# Class 4: Momentum, Impulse and Collisions

**Advanced Placement Physics** 

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## Momentum

#### **Linear Momentum**

**Linear momentum** (or **translational momentum**, or just **momentum**) is a quantity of motion defined as:

$$p = mv$$

Quantity	Symbol	SI Unit
Momentum	р	kg·m/s
Mass	m	kg
Velocity	V	m/s

For rotational motion of a rigid body, there is also **angular momentum** which will be studied in a later topic.

#### **General Form of Second Law of Motion**

Taking the time derivative of the momentum vector (from an inertial frame of reference) using the chain rule:

$$\frac{\mathrm{d}\boldsymbol{p}}{\mathrm{d}t} = \frac{\mathrm{d}(m\boldsymbol{v})}{\mathrm{d}t} = m\frac{\mathrm{d}\boldsymbol{v}}{\mathrm{d}t} + \frac{\mathrm{d}m}{\mathrm{d}t}\boldsymbol{v} = m\boldsymbol{a} + \dot{m}\boldsymbol{v}$$

For constant mass m (i.e.  $\dot{m}=0$ ), this right-hand-side reduces to the familiar form of the second law of motion,  $m\mathbf{a}$ .

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### First & Second Laws of Motion: General Form

In fact, the general form of the first and second law, now accounted for a changing mass, is that

- 1. The total momentum of an object remains constant until a net external force acts on it.
- II. The net external force acting on an object is the time rate of change of its momentum.

Summarizing this in a single equation:

$$\mathbf{F}_{net}(t) = \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t}$$

Like the "special case" from the dynamics section, this equation is only applicable from an inertial frame of reference.

# **Impulse**

## **Impulse**

**Impulse** *J* is defined as the time integral of force *F*:

$$\mathbf{J} = \int_{t_1}^{t_2} \mathbf{F}(t) \mathrm{d}t$$

We can calculate the force generated by

- any of the forces acting on the object, or
- the net force (called the **net impulse**)

over the time interval beteen  $t_1$  and  $t_2$ . Since F, p and J are all vectors, so the integral can be evaluated in each of the  $\hat{\imath}$ ,  $\hat{\jmath}$  and  $\hat{k}$  directions, e.g. for the x direction:

$$J_{x}=\int_{t_{1}}^{t_{2}}F_{x}dt$$

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## Impulse-Momentum Theorem

Rearranging the variables in the general form of the second law of motion:

$$\mathbf{F}_{net} = \frac{\mathrm{d}\mathbf{p}}{\mathrm{d}t} \rightarrow \mathbf{F}_{net}\mathrm{d}t = \mathrm{d}\mathbf{p}$$

Integrating both sides, we get the **impulse-momentum theorem**:

$$\int_{t_1}^{t_2} oldsymbol{F}_{net} \mathrm{d}t = \int_{p_1}^{p_2} \mathrm{d}oldsymbol{p} \quad 
ightarrow \quad oldsymbol{J}_{net} = \Deltaoldsymbol{p}$$

The **net impulse** is equalled to the change in momentum of the object.

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## **Average Force**

Average force  $\overline{F}$  is the time-averaged force vector that gets the same impulse. It is used extensively in introductory physics courses to avoid integration:

$$oldsymbol{J}=\int_{t_1}^{t_2} oldsymbol{F} \mathrm{d}t = oldsymbol{ar{F}} \Delta t$$

## Impulse: An Example

**Example 1:** Jim pushes a box with mass 1.0 kg with a 5.0 N force for 10 s while the box stays on the same place. Find the impulse of the pushing force, friction force, the gravitational force, and the net force.

## **Rocket Propulsion Problem**

**Example 2:** A rocket generates a thrust force by ejecting hot gases from an engine. If it takes 1 ms to combust 1.0 kg of fuel, ejecting it at a speed of 1000 m/s, what thrust is generated?

- A. 1000 N
- B. 10000 N
- C. 100 000 N
- D. 1000000N

## **Another Space Example**

**Example 3:** A rocket for mining the asteroid belt is designed like a large scoop. It is approaching asteroids at a velocity of  $10^4$  m/s. The asteroids are much smaller than the rocket. If the rocket scoops asteroids at a rate of 100 kg/s, what thrust (force) must the rocket's engine provide in order for the rocket to maintain constant velocity? Ignore any variation in the rocket's mass due to the burning fuel.

