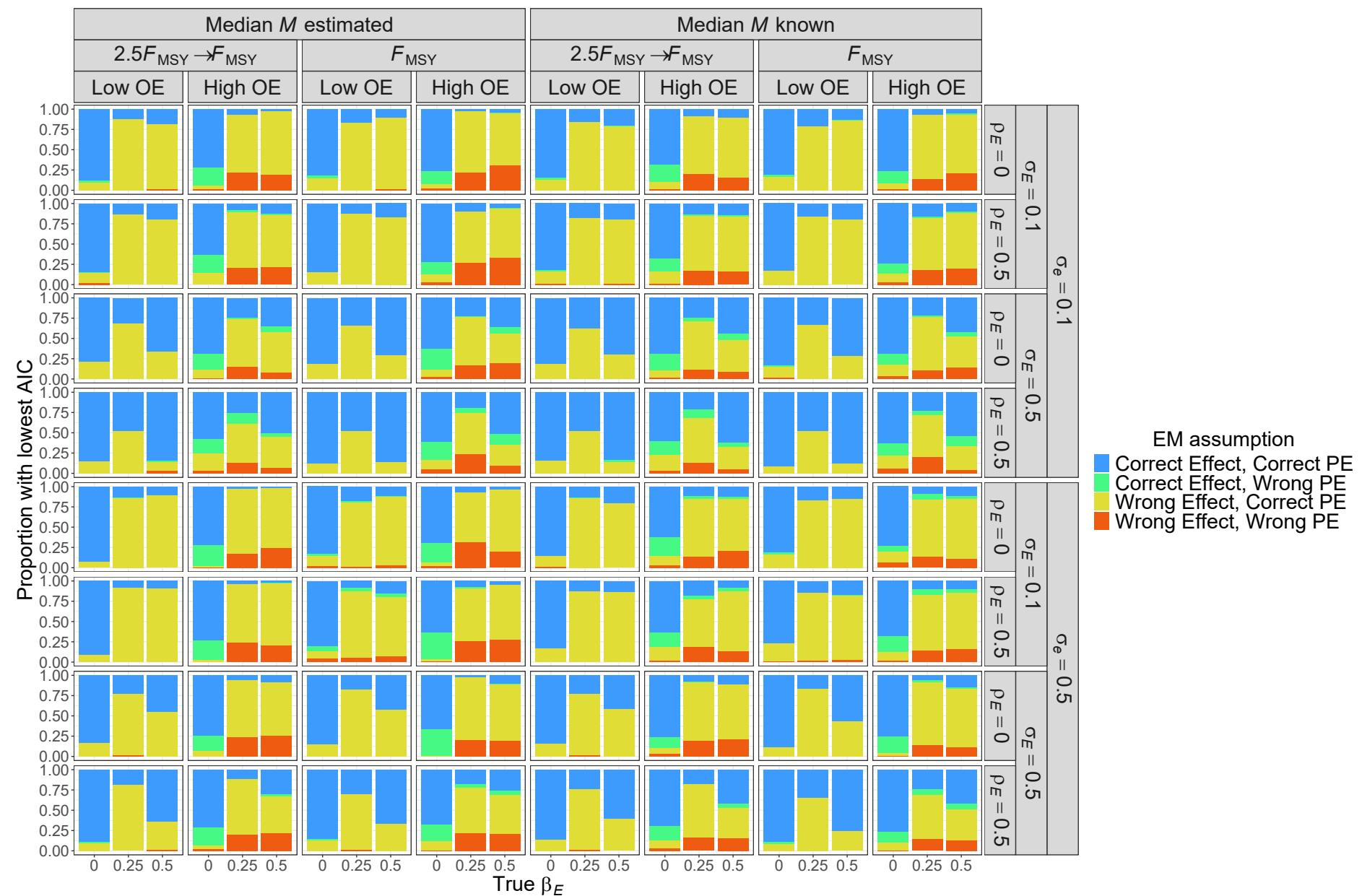


Fig. S16. Proportion of simulated data sets for R+S OMs where the EM type (treatment of environmental covariate and assumed process error type) had the lowest AIC.

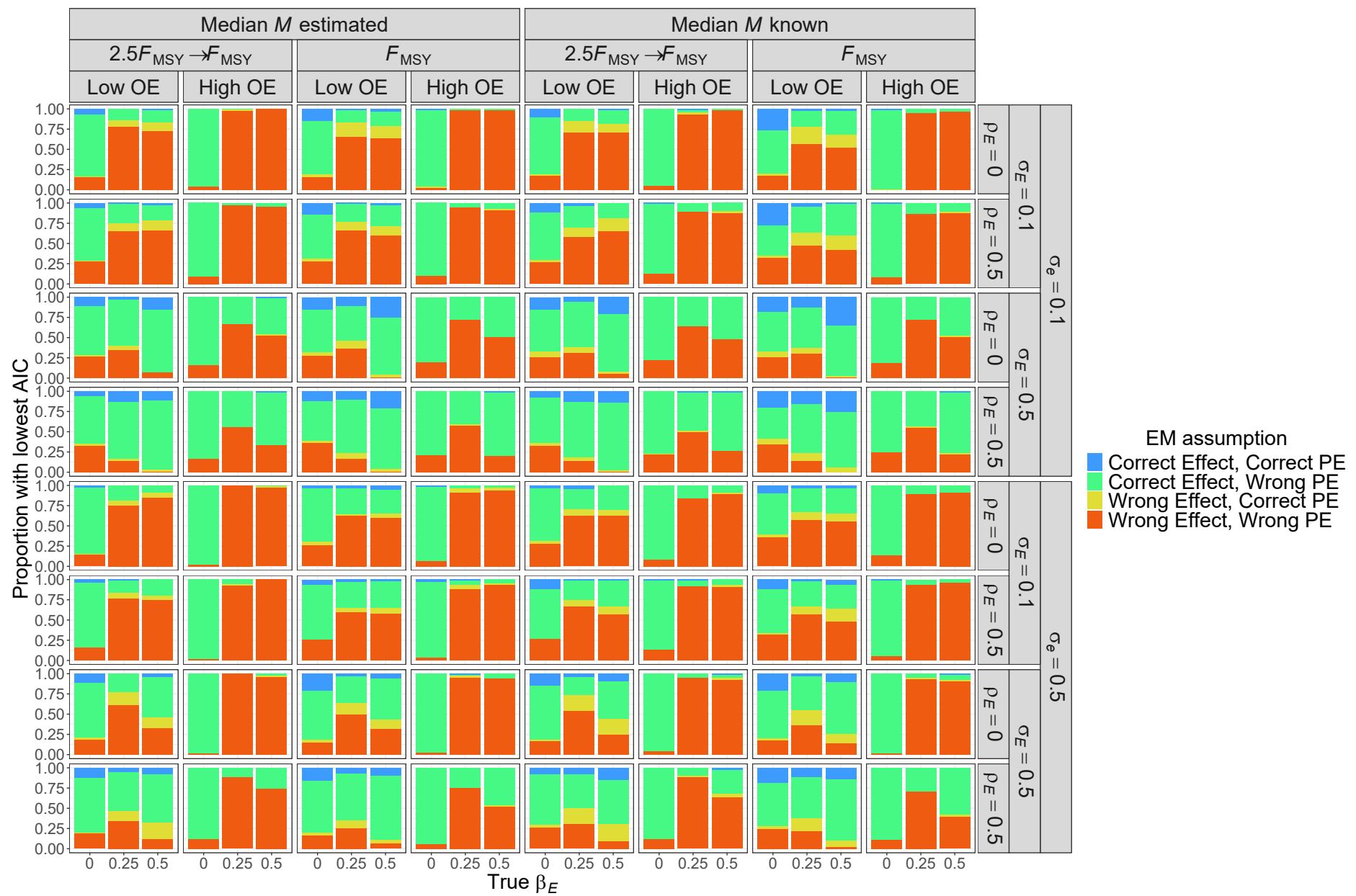


Fig. S17. Proportion of simulated data sets for R+M OMs where the EM type (treatment of environmental covariate and assumed process error type) had the lowest AIC.

598 Covariate effect bias

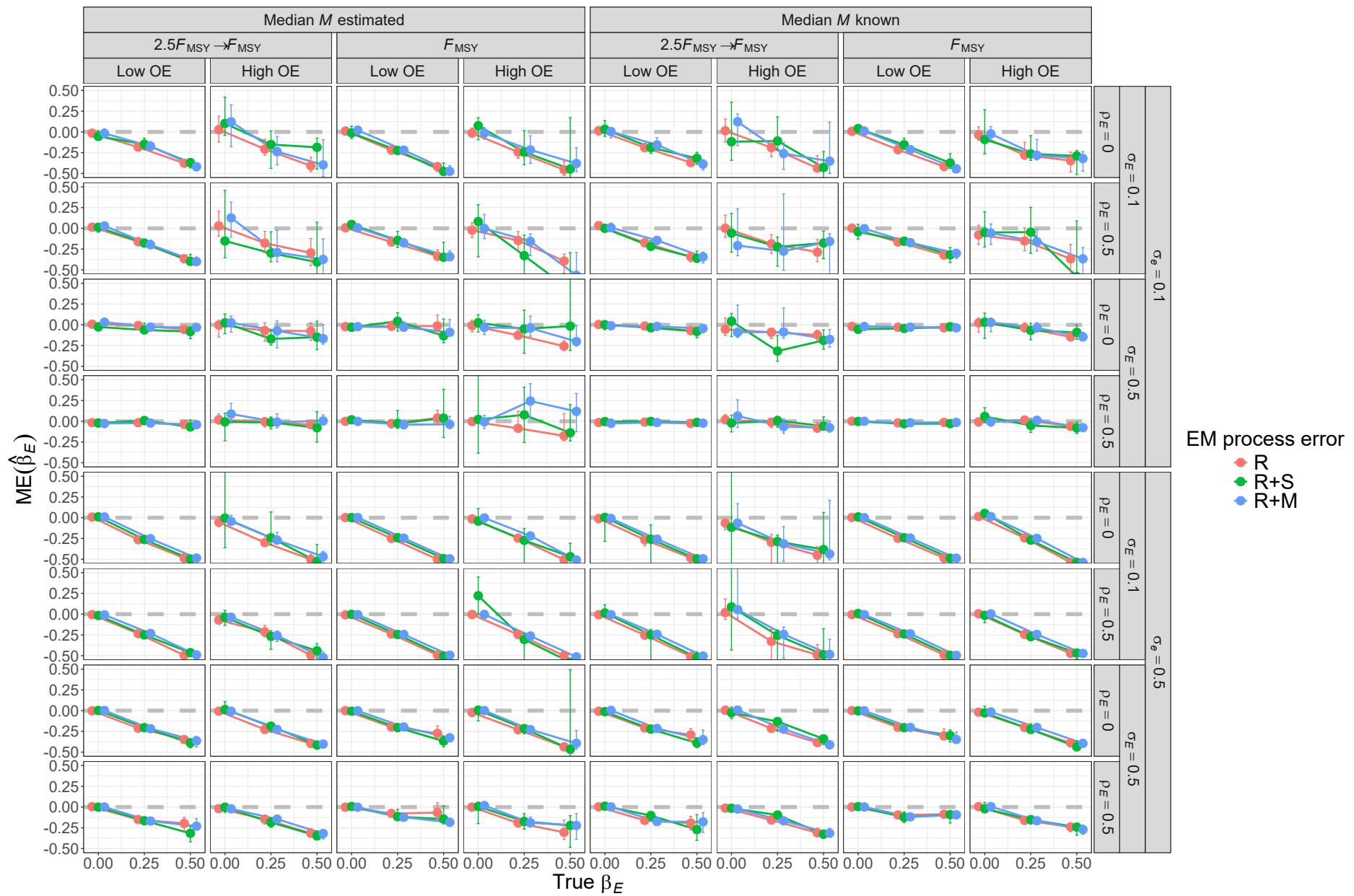


Fig. S18. For R OMs, median error (ME) of estimates of environmental effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

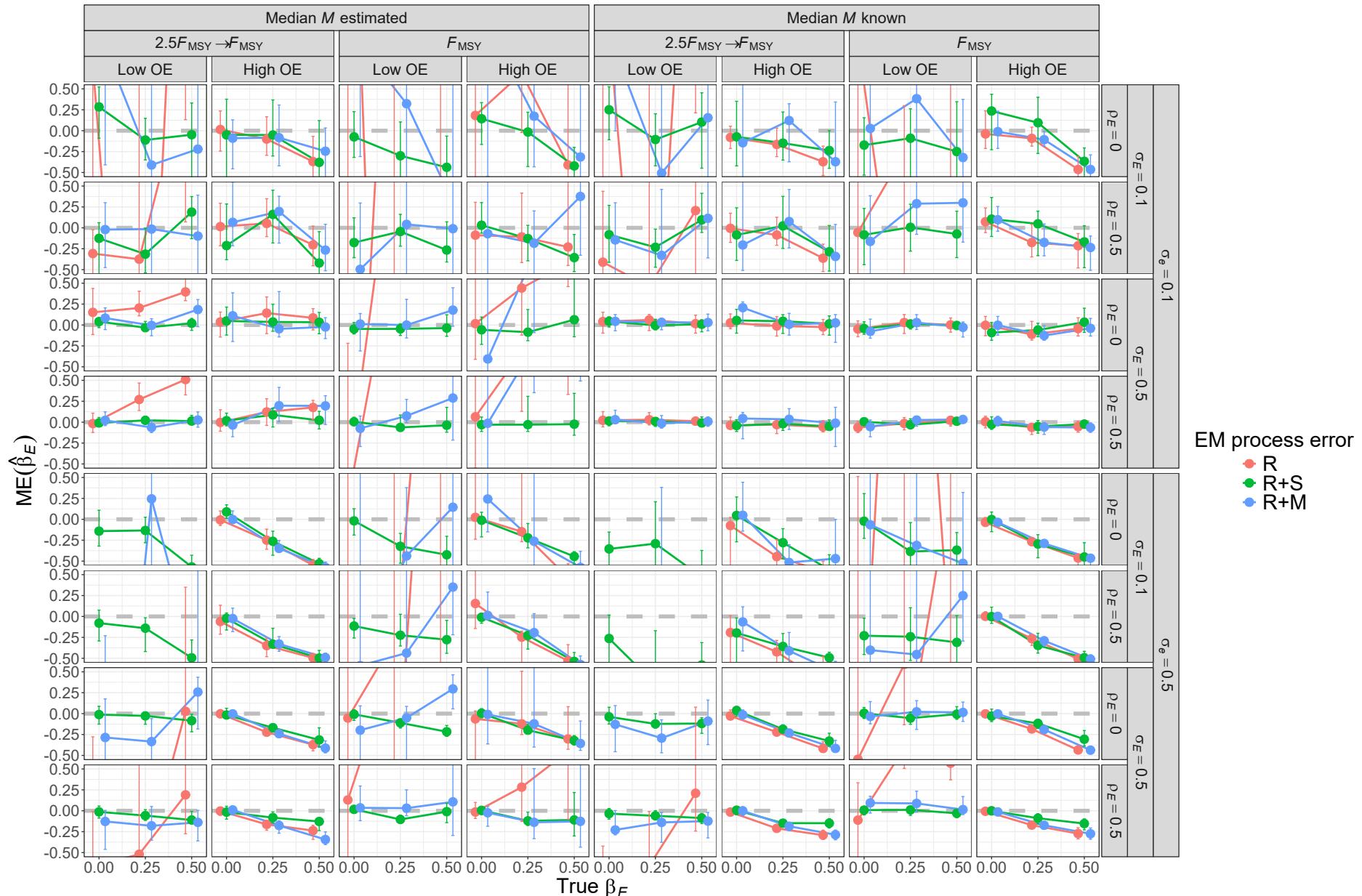


Fig. S19. For R+S OMs, median error (ME) of estimates of environmental effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

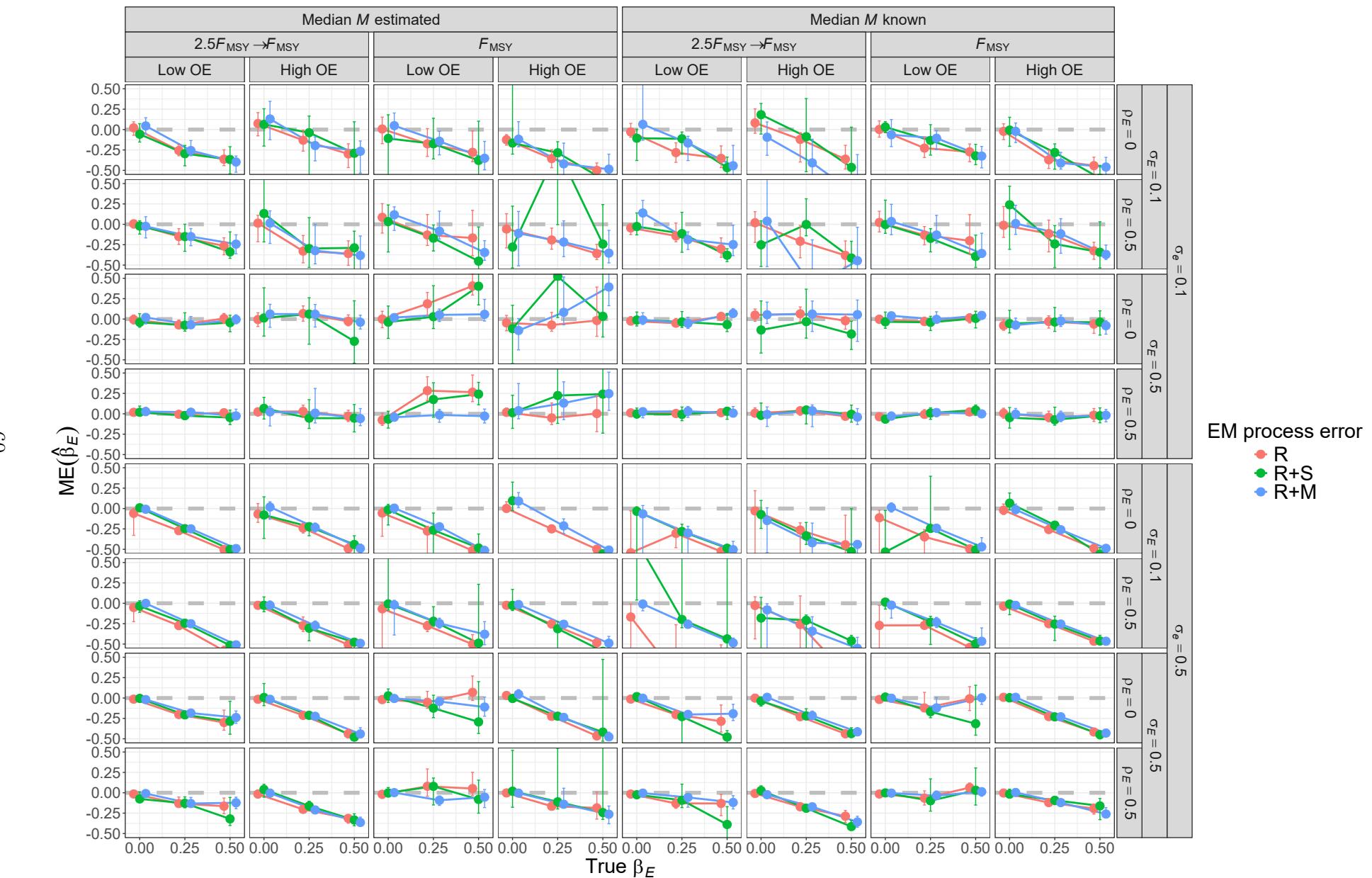


Fig. S20. For R+M OMs, median error (ME) of estimates of environmental effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

⁵⁹⁹ Covariate effect standard error estimation bias

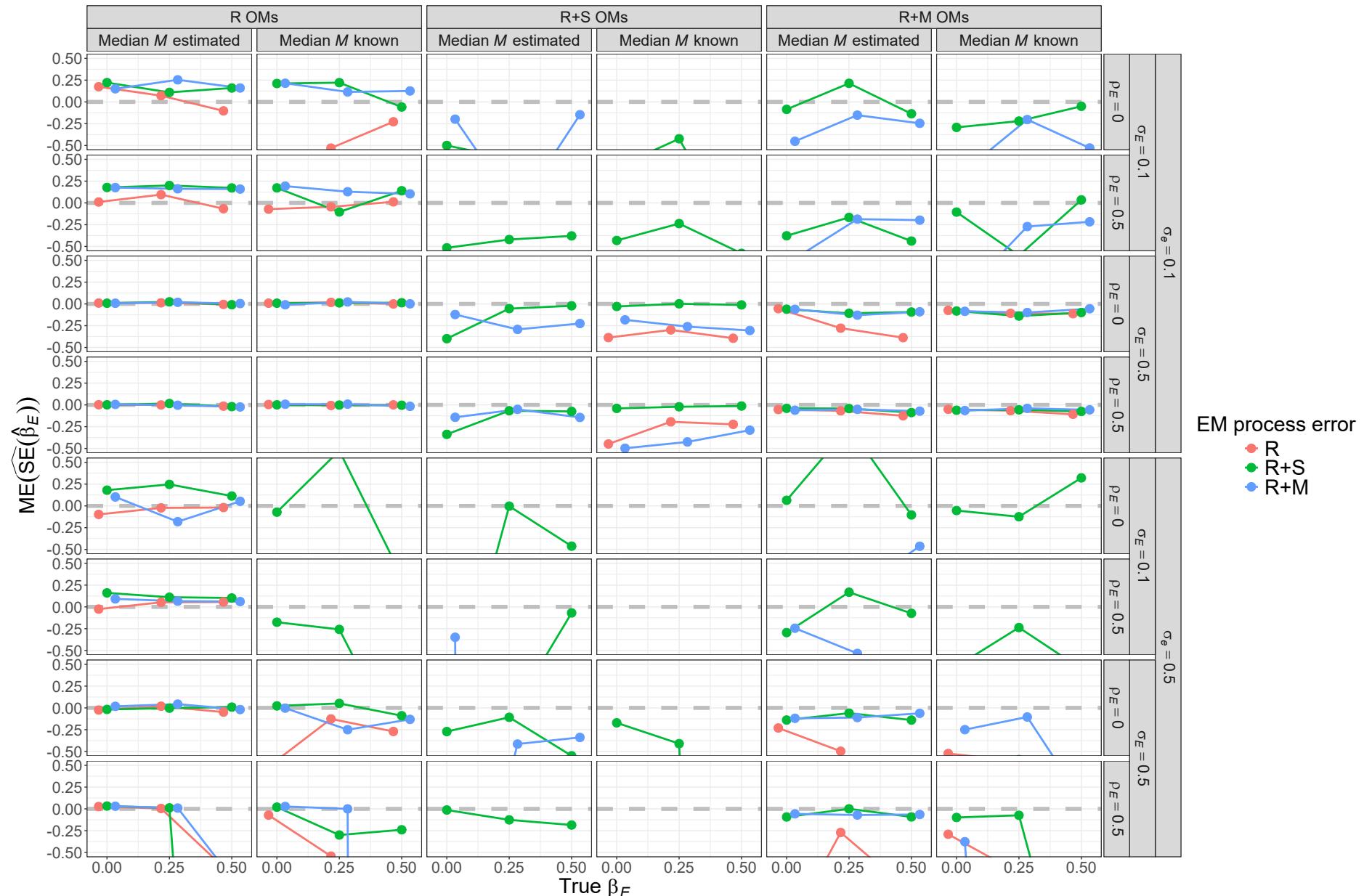


Fig. S21. Median error (ME) of Hessian-based estimates of standard error for covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). All OMs had low observation error and contrast in fishing mortality. True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

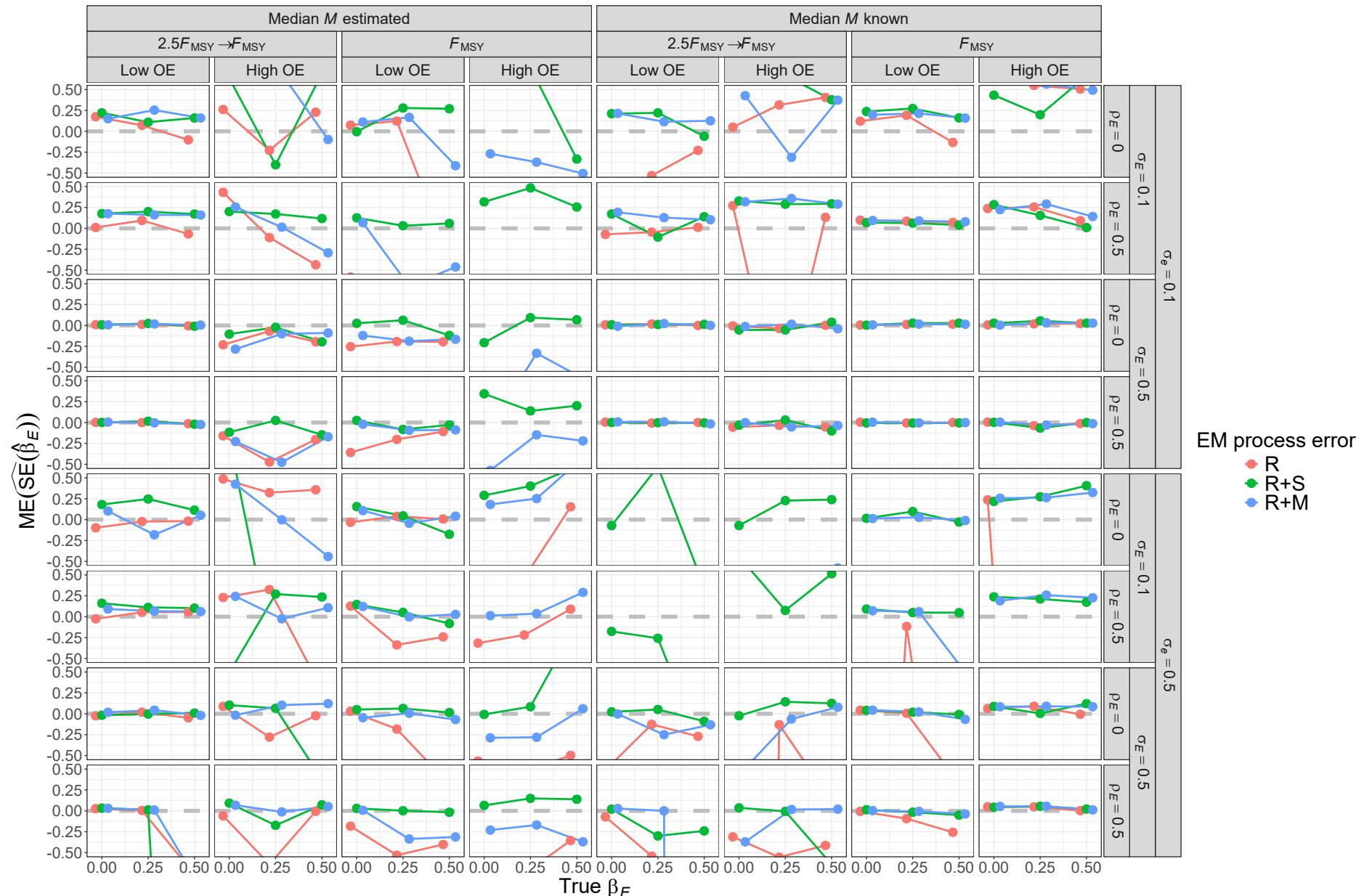


Fig. S22. For R OMs, median error (ME) of Hessian-based estimates of standard error for covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

