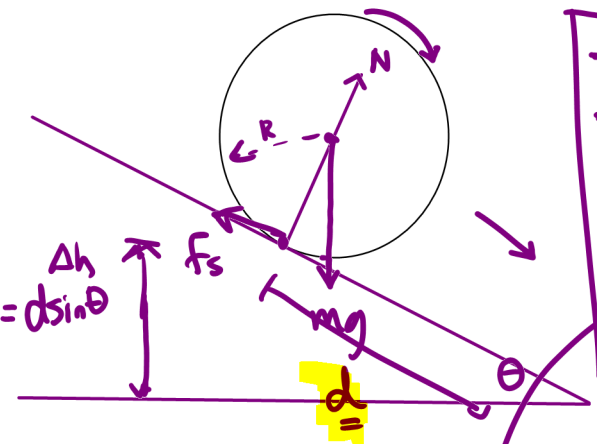


BALL ROLLING DOWN AN INCLINE WITHOUT SLIPPING



- assume rigid body \rightarrow no deformation
- normal force does not do work (\perp to motion)
- gravity does positive work (conservative)
- static friction does positive work (\vec{r} and \vec{C} is in the same direction both clockwise)

$$W = \Delta K$$

- increase of rotational kinetic energy as the ball rolls.

- K_{rot} comes from translational kinetic energy (can see from dynamics problem that the CM is translating more slowly when there is rotation compared to sliding case)

Still a closed system.
 \therefore Energy is conserved.

$$\begin{aligned} & \frac{1}{2} I \omega^2 \\ & = \frac{1}{2} \left(\frac{2}{5} m R^2 \right) \left(\frac{v^2}{R^2} \right) \end{aligned}$$

$$\underline{U} + \underline{K_{trans}} + K_{rot} = \text{constant}$$

$$mgh + \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2 = \text{constant}$$

$$+ \frac{1}{2} m v^2 + \left(\frac{1}{5} m v^2 \right) = \text{constant}$$

$$mgh + \frac{7}{10} m v^2 = \text{constant}$$

- after rolling for a distance d from rest $v_0 = 0$

$$\underbrace{m g d \sin \theta}_{\Delta h} = \frac{7}{10} m v^2 \quad \rightarrow \quad v = \sqrt{\frac{10}{7} g d \sin \theta} \quad \leftarrow \text{Same answer!!}$$

- dynamics: $a = \frac{5}{7} g \sin \theta \quad \rightarrow \quad \text{kinematics}$

$$v^2 = v_0^2 + 2 a d$$

$$v = \sqrt{2 a d} = \sqrt{\frac{10}{7} g d \sin \theta}$$