

Exponential families and learning in (undirected) graphical models

Guillaume Obozinski

Swiss Data Science Center



African Masters of Machine Intelligence, 2018-2019, AIMS, Kigali

Exponential family

Definition

An exponential family is a family of distributions of the form

$$p(x; \theta) d\nu(x) = h(x) \exp \left\{ \langle b(\theta), \phi(x) \rangle - \tilde{A}(\theta) \right\} d\nu(x),$$

where

- $h(x)$ the ancillary statistic,
- $d\nu(x)$ the reference measure (or base measure),
- $\phi(x)$ the sufficient statistic (also called feature vector),
- θ the parameter,
- $\eta = b(\theta)$ the canonical parameter,
- $\tilde{A}(\theta) = A(\eta) = \log Z(\eta)$ the log-partition function.

Canonical exponential family

A canonical exponential family is an exponential family with

$$b(\theta) = \theta = \eta$$

so that

$$p(x; \eta) = h(x) \exp(\langle \eta, \phi(x) \rangle - A(\eta))$$

Partition function and log-partition functions

Note that, in the discrete case since $\sum_{x \in \mathcal{X}} p(x; \eta) = 1$, we necessarily have $A(\eta) = \log Z(\eta)$ with

$$Z(\eta) = \sum_{x \in \mathcal{X}} h(x) e^{\langle \eta, \phi(x) \rangle}.$$

Similarly, in the continuous case

$$A(\eta) = \log Z(\eta) = \log \int_{x \in \mathcal{X}} h(x) e^{\langle \eta, \phi(x) \rangle} d\nu(x)$$

Multinomial distribution in exponential family form

Let X be a random variable on $\mathcal{X} = \{0, 1\}^K$. X follows a multinomial distribution of parameter $\pi \in [0, 1]^K$.

$$p(x; \pi) = \prod_{k=1}^K \pi_k^{x_k} = \exp\left(\sum_{k=1}^K x_k \log \pi_k\right) = \exp\left(\sum_{k=1}^K x_k \eta_k\right) = \exp(\langle x, \eta \rangle)$$

that we need to identify with

$$h(x) \exp(\langle \eta, \phi(x) \rangle - A(\eta)).$$

So, we easily recognize:

- $\eta = (\log \pi_1, \log \pi_2, \dots, \log \pi_K)^\top$;
- $\phi(x) = x$;
- $h(x) = 1$ the constant function equal to one;

But we don't recognize $A(\eta)$...

Multinomial distribution in exponential family form

Let us compute explicitly $A(\eta)$:

$$A(\eta) = \log \left(\sum_{x \in \mathcal{X}} \exp(\eta^T x) \right) = \log \left(\sum_{k=1}^K \exp(\eta_k) \right)$$

If $\eta = (\log \pi_1, \log \pi_2, \dots, \log \pi_K)^T$ then

$$A(\eta) = \log \sum_{k'=1}^K \exp \eta_{k'} = 0.$$

The canonical parameter is however not constrained in general to satisfy this constraint.

Many exponential families

Many of the families of distributions that are classical actually are actually exponential families:

- Bernoulli, Binomial, Multinomial distribution
- Gaussian distributions
- Poisson distributions
- Geometric distributions
- Exponential distributions
- Gamma distributions
- Wishart distributions
- Beta distributions
- Dirichlet distributions
- and more

Ising model: binary variables with pairwise interactions

$$p_{\eta_0}(x) = \frac{1}{Z(\eta_0)} \exp \sum_{(i,j) \in E} \psi_{ij}(x_i, x_j; \eta_0)$$

$$\psi_{ij}(x_i, x_j; \eta_0) = V_{ij}^{11} x_i x_j + V_{ij}^{10} x_i (1 - x_j) + V_{ij}^{01} (1 - x_i) x_j + V_{ij}^{00} (1 - x_i) (1 - x_j)$$

$$\eta_0 = (V_{ij}^{kk'})_{\substack{(i,j) \in E \\ k, k' \in \{0,1\}}} \quad \text{and} \quad \phi(x) = \left(\begin{array}{c} x_i x_j \\ (1 - x_i) x_j \\ \vdots \end{array} \right)_{(i,j) \in E}$$

This first expression is overparametrized. We can rewrite the expression with just one parameter per pair (x_i, x_j) :

$$p_{\eta}(x) = \frac{1}{Z(\eta)} \prod_{(i,j) \in E} \exp(\eta_{ij} x_i x_j) \prod_{i \in V} \exp(\eta_i x_i)$$

Potts' model: multinomial variables with pairwise interactions

We associate to node i a multinomial variable (with one-hot encoding)

$$X_i = (X_{i1}, \dots, X_{iK}),$$

encoding K possible states.

