# Possible Improvements

* Implementation of a possibility to save data: The data stored in the variable „databuffer“ might be used. By using a sampling rate the size of the file could be reduced.
* By now the image is only shown in black & white. If the color could be choosen by the user, a better visibility might be reached.
* As only one test camera was available, the option to choose another camera still has to be tested.
* The VRmUsbCamAPI.py could be extended. By now it is only working with single-sensor cameras. Furthermore the possible camera settings can be read out, which is not used yet.

For further possibilities see the documentations of the camera and the SDK located in ..\VRmagicUSBCam\SDK\docs.

* The fit performance can be improved.
* Introduce a “reference amplitude” displayed in the amplitude bar.