

Time-Weighted Difference-in-Differences: Accounting for Common Factors in Short T Panels

Timo Schenk (U Amsterdam & Tinbergen Institute)

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Motivation

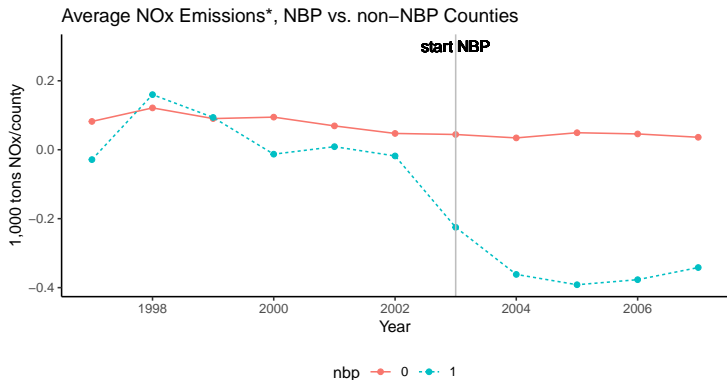
Setting: Binary treatment with **sharp** timing

- ▶ Observe outcome y_{it} for units $i = 1, \dots, N$ (large), periods $t = 1, \dots, T \geq 3$ (**small**),
- ▶ Two groups of units: $D_i = \begin{cases} 0 & \text{never treated} \\ 1 & \text{treated in } t = T_0 + 1, \dots, T \end{cases}$

Problem: Diff-in-diff (DID) estimation biased in presence of **interactive fixed effects**.

Solution: Equip the DID estimator with time weights.

Empirical example: Deschenes et al. (2017) AER

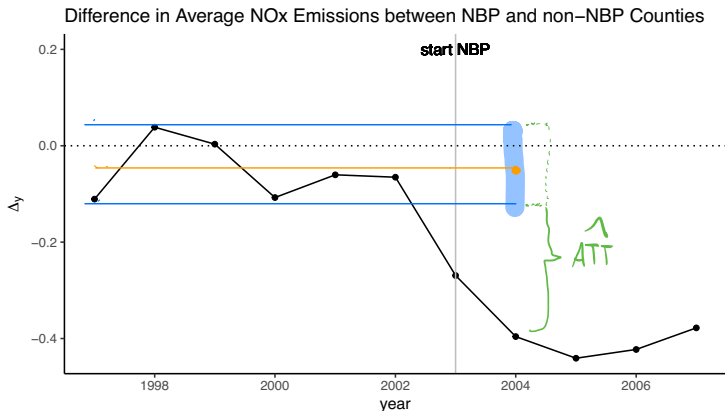


* difference in summer and winter emissions

NOx Budget Program (NBP) 2003-2008

- ▶ y_{it} : county/year level NOx emissions
- ▶ $N = 2539$ counties, of which ca. 50% are treated
- ▶ $T_0 = 6$ pre-treatment periods

Idea: use time weights



$$\widehat{ATT} = \Delta_T - \hat{\Delta}^{(0)}, \quad \Delta_t = \bar{y}_t^{(1)} - \bar{y}_t^{(0)}$$

Benchmark: $\hat{\Delta}_{did}^{(0)} = \frac{1}{T_0} \sum_{t \leq T_0} \Delta_t$

This paper: $\hat{\Delta}^{(0)}(\mathbf{v}) = \sum_{t \leq T_0} v_t \Delta_t$, with $\sum_t v_t = 1$, $v_t \geq 0$

Related work

Synthetic Control & Synthetic DID

Abadie et al. (2015), Ferman and Pinto (2016), Arkhangelsky et al. (2021)

- ▶ SC: unit weights, no time weights; small N , large T
- ▶ SDID: unit weights and time weights; large N , large T

Panel Data with Interactive Fixed Effects (IFE)

Pesaran (2006), Bai (2009), Moon and Weidner (2015), Gobillon and Magnac (2016)