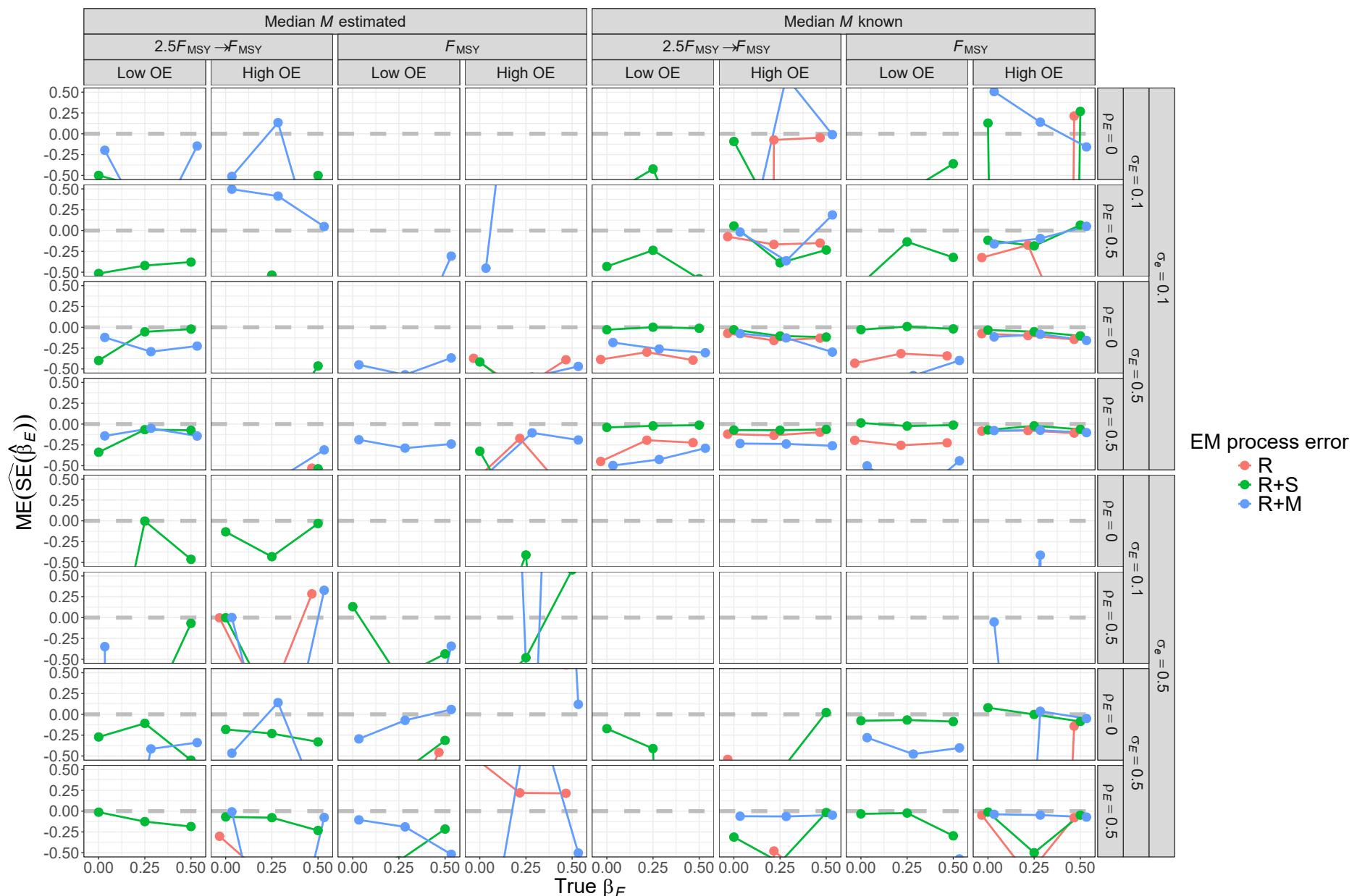


Fig. S23. For R+S OMs, median error (ME) of Hessian-based estimates of standard error for covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

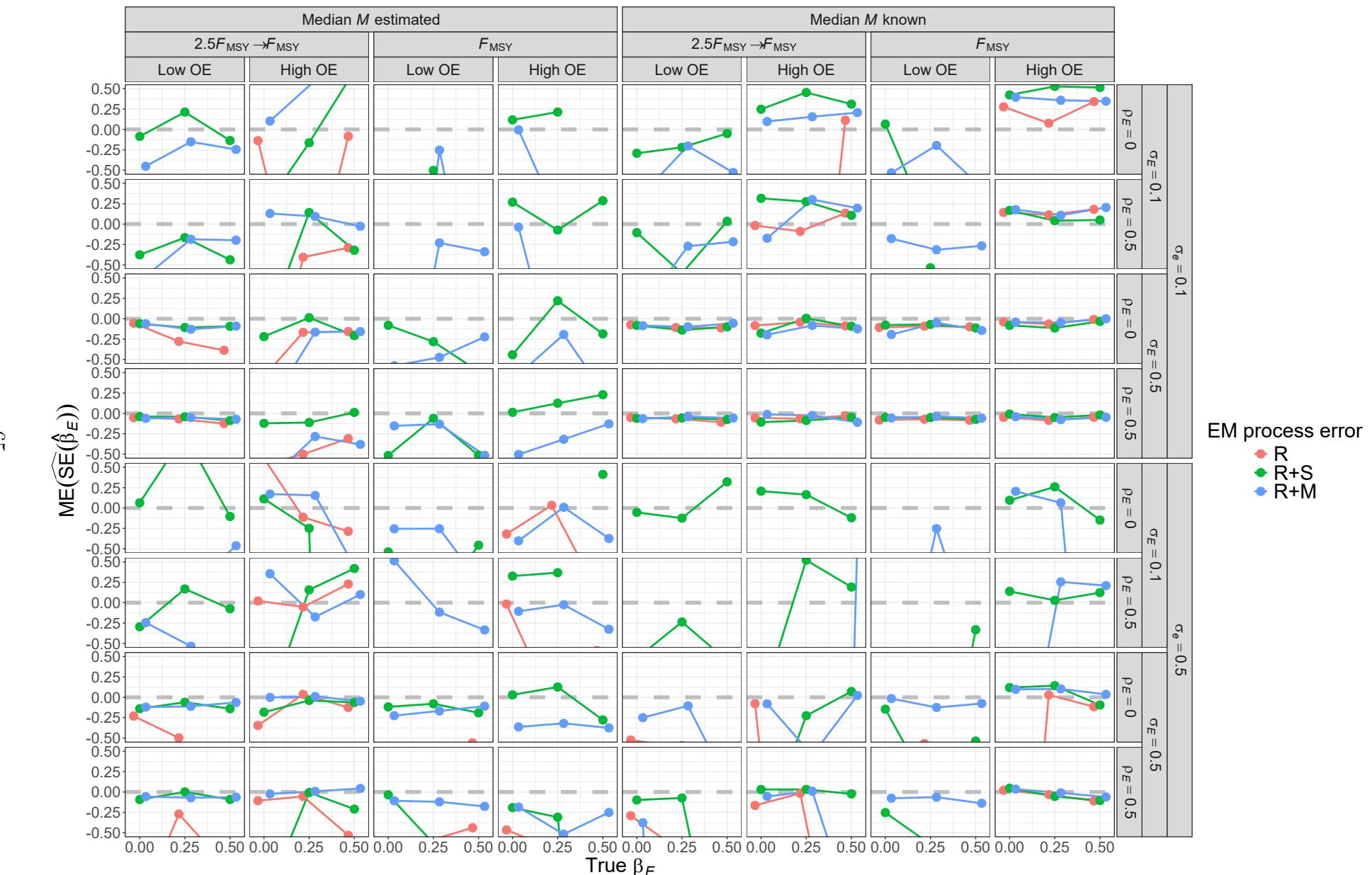


Fig. S24. For R+M OMs, median error (ME) of Hessian-based estimates of standard error for covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

600 Covariate effect confidence interval coverage

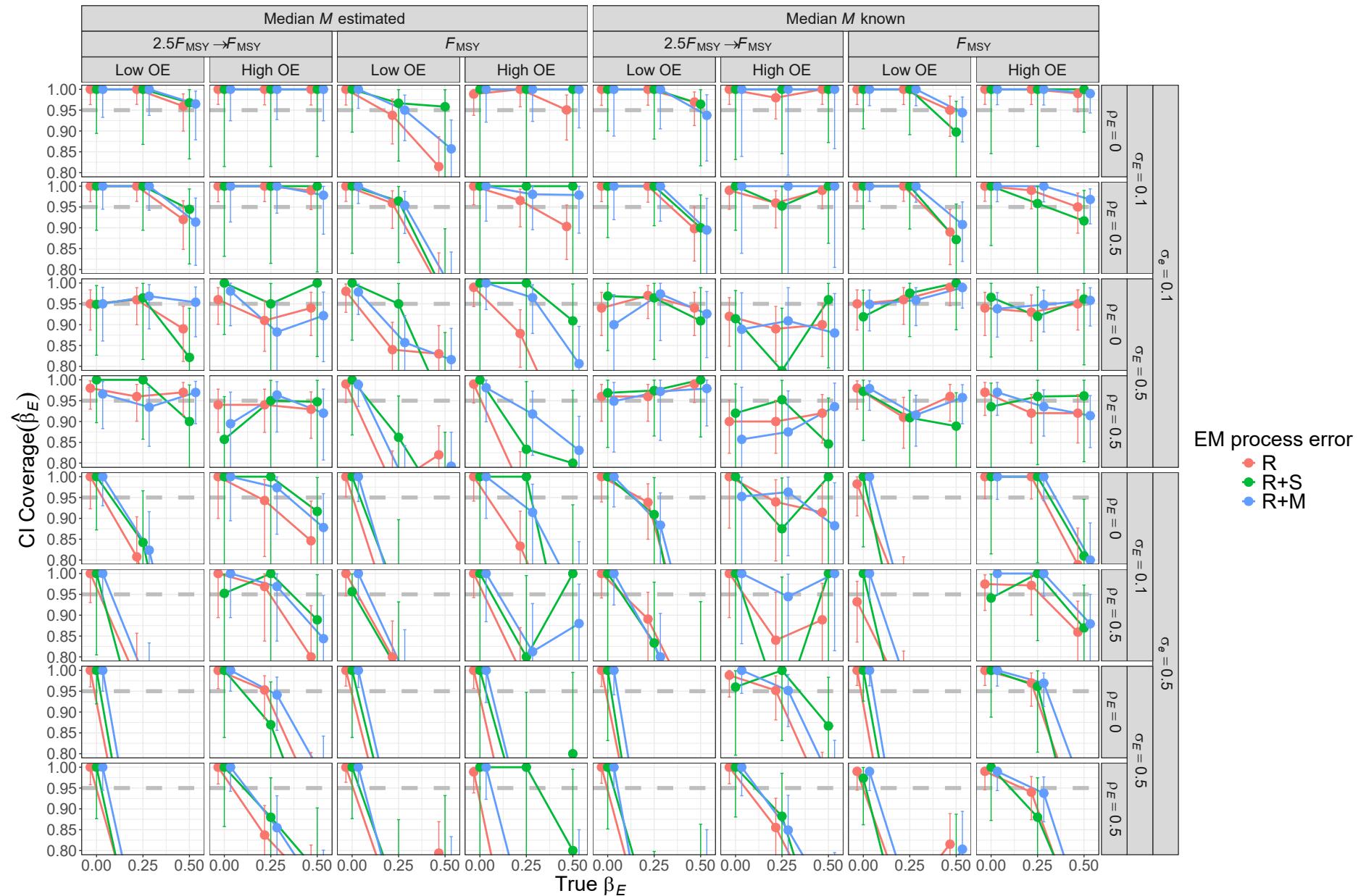


Fig. S25. For R OMs, probability of 95% confidence interval for β_E containing the true value for EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

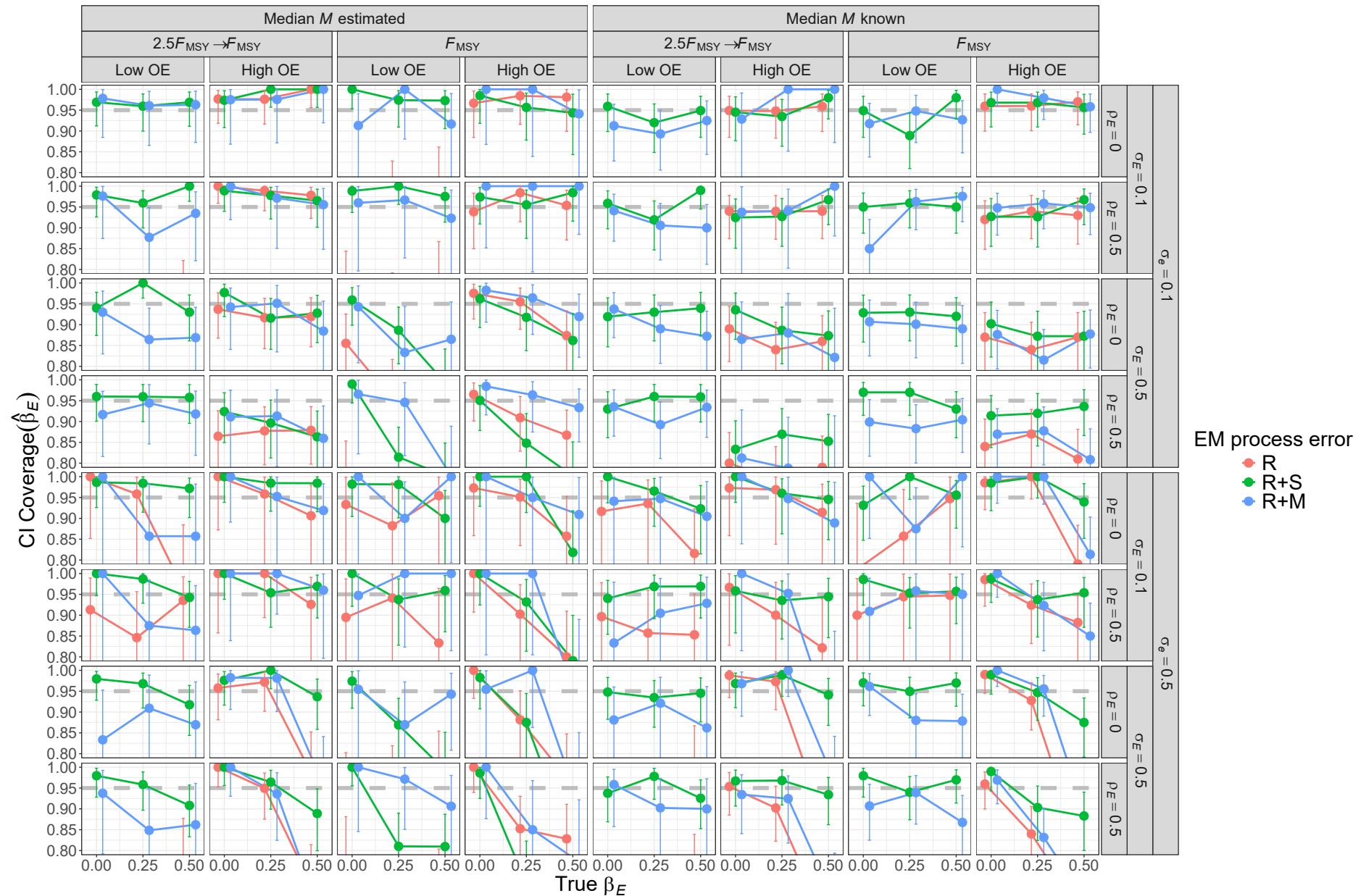


Fig. S26. For R+S OMs, probability of 95% confidence interval for β_E containing the true value for EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

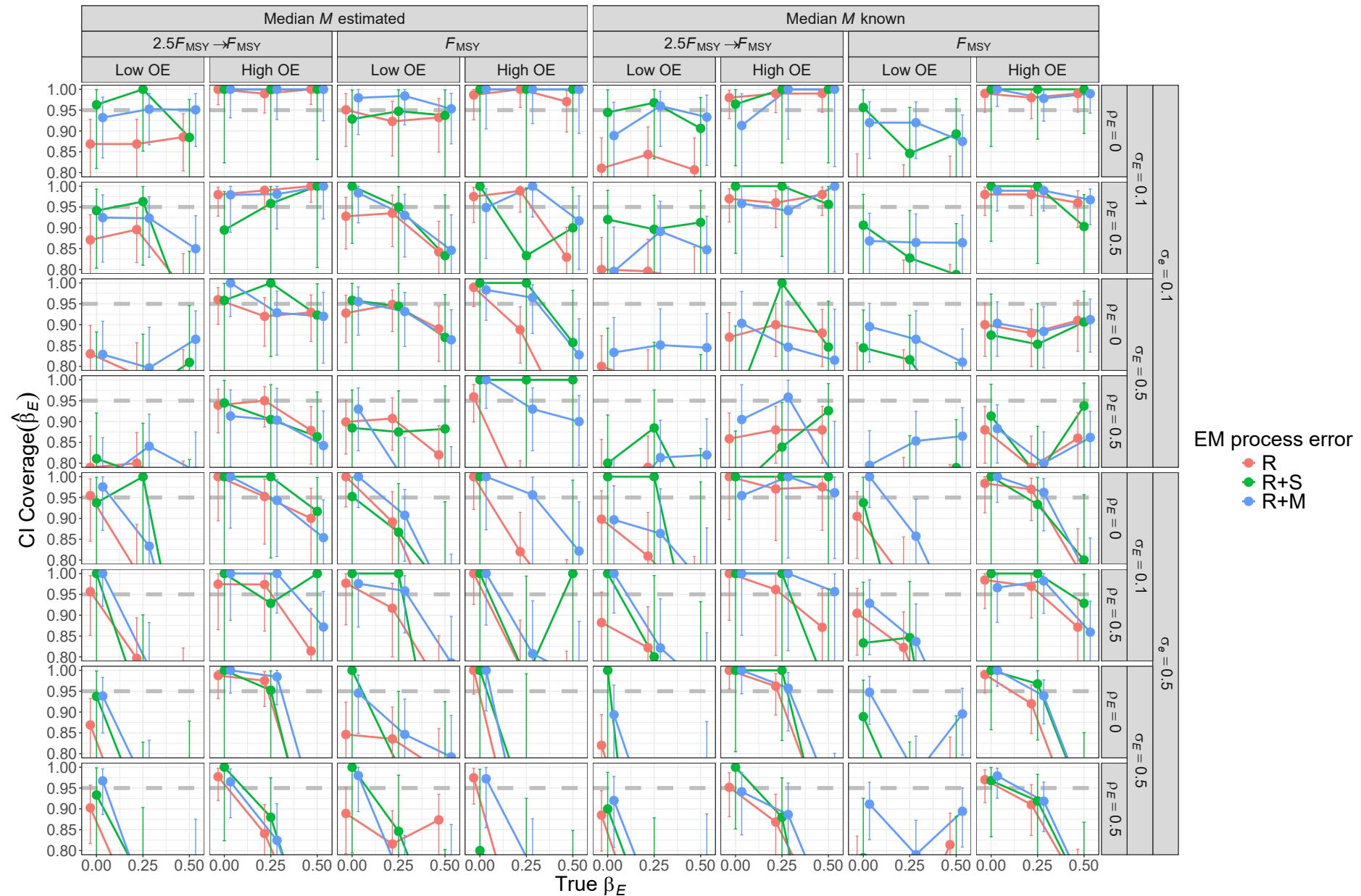


Fig. S27. For R+M OMs, probability of 95% confidence interval for β_E containing the true value for EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). Vertical lines represent 95% confidence intervals.

₆₀₁ Covariate effect RMSE

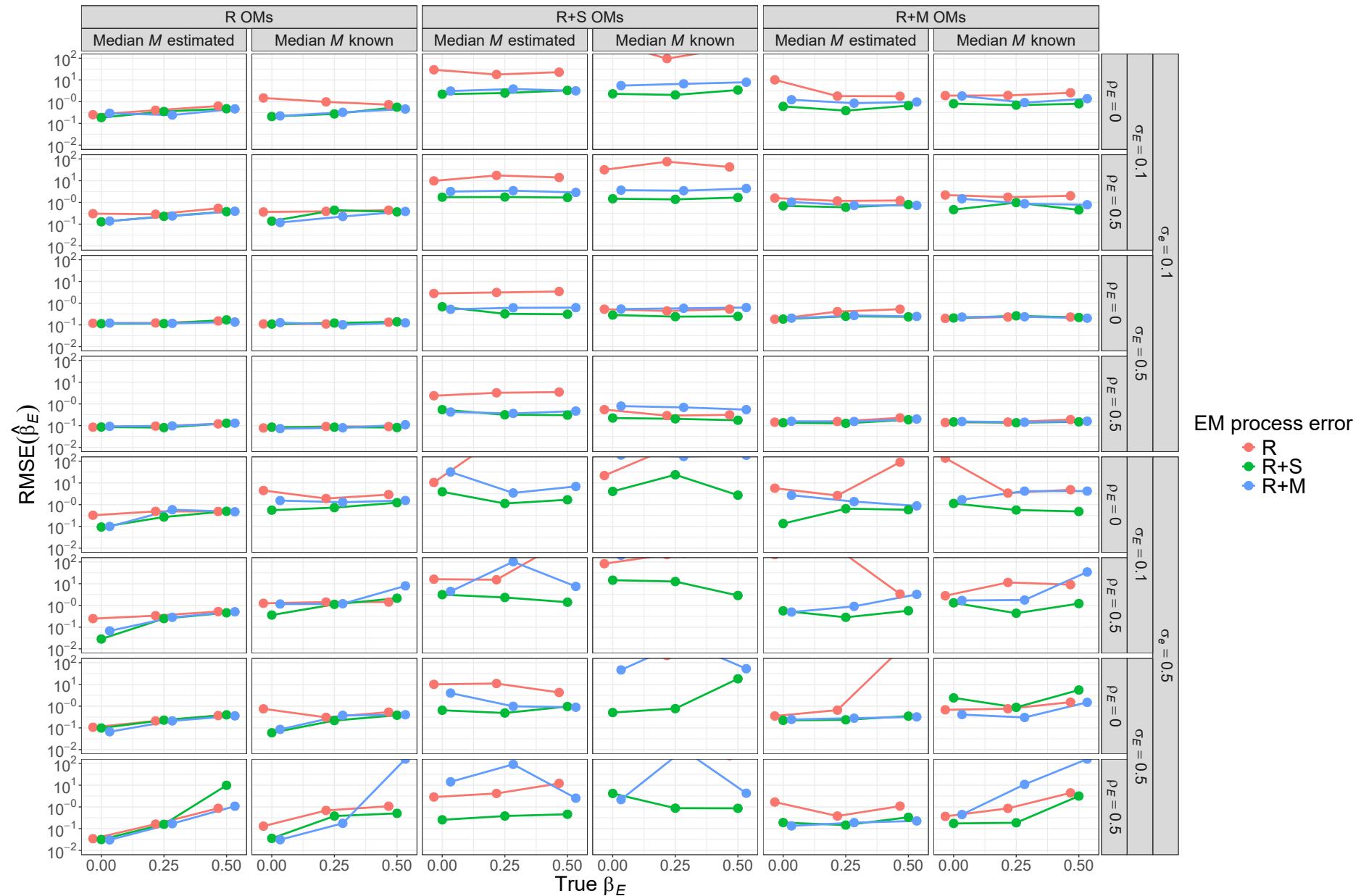


Fig. S28. Root mean square error (RMSE) of estimates of covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated). All OMs had low observation error and contrast in fishing mortality.

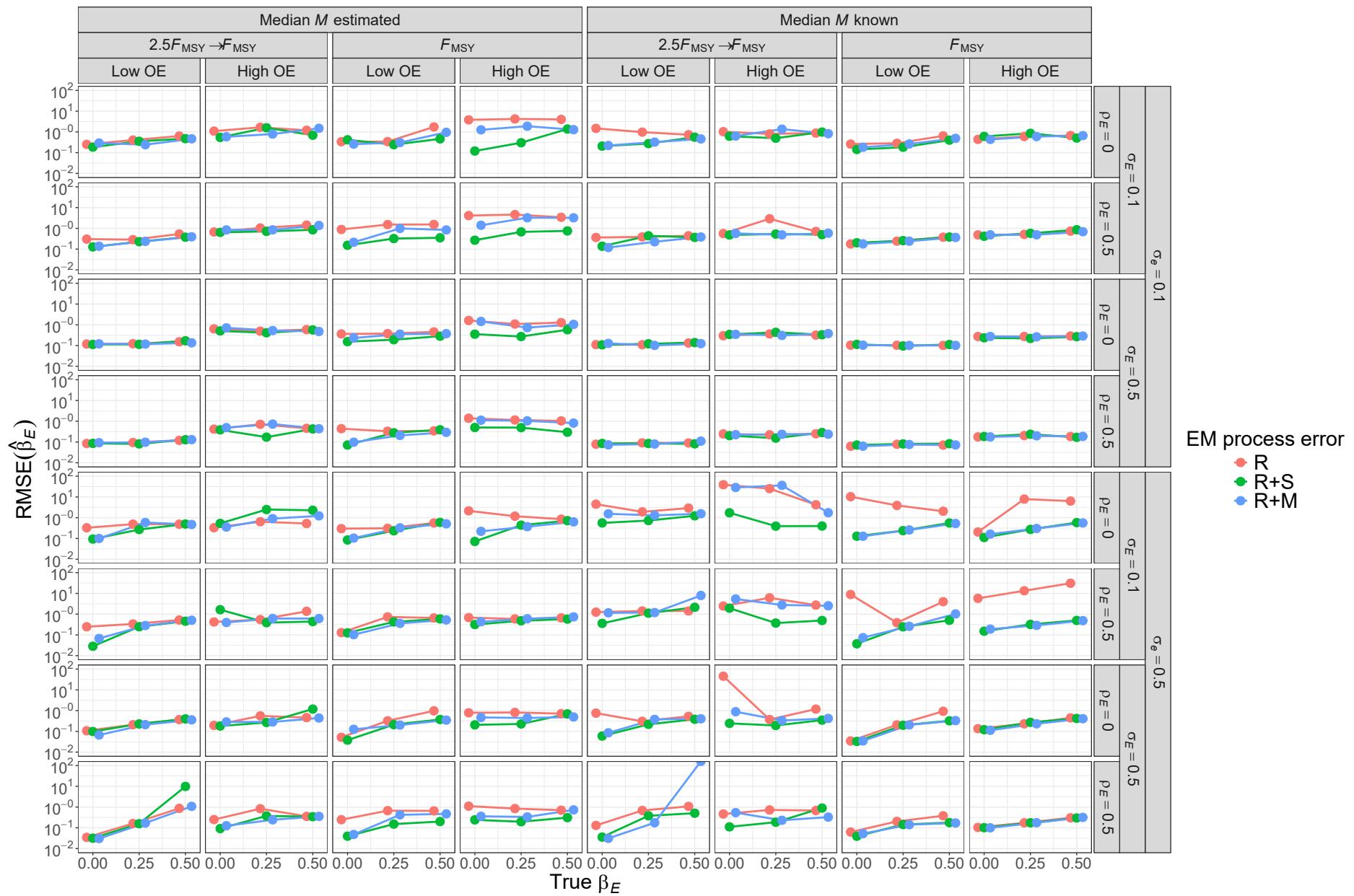


Fig. S29. For R OMs, root mean square error (RMSE) of estimates of covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated).

