

Notes on the deformation of thick-walled vessels affected by transmural pressure changes

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Abstract: These are supplementary notes to (Ströhle and Petit (2025)), where the flow of incompressible fluids within compliant vessels and its control is investigated. To model this physical system, a law for the fluid-structure interaction needs to be established. Therefore, in these notes, the deformation of thick-walled vessels affected by a change in transmural pressure is investigated. We aim to give more details on this issue.

A thick-walled vessel with cylindrical symmetry is investigated. The vessel has an inner (luminal) radius a and an outer radius b such that the vessels wall has thickness $h = b - a$. Furthermore, the vessel is affected by the luminal and extraluminal pressure P_a and P_b , resp. (see Fig. 1). We aim to find a law that relates the transmural pressure $P = P_a - P_b$ to the luminal cross-sectional area $A = \pi a^2$. For the sake of generality, a thick-walled vessel is considered, but the formula is also valid for thin walls, considered in Ströhle and Petit (2025).

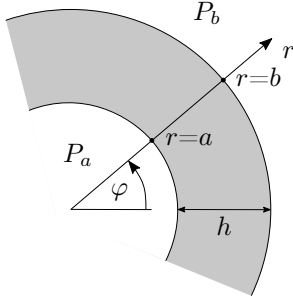


Fig. 1. Illustration of a segment of a circular cross-sectional area of an elastic thick-walled vessel with wall-thickness h , affected by transmural pressure $P = P_a - P_b$.

The static equilibrium conditions in radial direction of an infinitesimal small piece of the vessels wall can be established in polar coordinates r and φ as

$$(\sigma_r + d\sigma_r)(r + dr)d\varphi = d\varphi\sigma_\varphi dr + \sigma_r r d\varphi.$$

When neglecting higher order terms, this condition reduces to the following ordinary differential equation

$$\frac{d\sigma_r}{dr} + \frac{\sigma_r - \sigma_\varphi}{r} = 0. \quad (1)$$

Herein, the radial and circumferential stresses σ_r and σ_φ , resp. has been introduced (see Fig. 2). Due to symmetry, the static equilibrium condition in circumferential direction proves the invariance of σ_φ w.r.t. changes in φ .

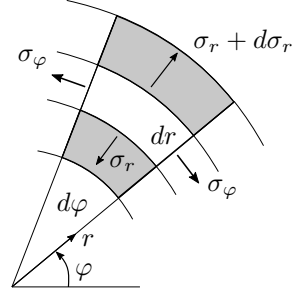


Fig. 2. Infinitesimal piece of a thick-walled vessel affected by radial and circumferential stresses σ_r and σ_φ , respectively.

By assuming material linearity, both stresses σ_r and σ_φ can be related to the deformation of the vessels wall, i.e. to the radial and circumferential strains ε_r and ε_φ , respectively. For the plane stress case the following stress-strain relation can be established

$$\varepsilon_r = \frac{1}{E}(\sigma_r - \nu\sigma_\varphi), \quad \varepsilon_\varphi = \frac{1}{E}(\sigma_\varphi - \nu\sigma_r). \quad (2)$$

Herein the Young's modulus E and the Poisson's ratio ν have been introduced. The radial displacement x is a function of the radial variable r . To link $x(r)$ to the radial and circumferential strains, small deformations are assumed s.t. the following kinematical relations for the strains

$$\varepsilon_r = \frac{x + dx - x}{dr} = \frac{dx}{dr}, \quad \varepsilon_\varphi = \frac{(r + x)d\varphi - r d\varphi}{r d\varphi} = \frac{x}{r} \quad (3)$$

can be established (cf. Fig. 3). The combination of (1) - (3) gives rise to an ordinary differential equation of Cauchy-Euler type, governing the displacement of the vessels wall, i.e.

$$x''(r) + \frac{1}{r}x'(r) - \frac{x}{r^2} = 0, \quad (4)$$

that is solved by the general solution $x = C_1 r + C_2 \frac{1}{r}$.

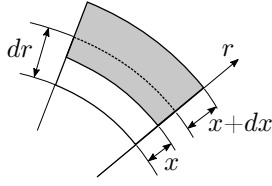


Fig. 3. Radial displacement $x(r)$ of an infinitesimal piece of a thick-walled vessel.

By noticing that $\sigma_r(a) = P_a$ and $\sigma_r(b) = P_b$, the coefficients C_1 and C_2 are determined by static boundary conditions

$$\frac{dx}{dr}(a) = C_1 - C_2 \frac{1}{a^2} = \frac{1}{E}(P_a - \nu \sigma_\varphi(a)) \quad (5)$$

$$\frac{dx}{dr}(b) = C_1 - C_2 \frac{1}{b^2} = \frac{1}{E}(P_b - \nu \sigma_\varphi(b)) \quad (6)$$

as well as geometric boundary conditions

$$x(a) = C_1 a + C_2 \frac{1}{a} = \frac{a}{E}(\sigma_\varphi(a) - \nu P_a) \quad (7)$$

$$x(b) = C_1 b + C_2 \frac{1}{b} = \frac{b}{E}(\sigma_\varphi(b) - \nu P_b) \quad (8)$$

such that

$$C_1 = \frac{(1 + \nu)(1 - 2\nu)P_a a^2 - P_b b^2}{E(b^2 - a^2)} \quad (9)$$

$$C_2 = \frac{(1 + \nu)a^2 b^2 (P_a - P_b)}{E(b^2 - a^2)} \quad (10)$$

can be established. By assuming incompressible material for the tube, i.e. $\nu = \frac{1}{2}$ hence $C_1 = 0$, the displacement of the tube at $r = a$ can be established as

$$x(a) = \frac{3a^2 b^2}{2E(b^2 - a^2)} \frac{P_a - P_b}{a}$$

Introducing the deformed luminal cross-sectional area as $A = \pi(a + x(a))^2$ as well as the initial luminal cross-sectional area $A_0 = a^2 \pi$, the (luminal) pressure P_a can be related to A and A_0 as

$$P_a = \frac{2E}{3} \frac{b^2 - a^2}{b^2} \left(\left(\frac{A}{A_0} \right)^{\frac{1}{2}} - 1 \right) + P_b \quad (11)$$

It is convenient to describe this relation in terms of the ratio $\frac{h}{a}$, where $h = b - a$ indicates the wall thickness. Thus

$$\frac{b^2 - a^2}{b^2} = 2 \frac{h}{a} \phi \quad \text{with} \quad \phi = \frac{1 + \frac{1}{2} \frac{h}{a}}{1 + 2 \frac{h}{a} + \frac{h^2}{a^2}} \quad (12)$$

and (11) can be written as

$$P_a = \phi \frac{4\sqrt{\pi}(Eh)(s)}{3\sqrt{A_0}} \left(\left(\frac{A}{A_0} \right)^{\frac{1}{2}} - 1 \right) + P_b \quad (13)$$

This relation can be rewritten as

$$P_a = \phi \beta(s) f(A) + P_b \quad (14)$$

by introducing

$$f(A) = A^{\frac{1}{2}} - A_0^{\frac{1}{2}}, \quad (15)$$

and

$$\beta(s) = \frac{4\sqrt{\pi}(Eh)(s)}{3A_0}, \quad (16)$$

For the special case of thin-walled vessels $\phi \equiv 1$. For more details on the derivation of the tube-law see e.g. Formaggia et al. (2003), Mynard and Nithiarasu (2008), Parker (2021) and references therein.

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