- ▶ large N , large T

Treatment Effects with IFE

Callaway and Karami, (2022)

- ▶ large N , small T
- ▶ requires time-invariant covariate Z_i with constant effect on y_{it}

This paper: only time weights, no covariate Z_i ; large N , small T

Potential outcomes framework

Object of interest:

$$\tau := ATT = E[y_{i,T}(1) - y_{i,T}(0) | D_i = 1]$$

- ▶ Potential outcomes $y_{it}(0), y_{it}(1)$
- ▶ Observed outcome $y_{it} = y_{it}(1)D_i + y_{it}(0)(1 - D_i)$,
- ▶ In the paper: multiple treated periods and staggered adoption.

Assumption

$y_{it}(1) = y_{it}(0)$ for all $t \leq T_0$ (no anticipation)

Interactive fixed effects model

$$y_{it}(0) = \beta_i + \lambda_i' \mathbf{f}_t + \varepsilon_{it}$$

- ▶ $E[\varepsilon_i | D_i, \lambda_i] = 0$ and $E[\varepsilon_i \varepsilon_i' | D_i, \lambda_i] = \Sigma_{\varepsilon, i} > 0$
- ▶ \mathbf{f}_t : unobserved common factors with loadings λ_i
- ▶ $\text{Var}[\lambda_i | D_i = j] = \Sigma_{\lambda}^{(j)} > 0$: variation in how units are affected by \mathbf{f}_t
- ▶ $E[\lambda_i | D_i = 1] - E[\lambda_i | D_i = 0] = \xi_{\lambda}$:
treated and untreated units differ in how they are (on average)
affected by \mathbf{f}_t .

Convex Hull Condition (CHC)

Assumption

The post-treatment factor \mathbf{f}_T can be written as weighted average of pre-treatment factors $\mathbf{f}_1, \dots, \mathbf{f}_{T_0}$:

$$\exists \mathbf{v} \in \mathbb{V}: \mathbf{f}_T = \mathbf{F}'_{\text{pre}} \mathbf{v} \quad (= \sum_{t \leq T_0} v_t \mathbf{f}_t)$$

with $\mathbb{V} = \{\mathbf{v} \in \mathbb{R}^{T_0}: v_t \geq 0, \sum_{t=1}^{T_0} v_t = 1\}$ the set of non-negative weights that sum to one.

Examples

- ▶ $\mathbf{f} = (1, 2; 3)'$ CHC violated
- ▶ $\mathbf{f} = (1, 2; 1.5)'$ CHC met for $\mathbf{v} = (0.5, 0.5)'$
- ▶ $\mathbf{f} = (1, 2, 3; 2)'$ CHC met for $\mathbf{v} = (\alpha, 1 - 2\alpha, \alpha)'$ for all $\alpha \in [0, 0.5]$

Decomposing the ATT

$$\begin{aligned} ATT &= E[y_{i,T}(1)|D_i = 1] - E[y_{i,T}(0)|D_i = 0] \\ &\quad - \sum_{t \leq T_0} v_t (E[y_{i,t}(0)|D_i = 1] - E[y_{i,t}(0)|D_i = 0]) \\ &\quad - \xi'_\lambda(\mathbf{f}_T - \sum_{t \leq T_0} v_t \mathbf{f}_t) \end{aligned}$$

with factor imbalance $\xi_f(\mathbf{v}) = \mathbf{f}_T - \sum_{t \leq T_0} v_t \mathbf{f}_t$.

- ▶ DID: requires $\xi_\lambda = 0$ (parallel trends), use $v_t = \frac{1}{T_0}$.
- ▶ TWDID: requires $\xi_f(\mathbf{v}) = 0$ (no trends) for some \mathbf{v} .