- A.  $10^3 \, \text{N}$
- B.  $10^6 \, \text{N}$
- C. 10<sup>9</sup> N
- D. 10<sup>12</sup> N

# **Collisions**

#### **Conservation of Momentum**

- From the third law of motion, we know that the action and reaction forces are always equal in magnitude and in opposite direction. Thus, their total impulse would be zero.
- When there is no external force, the momentum of the total system will always be constant. We saw that a few slides ago:

$$\sum oldsymbol{p}_i = \sum oldsymbol{p}_i'$$

#### **Classifications of Collisions**

- Elastic Collision:
  - Total kinetic energy is conserved
  - Momentum is conserved
- Inelastic collision:
  - Kinetic energy is not conserved
  - Momentum is conserved
- Completely inelastic collision:
  - "Perfectly inelastic collision"
  - A special case of inelastic collision
  - The objects move together after the collision
  - Kinetic energy is not conserved
  - Momentum is conserved

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#### **How to Solve Conservation of Momentum Problem**

- 1. Check whether the condition for the conservation of momentum is satisfied (i.e. are there any external forces?)
- 2. If so, write out expressions for initial momentum and final momentum, and equate the two. You will get 1 to 3 equations (one for each direction).
- 3. Solve these equations, find the quantity you need to find.

Remember that momentum is a vector. If there is no external force component in some direction, then the momentum component in this direction is still conserved.

#### **Before We Dive Into Some Exercises**

The most typical applications of momentum conservation are collision and explosions

- Collision: A hits B
  - Regardless of whether they move together or not afterwards, momentum is conserved
  - Head-on collisions are usually 1D
  - Glancing collisions are usually 2D or 3D
- Explosion: A explodes and becomes B and C (and D and E...)
  - A perfectly inelastic collision in reverse
  - Total momentum of B and C (and D and E...) is the same as A in the beginning
  - Usually a 2D or 3D problem

#### **Collision Problem**

**Example 5:** Two objects with equal mass are heading toward each other with equal speeds, undergo a head-on collision. Which one of the following statement is correct?

- A. Their final velocities are zero
- B. Their final velocities may be zero
- C. Each must have a final velocity equal to the other's initial velocity
- D. Their velocities must be reduced in magnitude

## **Conservation of Momentum Example**

**Example 6:** Two astronauts, each of mass 75 kg, are floating next to each other in space, outside the space shuttle. One of them pushes the other through a distance of 1.0 m (about an arm's length) with a force of 300 N. What is the final relative velocity of the two?

- A.  $2.0 \, \text{m/s}$
- B.  $2.83 \,\mathrm{m/s}$
- C.  $4.0 \, \text{m/s}$
- D.  $16.0 \, \text{m/s}$

## **Glancing Collision**

**Example 7:** A billiard ball of mass 0.155 kg ("cue ball") moves with a velocity of 1.25 m/s toward a stationary billiard ball ("eight ball") of identical mass and strikes it with a glancing blow. The cue ball moves off at an angle of 29.7° clockwise from its original direction, with a speed of 0.956 m/s. What is the final velocity of the eight ball?

**Elastic Collisions** 

#### **Elastic Collision Problems**

In elastic collisions, *both* momentum and kinetic energy is conserved. In a 1D collision, both equations below have to be satisfied:

$$\sum_{i} m_i v_i = \sum_{i} m_i v_i'$$
$$\sum_{i} \frac{1}{2} m_i v_i^2 = \sum_{i} \frac{1}{2} m_i v_i'^2$$

**How kinetic energy is conserved:** In an elastic collision, energy is first converted into a potential energy (e.g. elastic potential energy in a spring), and then all the energy is released back as kinetic energy.

## Conservation of Momentum & Energy in Elastic Collisions

For collision of two objects, the conservation of momentum equation can be expressed as:

$$m_1(v_1-v_1')=m_2(v_2'-v_2)$$
 (1)

By moving  $m_1$  terms to the left, and  $m_2$  terms to the right. Likewise, the conservation of energy can also be arranged as:

$$m_1(v_1^2 - v_1'^2) = m_2(v_2'^2 - v_2^2)$$
 (2)

By multiplying every term by 2, and again, moving  $m_1$  terms to the left, and  $v_2$  terms to the right.