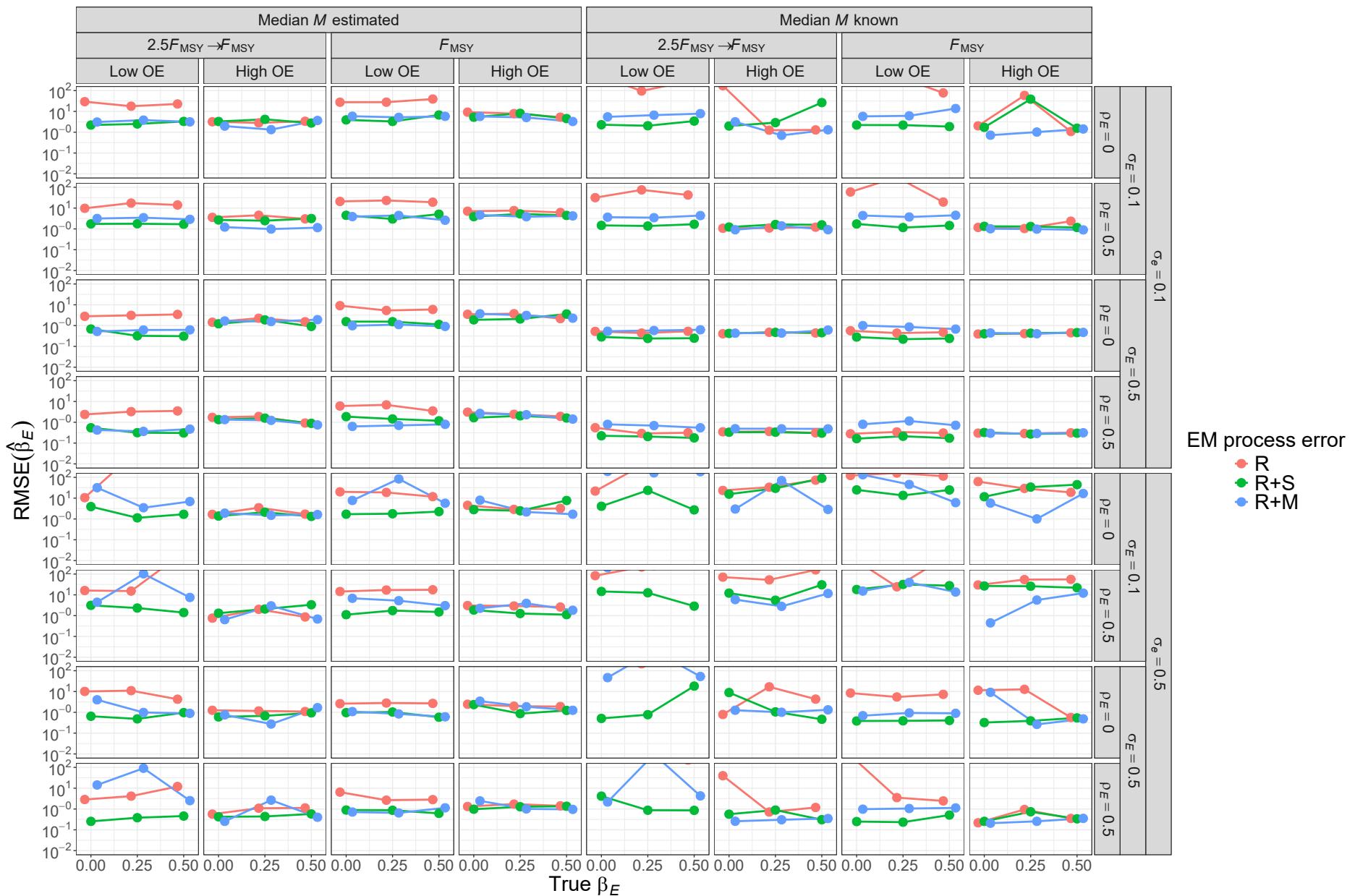


Fig. S30. For R+S OMs, root mean square error (RMSE) of estimates of covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated).

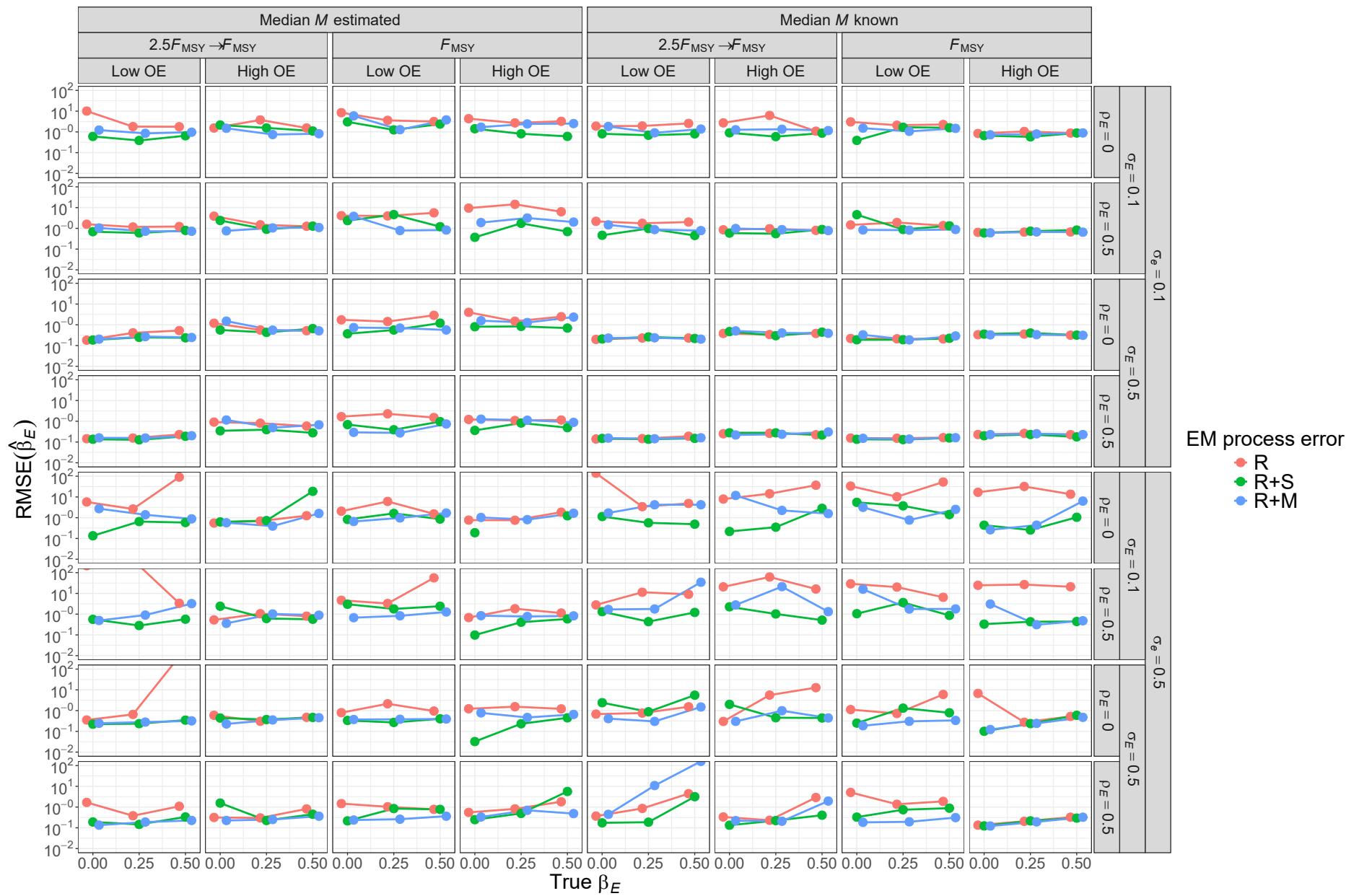


Fig. S31. For R+M OMs, root mean square error (RMSE) of estimates of covariate effect on natural mortality β_E from fitting EMs with alternative process error assumptions and treatment of median natural mortality (e_M^β known or estimated).

602 Covariate effect estimate and standard error example

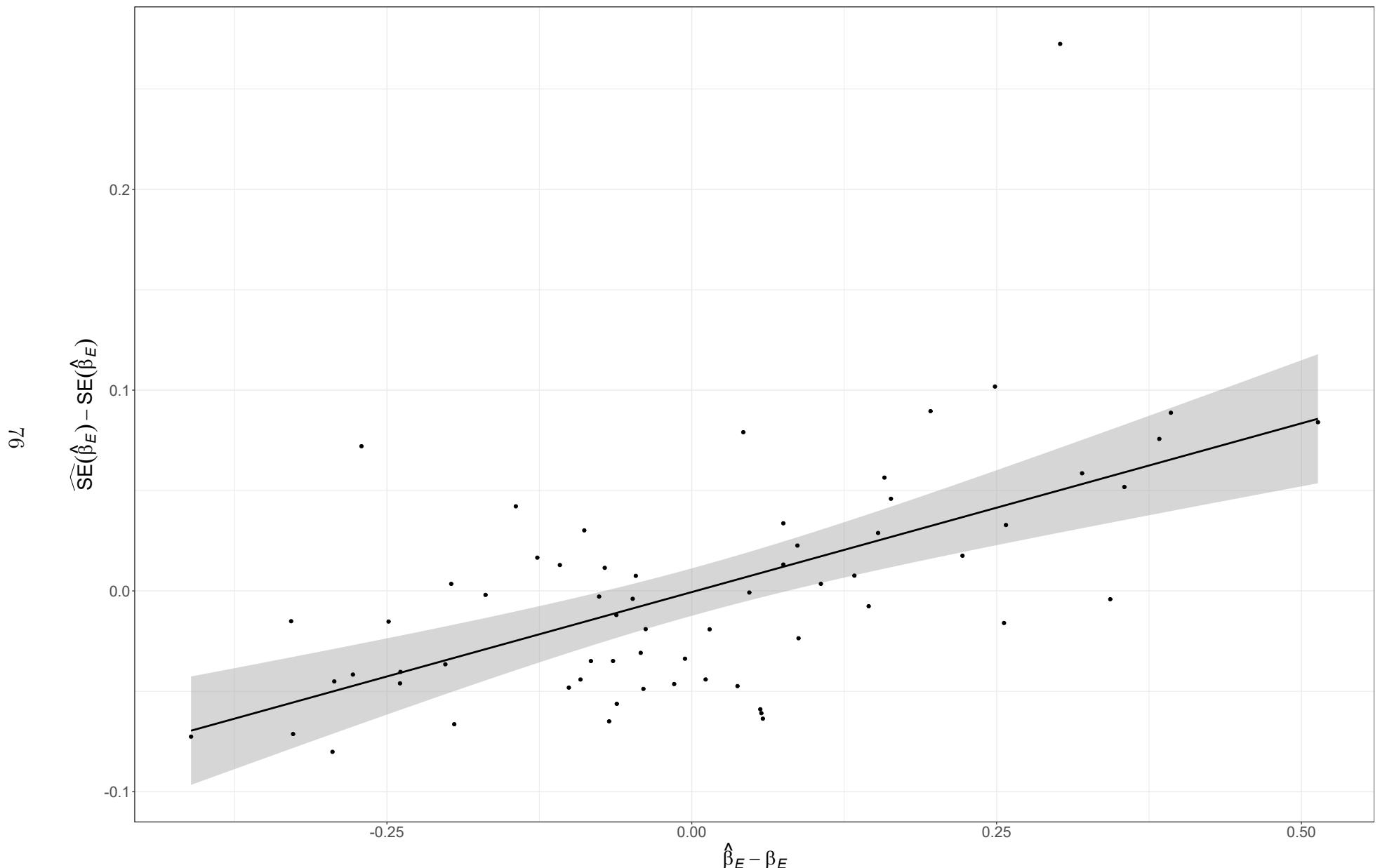


Fig. S32. Positive correlation of covariate effect estimates and Hessian-based standard error estimates for EM that also estimates the median natural mortality parameter and has correct R+M process error assumption fitted to simulated data from the OM with R+M process errors, temporal contrast in fishing pressure, low observation uncertainty for both population (*LowOE*) and covariate observations ($\sigma_e = 0.1$), high and uncorrelated temporal variability in the true covariate ($\sigma_E = 0.5$ and $\rho_E = 0$), and

603 Median Natural mortality parameter bias

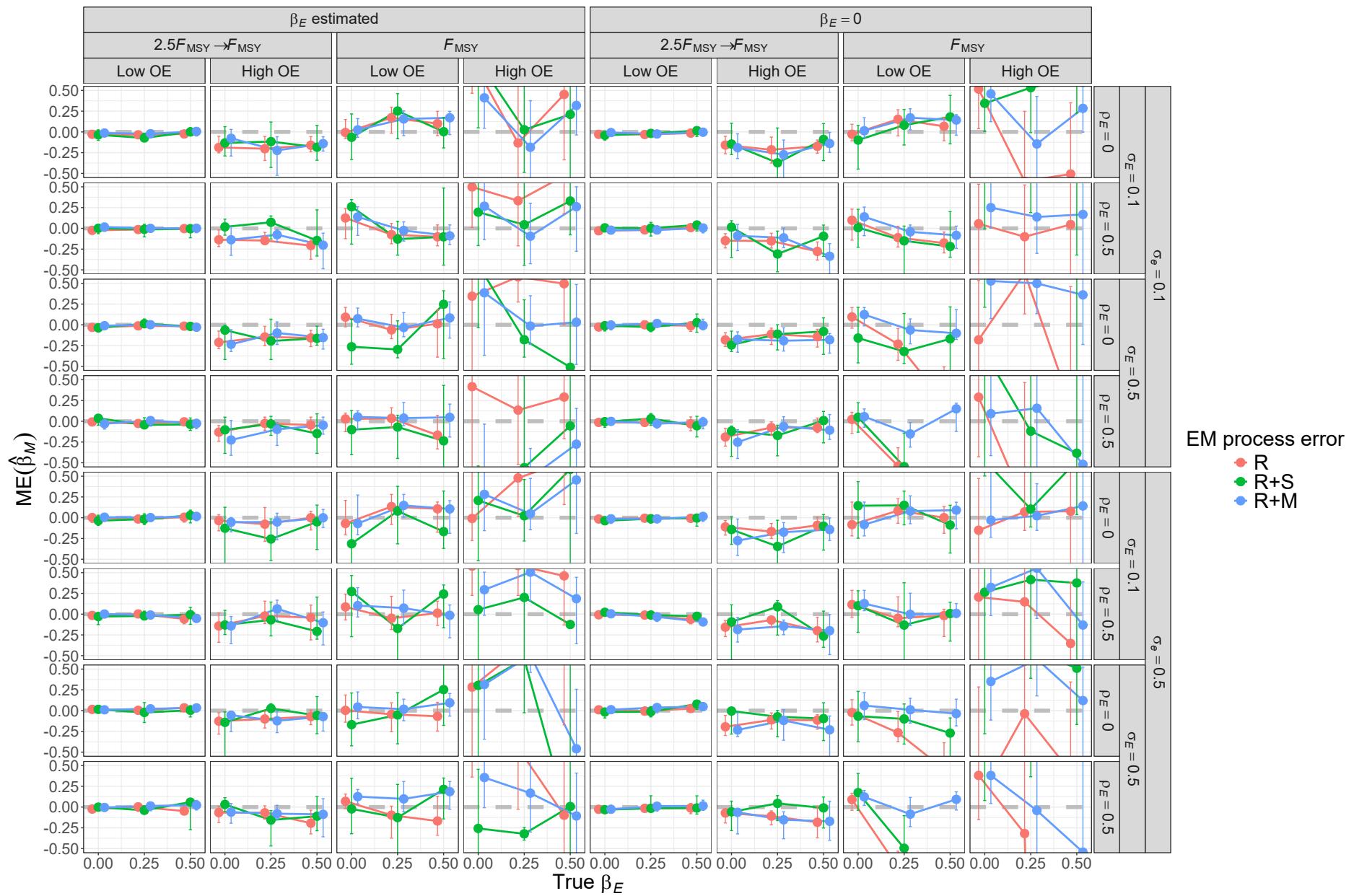


Fig. S33. For R OMs, median error (ME) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

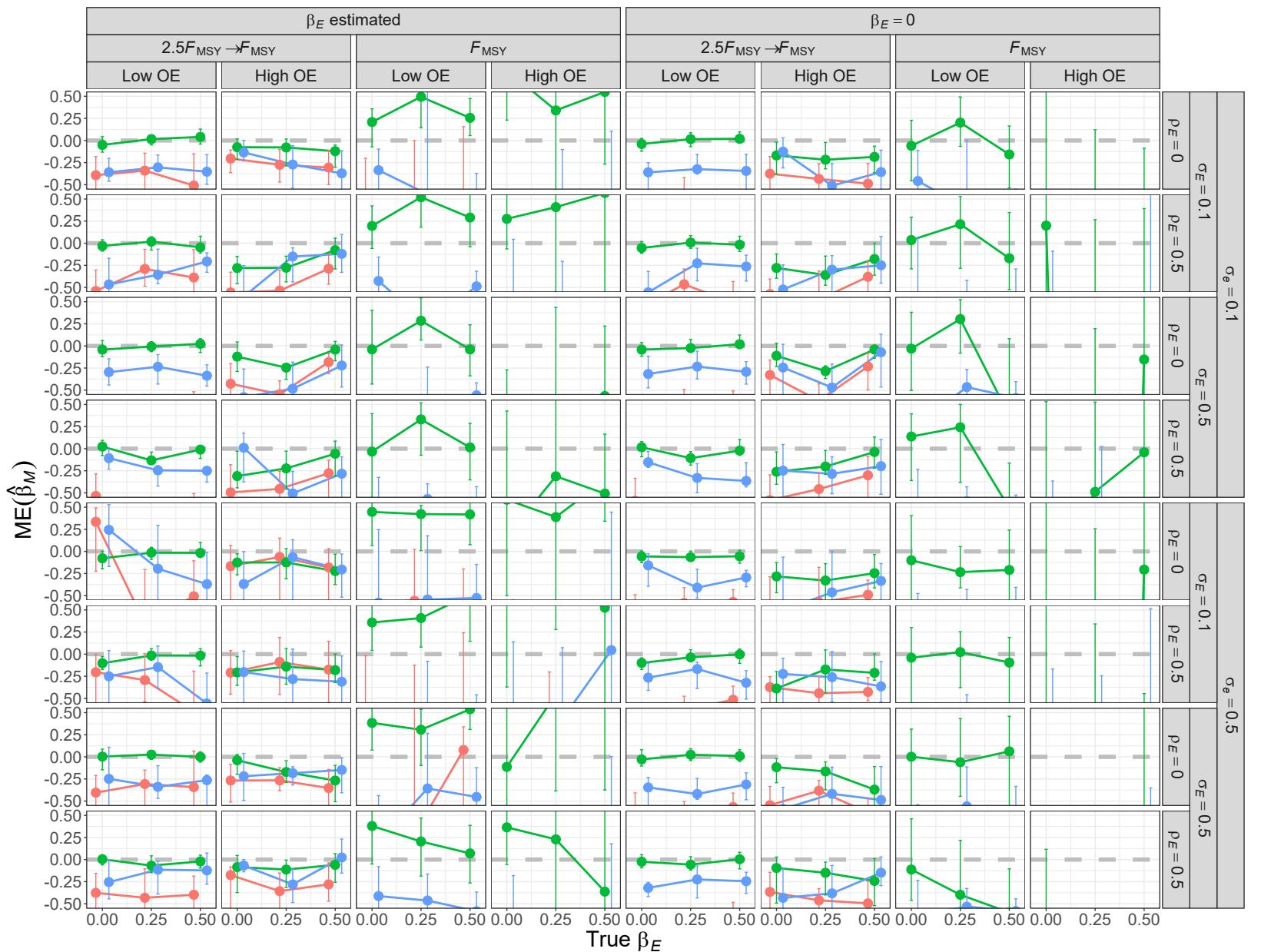


Fig. S34. For R+S OMs, median error (ME) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

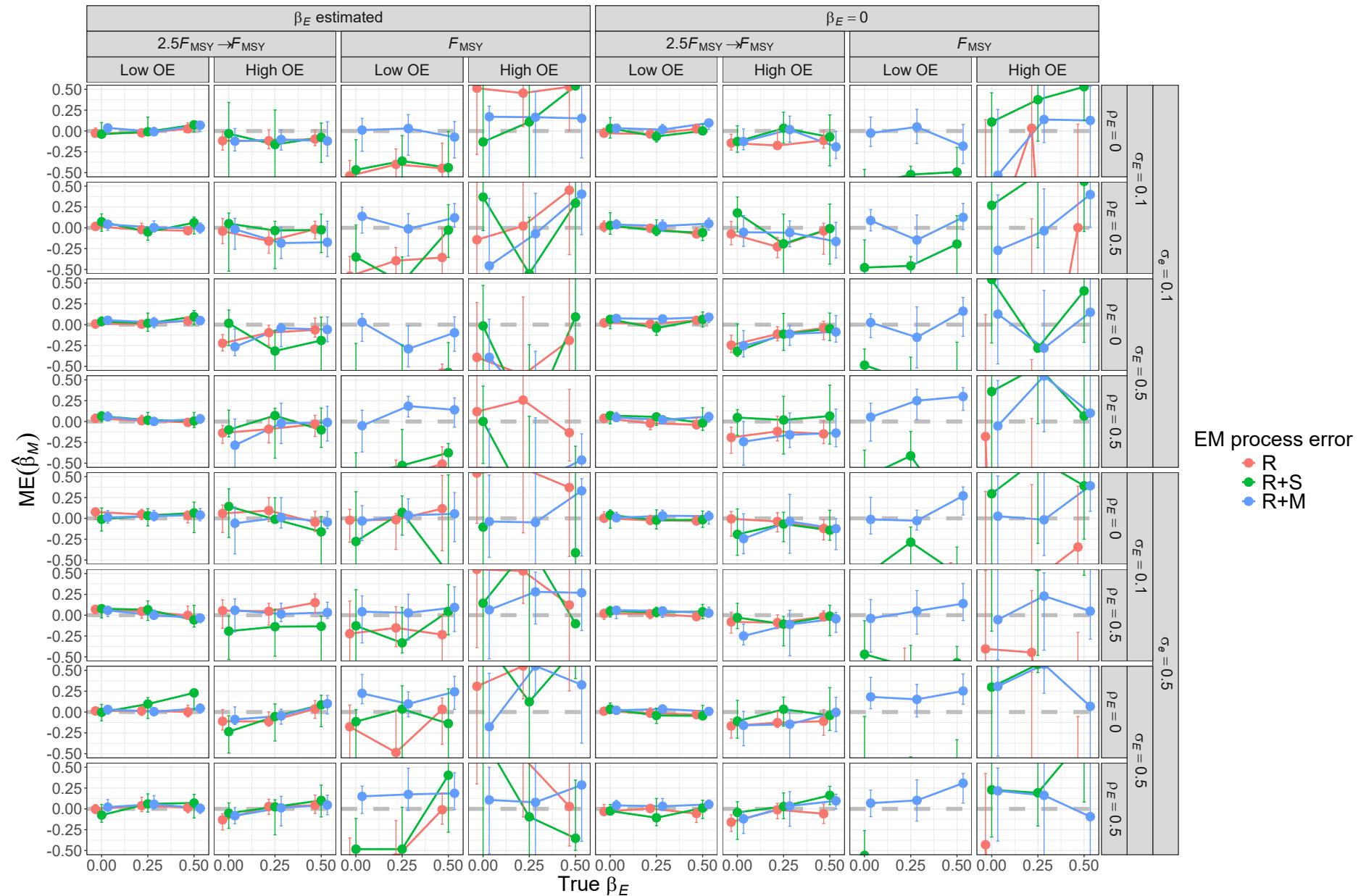


Fig. S35. For R+M OMs, median error (ME) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