Balancing common shocks with time weights

Time weighted DID estimator for given weights \mathbf{v} :

$$\hat{\tau}(\mathbf{v}) = \bar{y}_T^{(1)} - \bar{y}_T^{(0)} - \sum_{t \leq T_0} v_t (\bar{y}_t^{(1)} - \bar{y}_t^{(0)})$$

which is implemented by a weighted 2wfe regression.

Theorem

1. $E[\hat{\tau}(\mathbf{v}) - \tau] = \boldsymbol{\xi}'_{\lambda} \boldsymbol{\xi}_f(\mathbf{v})$
2. $\text{Var}[\hat{\tau}(\mathbf{v})] = \boldsymbol{\xi}_f(\mathbf{v})' \boldsymbol{\Sigma}_{\lambda} \boldsymbol{\xi}_f(\mathbf{v}) + V_z(\mathbf{v})$

Factor imbalance causes bias and amplifies the variance.

Estimating the weights from control units

Which **weighted average** of **pre-treatment outcomes** predicts best the **post-treatment outcome**?

Estimate

$$y_{i,T} = \alpha + \sum_{t \leq T_0} v_t y_{it} + \eta_i, \quad i \in \mathcal{N}_0 \text{ (control units)}$$

s.t. $\sum_{t \leq T_0} v_t = 1$ and $v_t \geq 0$ by restricted least-squares.

$$\min_{\mathbf{v} \in \mathbb{V}, \alpha} \sum_{i \in \mathcal{N}_0} \left(y_{i,T} - \alpha - \sum_{t \leq T_0} v_t y_{it} \right)^2$$

Properties of the estimated time weights

Does $\hat{\mathbf{v}}$ converge to something desirable?

Theorem

$$\hat{\mathbf{v}} \xrightarrow{P} \mathbf{v}^* := \arg \min_{\mathbf{v} \in \mathbb{V}} \underbrace{\left\{ \xi_f(\mathbf{v})' \Sigma_{\lambda}^{(0)} \xi_f(\mathbf{v}) + V_z^{(0)}(\mathbf{v}) \right\}}_{\text{Var}[\hat{\tau}(\mathbf{v})]}$$

and

$$\sqrt{N}(\hat{\mathbf{v}} - \mathbf{v}^*) \xrightarrow{d} \mathcal{N}[0, \Sigma_{\hat{\mathbf{v}}}]$$

Take-away

- ▶ The weights minimize the limiting variance of $\hat{\tau}(\mathbf{v})$,
- ▶ ...but may not balance the factors perfectly ($\xi_f(\mathbf{v}^*) \neq 0$)
- ▶ ...so some bias $b(\mathbf{v}^*) = \xi_{\lambda}' \xi_f(\mathbf{v}^*)$ remains

On the remaining bias

Define oracle weights

$$\mathbf{v}_0 = \arg \min_{\mathbf{v} \in \mathbb{V}} V_z^{(0)}(\mathbf{v}) \quad \text{s.t.} \quad \xi_f(\mathbf{v}) = 0$$

and variance minimizing weights

$$\mathbf{v}_\varepsilon = \arg \min_{\mathbf{v} \in \mathbb{V}} V_z^{(0)}(\mathbf{v})$$

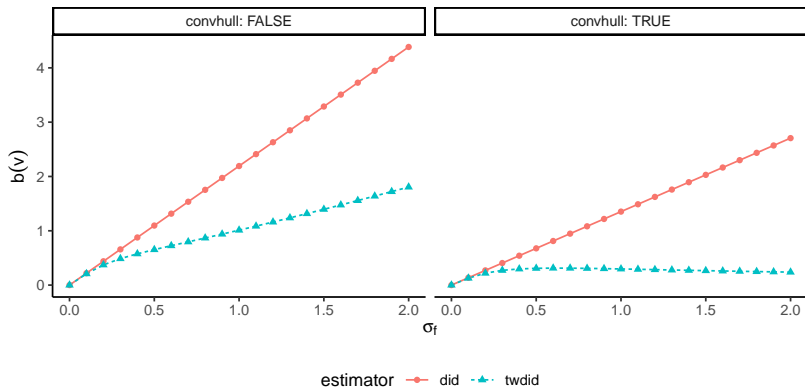
Then

$$\xi_f(\mathbf{v}^*) = \mathbf{F}'_{\text{pre}}(\mathbf{I} + \mathbf{A}_{\text{snr}})^{-1}(\mathbf{v}_0 - \mathbf{v}_\varepsilon)$$

with \mathbf{A}_{snr} measuring the signal-to-noise ratio.