## Conservation of Momentum & Energy in Elastic Collisions

Dividing the equations (2) by (1) from the last slide, we get:

$$\frac{(2)}{(1)} \rightarrow \frac{m_1(v_1^2 - v_1'^2)}{m_1(v_1 - v_1')} = \frac{m_2(v_2'^2 - v_2^2)}{m_2(v_2' - v_2)}$$

 $m_1$  and  $m_2$  terms cancel out, while the terms in the numerator can be expanded as the difference of two squares which is then simplified:

$$\frac{(v_1+v_1')(v_1-v_1')}{(v_1-v_1')} = \frac{(v_2'+v_2)(v_2'-v_2)}{(v_2'-v_2)}$$

Leading to the final expression, which is substituted back into (1)

$$v_1 + v_1' = v_2 + v_2'$$

#### **Final Velocities in an Elastic Collision**

When two objects 1 and 2 of mass  $m_1$  and  $m_2$  and collide elastically, their final velocities will be determined by the initial velocities  $v_1$  and  $v_2$ :

$$v'_{1} = \frac{m_{2} - m_{1}}{m_{2} + m_{1}} v_{1} + \frac{2m_{2}}{m_{2} + m_{1}} v_{2}$$

$$v'_{2} = \frac{2m_{2}}{m_{2} + m_{1}} v_{1} + \frac{m_{2} - m_{1}}{m_{2} + m_{1}} v_{2}$$

These equations are *not* provided in the AP exam equation sheet, which means that we are more interested in the behavior qualitatively rather than quantitatively.

## **Special Cases**

If both objects have equal mass ( $m_1 = m_2 = m$ ) and the second object is initially at rest ( $v_2 = 0$ ), then the equations simplifies to

$$v'_{1} = \frac{v_{1}(m-m) + 2mv_{2}}{m+m} = 0$$

$$v'_{2} = \frac{v_{2}(m-m) + 2mv_{1}}{m+m} = v_{1}$$

All the momentum and energy from  $m_1$  is transferred to  $m_2$ . Object 1 stops all together, while object 2 continues with the initial momentum and velocity of Object 1.

## **Special Cases**

Another special case is when  $m_1 \gg m_2$  and  $v_2 = 0$  (i.e. a large object colliding with a small stationary object) then we can effectively "ignore"  $m_2$ :

$$\begin{aligned} v_1' &= \frac{v_1(m_1 - m_2) + 2m_2v_2}{m_1 + m_2} \approx \frac{m_1v_1}{m_1} = v_1 \\ v_2' &= \frac{v_2(m_2 - m_1) + 2m_1v_1}{m_1 + m_2} \approx \frac{2m_1v_1}{m_1} = 2v_1 \end{aligned}$$

Object 1 continues to move like nothing happened, but object 2 is pushed to move at *twice* the initial speed of object 1.

## **Special Cases**

In the reverse case, if  $m_1 \ll m_2$ , and  $v_2 = 0$  (a small object colliding with a large stationary object), then we can "ignore" the  $m_1$  term:

$$\begin{split} v_1' &= \frac{v_1(m_1-m_2) + 2m_2v_2}{m_1+m_2} \approx \frac{-m_2v_1}{m_2} = -v_1 \\ v_2' &= \frac{v_2(m_2-m_1) + 2m_1v_1}{m_1+m_2} \approx 0 \end{split}$$

Object 1 bounces off object 2, and travels in the opposite direction with the same velocity magnitude, while object 2 does not move.

**Example 8:** Blocks A and B have the same mass; A hits B with a speed of 5.0 m/s while B is initially at rest. If the collision is elastic, what would be the final speed of these two objects?

**Example 9:** Blocks A and B with the same mass; A has a velocity 3.0 m/s to the east while B has 2 m/s to the west. If the collision is elastic, after the collision, what would the velocity of the two blocks be?

**Example 10:** Throw a ball to a really big wall, when the ball reaches the wall, it has a velocity 10 m/s toward the wall. If the collision is elastic, what would the final velocity of the ball be?

**Example 11:** Throw a ball with a velocity 4.0 m/s toward a train with a velocity 40 m/s toward the ball. If the collision is elastic, what would the final velocity of the ball be?

## **Inelastic Collision: Calculating Energy Loss**

**Example 12:** Two blocks A and B with mass 2.0 kg, block A hits B with velocity 4.0 m/s while B is at rest.

- (a) Suppose the collision is completely inelastic, what would the final velocity of A and B be?
- (b) What is the loss of energy?