The expression for the Ising model generalizes to

$$p_{\eta}(x) = \exp \left(\sum_{i \in V} \sum_{k=1}^K \eta_{ik} x_{ik} + \sum_{(i,j) \in E} \sum_{k,\ell=1}^K \eta_{ijkl} x_{ik} x_{j\ell} - A(\eta) \right)$$

Gibbs model in exponential family form

In the general case of a discrete graphical model **such that** $p(x) > 0$ for all $x \in \mathcal{X}$, we have:

$$\begin{aligned} p(x) &= \frac{1}{Z} \prod_{c \in \mathcal{C}} \Psi_c(x_c) \\ &= \frac{1}{Z} \exp \left\{ \sum_{c \in \mathcal{C}} \log \Psi_c(x_c) \right\} \\ &= \frac{1}{Z} \exp \left\{ \sum_{c \in \mathcal{C}} \sum_{y_c \in \mathcal{X}_c} \delta_{\{y_c = x_c\}} \log \Psi_c(y_c) \right\} \end{aligned}$$

where $\mathcal{X}_c = \{ \text{set of all possible values of the r.v. on the clique } c \}$.
We recognize:

$$\phi(x) = (\delta_{\{x_c = y_c\}})_{y_c \in \mathcal{X}_c, c \in \mathcal{C}}$$

and

$$\eta = (\log \Psi_c(y_c))_{y_c \in \mathcal{X}_c, c \in \mathcal{C}}$$

Maximum likelihood in a canonical exponential family

Assume an i.i.d. sample $x^{(1)}, \dots, x^{(n)}$ For a model which is an exponential family, the likelihood of the parameter η

$$\mathcal{L}(\eta) = \prod_{i=1}^n p_{\eta}(x^{(i)}) = \prod_{i=1}^n h(x^{(i)}) \exp (\langle \eta, \phi(x^{(i)}) \rangle - A(\eta))$$

So that the log-likelihood is

$$\ell(\eta) = \sum_{i=1}^n \log h(x^{(i)}) + \sum_{i=1}^n \langle \eta, \phi(x^{(i)}) \rangle - nA(\eta).$$

Equivalently,

$$\frac{1}{n} \ell(\eta) = \langle \eta, \bar{\phi} \rangle - A(\eta) + c$$

$$\text{with } \bar{\phi} = \frac{1}{n} \sum_{i=1}^n \phi(x^{(i)}) \text{ and } c = \frac{1}{n} \sum_{i=1}^n \log h(x^{(i)}).$$

Qualities of canonical exponential family likelihoods

$$\frac{1}{n}\ell(\eta) = \langle \eta, \bar{\phi} \rangle - A(\eta) + c$$

Proposition

For an exponential family, A is a \mathcal{C}^∞ **convex** function.

Corollary

In a canonical exponential family, ℓ is a **concave** function.



Does not hold in a *curved* (i.e. non-canonical) exponential family

Proposition

The maximum likelihood parameter $\hat{\eta}_{\text{ML}}$ satisfies

$$\nabla A(\hat{\eta}_{\text{ML}}) = \bar{\phi}.$$

Proof: The maxima of a concave differentiable function are exactly its stationary points, i.e. points such that $\nabla \ell(\eta) = 0$.

Who is ∇A ?

Consider the discrete case

$$\nabla A(\eta) = \nabla(\log Z(\eta)) = \frac{1}{Z(\eta)} \nabla Z(\eta).$$

But

$$\begin{aligned}\nabla Z(\eta) &= \sum_{x \in \mathcal{X}} \nabla(e^{\langle \eta, \phi(x) \rangle}) \\ &= \sum_{x \in \mathcal{X}} \phi(x) e^{\langle \eta, \phi(x) \rangle} \\ &= Z(\eta) \sum_{x \in \mathcal{X}} \phi(x) e^{\langle \eta, \phi(x) \rangle - A(\eta)} \\ &= Z(\eta) \mathbb{E}_{\eta}[\phi(X)]\end{aligned}$$

So that

$$\boxed{\mu(\eta) := \nabla A(\eta) = \mathbb{E}_{\eta}[\phi(X)]}$$

$\mu(\eta)$ is called the *moment parameter* of the exponential family.

Moment matching property of the MLE

Combining the fact that $\nabla A(\eta) = \mathbb{E}_\eta[\phi(X)]$ for any η and that for the MLE we have $\nabla A(\hat{\eta}_{\text{ML}}) = \bar{\phi}$, we get

Theorem

The maximum likelihood estimator(s) is(/are) characterized by the *moment matching condition*:

$$\mu(\hat{\eta}_{\text{ML}}) := \mathbb{E}_{\hat{\eta}_{\text{ML}}}[\phi(X)] = \bar{\phi}$$

Interpretation: the MLE is the set of parameters such that the expected value of the vector of sufficient statistics under the chosen parameters $\mathbb{E}_{\hat{\eta}_{\text{ML}}}[\phi(X)]$ matches the empirical average value $\bar{\phi}$ of the vector of *sufficient statistics* in the data.