⁶⁰⁴ Median natural mortality parameter standard error estimation bias

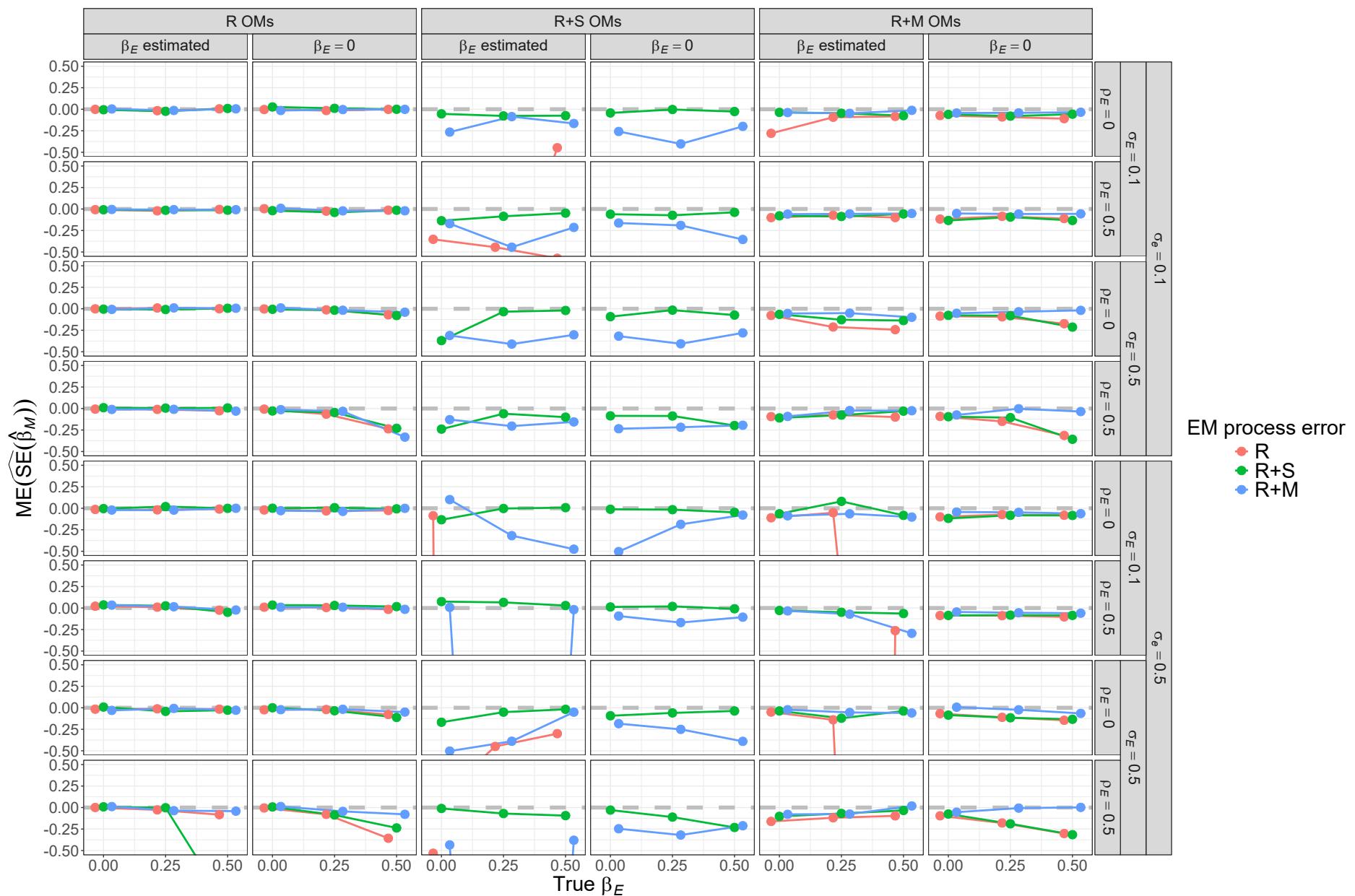


Fig. S36. Median error (ME) of Hessian-based estimates of standard error for median natural mortality parameter β_M from fitting EMs with alternative process error assumptions and treatment of the covariate effect ($\beta_E = 0$ or estimated). All OMs had low observation error and contrast in fishing mortality. True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

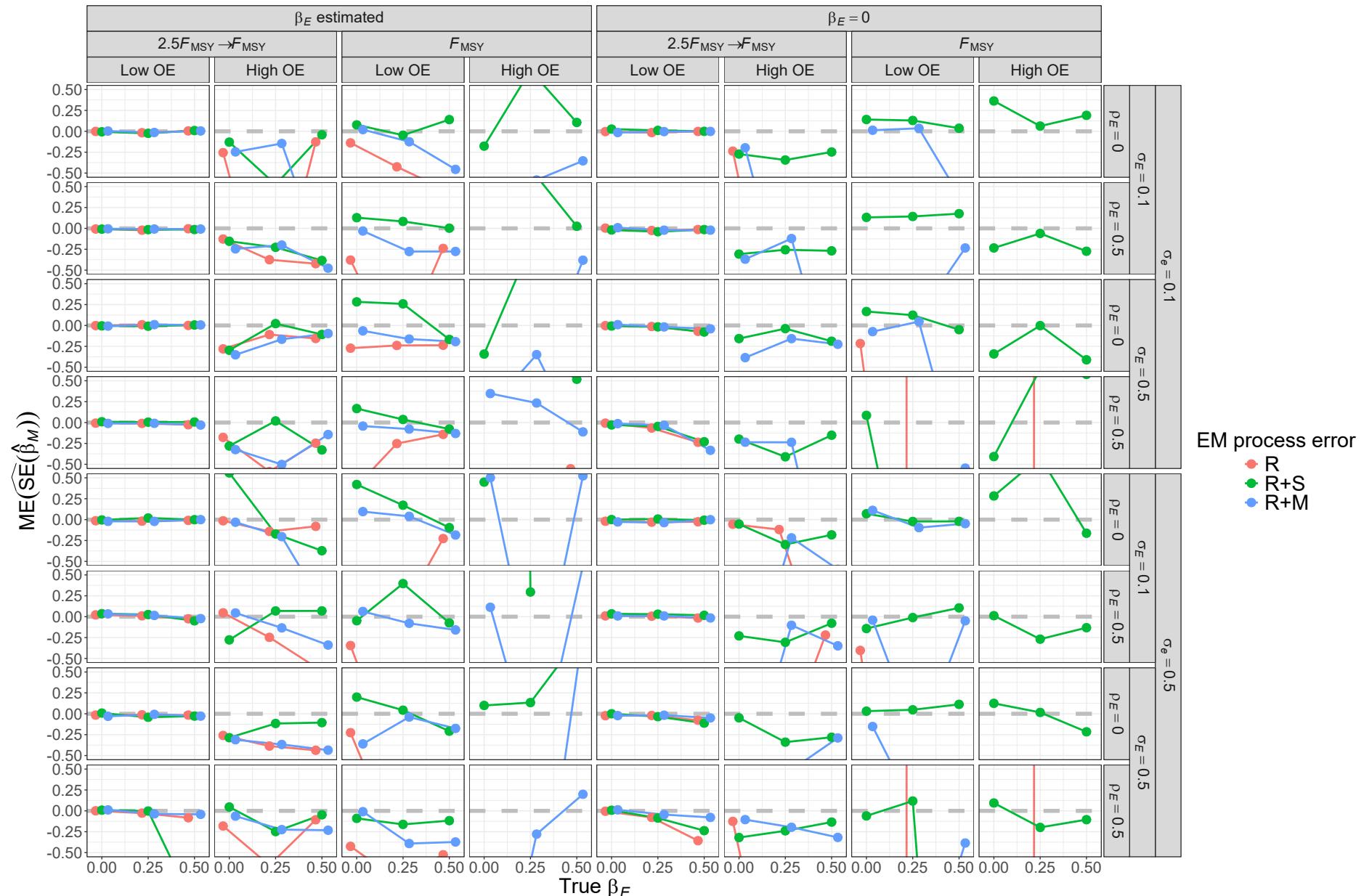


Fig. S37. For R OMs, median error (ME) of Hessian-based estimates of standard error for median natural mortality parameter β_M from fitting EMs with alternative process error assumptions and treatment of the covariate effect ($\beta_E = 0$ or estimated). True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

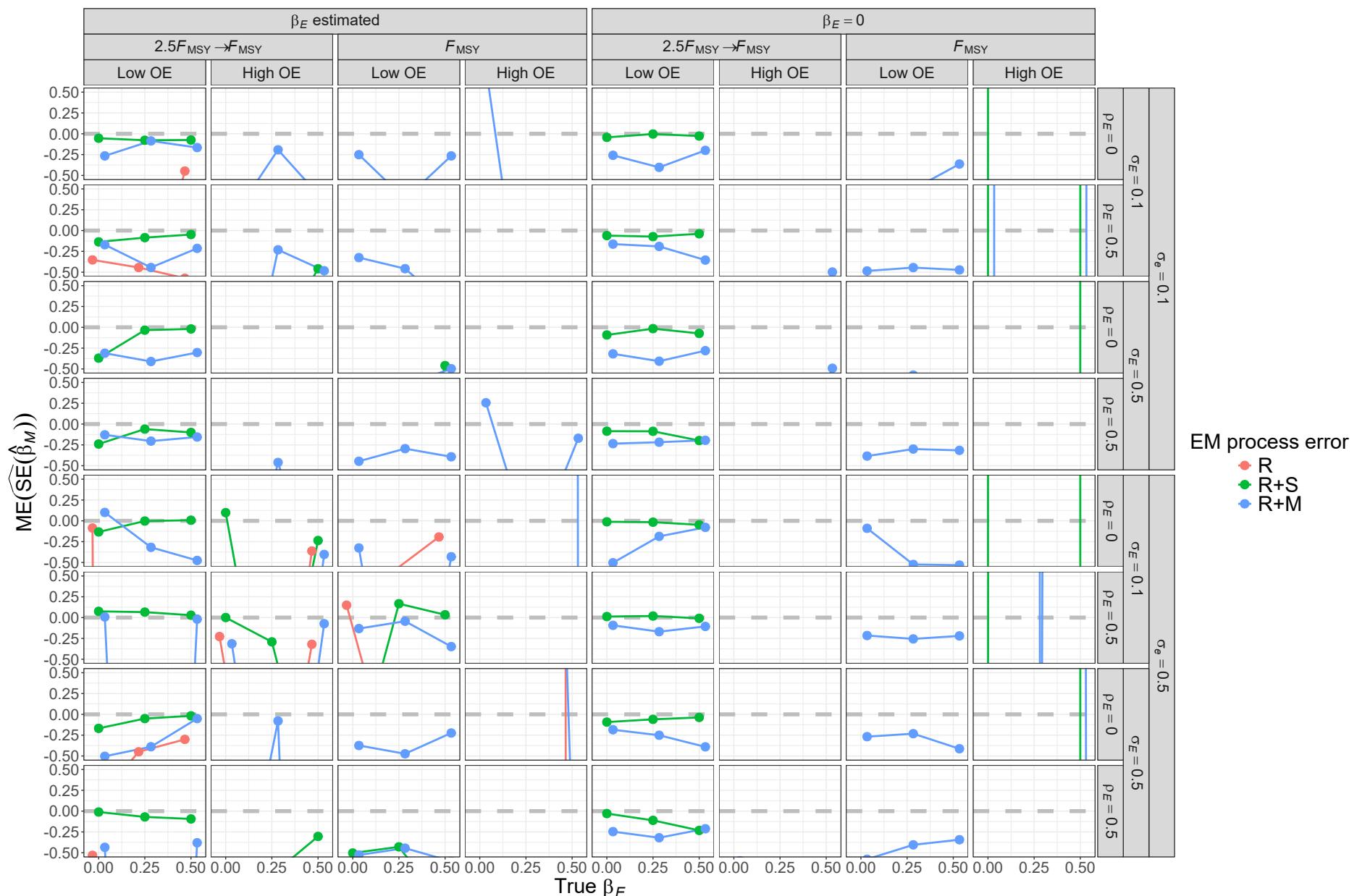


Fig. S38. For R+S OMs, median error (ME) of Hessian-based estimates of standard error for median natural mortality parameter β_M from fitting EMs with alternative process error assumptions and treatment of the covariate effect ($\beta_E = 0$ or estimated). True standard error is defined as the mean of the standard error estimates accross converged fits to simulated data sets for a given OM scenario.

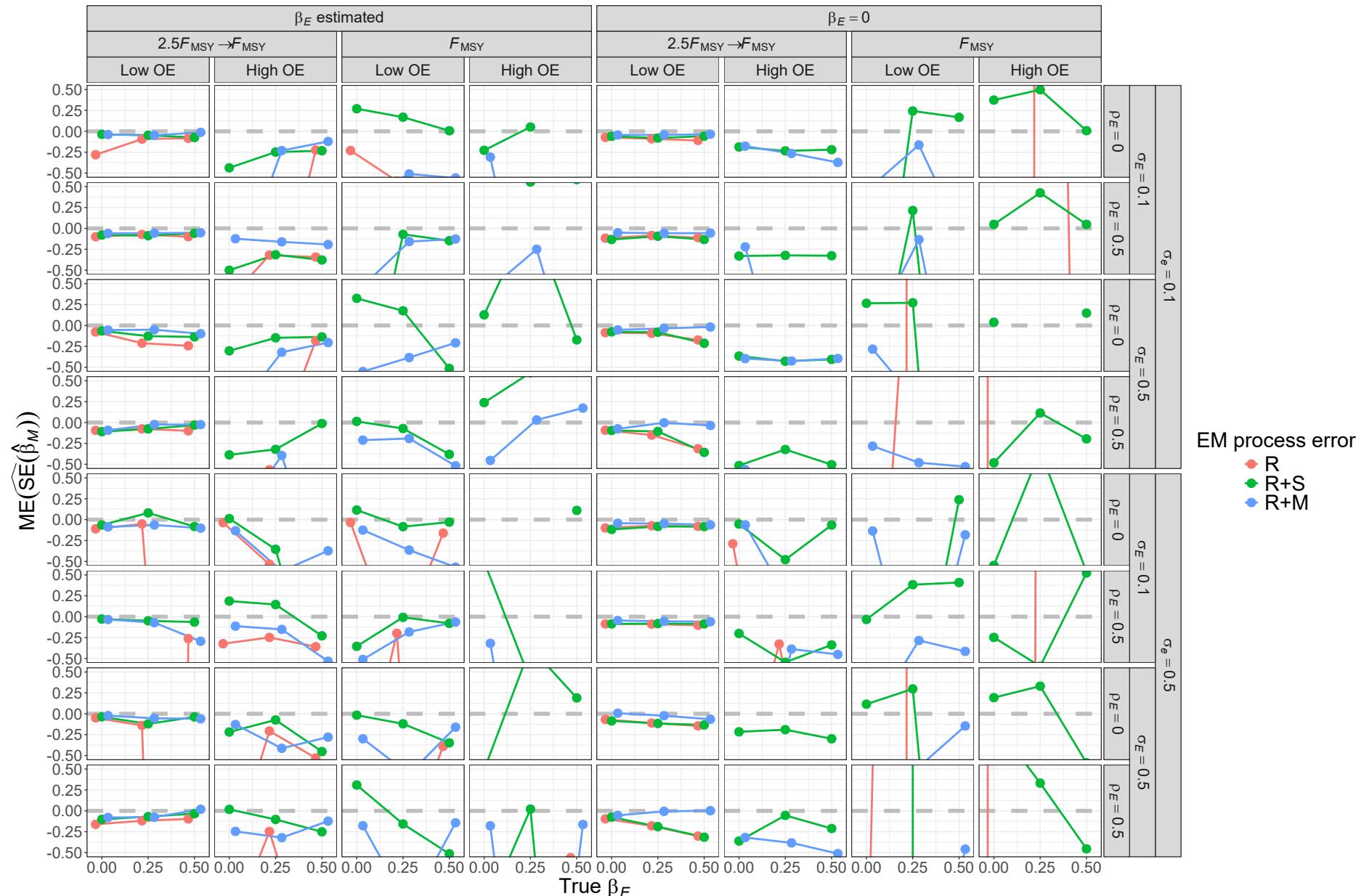


Fig. S39. For R+M OMs, median error (ME) of Hessian-based estimates of standard error for median natural mortality parameter β_M from fitting EMs with alternative process error assumptions and treatment of the covariate effect ($\beta_E = 0$ or estimated). True standard error is defined as the mean of the standard error estimates across converged fits to simulated data sets for a given OM scenario.

605 Median Natural mortality parameter confidence interval coverage

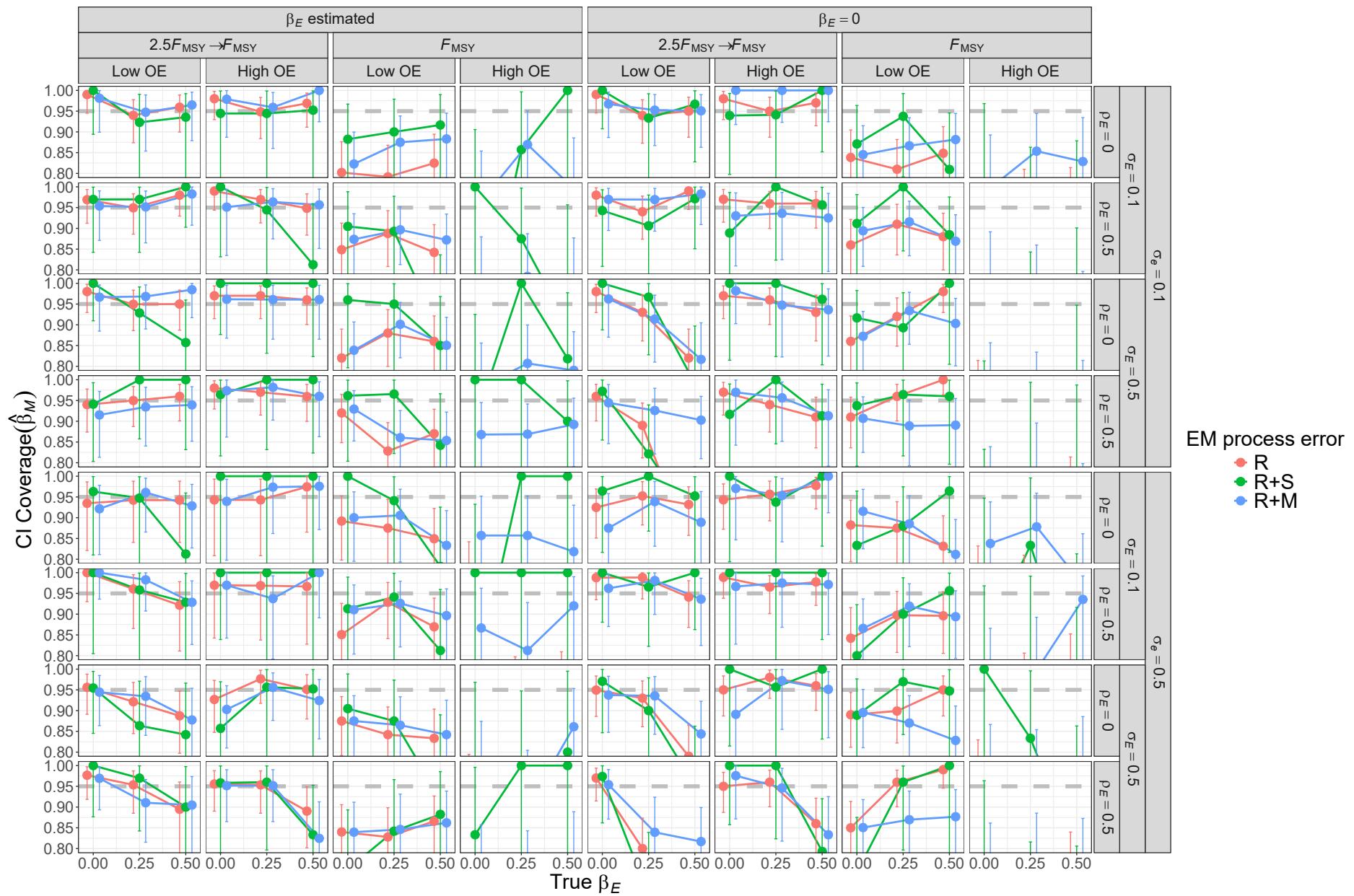


Fig. S40. For R OMs, probability of 95% confidence interval for β_M containing the true value for EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

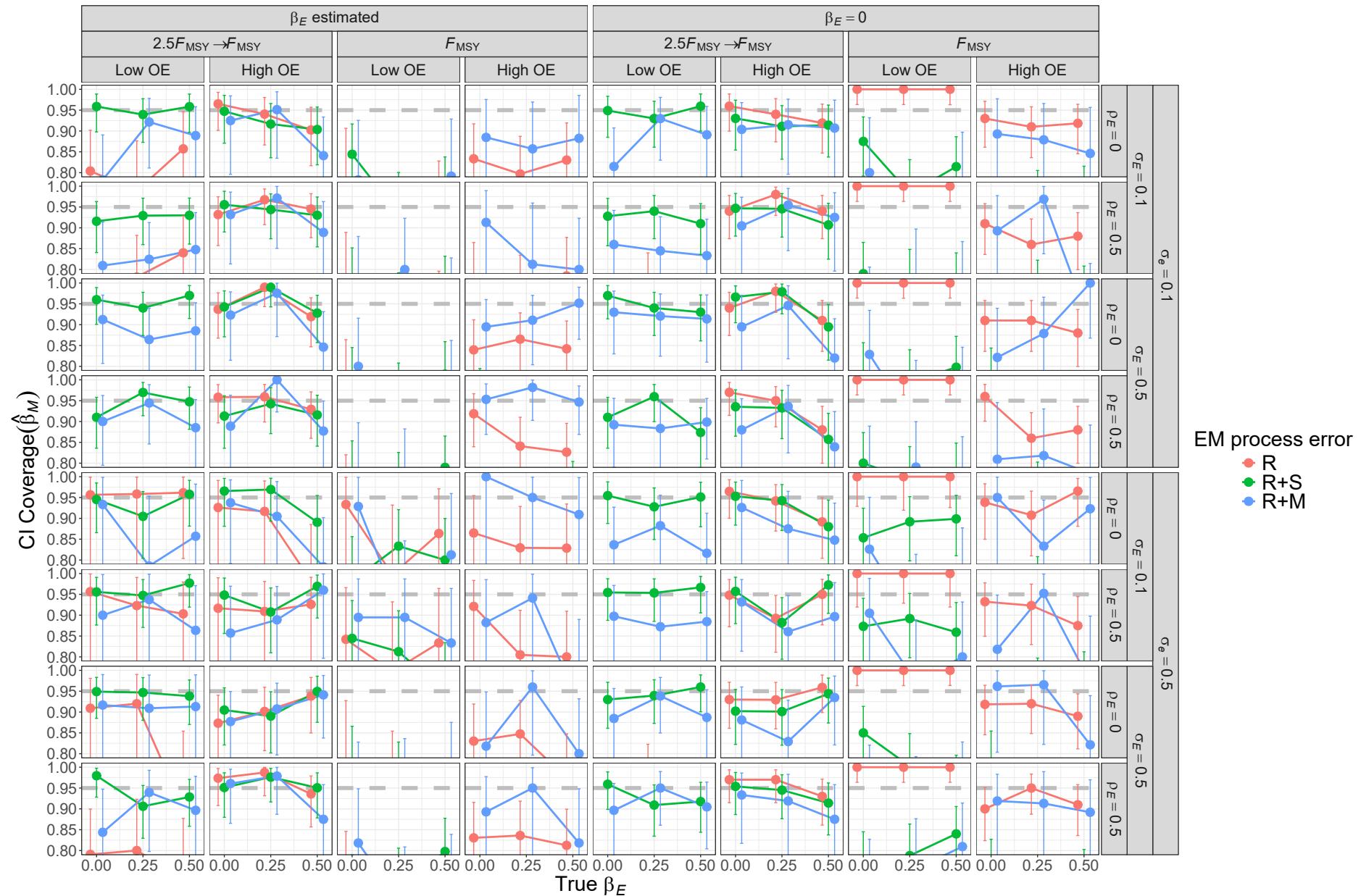


Fig. S41. For R+S OMs, probability of 95% confidence interval for β_M containing the true value for EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

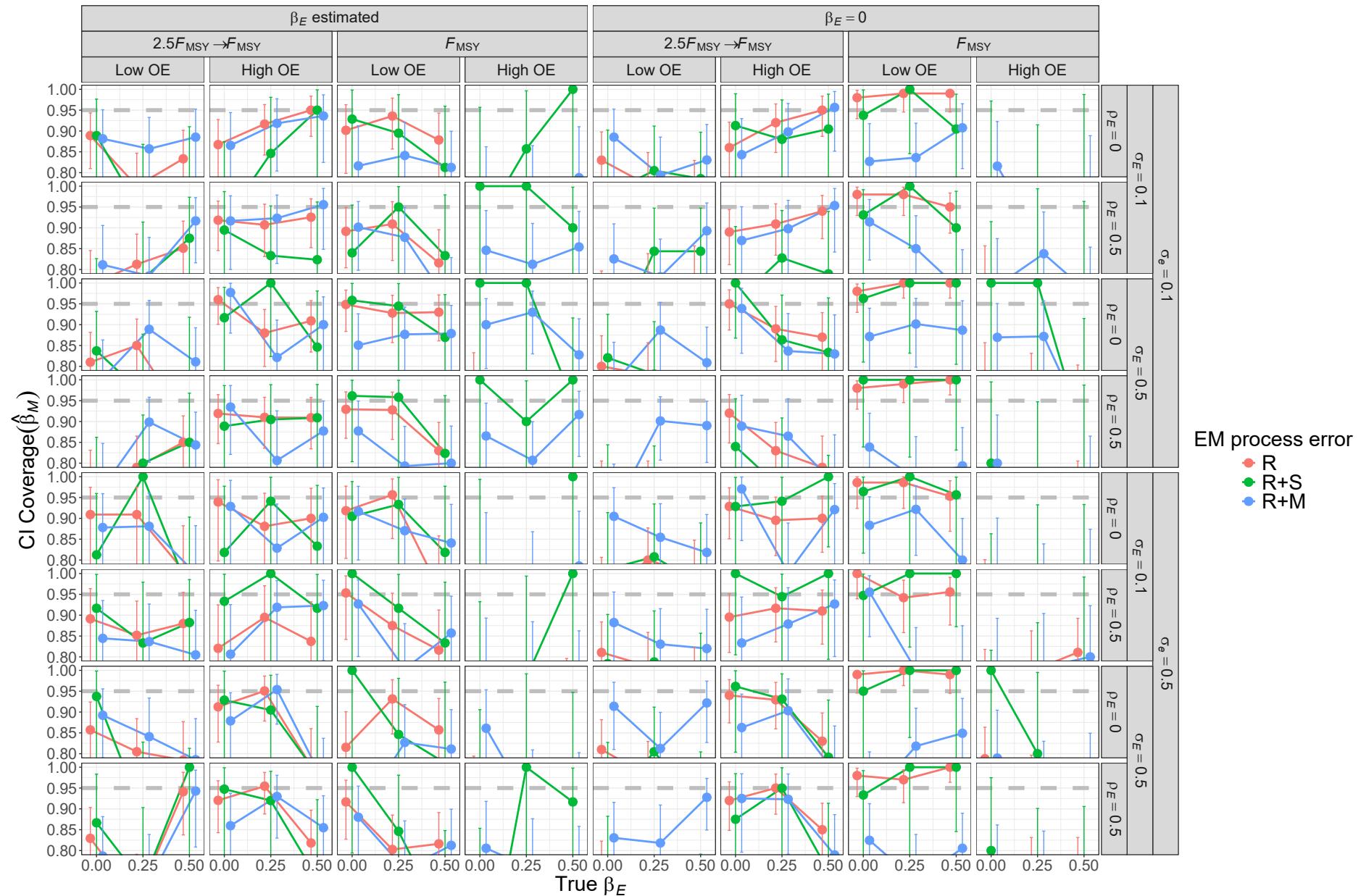


Fig. S42. For R+M OMs, probability of 95% confidence interval for $\hat{\beta}_M$ containing the true value for EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). Vertical lines represent 95% confidence intervals.