Monte Carlo: Bias

Simulated Magnitude of the Bias

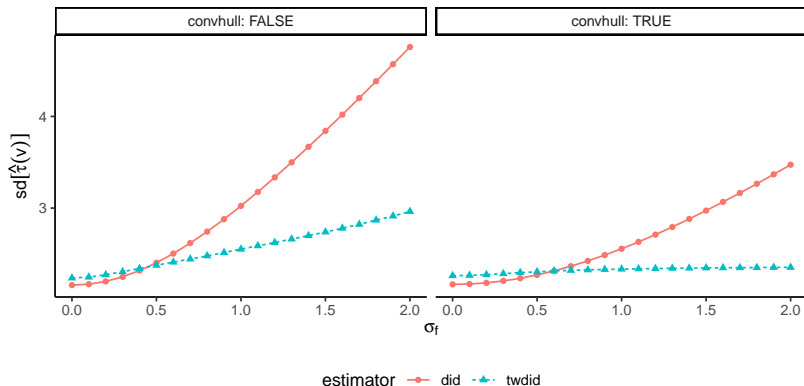


$N = 100, T = 7$

- ▶ DGP: $y_{it} = \sigma_f \lambda_i f_t + \varepsilon_{it}$, $\lambda_i | D_i \sim \mathcal{N}[1 + 0.2D_i, 1]$, $\varepsilon_{it} \sim \mathcal{N}[0, 1]$
- ▶ $f_t \sim \mathcal{N}[0, 1] \forall t$ (left) vs. $f_t \sim \mathcal{N}[0, 1] \forall t \leq T_0$, $f_T \sim \mathcal{TN}[f_{(1)}, f_{(T_0)}]$ (right)

Monte Carlo: Standard Deviation

Simulated Conditional Standard Deviation



N = 100, T = 7

- ▶ DGP: $y_{it} = \sigma_f \lambda_i f_t + \varepsilon_{it}$, $\lambda_i | D_i \sim \mathcal{N}[1 + 0.2D_i, 1]$, $\varepsilon_{it} \sim \mathcal{N}[0, 1]$
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Inference

Asymptotic normality

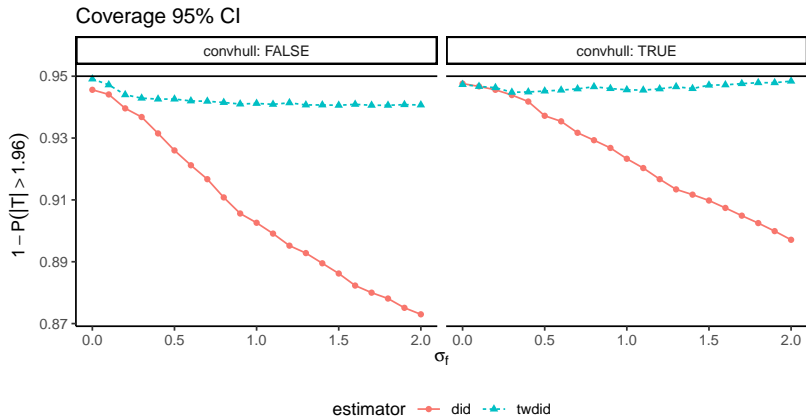
$$\sqrt{N}(\hat{\tau}(\hat{\mathbf{v}}) - \tau - b(\mathbf{v}^*)) \xrightarrow{d} \mathcal{N}[0, V_{\hat{\tau}}]; \quad V_{\hat{\tau}} = \text{var}[\hat{\tau}(\mathbf{v}^*)] + \boldsymbol{\xi}'_{\lambda} \mathbf{F}'_{pre} \boldsymbol{\Sigma}_{\hat{\mathbf{v}}} \mathbf{F}_{pre} \boldsymbol{\xi}_{\lambda}$$

