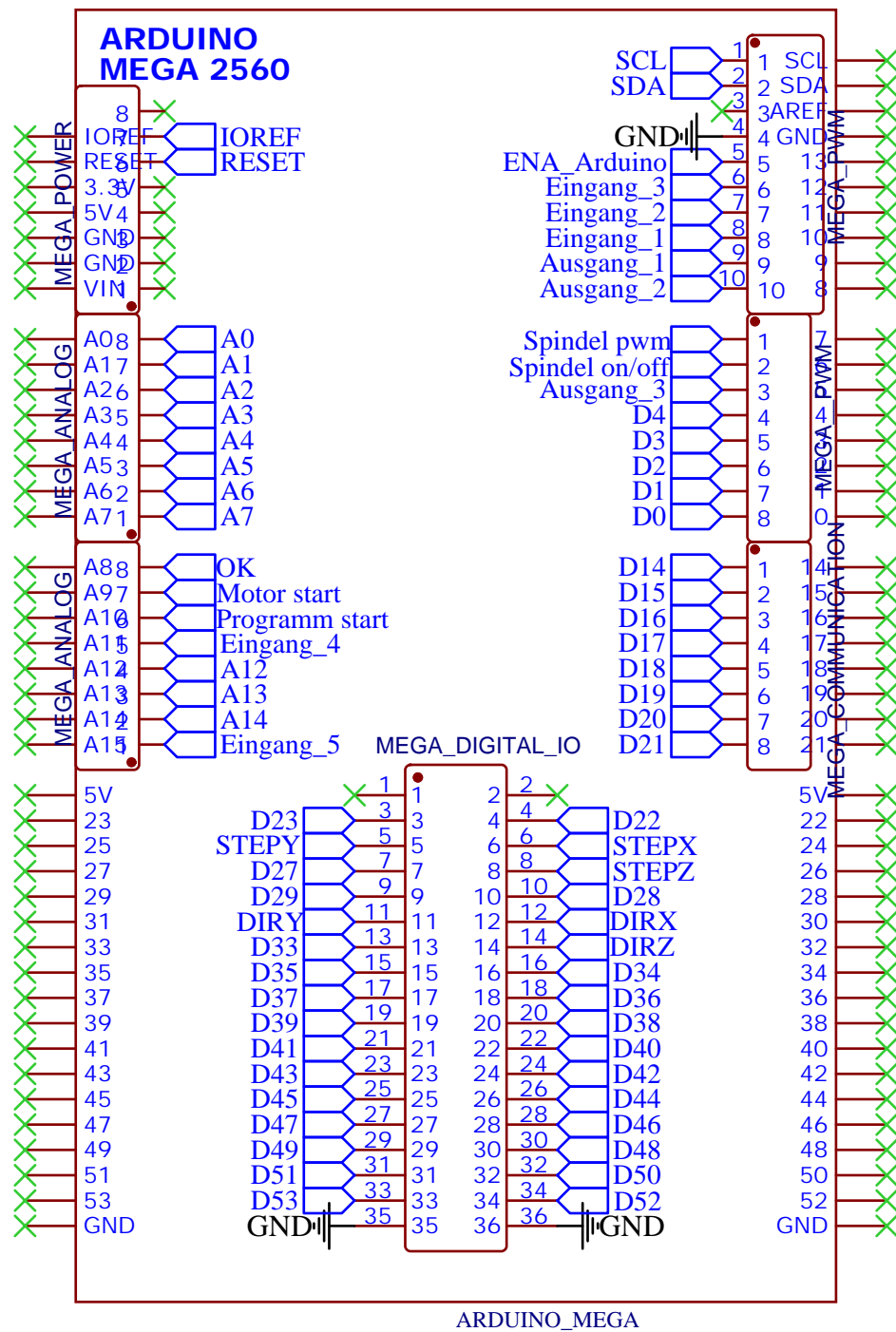
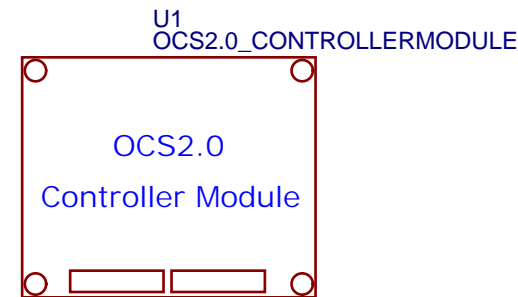


