

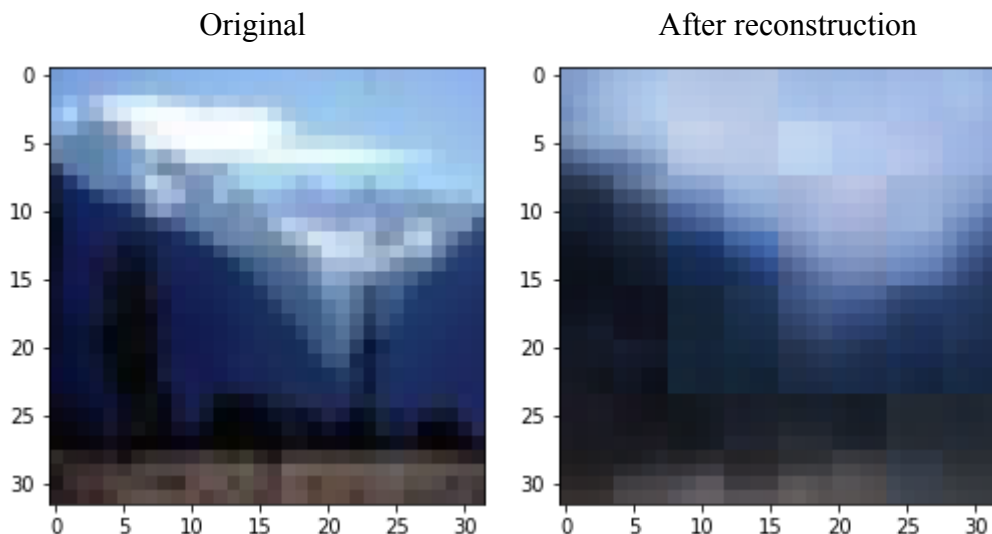
1. (1%) 請使用不同的Autoencoder model，以及不同的降維方式(降到不同維度)，討論其 reconstruction loss & public / private accuracy。（因此模型需要兩種，降維方法也需要兩種，但clustrering不用兩種。）

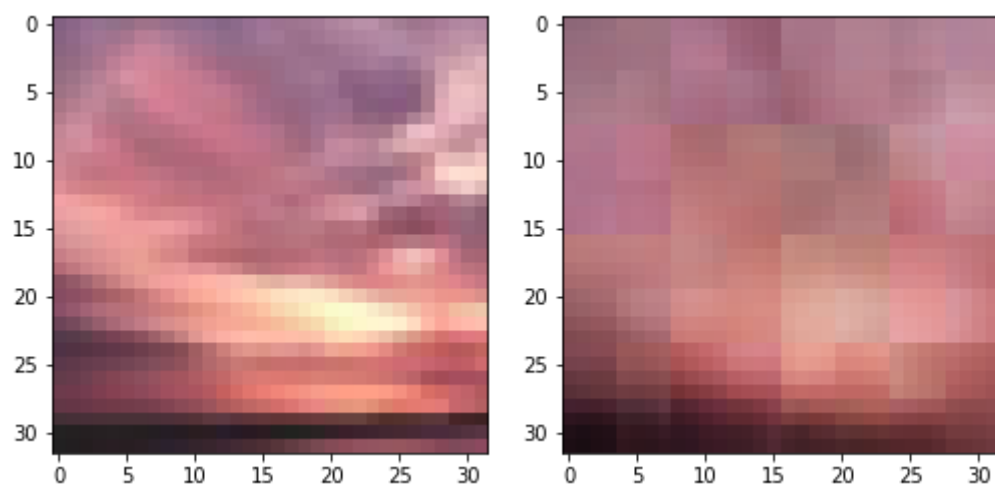
epoch 皆設為 200 或直到 reconstruction loss 收斂，lr = 3e-3