Standard errors accounting for **weight estimation uncertainty**:

$$\hat{V}_{\hat{\tau}} = \hat{V}_{\text{ccm}} + \dot{\Delta}'_{pre} \hat{\Sigma}_{\hat{\mathbf{v}}} \dot{\Delta}_{pre}$$

- ▶ \hat{V}_{ccm} weighted cluster covariance matrix (CCM) estimator
- ▶ $\hat{\Sigma}_{\hat{\mathbf{v}}}$ the estimated time weight covariance matrix
- ▶ $\dot{\Delta}_{pre}$ the demeaned pre-treatment differences in outcomes

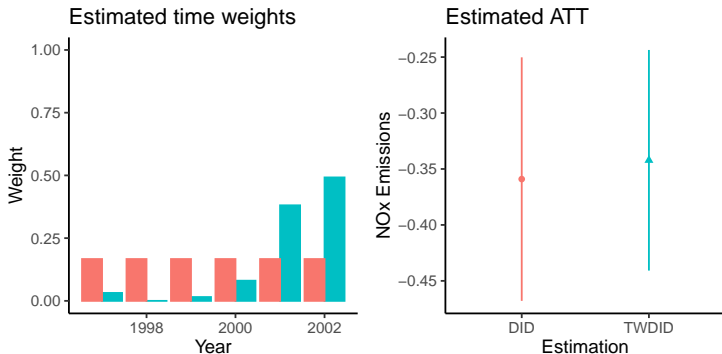
DID vs. TWDID: Coverage of CI



$N = 100, T = 7$

What difference does time weighting make?

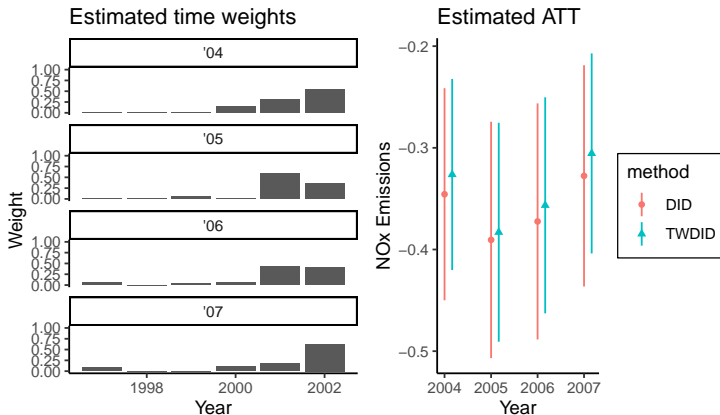
Average ATT



- ▶ 95% confidence interval: $\left[\hat{\tau}(\hat{\mathbf{v}}) \pm 1.96 \sqrt{\hat{V}_{\hat{\tau}}} \right]$
- ▶ TWDID standard error 10% smaller, point estimate similar.

What difference does time weighting make?

Dynamic ATT



Summary

Problem: Diff-in-diff (DID) estimation biased in presence of interactive fixed effects.

Solution: Equip the DID estimator with time weights!

- ▶ Substantial bias and variance reduction
- ▶ Standard errors need to be adjusted for weight estimation uncertainty
- ▶ NOx application: TWDID yields similar point estimates but 10% smaller standard errors

Thank you!

