

view_frames Result

Recorded at time: 5148.817

map

odom

base_link

lidar_on_base_link

left_wheel_link

right_wheel_link

Broadcaster: /amcl
Average rate: 20.204 Hz
Most recent transform: 5149.284 (-0.467 sec old)
Buffer length: 4.900 sec

Broadcaster: /gazebo
Average rate: 20.204 Hz
Most recent transform: 5148.800 (0.017 sec old)
Buffer length: 4.900 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (5148.817 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 5148.756 (0.061 sec old)
Buffer length: 4.800 sec

Broadcaster: /robot_state_publisher
Average rate: 10.208 Hz
Most recent transform: 5148.756 (0.061 sec old)
Buffer length: 4.800 sec