606 Median natural mortality parameter estimate and standard error

607 example

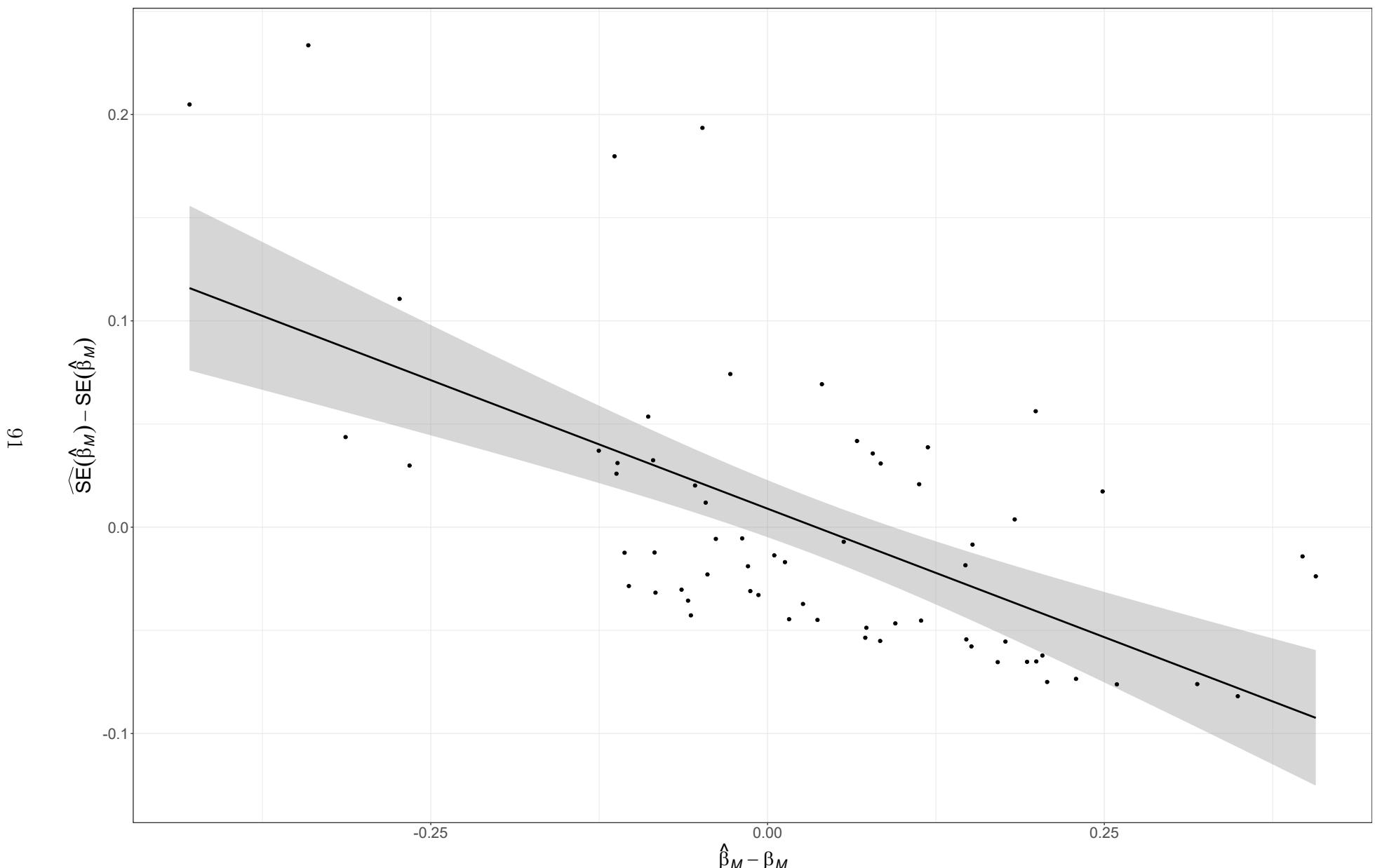


Fig. S43. Negative correlation of β_M estimates and Hessian-based standard error estimates for EM that also estimates the covariate effect and has correct R+M process error assumption fitted to simulated data from the OM with R+M process errors, temporal contrast in fishing pressure, low observation uncertainty for both population (*LowOE*) and covariate observations ($\sigma_e = 0.1$), high and uncorrelated temporal variability in the true covariate ($\sigma_E = 0.5$ and $\rho_E = 0$), and the strongest covariate

⁶⁰⁸ Median Natural mortality parameter RMSE

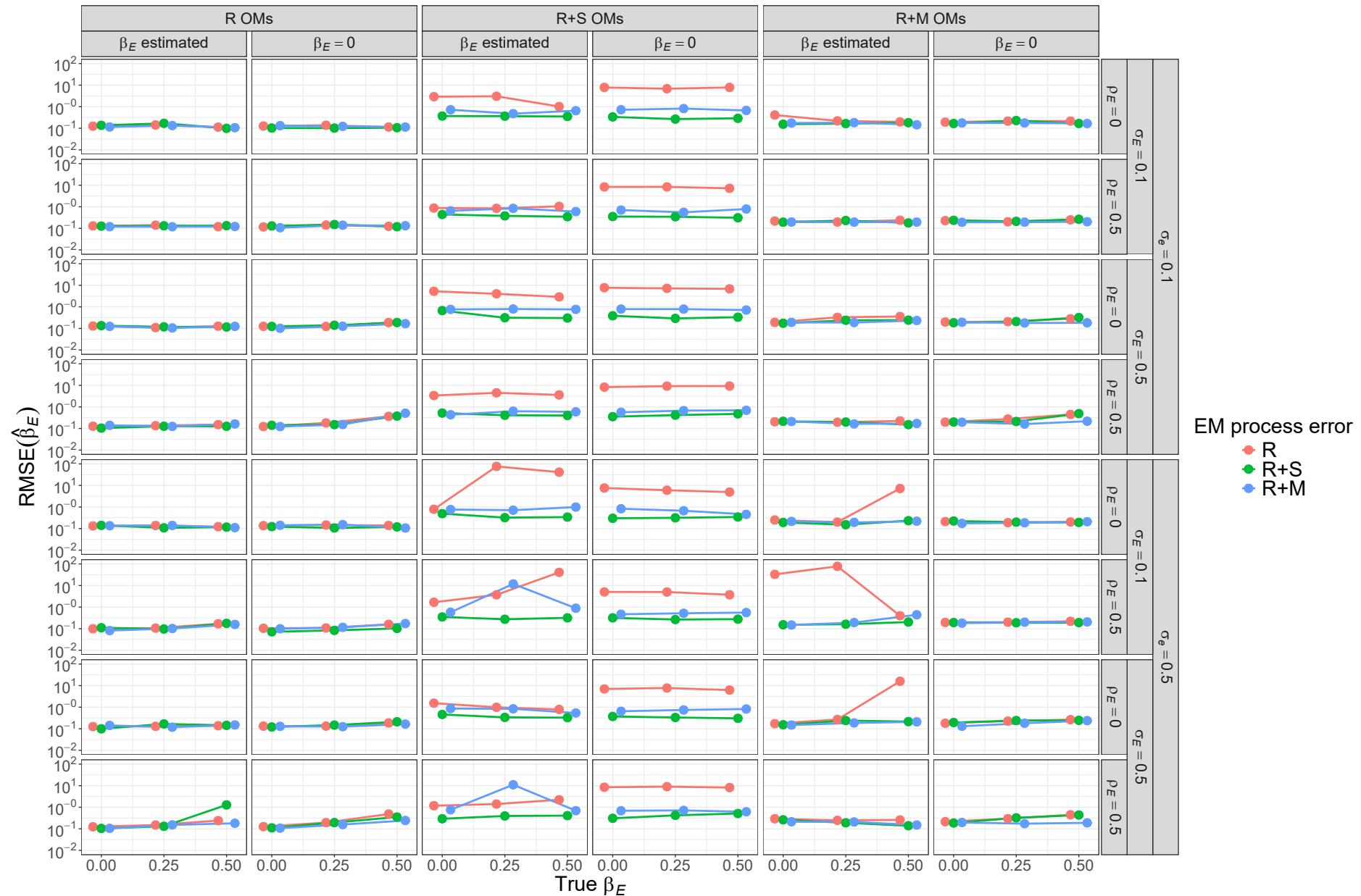


Fig. S44. Root mean square error (RMSE) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated). All OMs had low observation error for population observations and contrast in fishing mortality.

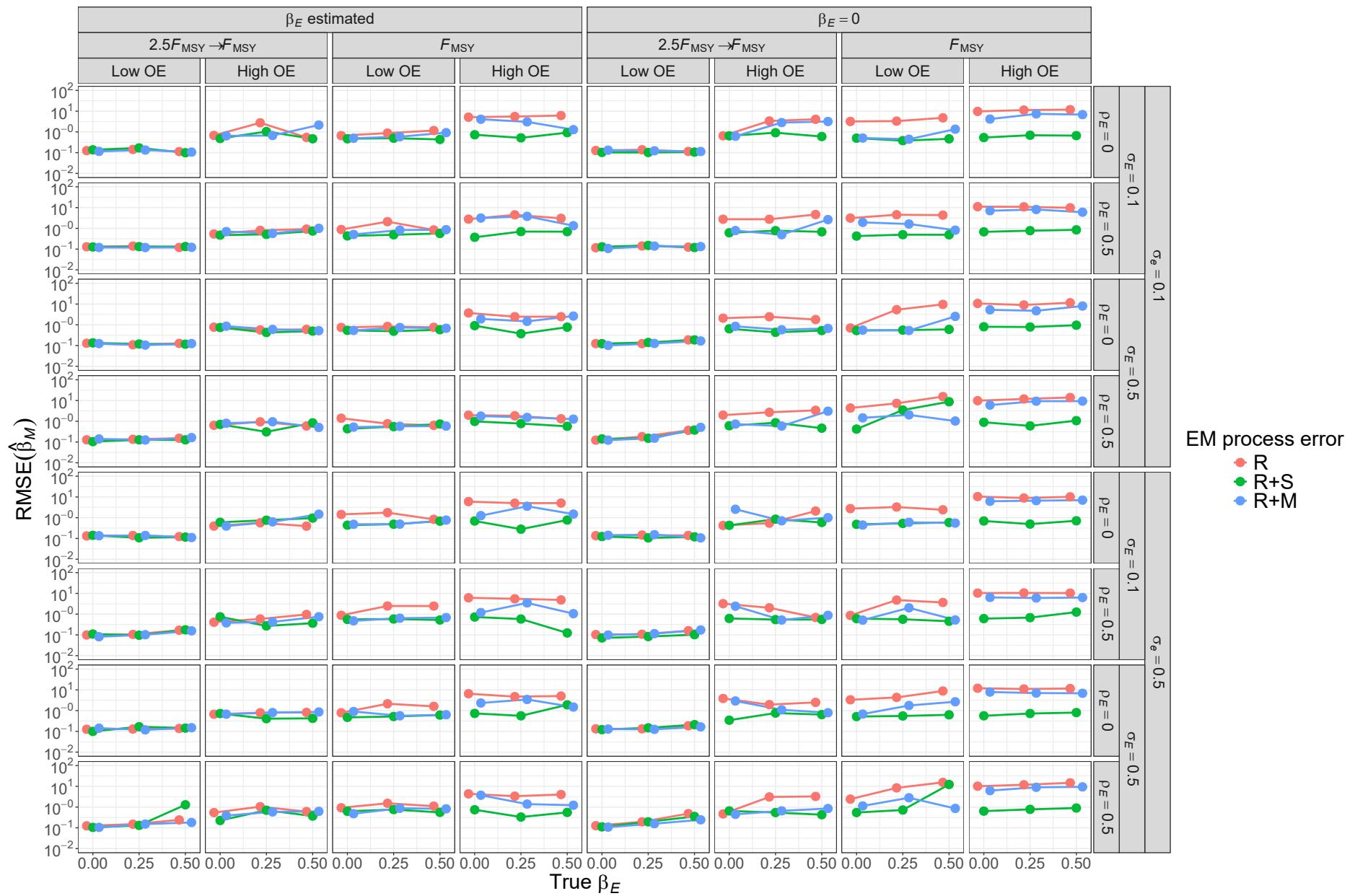


Fig. S45. For R OMs, root mean square error (RMSE) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated).

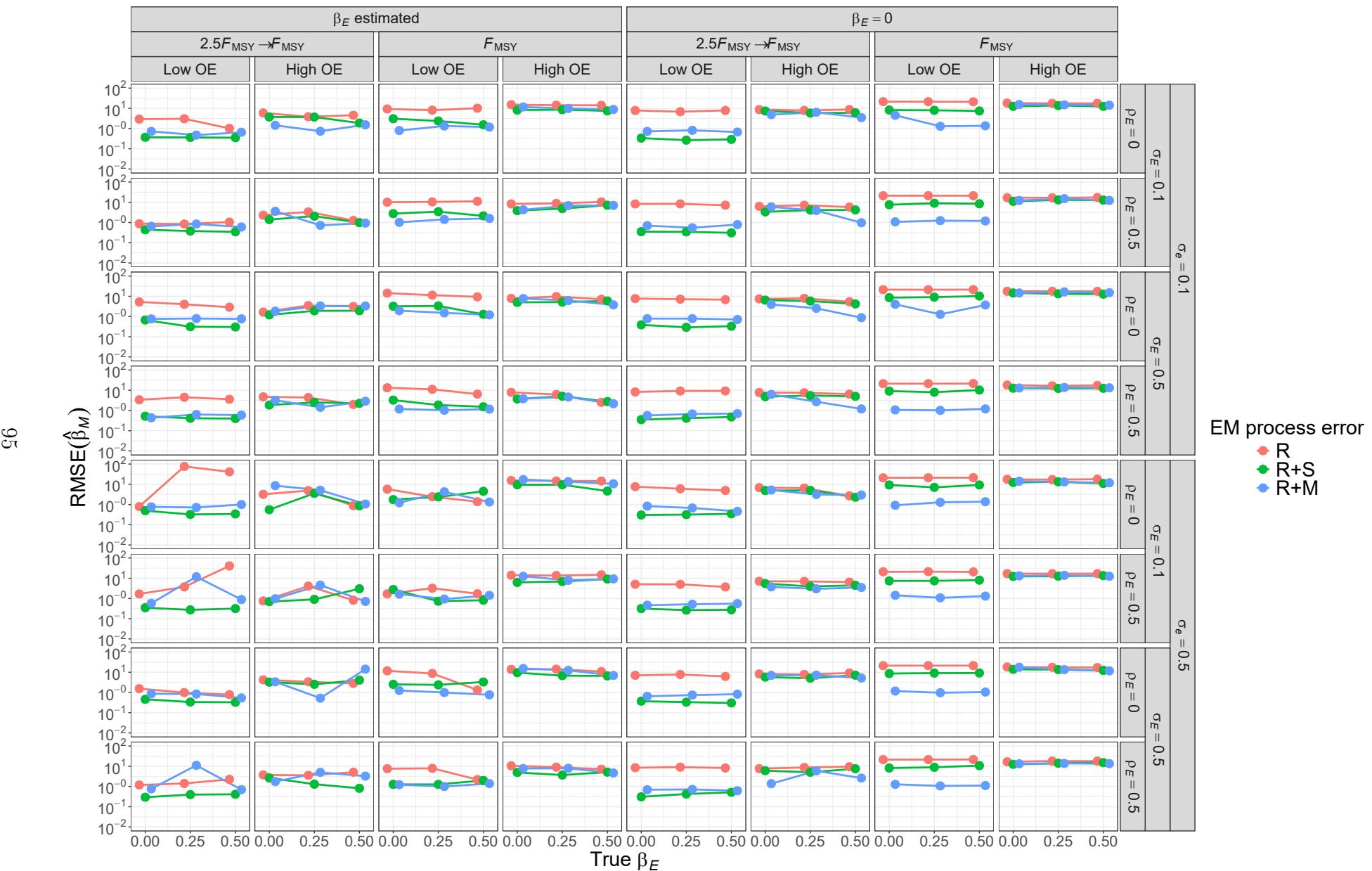


Fig. S46. For R+S OMs, root mean square error (RMSE) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated).

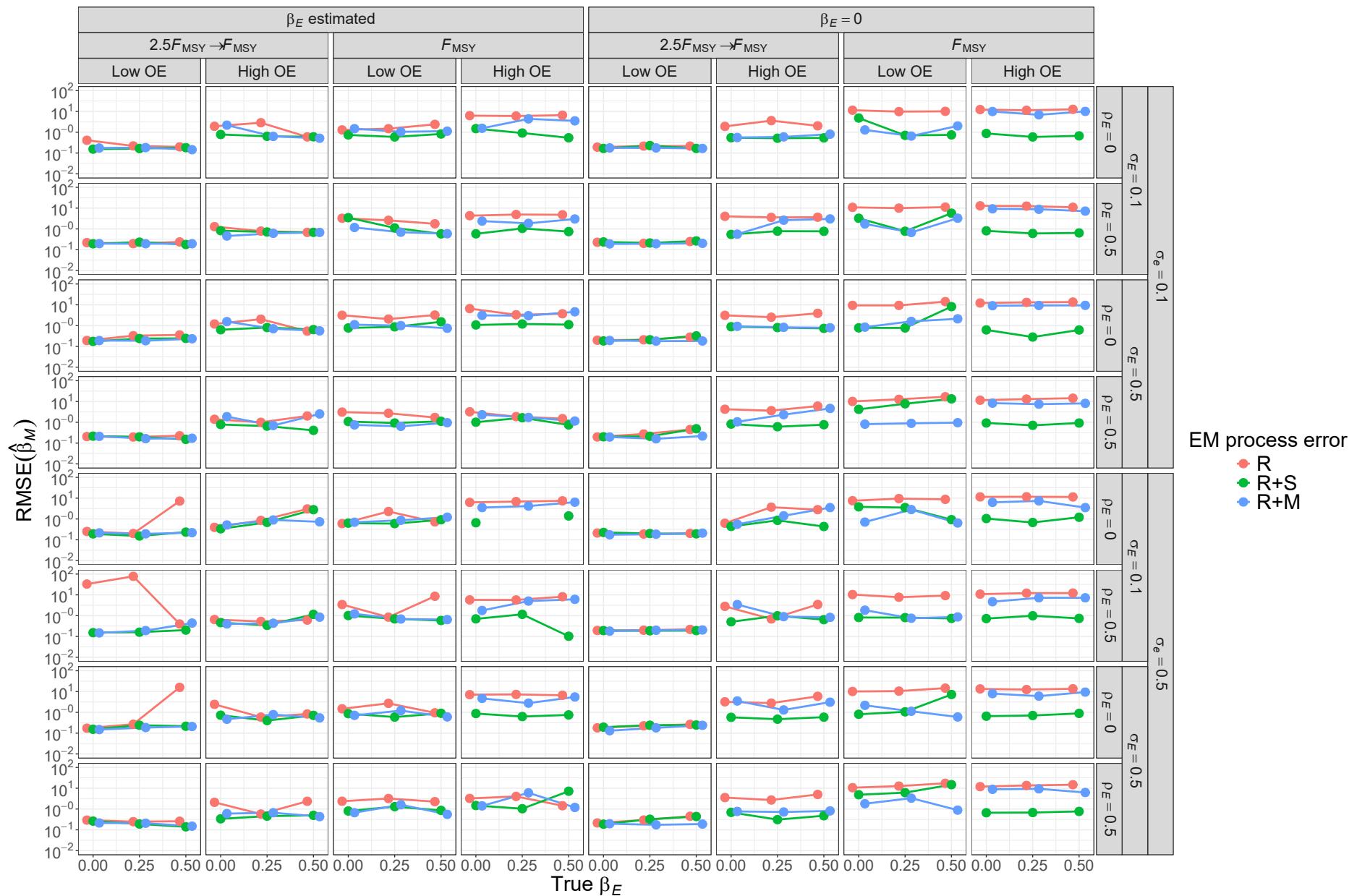


Fig. S47. For R+M OMs, root mean square error (RMSE) of estimates of β_M from fitting EMs with alternative process error assumptions and treatment of covariate effect ($\beta_E = 0$ or estimated).

⁶⁰⁹ Terminal year natural mortality bias

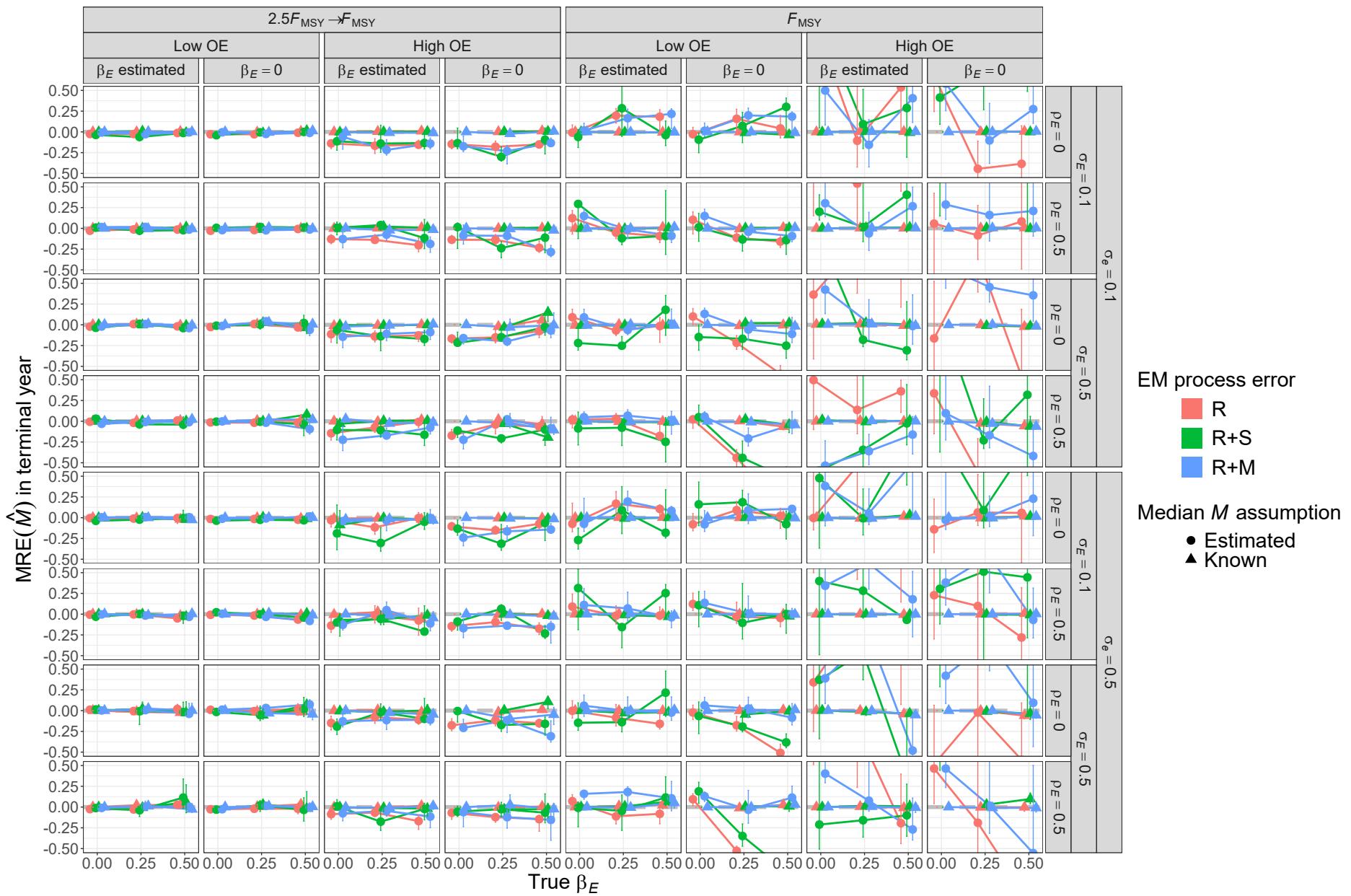


Fig. S48. For R OMs, median relative error (MRE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

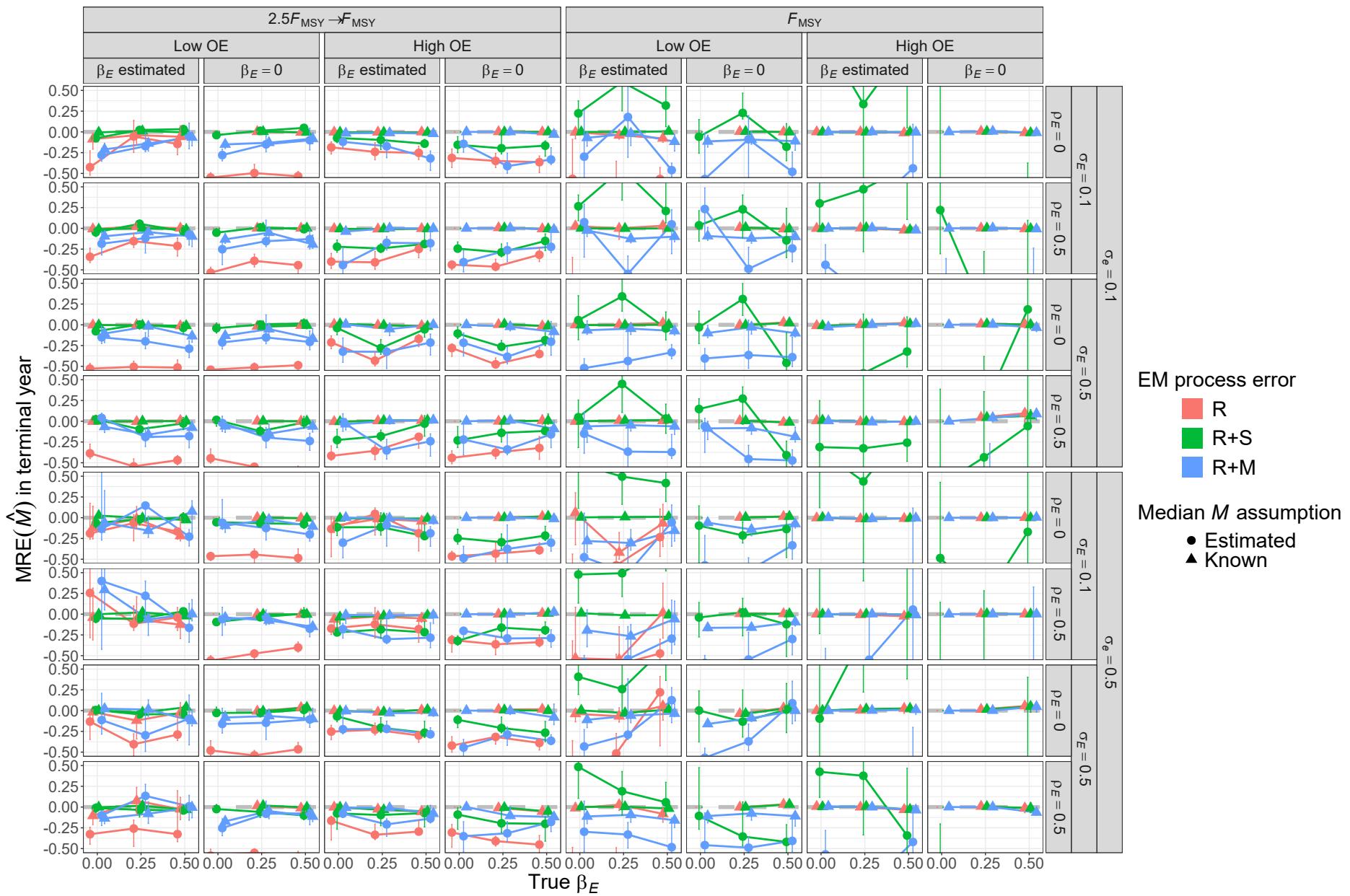


Fig. S49. For R+S OMs, median relative error (MRE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