✉ t.d.schenk@uva.nl

🌐 timoschenk.github.io

Time weight estimation

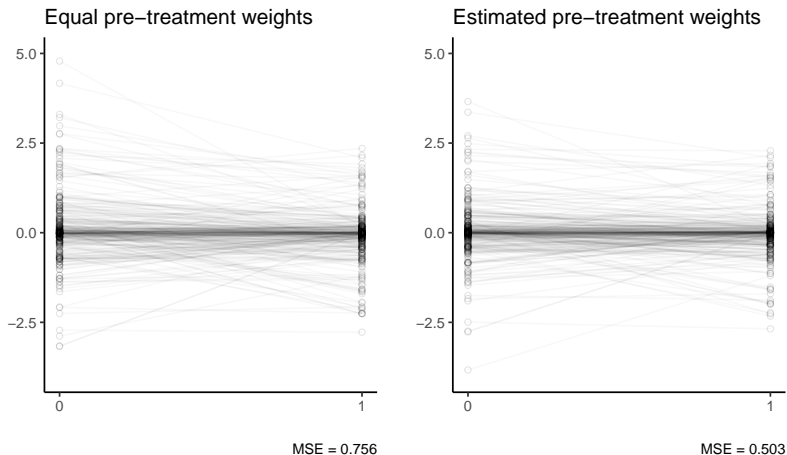
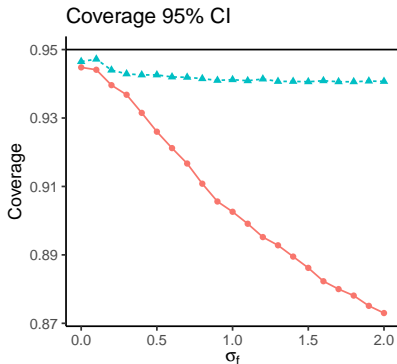


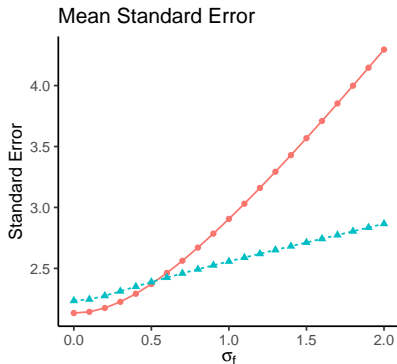
Figure: $\sum_{t \leq T_0} v_t y_{it}$ (0) vs. $\bar{y}_{i,post}$ (1) for control unit $i \in \mathcal{N}_0$. Left: equal weights $v_t = \frac{1}{T_0}$, Right: estimated weights \hat{v}_t .

DID vs. TWDID: Coverage and length of CI



estimator — did — twdid

N = 100, T = 7



estimator — did — twdid

N = 100, T = 7

Average NOx Emissions in NBP and non-NBP States

Winter vs. Summer

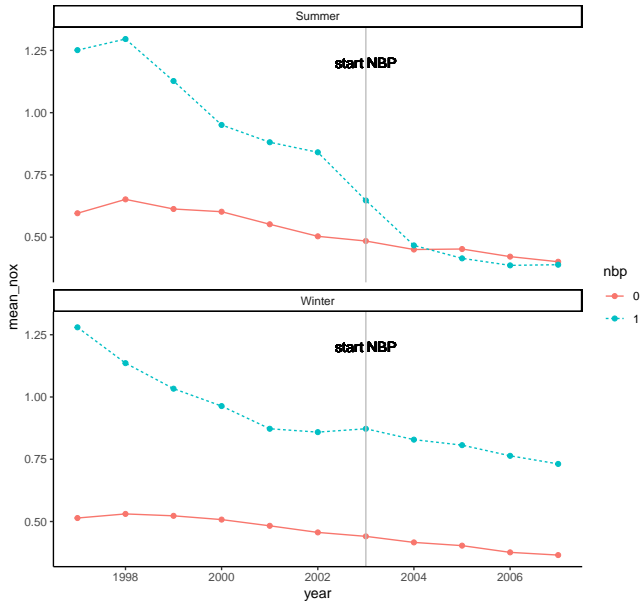
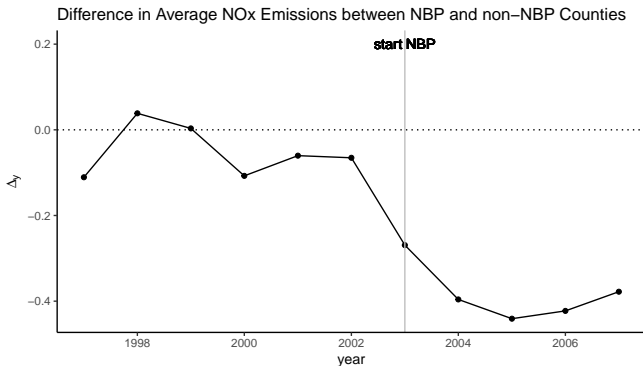


