

Class 5: Center of Mass

Advanced Placement Physics C

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Finding an object's center of mass is important, because

- The laws of motion are formulated by treating an objects as point masses (for real-life objects, we let the forces apply to the center of mass)
- Objects can have *rotational* motion in addition to *translational* motion as well (we will examine that a bit more in a very-important topic later)

Start with a Definition

The **center of mass** (“CM”) is the *weighted average of the masses in a system*. The “system” may be:

- A collection of individual particles
- A continuous distribution of mass with constant density. In this case, CM is also the geometric center (**centroid**) of the object
- A continuous distribution of mass with varying density
- If the masses are inside of a gravitational field, then the CM is also its **center of gravity** (“CG”)

Simple Example

We start with a very simple example: there are two equal masses along the x-axis. What is the center of mass of the system?



Answer: the half way point between the two masses!

Slightly More Challenging

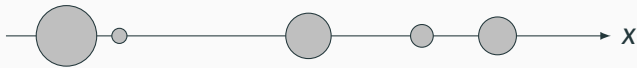
- What if one of the masses are increased to $2m$?
- This is still not a terribly difficult problem; you can still *guess* the right answer without knowing the equation for center of mass.



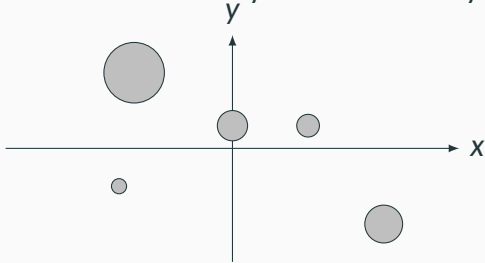
The answer is still simple. The CM is no longer half way between the two masses, but now $\frac{1}{3}$ the total distance from the larger masses.

Complicating Things Further

If we increase the number of point masses along the x -axis, our problem can become much more complicated (although still not devastatingly so)



Difficulties really arise when there are many masses in the system in 2D or 3D:



An Equation Helps

The center of mass is defined for discrete number of masses as:

$$\vec{x}_{\text{CM}} = \frac{\sum \vec{x}_i m_i}{\sum m_i}$$

| Quantity | Symbol | SI Unit |
|-------------------------------------|-----------------------|---------|
| Position of center of mass (vector) | \vec{x}_{CM} | m |
| Position of point mass i (vector) | \vec{x}_i | m |
| Point mass i | m_i | kg |

In components:

$$x_{\text{CM}} = \frac{\sum x_i m_i}{\sum m_i} \quad y_{\text{CM}} = \frac{\sum y_i m_i}{\sum m_i} \quad z_{\text{CM}} = \frac{\sum z_i m_i}{\sum m_i}$$

An Example

Example 1: Consider the following masses and their coordinates which make up a “discrete mass” rigid body”

$$m_1 = 5.0 \text{ kg}$$

$$\vec{x}_1 = 3\hat{i} - 2\hat{k}$$

$$m_2 = 10.0 \text{ kg}$$

$$\vec{x}_2 = -4\hat{i} + 2\hat{j} + 7\hat{k}$$

$$m_3 = 1.0 \text{ kg}$$

$$\vec{x}_3 = 10\hat{i} - 17\hat{j} + 10\hat{k}$$

What are the coordinates for the center of mass of this system?

Continuous Mass Distribution

In general, objects are not a discrete collection of point masses, but a continuous distribution of mass. Therefore, we take the limit of when the number of masses approaches ∞ :

$$\vec{x}_{\text{CM}} = \lim_{n \rightarrow \infty} \left(\frac{\sum_{i=1}^n \vec{x}_i m_i}{\sum_{i=1}^n m_i} \right)$$

This gives us an integral form of our equation:

$$\boxed{\vec{x}_{\text{CM}} = \frac{\int \vec{x} dm}{\int dm}}$$

Densities

- Linear density (for 1D problems)

$$\gamma = \frac{dm}{dL} \quad \rightarrow \quad dm = \gamma dL$$

- Surface area density (for 2D problems)

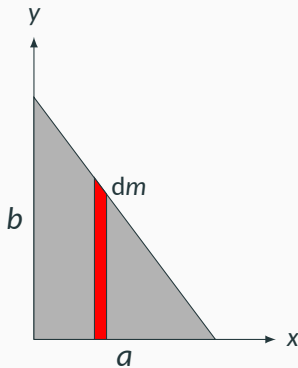
$$\sigma = \frac{dm}{dA} \quad \rightarrow \quad dm = \sigma dA$$

- Volume density (for 3D problems)

$$\rho = \frac{dm}{dV} \quad \rightarrow \quad dm = \rho dV$$

An Example with Integrals

Example 2: A triangular plate is placed in a Cartesian coordinate system with two of its edges along the x and y -axis. The length of the edges along the axes are a and b respectively. Assuming that the surface area density σ is uniform, determine the coordinate of its center of mass.

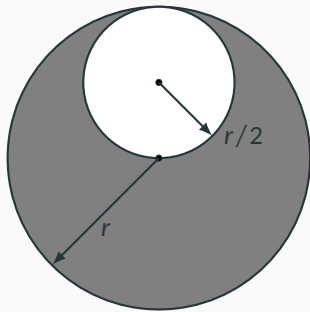


Symmetry

- Any plane of symmetry, mirror line, axis of rotation, point of inversion *must* contain the center of mass.
- Caveat: only works if the density distribution is also symmetric
- Again: if density is uniform, CM is also geometric center (centroid)

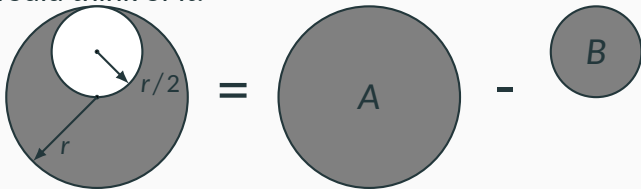
“Negative Mass”

- Where there is a “hole” in the geometry, treat it as having negative mass density $-\sigma$ in that region.
- Negative masses don’t exist, so this is really just a trick.
- **Example:** What is the center of mass of this shape?



Negative Mass Example

- This is how we would think of it:



- Let the origin of the coordinate system to be located at the center of A
- Based on symmetry: $x_{\text{CM}} = 0$; only have to find y-coordinate.
- Sum our weighted average:

$$y_{\text{CM}} = \frac{\sum y_i m_i}{\sum m_i} = \frac{m_A(0) + m_B(r/2)}{m_A + m_B} = \frac{-\sigma\pi (r/2)^2 (r/2)}{\sigma\pi r^2 - \sigma\pi (r/2)^2} =$$

Velocity, Acceleration and Momentum

Take time derivative of the equation for \vec{x}_{CM} to get the velocity at the CM:

$$\vec{v}_{\text{CM}} = \frac{d\vec{x}_{\text{CM}}}{dt} = \frac{1}{m} \frac{d}{dt} \left(\int \vec{x} dm \right) = \frac{1}{m} \int \frac{d\vec{x}}{dt} dm = \frac{\int \vec{v} dm}{m}$$

The integral in the numerator is the sum of the momentum of all the masses in the system (\vec{p}_{net}) which means that we have

$$\vec{p}_{\text{net}} = m\vec{v}_{\text{CM}}$$

Taking the derivative of \vec{p}_{net} relates force and acceleration at the CM as well:

$$\vec{F}_{\text{net}} = \frac{d\vec{p}_{\text{net}}}{dt} = m \frac{d\vec{v}_{\text{CM}}}{dt} = m\vec{a}_{\text{CM}}$$