Autoencoder model	二次降維	reconstruction loss	public accuracy	private accuracy
Encoder: Conv2d(3 -> 32 -> 64) Linear(8*8*64 -> 50) Decoder: Linear(50 -> 8*8*64) Conv2d(64 -> 32 -> 3)	PCA (n=32)	0.026530	0.72000	0.71730
Same as above	TSNE (n=2)	0.026530	0.81296	0.81380
Encoder: Conv2d(3 -> 32 -> 64 -> 128 -> 256) Linear(2*2*256 -> 256 -> 128 -> 50) Decoder: Linear(50 -> 128 -> 256 -> 2*2*256) Conv2d(256 -> 128 -> 64 -> 32 -> 3)	PCA (n=32)	0.038232	0.70592	0.70809
Same as above	TSNE (=2)	0.038232	0.77703	0.77079

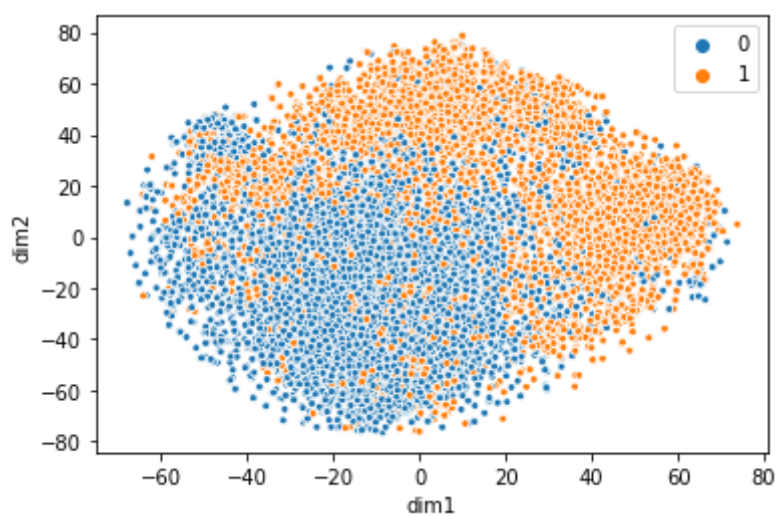
較多層的 Autoencoder 因為較難 train 所以在相同 epoch 與 lr 情況下表現不見得比較簡單的 Autoencoder 差；而二次降維使用 TSNE 的準確率普遍都比使用 PCA 來的佳。

2. (1%) 從dataset選出2張圖，並貼上原圖以及經過autoencoder後reconstruct的圖片。





3. (1%) 在之後我們會給你dataset的label。請在二維平面上視覺化label的分佈。



4. (3%)Refer to math problem
1.

$$1. \quad \Sigma = \frac{1}{10} \sum (x_i - \bar{x})(x_i - \bar{x})^T = \begin{bmatrix} 12.04 & 0.5 & 3.28 \\ 0.5 & 12.2 & 2.9 \\ 3.28 & 2.9 & 8.16 \end{bmatrix}$$

$$\lambda_1 = 15.3, u_1 = [-0.62, -0.59, -0.52]^T,$$

$$\lambda_2 = 11.63, u_2 = [-0.68, 0.73, -0.03]^T,$$

$$\lambda_3 = 5.47, u_3 = [0.4, 0.34, -0.85]^T$$

$$(a) u_1, u_2, u_3 \quad \times$$

$$(b) z_i = W \times x_i, \quad W = \begin{bmatrix} -0.62 & -0.59 & -0.52 \\ -0.68 & 0.73 & -0.03 \\ 0.4 & 0.34 & -0.85 \end{bmatrix}$$

$$z_1 = [-3.36, 0.71, 1.48]^T, z_2 = [-9.79, 3.03, -0.04]^T,$$

$$z_3 = [-13.62, 6.53, 2.42]^T, z_4 = [-7.94, 5.06, 1.16]^T,$$

$$z_5 = [-12.37, 6.84, -5.02]^T, z_6 = [-7.19, -1.84, -3.3]^T,$$

$$z_7 = [-14.96, -0.47, 1.37]^T, z_8 = [-7.08, 3.81, -3.05]^T,$$

$$z_9 = [-12.86, -3.95, -0.97]^T, z_{10} = [-16.3, 1.11, -1.75]^T \quad \times$$

$$(c) \frac{1}{10} \sum (x_i - \hat{y}_i)^2 = 6.064 \quad \times$$

2.