Figure: Deschenes et al. (2017)

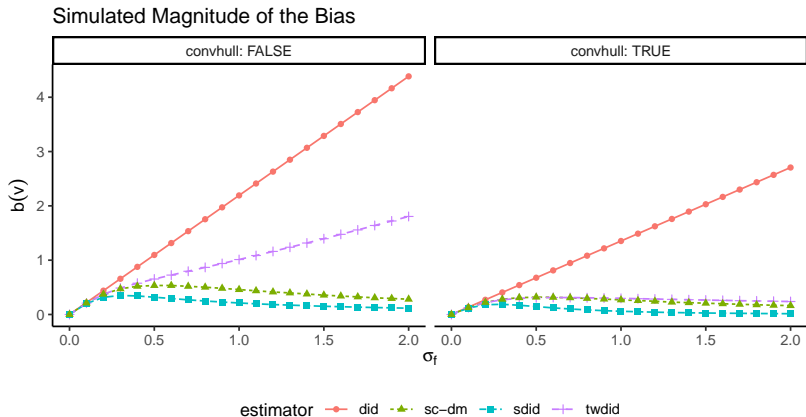
Evidence of the factor structure



$$\Delta_t = \bar{\beta}^{(1)} - \bar{\beta}^{(0)} + \xi'_\lambda \mathbf{f}_t + \tau I(t > T_0) + O_p\left(\frac{1}{\sqrt{N}}\right)$$