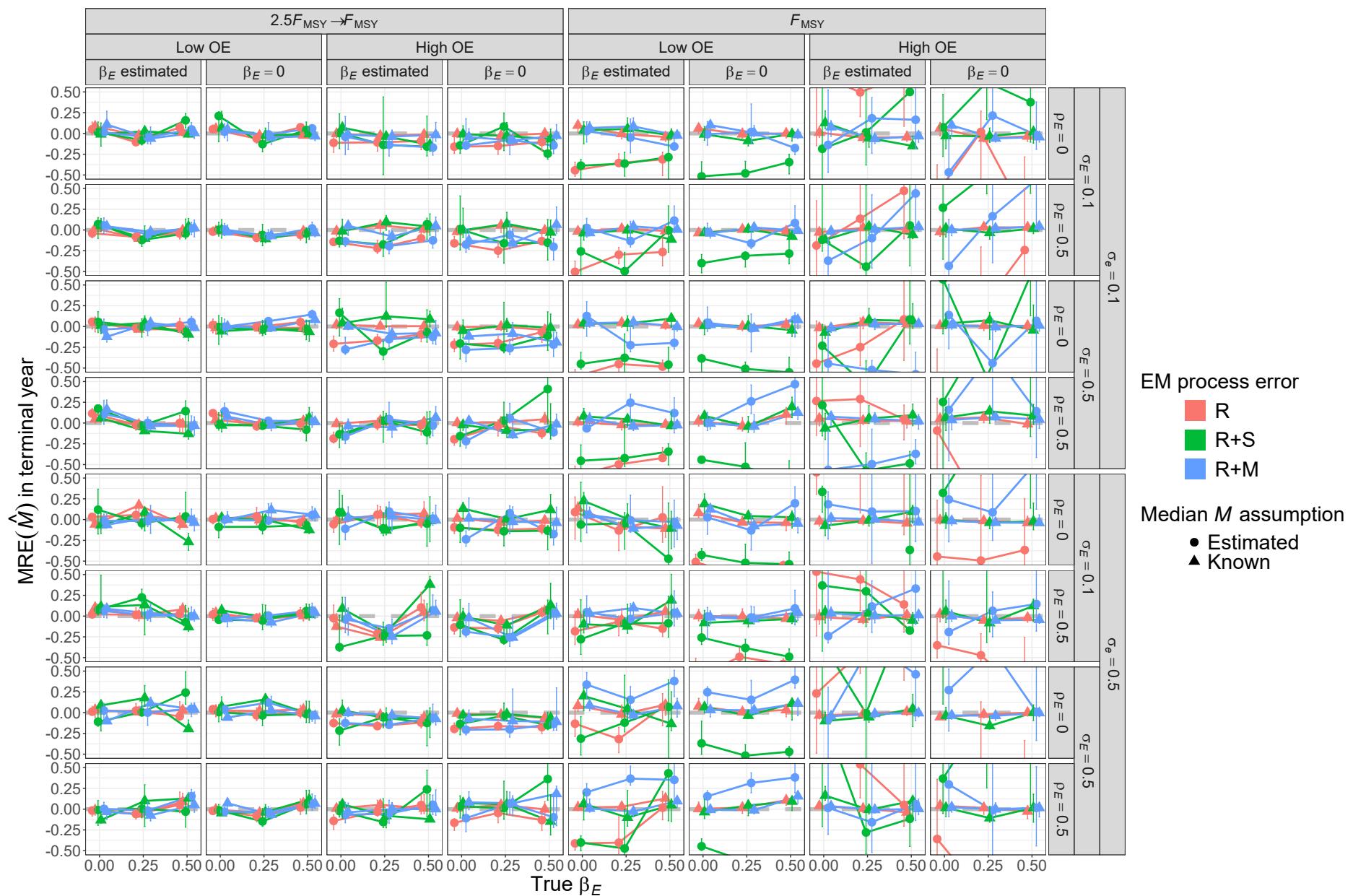


Fig. S50. For R+M OMs, median relative error (MRE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

₆₁₀ Terminal year natural mortality RMSE

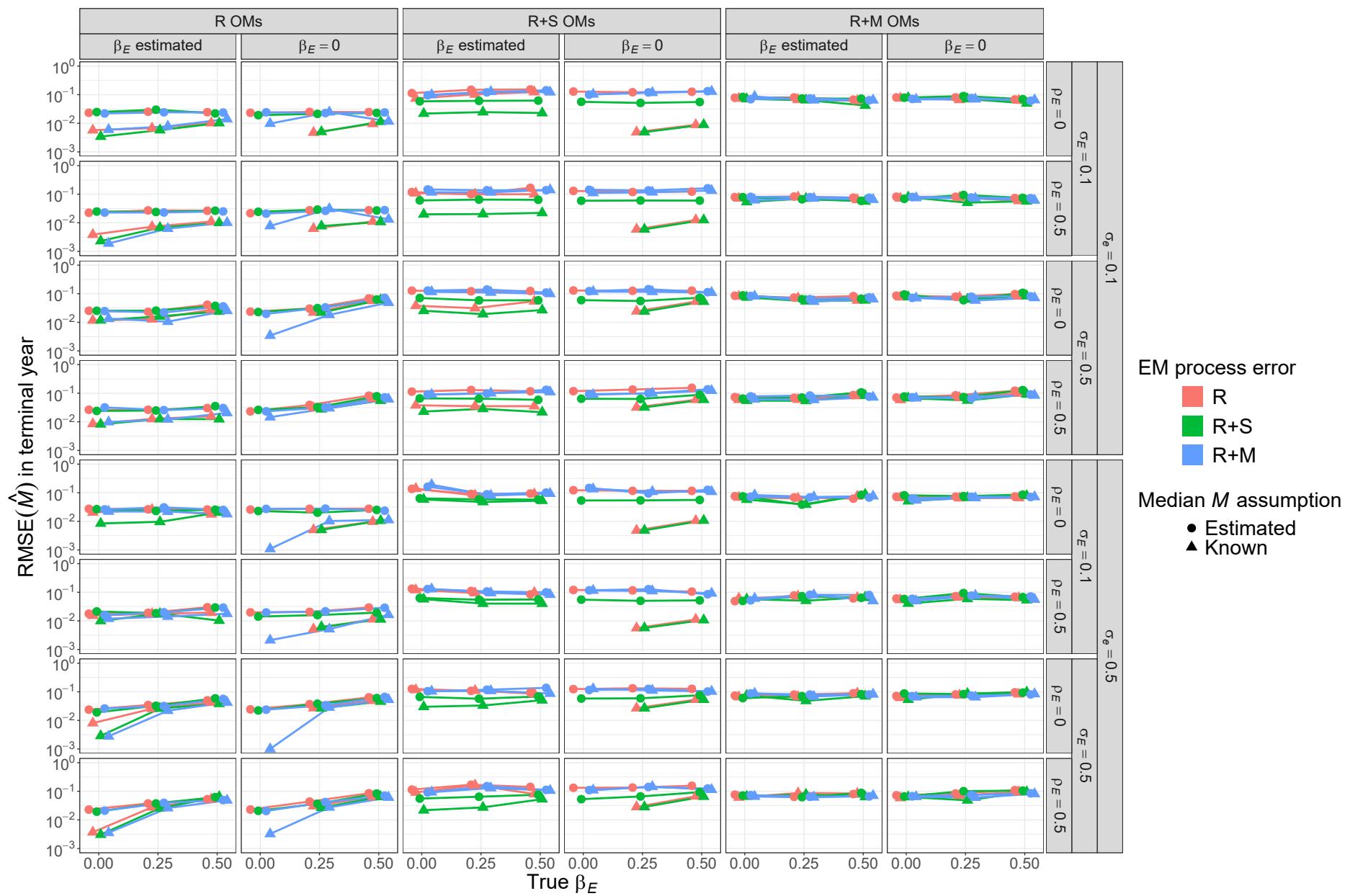


Fig. S51. Root mean square error (RMSE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low population observation error and contrast in fishing mortality.

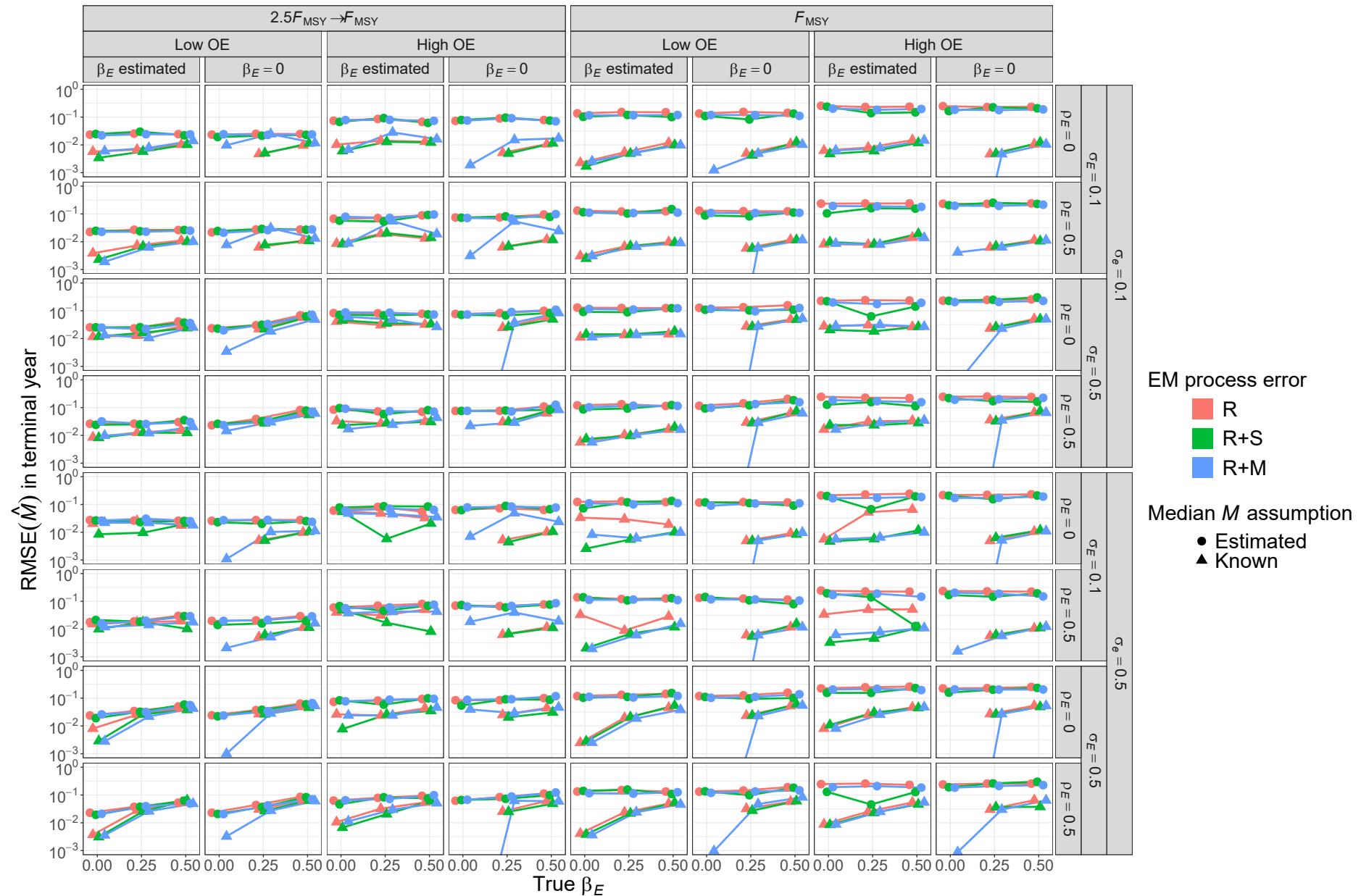


Fig. S52. For R OMs, root mean square error (RMSE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

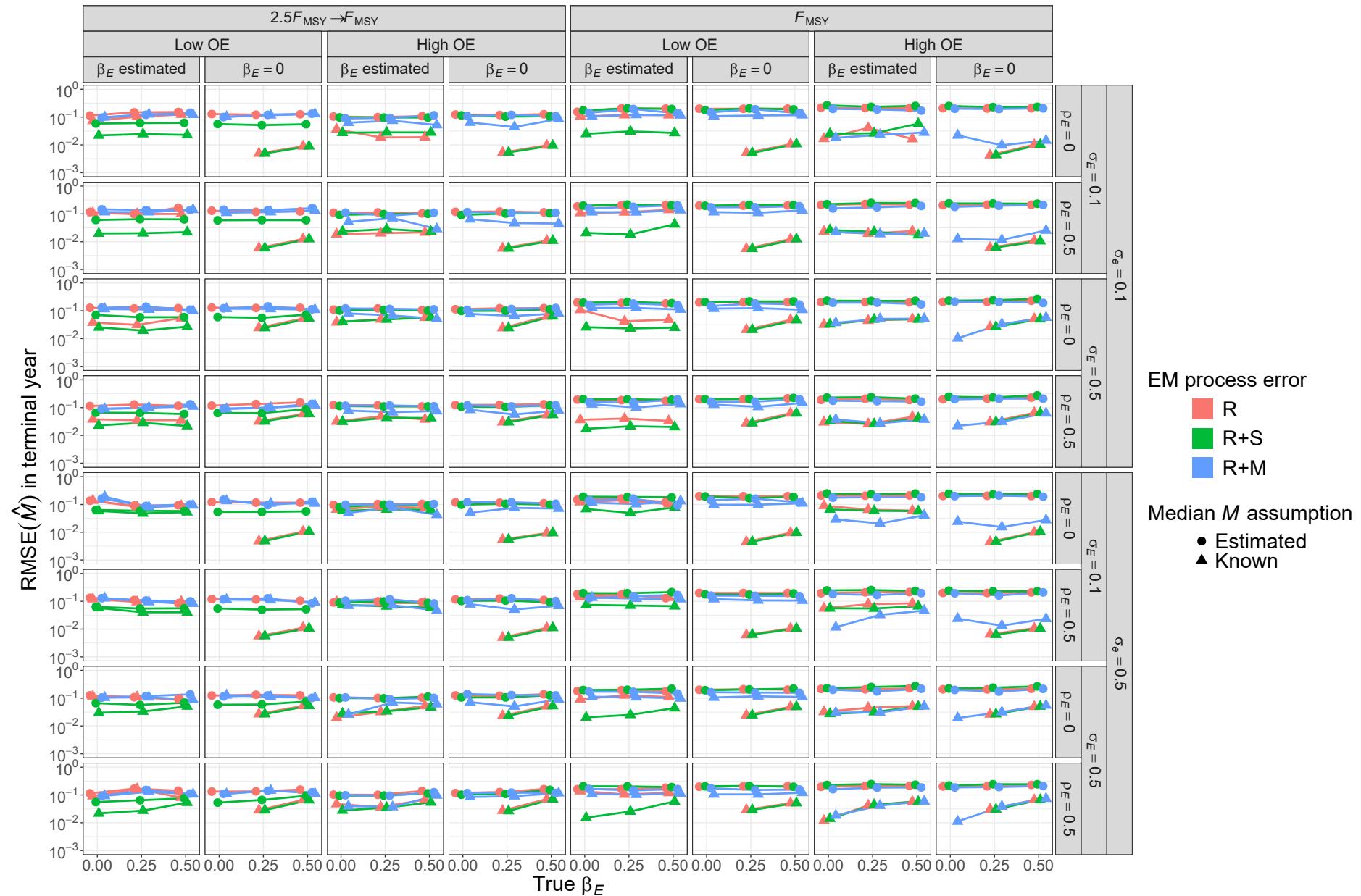


Fig. S53. For R+S OMs, root mean square error (RMSE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

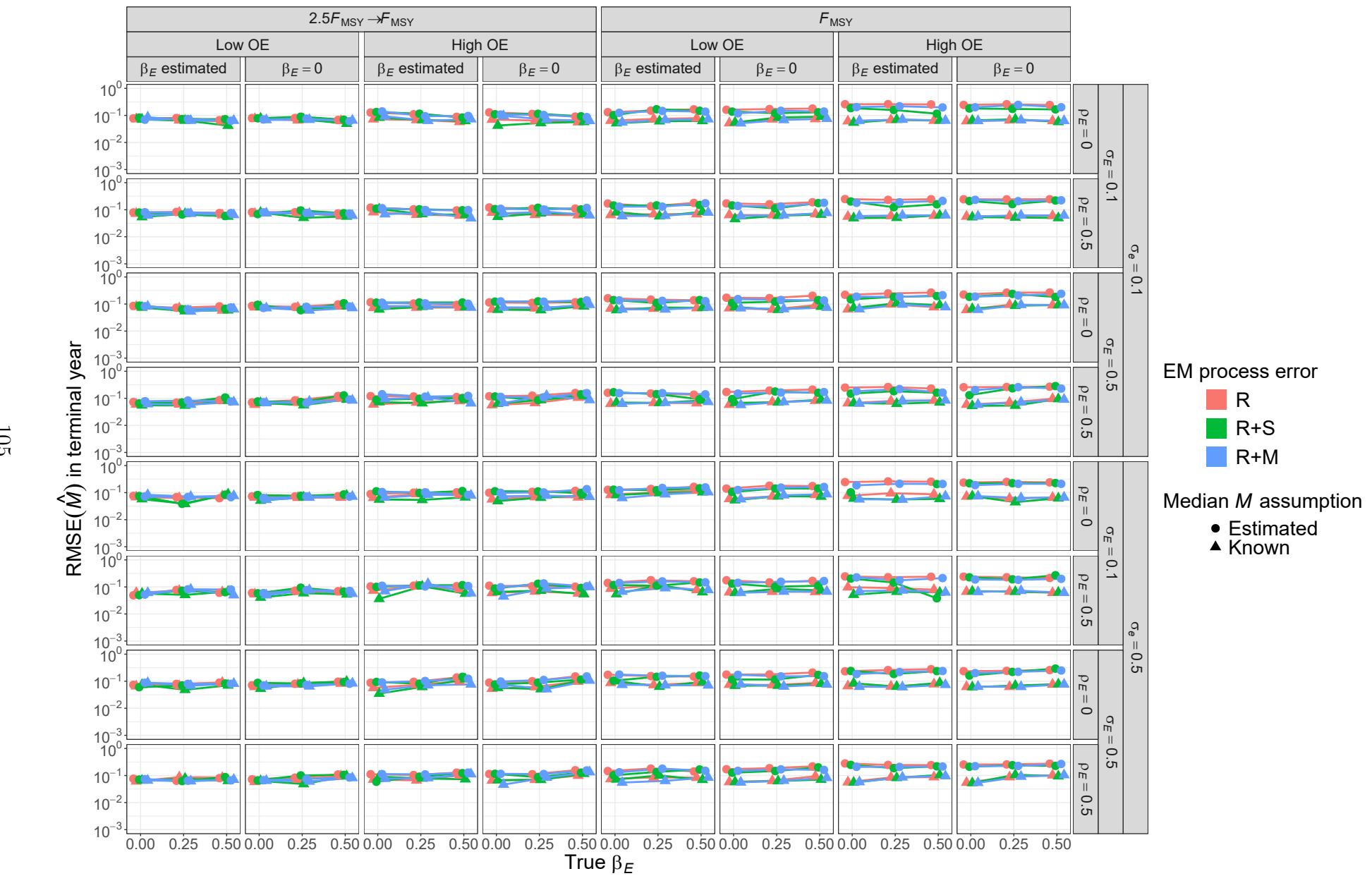


Fig. S54. For R+M OMs, root mean square error (RMSE) of estimates of natural mortality rate in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

⁶¹¹ Terminal year spawning stock biomass bias

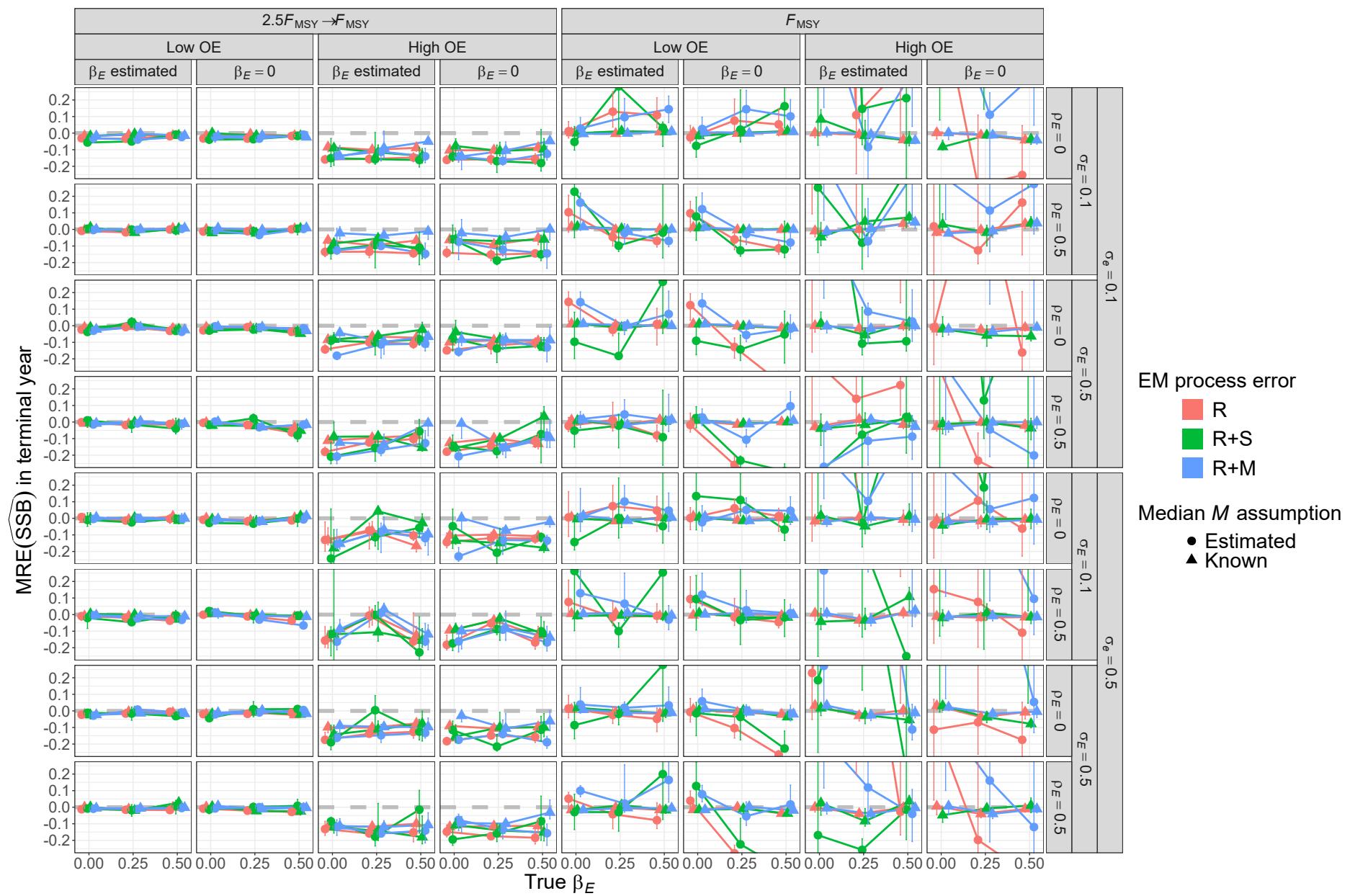


Fig. S55. For R OMs, median relative error (MRE) of estimates of spawning stock biomass (SSB) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