2.

$$(a) (AA^T)^T = (A^T)^T A^T = AA^T \Rightarrow AA^T \text{ is symmetric}$$

$$(A^T A)^T = A^T (A^T)^T = A^T A \Rightarrow A^T A \text{ is symmetric}$$

$$z^T (AA^T) z = (A^T z)^T A^T z = \|A^T z\|^2 \geq 0$$

$$\Rightarrow AA^T \text{ is positive semi-definite}$$

$$z^T (A^T A) z = (Az)^T A z = \|Az\|^2 \geq 0$$

$$\Rightarrow A^T A \text{ is positive semi-definite}$$

Duct

$$(AA^T)x = \lambda x, \quad \lambda \neq 0, \quad A^T A(A^T x) = \lambda (A^T x), \quad \lambda = \|A\|^2,$$

$$(A^T A)x = \lambda x, \quad \lambda \neq 0, \quad AA^T(Ax) = \lambda (Ax), \quad \lambda = \|A\|^2$$

No.

Date

(b) for all $x \in \mathbb{R}^n$,

$$Cov(x) = E[(x - \mu)(x - \mu)^T] = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)(x_i - \mu)^T = \Sigma,$$

let $M = (x - \mu)(x - \mu)^T \Rightarrow M$ is symmetric and positive semi-definite

$x = (x_1, \dots, x_n)$ 可為任意實數。 ✕

3.

3.

Find $g_{T+1}^k(x)$, $k=1 \dots K$, minimize $L(g_1^1, \dots, g_T^K)$,For every $k=1 \dots K$,

$$g_{T+1}^k(x) = g_T^k(x) - \eta \frac{\partial L(g)}{\partial g_T^k(x)}$$

$$g_{T+1}^k(x) = g_T^k(x) + \underline{\alpha_{T+1}^k f_{T+1}^k(x)} \rightarrow \text{same direction}$$

$$\frac{\partial L}{\partial g_T^k(x)} = \sum_{\hat{n}=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq \hat{y}_{\hat{n}}} g_T^k(x_{\hat{n}}) - g_T^{\hat{y}_{\hat{n}}}(x_{\hat{n}})\right) \times D$$

$$(D = \begin{cases} \frac{1}{K-1}, & \text{if } k \neq \hat{y}_{\hat{n}} \\ -1, & \text{else} \end{cases})$$

- We want to find $f_{T+1}(x)$ maximizing

$$\sum_{\hat{n}=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq \hat{y}_{\hat{n}}} g_T^k(x_{\hat{n}}) - g_T^{\hat{y}_{\hat{n}}}(x_{\hat{n}})\right) \times D \times f_{T+1}(x)$$

We want to α_T^k minimizing $L(g)$,Find α_T^k such that $\frac{\partial L}{\partial \alpha_T^k} = 0$

$$* \frac{\partial L}{\partial \alpha_T^k} = \sum_{\hat{n}=1}^n \exp\left(\frac{1}{K-1} \sum_{k \neq \hat{y}_{\hat{n}}} \sum_{t=1}^T \alpha_t^k f_t(x_{\hat{n}}) - \sum_{t=1}^T \alpha_t^{\hat{y}_{\hat{n}}} f_t(x_{\hat{n}})\right) \times E$$

$$(E = f_t(x_{\hat{n}}) \times \frac{1}{K-1} \text{ if } k \neq \hat{y}_{\hat{n}} \text{ else } f_t(x_{\hat{n}}))$$