with loading imbalance $\xi_\lambda = \bar{\lambda}^{(1)} - \bar{\lambda}^{(0)}$

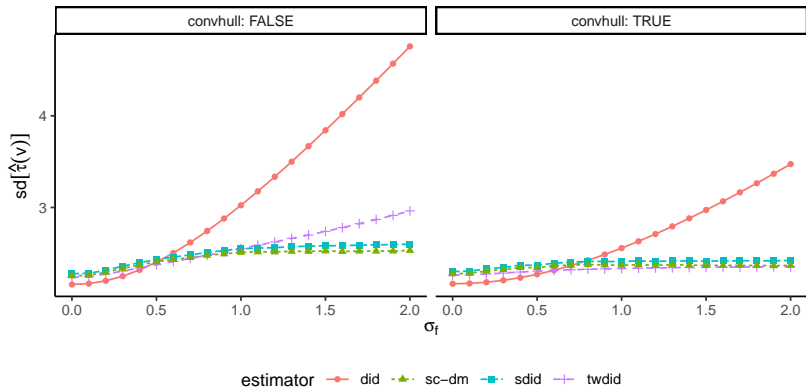
Additional Simulations



$N = 100, T = 7$

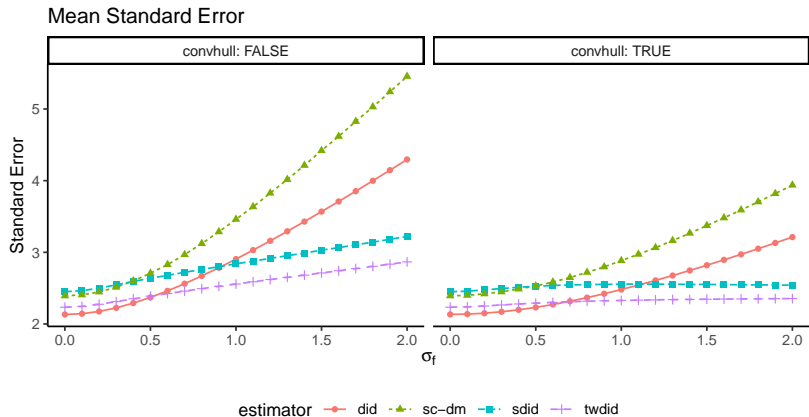
Additional Simulations

Simulated Conditional Standard Deviation



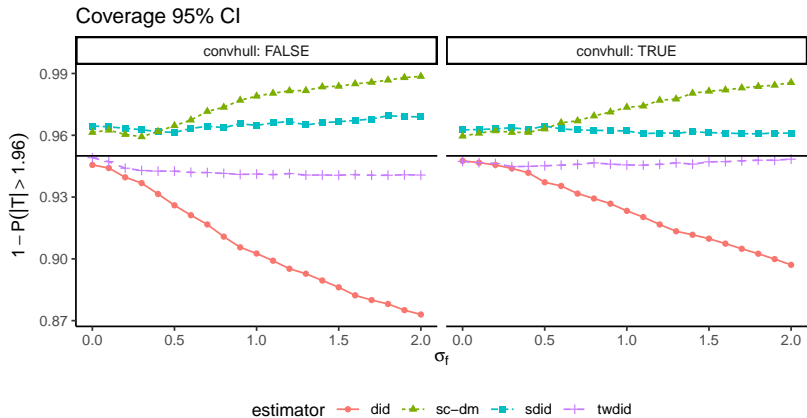
$N = 100, T = 7$

Additional Simulations



$N = 100, T = 7$

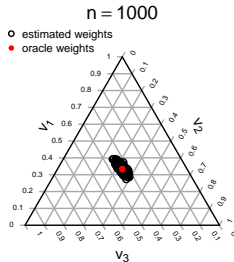
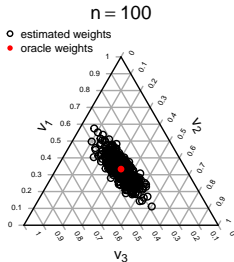
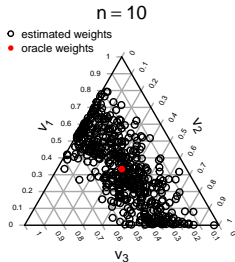
Additional Simulations



$N = 100, T = 7$

Convergence of the time weights

Simulate $\hat{\mathbf{v}}$ with $T_0 = 3$, $\mathbf{v}_0 = (\frac{1}{3}, \frac{1}{3}, \frac{1}{3})'$, $\Sigma_\varepsilon = \sigma_\varepsilon^2 \mathbf{I}_T$.



Difference-in-Differences in Environmental Economics

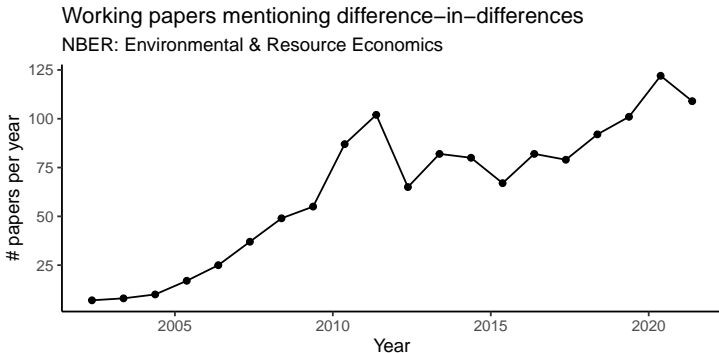


Figure: Papers contain the phrase “difference-in-differences”, manually obtained from <https://www.nber.org/>.