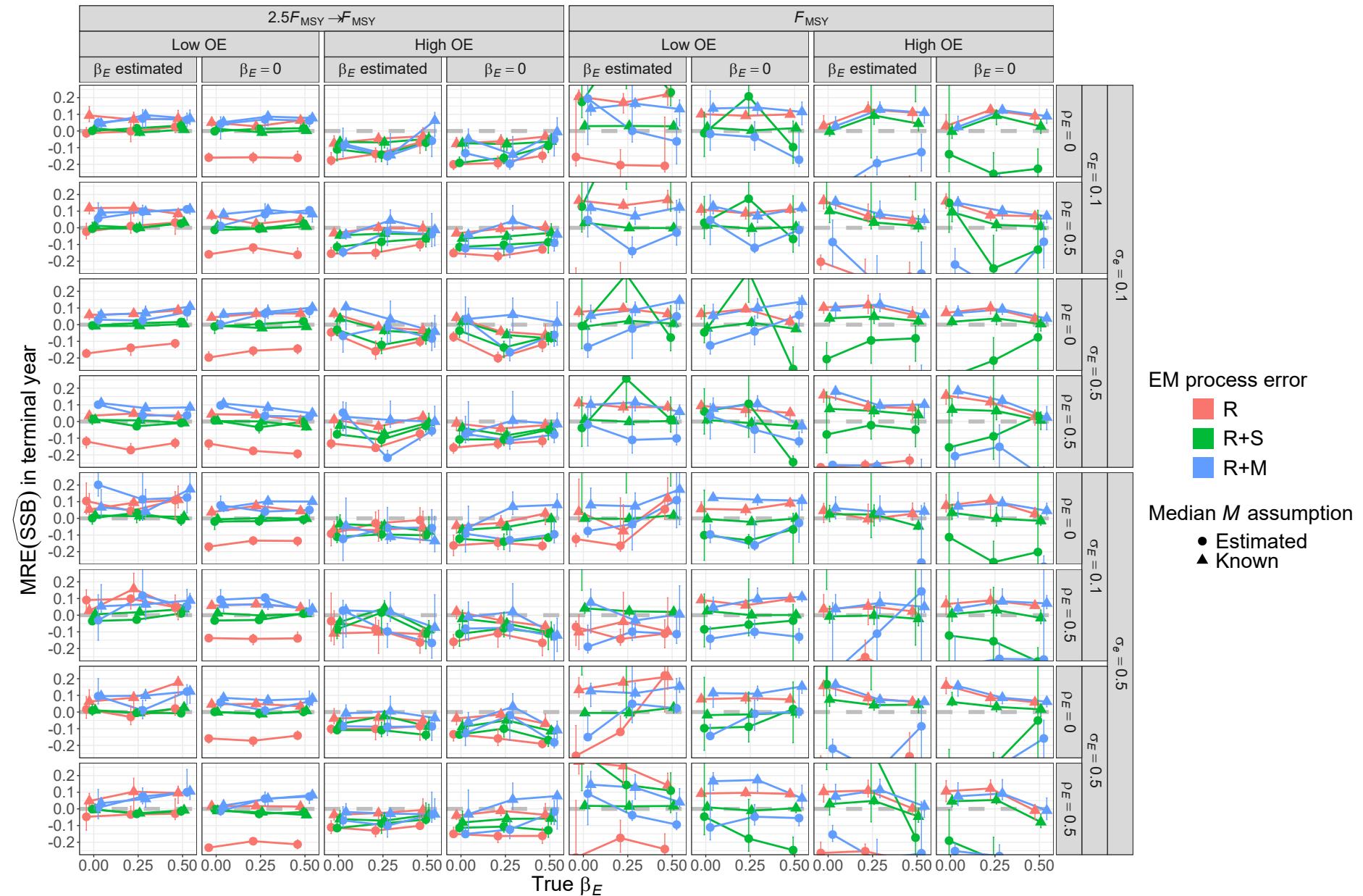


Fig. S56. For R+S OMs, median relative error (MRE) of estimates of spawning stock biomass (SSB) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

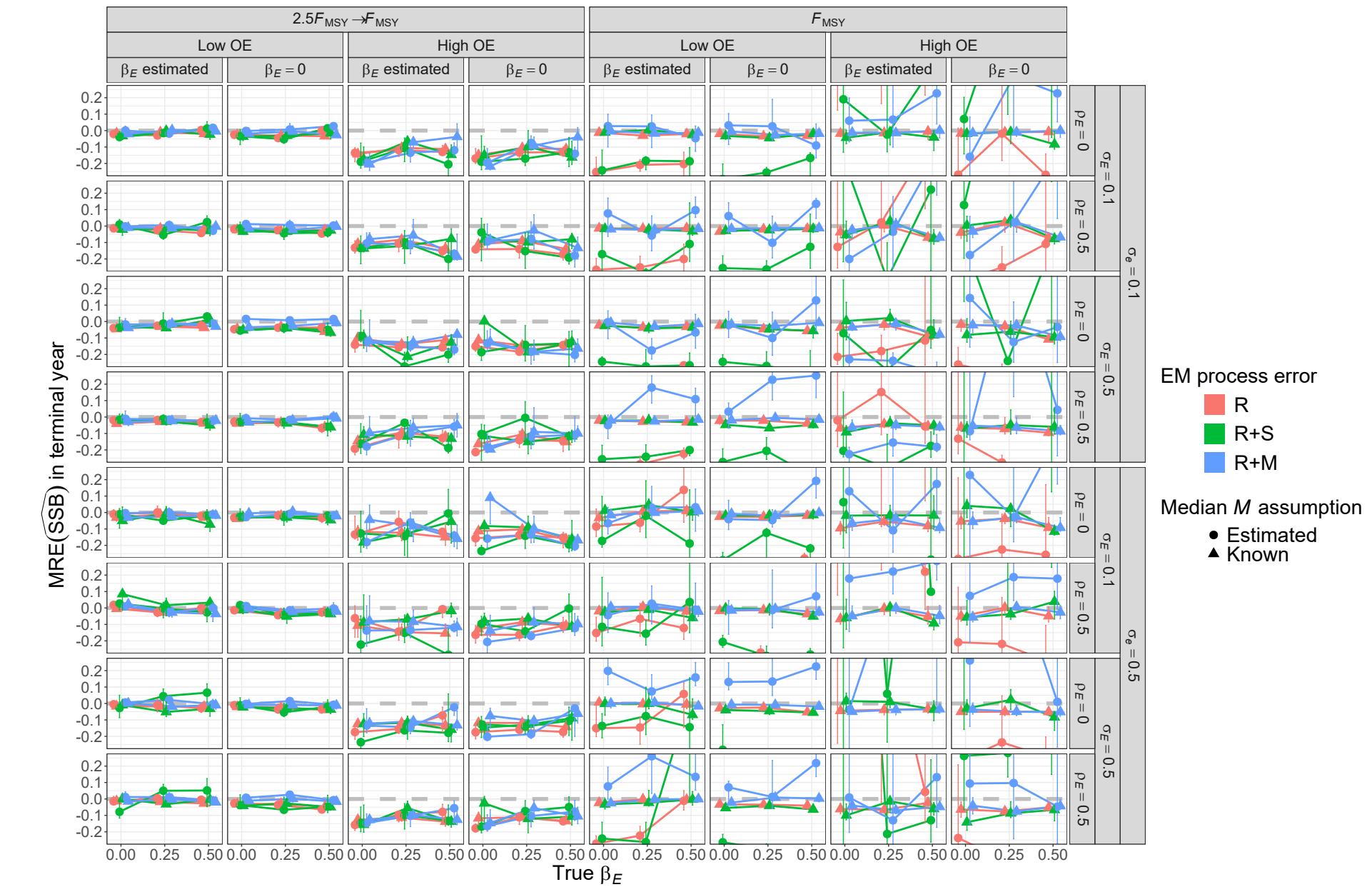


Fig. S57. For R+M OMs, median relative error (MRE) of estimates of spawning stock biomass (SSB) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

⁶¹² Terminal year spawning stock biomass RMSE

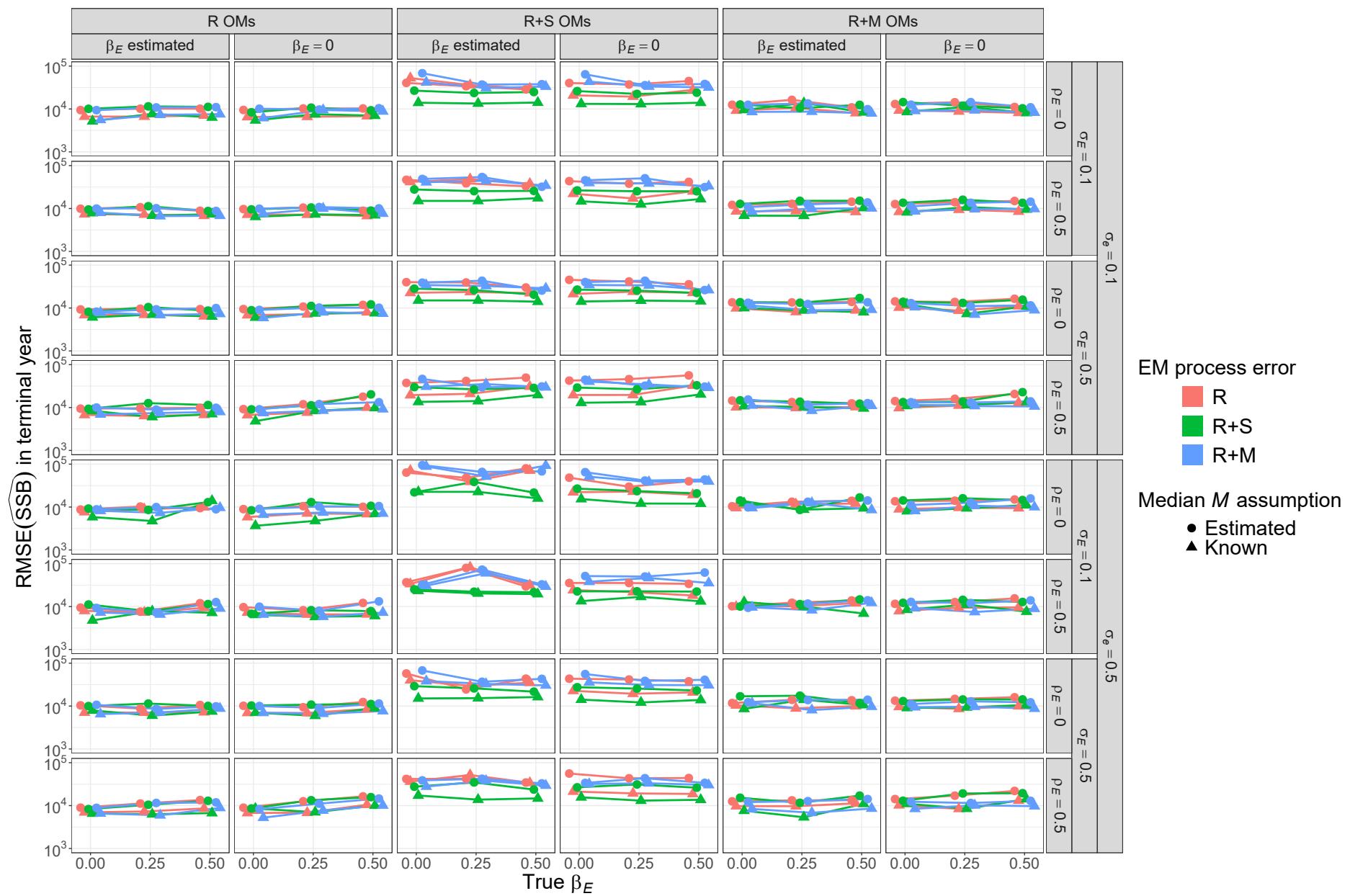


Fig. S58. Root mean square error (RMSE) of estimates of spawning stock biomass in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low population observation error and contrast in fishing mortality.

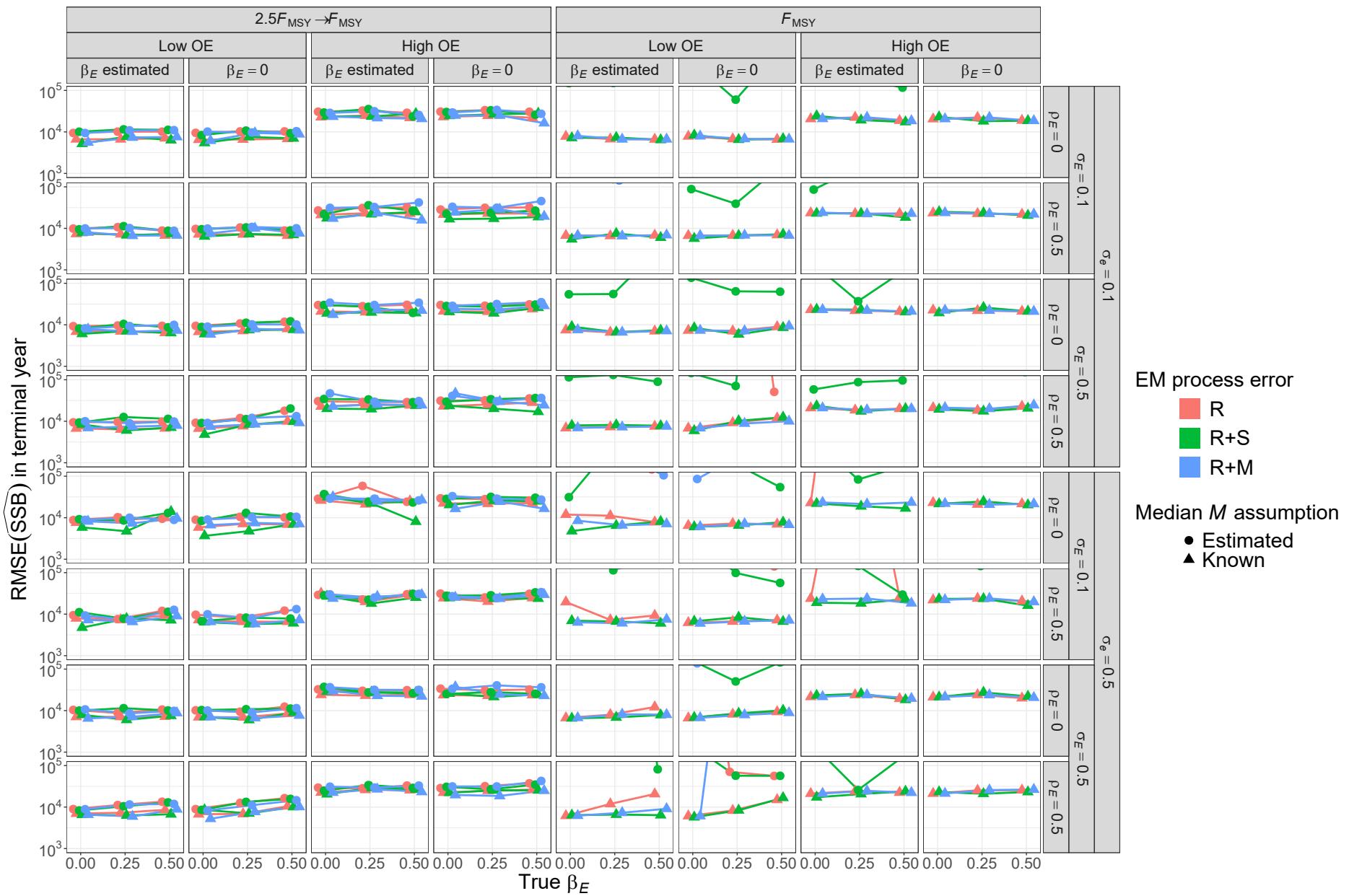


Fig. S59. For R OMs, root mean square error (RMSE) of estimates of spawning stock biomass in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

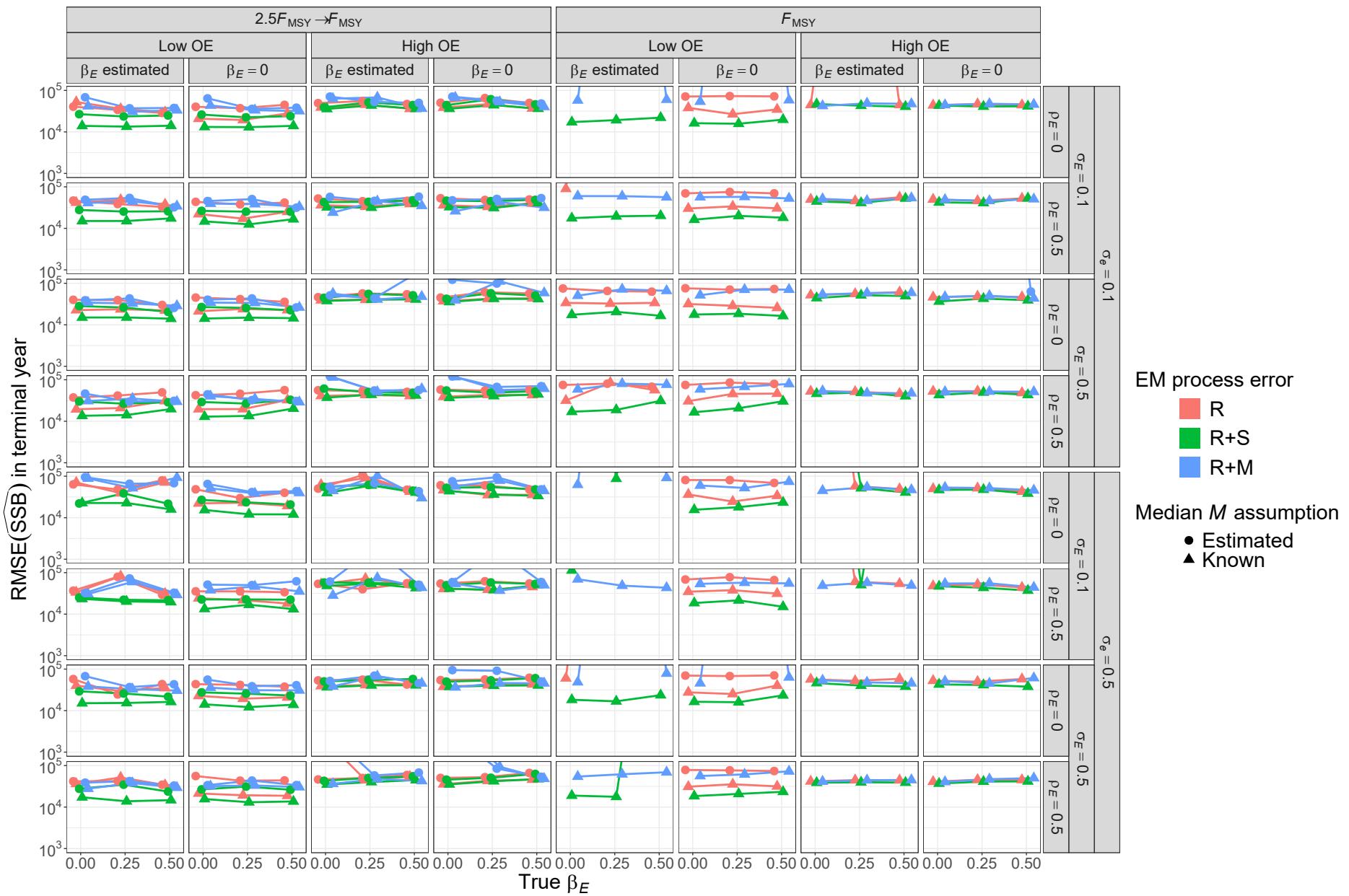


Fig. S60. For R+S OMs, root mean square error (RMSE) of estimates of spawning stock biomass in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

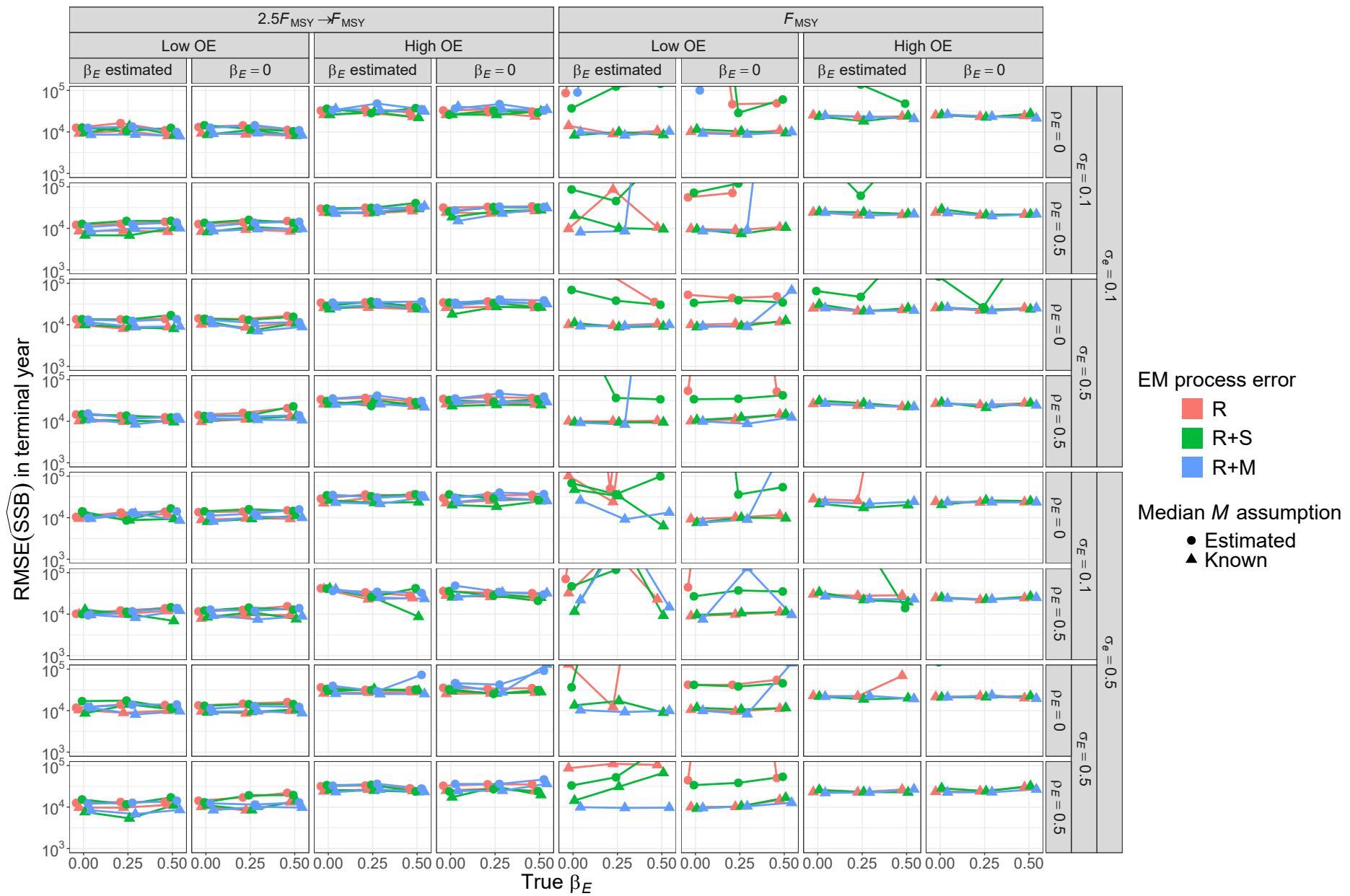


Fig. S61. For R+M OMs, root mean square error (RMSE) of estimates of spawning stock biomass in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

⁶¹³ Terminal year fishing mortality bias

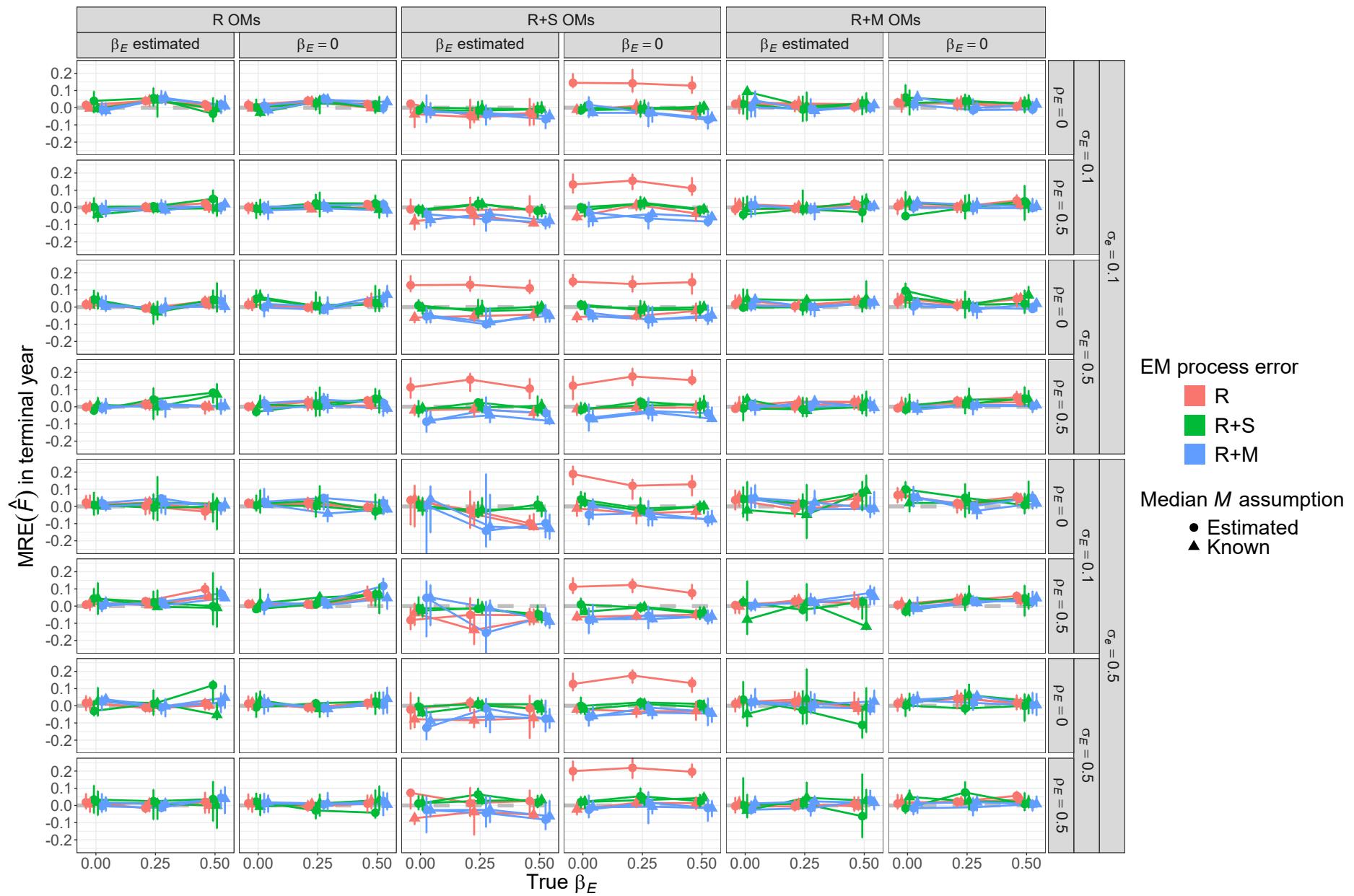


Fig. S62. Median relative error (MRE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low population observation error and contrast in fishing mortality.

