Topic 5: Center of Mass

Advanced Placement Physics C

Dr. Timothy Leung

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Olympiads School

Center of Mass

Finding an object's center of mass is important, because

- The laws of motion are formulated by treating an objects as point masses (for real-life objects, we let the forces apply to the center of mass)
- Objects can have rotational motion in addition to translational motion as well (we will examine that a bit more in a very-important topic later)

Start with a Definition

The **center of mass** ("CM") is the weighted average of the masses in a system. The "system" may be:

- A collection of individual particles
- A continuous distribution of mass with constant density. In this case, CM is also the geometric center (centroid) of the object
- A continuous distribution of mass with varying density
- If the masses are inside of a gravitational field, then the CM is also its center of gravity ("CG")

Simple Example

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Answer: the half way point between the two masses!

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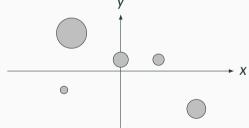
The answer is still simple. The CM is no longer half way between the two masses, but now $\frac{1}{3}$ the total distance from the larger masses.

Complicating Things Further

If we increase the number of point masses along the *x*-axis, our problem can become much more complicated (although still not devastatingly so)



Difficulties really arises when there are many masses in the system in 2D or 3D:



An Equation Helps

The center of mass is defined for discrete number of masses as:

$$\mathbf{x}_{\mathsf{CM}} = rac{\sum \mathbf{x}_{\mathsf{i}} m_{\mathsf{i}}}{\sum m_{\mathsf{i}}}$$

Quantity	Symbol	SI Unit
Position of center of mass (vector)	X _{CM}	m
Position of point mass i (vector)	Xi	m
Point mass i	m_i	kg

In components:

$$x_{CM} = rac{\sum x_i m_i}{\sum m_i}$$
 $y_{CM} = rac{\sum y_i m_i}{\sum m_i}$ $z_{CM} = rac{\sum z_i m_i}{\sum m_i}$

An Example

Example 1: Consider the following masses and their coordinates which make up a "discrete mass" rigid body"

$$m_1 = 5.0 \text{ kg}$$
 $\mathbf{x}_1 = 3\hat{\imath} - 2\hat{\mathbf{k}}$
 $m_2 = 10.0 \text{ kg}$ $\mathbf{x}_2 = -4\hat{\imath} + 2\hat{\jmath} + 7\hat{\mathbf{k}}$
 $m_3 = 1.0 \text{ kg}$ $\mathbf{x}_3 = 10\hat{\imath} - 17\hat{\jmath} + 10\hat{\mathbf{k}}$

What are the coordinates for the center of mass of this system?

Continuous Mass Distribution

In general, objects are not a discrete collection of point masses, but a continuous distribution of mass. Therefore, we take the limit of when the number of masses approaches ∞ :

$$\mathbf{x}_{CM} = \lim_{n \to \infty} \left(\frac{\sum_{i=1}^{n} \mathbf{x}_{i} m_{i}}{\sum_{i=1}^{n} m_{i}} \right)$$

This gives us an integral form of our equation:

$$\mathbf{x}_{\mathsf{CM}} = rac{\int \mathbf{x} d\mathbf{m}}{\int d\mathbf{m}}$$

9

Densities

• Linear density (for 1D problems)

$$\gamma = \frac{m}{L}$$

• Surface area density (for 2D problems)

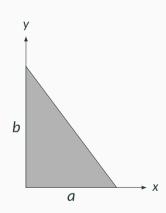
$$\sigma = \frac{m}{A}$$

Volume density (for 3D problems)

$$o = \frac{m}{V}$$

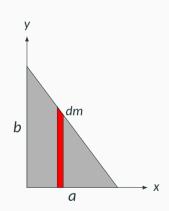
An Example with Integrals

Example 2: A triangular plate is placed in a Cartesian coordinate system with two of its edges along the x and y-axis. The length of the edges along the axes are a and b respectively. Assuming that the surface area density σ is uniform, determine the coordinate of its center of mass.



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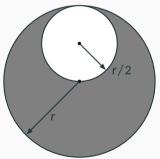


Symmetry

- Any plane of symmetry, mirror line, axis of rotation, point of inversion *must* contain the center of mass.
- Caveat: only works if the density distribution is also symmetric
- Again: if density is uniform, CM is also geometric center (centroid)

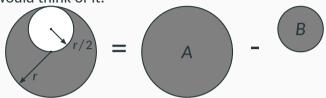
"Negative Mass"

- Where there is a "hole" in the geometry, treat it as having negative mass density $-\sigma$ in that region.
- Negative masses don't exist, so this is really just a trick.
- **Example:** What is the center of mass of this shape?



Negative Mass Example

• This is how we would think of it:



- Let the origin of the coordinate system to located at the center of A
- Based on symmetry: $x_{CM} = 0$; only have to find y-coordinate.
- Sum our weighted average:

$$y_{CM} = \frac{\sum y_i m_i}{\sum m_i} = \frac{m_A(0) + m_B(r/2)}{m_A + m_B} = \frac{-\sigma\pi (r/2)^2 (r/2)}{\sigma\pi r^2 - \sigma\pi (r/2)^2}$$

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Velocity, Acceleration and Momentum

Take time derivative of the equation for \mathbf{x}_{CM} to get the velocity at the CM:

$$\mathbf{v}_{\mathsf{CM}} = \frac{d\mathbf{x}_{\mathsf{CM}}}{dt} = \frac{1}{m} \frac{d}{dt} \left(\int \mathbf{x} dm \right) = \frac{1}{m} \int \frac{d\mathbf{x}}{dt} dm = \frac{\int \mathbf{v} dm}{m}$$

The integral in the numerator is the sum of the momentum of all the masses in the system (p_{net}) which means that we have

$$p_{\text{net}} = m v_{\text{CM}}$$

Taking the derivative of p_{net} relates force and acceleration at the CM as well:

$$\mathbf{F}_{\text{net}} = \frac{d\mathbf{p}_{\text{net}}}{dt} = m \frac{d\mathbf{v}_{\text{CM}}}{dt} = m \mathbf{a}_{\text{CM}}$$