Computing the MLE

- The moment matching condition gives immediately the MLE for the moment parameter since

$$\hat{\mu}_{\text{ML}} = \mu(\hat{\eta}_{\text{ML}}) = \bar{\phi}.$$

- Solving for $\hat{\eta}_{\text{ML}}$ can most of the time not be done in closed form
⇒ Need to use numerical methods, e.g. gradient based methods.
⇒ Need to compute the gradient of ℓ ...

Gradient of the log-likelihood

$$\nabla \ell(\eta) = \bar{\phi} - \mathbb{E}_{\eta}[\phi(X)]$$

- How to compute $\mathbb{E}_{\eta}[\phi(X)]$?

Example 1: Ising model

Reminder: $X = (X_i)_{i \in V}$ is a vector of random variables, taking value in $\{0, 1\}^{|V|}$, whose distribution has the following exponential form:

$$p(x) = e^{-A(\eta)} \prod_{i \in V} e^{\eta_i x_i} \prod_{(i,j) \in E} e^{\eta_{i,j} x_i x_j}$$

The associated log-likelihood is this:

$$\ell(\eta) = \sum_{i \in V} \eta_i x_i + \sum_{(i,j) \in E} \eta_{i,j} x_i x_j - A(\eta)$$

with sufficient statistics

$$\phi(x) = \begin{pmatrix} (x_i)_{i \in V} \\ (x_i x_j)_{(i,j) \in E} \end{pmatrix}$$

Example 1: Ising model

So with

$$\begin{aligned}\ell(\eta) &= \phi(x)^T \eta - A(\eta) \\ \nabla_{\eta} \ell(\eta) &= \phi(x) - \underbrace{\nabla_{\eta} A(\eta)}_{\mathbb{E}_{\eta}[\phi(X)]}\end{aligned}$$

We therefore need to compute $\mathbb{E}_{\eta}[\phi(X)]$.

In the case of the Ising model, we get:

$$\begin{aligned}\mathbb{E}_{\eta}[X_i] &= \mathbb{P}_{\eta}[X_i = 1] \\ \mathbb{E}_{\eta}[X_i X_j] &= \mathbb{P}_{\eta}[X_i = 1, X_j = 1]\end{aligned}$$

Example 2: Potts model

Reminder: C_i are random variables, taking value in $\{1, \dots, K_i\}$. We note X_{ik} the random variable such that $X_{ik} = 1$ if and only if $C_i = k$. Then,

$$p(x) = \exp \left[\sum_{i \in V} \sum_{k=1}^{K_i} \eta_{i,k} x_{ik} + \sum_{(i,j) \in E} \sum_{k=1}^{K_i} \sum_{k'=1}^{K_j} \eta_{i,j,k,k'} x_{ik} x_{jk'} - A(\eta) \right]$$

and

$$\phi(x) = \begin{pmatrix} (x_{ik})_{i,k} \\ (x_{ik} x_{jk'})_{i,j,k,k'} \end{pmatrix}$$

So that the expected value of the vector of sufficient statistics has components:

$$\begin{aligned} \mathbb{E}_\eta[X_{ik}] &= \mathbb{P}_\eta[C_i = k] \\ \mathbb{E}_\eta[X_{ik} X_{jk'}] &= \mathbb{P}_\eta[C_i = k, C_j = k'] \end{aligned}$$

On ties between learning and inference

In an exponential family

- *learning with the maximum likelihood principle* is the problem of computing η given a fixed value of $\mu(\eta) = \bar{\phi}$
- *performing probabilistic inference* is the problem of computing $\mu(\eta)$ given η .

So we can think of these problems as inverse of each other.

Learning η numerically using a gradient method requires to solve an inference problem at each iteration.

Some recent methods exploiting convex duality avoid to have to solve a whole inference problem at each iteration (Meshi et al., 2010; Pletscher et al., 2010; Meshi et al., 2015), but the connection and potential hardness related to inference is inescapable.

References I

- Meshi, O., Sontag, D., Globerson, A., and Jaakkola, T. S. (2010). Learning efficiently with approximate inference via dual losses. In *Proceedings of the 27th International Conference on Machine Learning (ICML-10)*, pages 783–790.
- Meshi, O., Srebro, N., and Hazan, T. (2015). Efficient training of structured SVMs via soft constraints. In *AISTATS*.
- Pletscher, P., Ong, C. S., and Buhmann, J. M. (2010). Entropy and margin maximization for structured output learning. In *ECML*.