# Arduino\_Mega\_2560

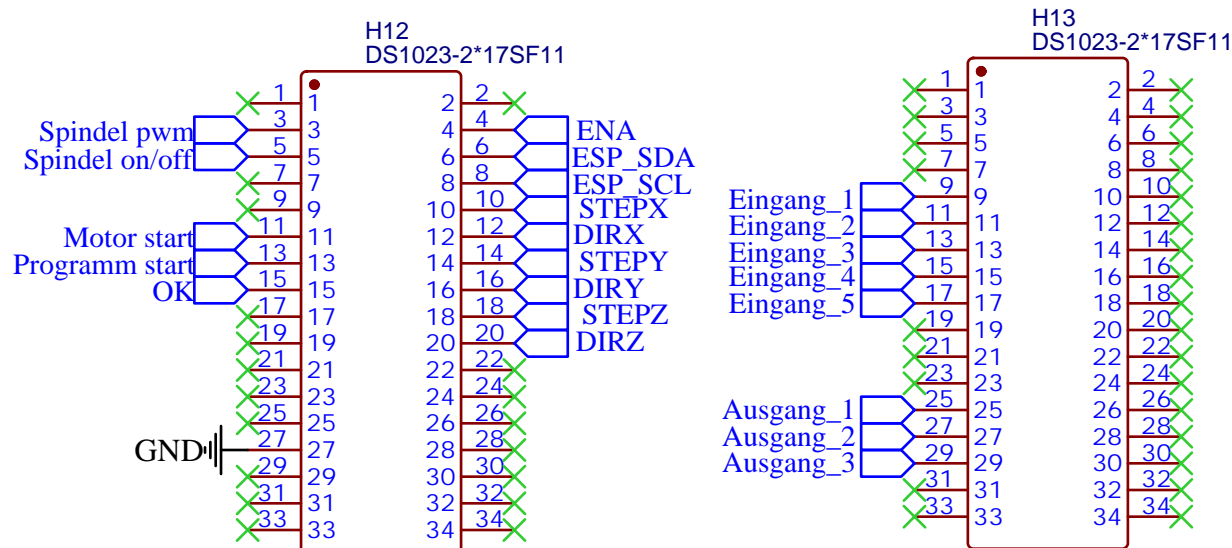


X-Limit = Eingang 1  
Y-Limit = Eingang 2  
Z-Limit = Eingang 3  
Spindle Enable = Spindle on/off  
Spindle = Spindel pwm  
Spindle Direction = Ausgang 3  
Flood = Ausgang 2  
Mist = Ausgang 1

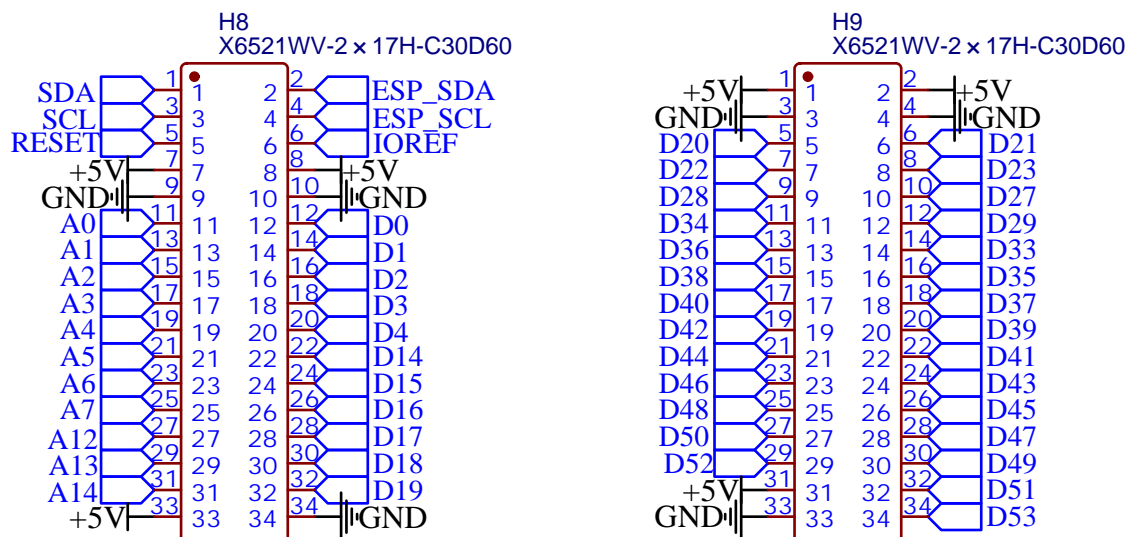
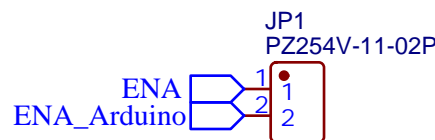
reset = OK  
feed hold = motor start  
cycle start = programm start  
safety door = Eingang 4  
probe input = Eingang 5  
driver enable = ENA



## Controller connector



## Pin outs



TITLE: Sheet_1		REV: 1.0
	Company: Your Company	Sheet: 1/1
	Date: 2022-04-24	Drawn By: timoa