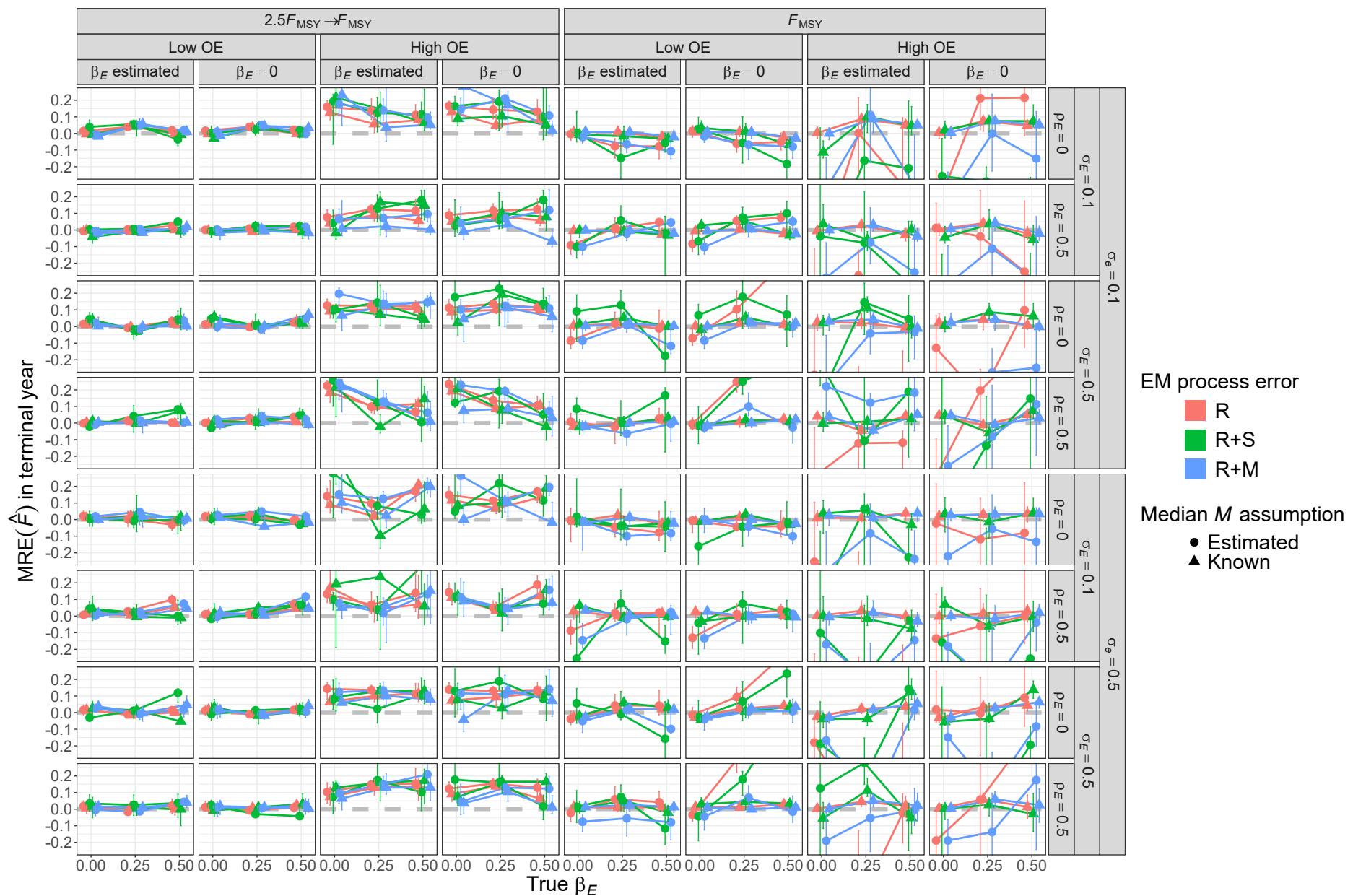


Fig. S63. For R OMs, median relative error (MRE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low observation error and contrast in fishing mortality.

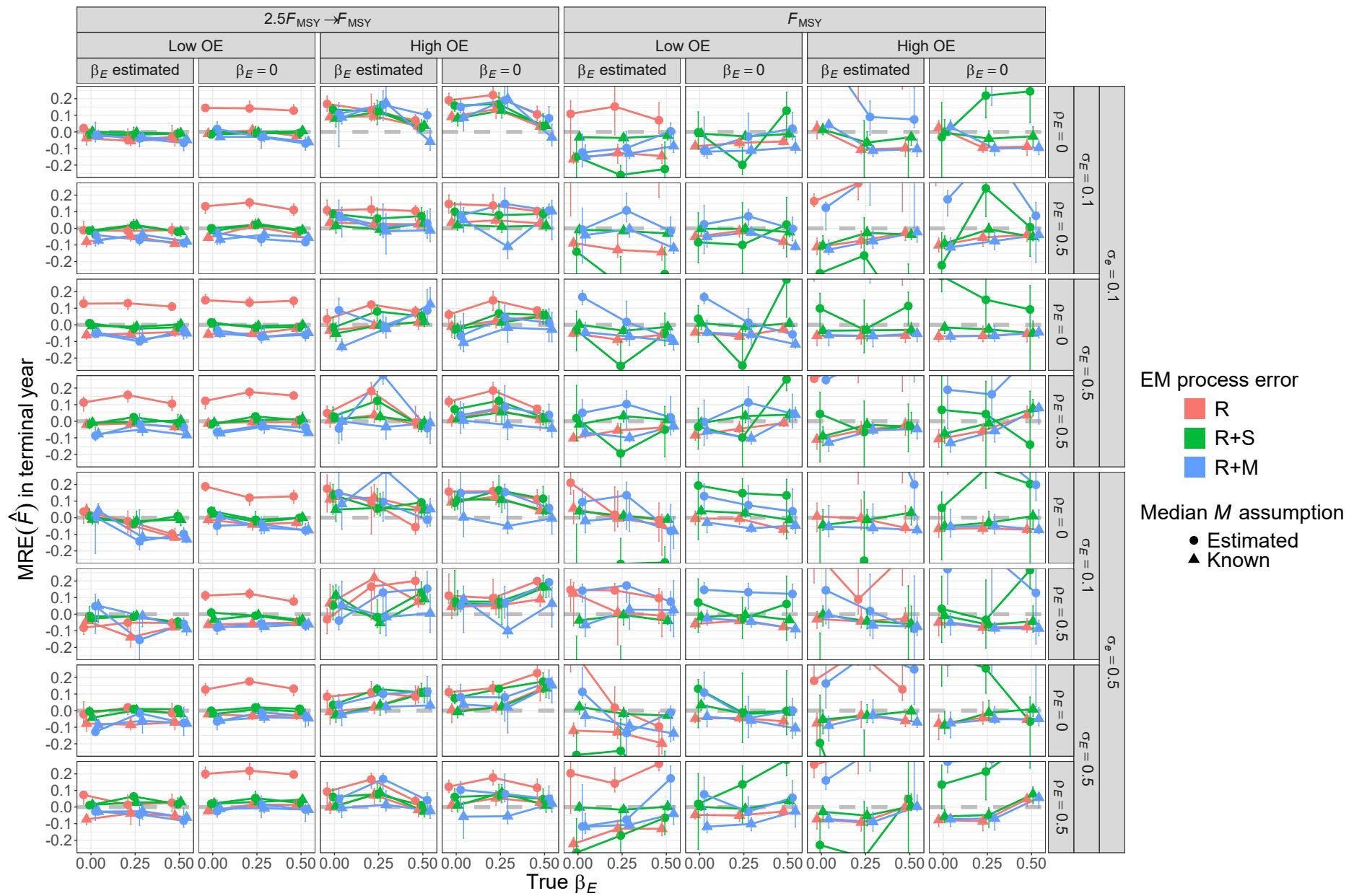


Fig. S64. For R+S OMs, median relative error (MRE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low observation error and contrast in fishing mortality.

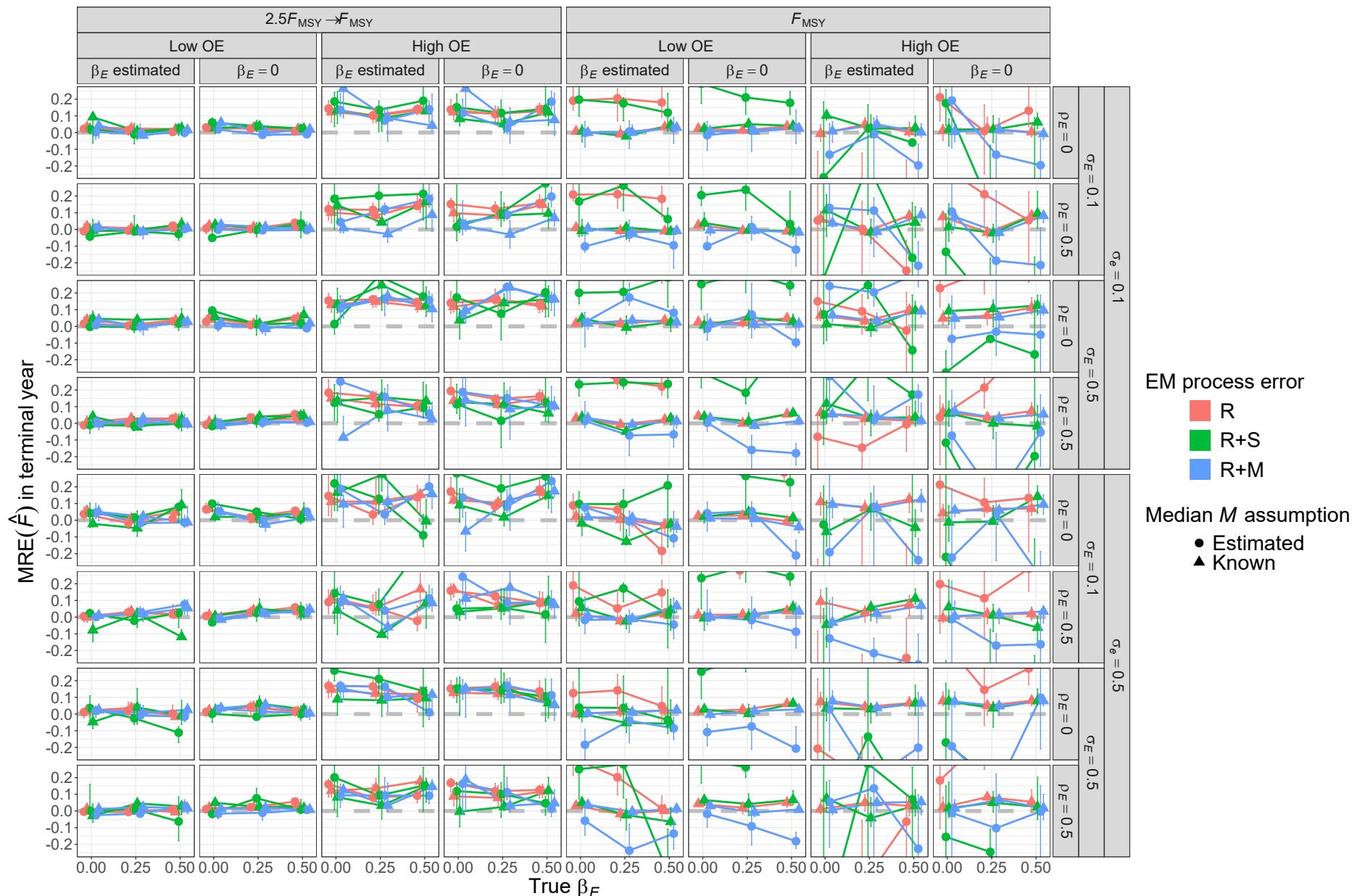


Fig. S65. For R+M OMs, median relative error (MRE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low observation error and contrast in fishing mortality.

⁶¹⁴ Terminal year fishing mortality RMSE

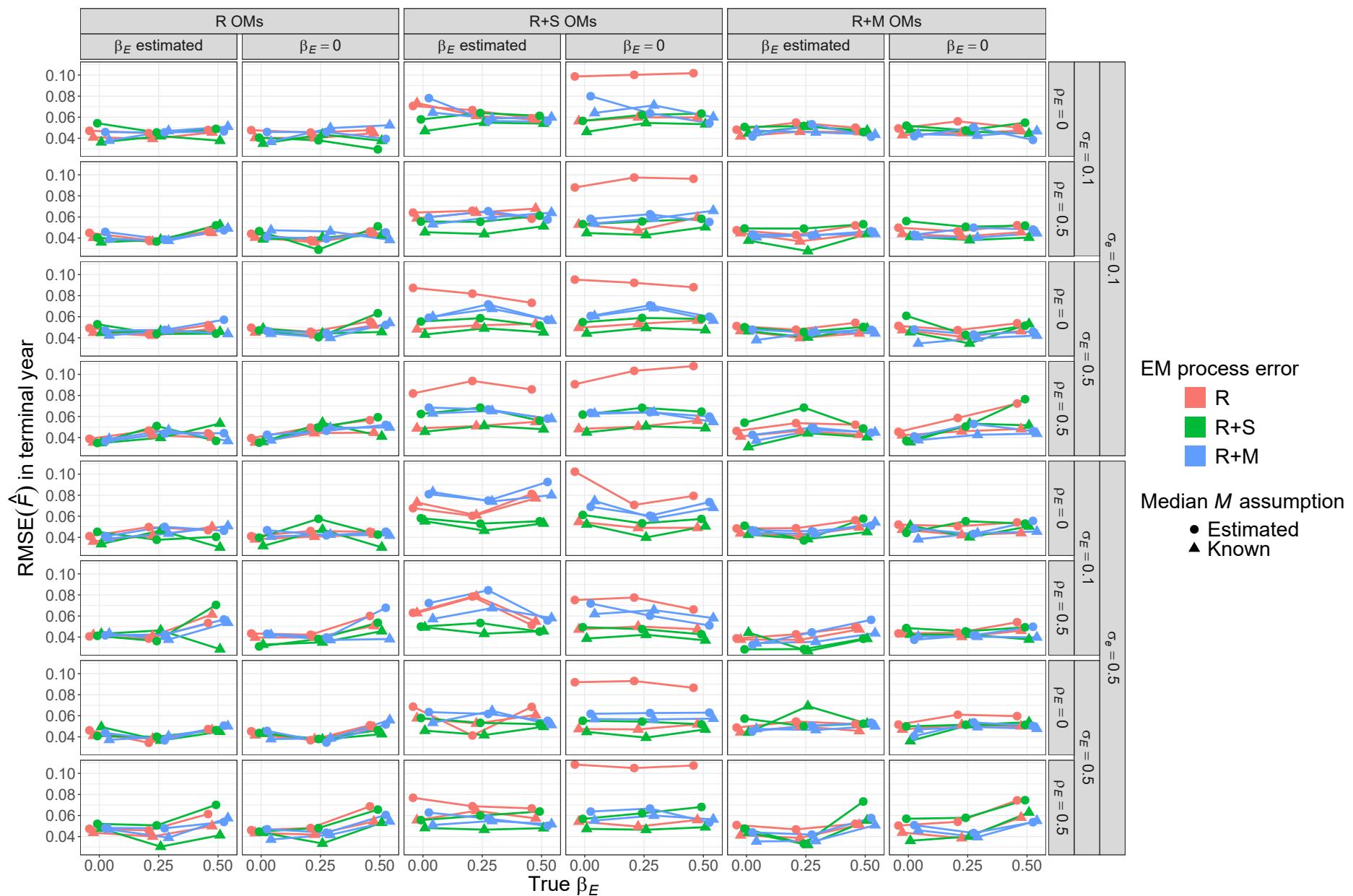


Fig. S66. Root mean square error (RMSE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known). All OMs had low population observation error and contrast in fishing mortality.

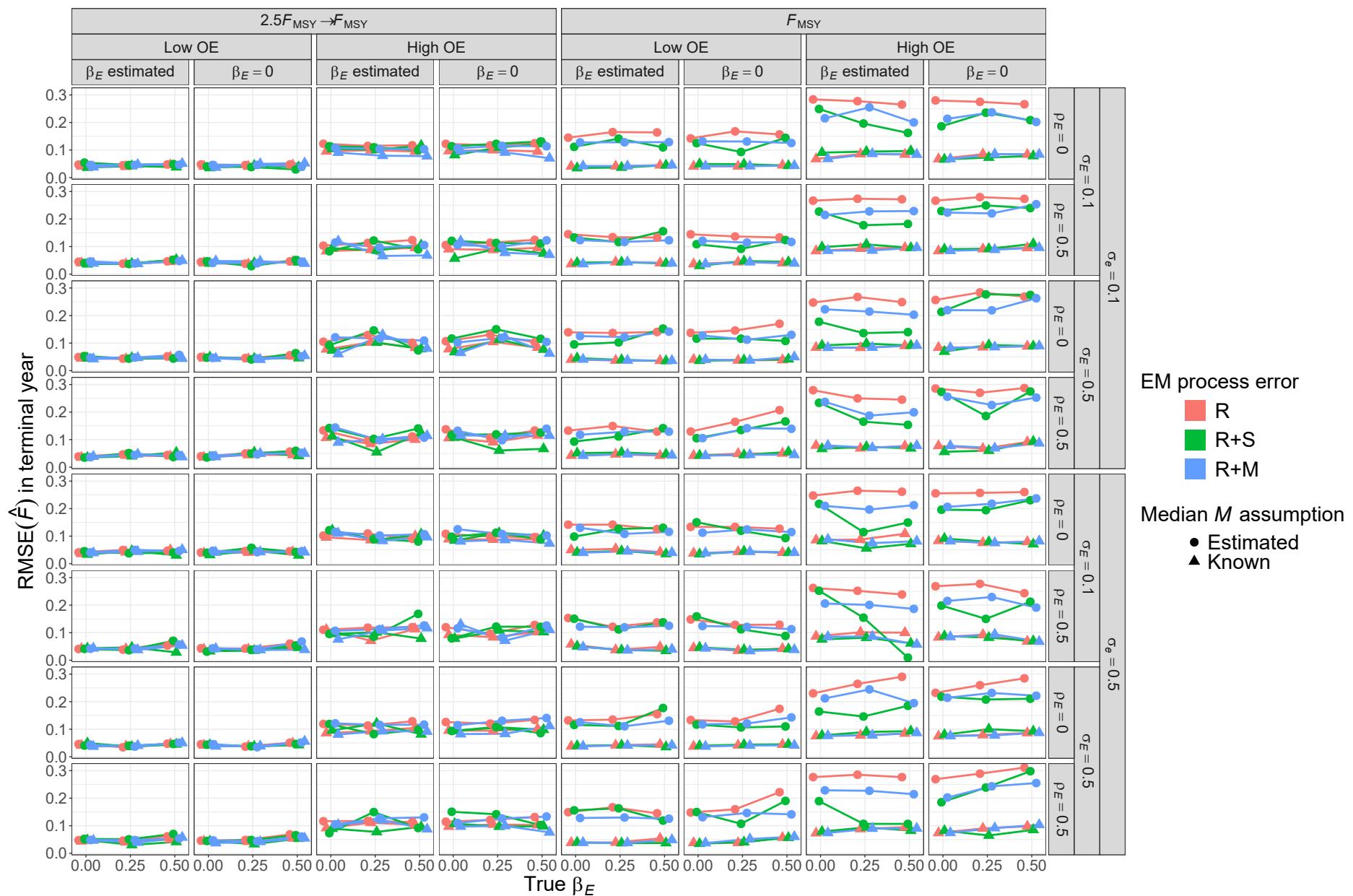


Fig. S67. For R OMs, root mean square error (RMSE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

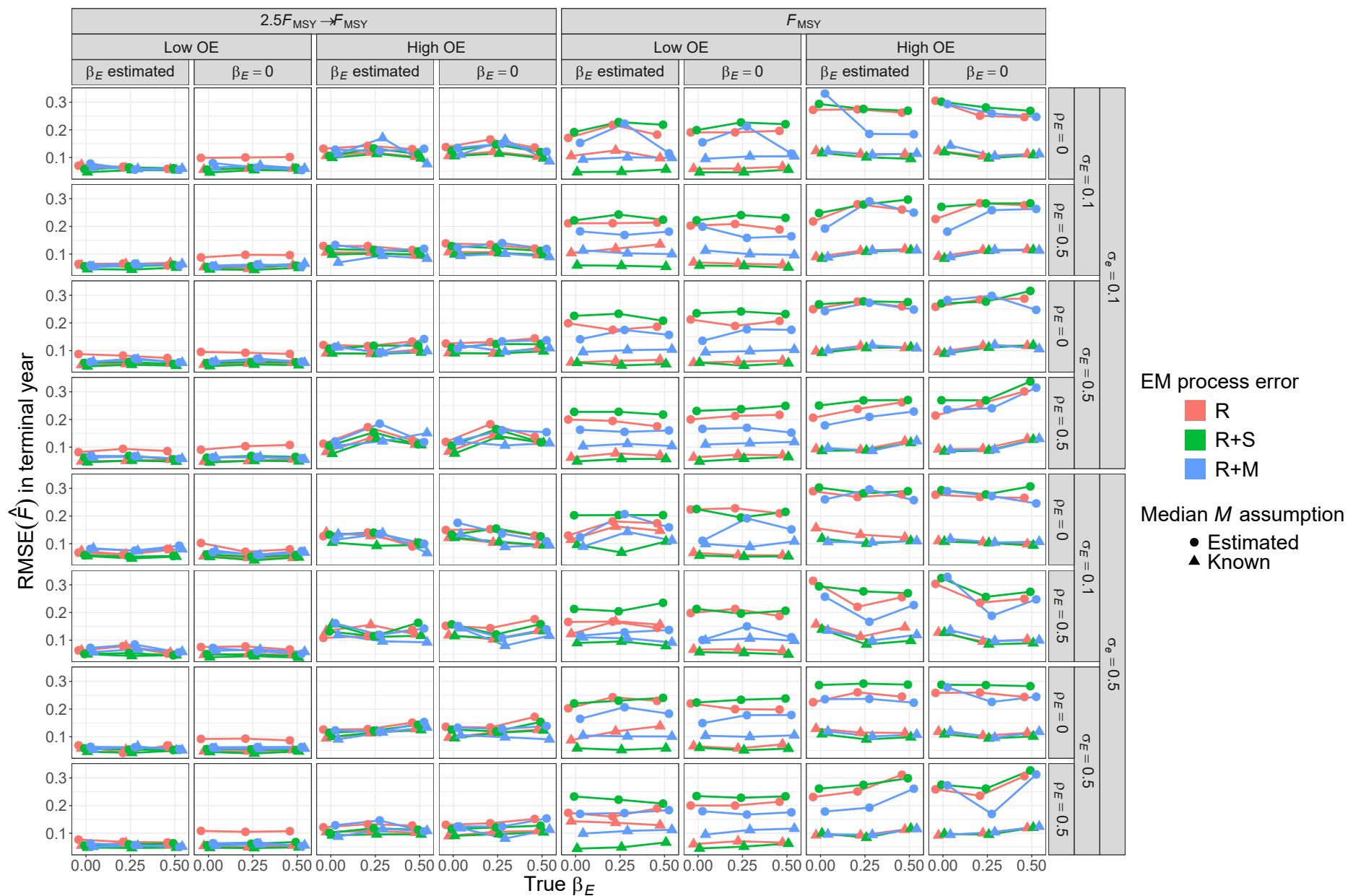


Fig. S68. For R+S OMs, root mean square error (RMSE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).

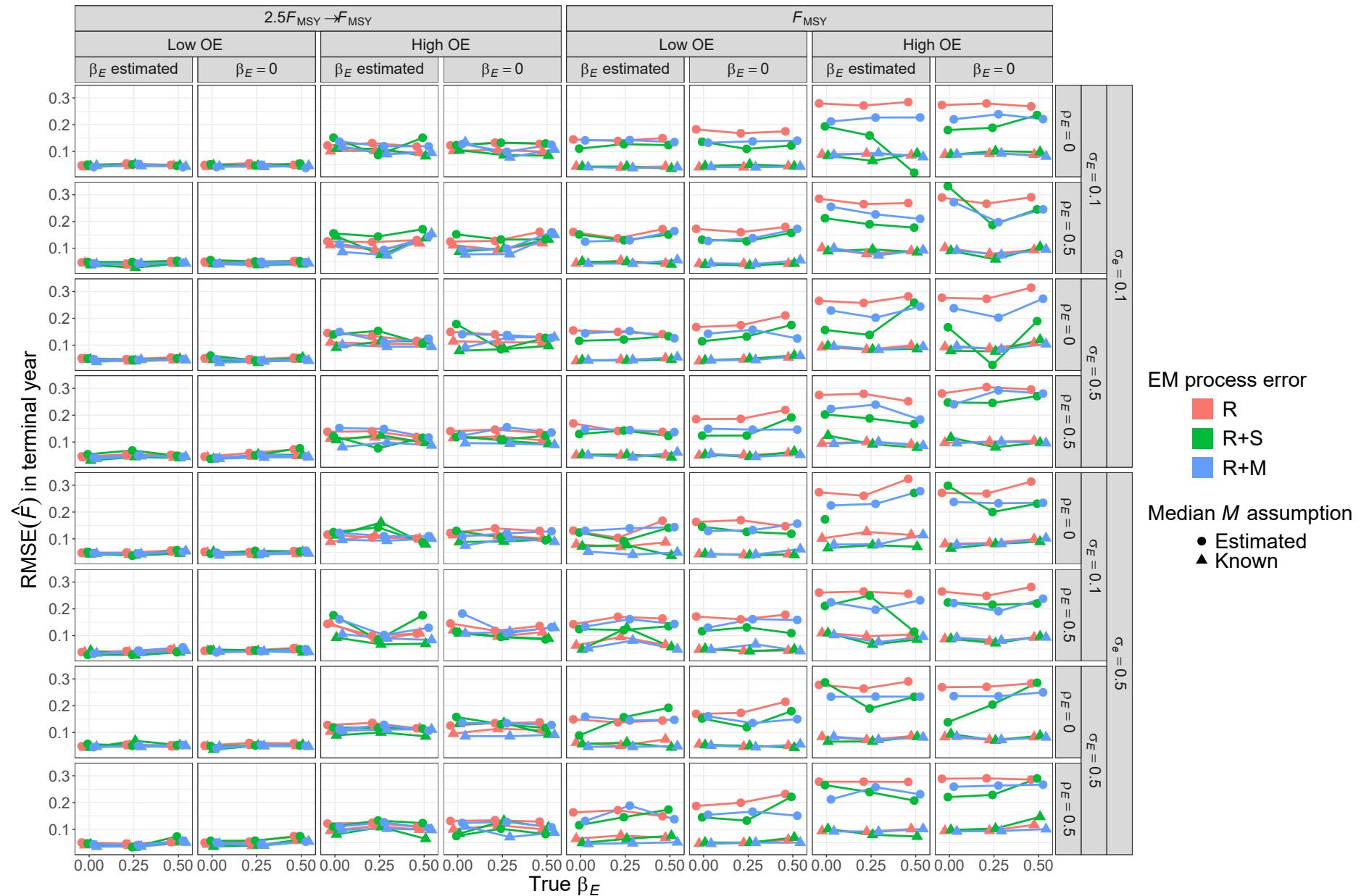


Fig. S69. For R+M OMs, root mean square error (RMSE) of estimates of fully-selected fishing mortality (F) in the terminal year for EMs with alternative process error assumptions, treatment of covariate effect ($\beta_E = 0$ or estimated), and treatment of median natural mortality parameter (β_M estimated or known).