Question 10: *A*. we stort with our unit circle going CCW and apply trons for mations to get to our desired trajectory: $\langle X, y \rangle = \langle (05t, sint)$ Trons form the rodius so r=2 $\langle X, Y \rangle = \langle 2 \cos t, 2 \sin t \rangle$ Change the direction from CCW to CW $\langle X, Y \rangle = \langle 2 \cos(-t), 2 \sin(-t) \rangle$ = $\langle 2 \cos(t), -2 \sin(t) \rangle$ NOW WE want to Change the Speed with out Changing the trajectory of the curve. We can achieve this by multiplying t by a (on stant &. $r(t) = \langle 2(0s(\lambda t), -2 \sin(\lambda t)) \rangle$ From the problem we wont the speed to be 3 m/s, so we have the following equation: $\left|\frac{d}{dt} r(t)\right| = \left|\left(\frac{d}{dt} 2 \cos(\alpha t)\right) \frac{d}{\alpha t} \left(-2 \sin(\alpha t)\right)\right>$

while it may seem that $\Delta = -\frac{3}{2}$ is a volid solution, this would reverse the direction and make our trajectory ((ord hence is not valid in the Context of this problem making $\Delta = \frac{3}{2}$ our only volid value

putting every thing to gether we get,

$$r(t) = \langle 2\cos(\frac{3}{2}t), -2\sin(\frac{3}{2}t) \rangle$$

B. (we already did this when solving A)

$$\frac{d}{dt} \vec{r}(t) = \left(\frac{d}{dt} \left(2 \cos \left(\frac{3}{2} t \right) \right), \frac{d}{dt} \left(-2 \sin \left(\frac{3}{2} t \right) \right) \right)$$

$$= \left\langle -3\sin\left(\frac{3}{2}t\right), -3\cos\left(\frac{3}{2}t\right) \right\rangle$$

$$\Gamma'(t) = \langle -3 \sin(\frac{3}{2}t) \rangle - 3 \cos(\frac{3}{2}t) \rangle = \langle -2, 2 \rangle$$

$$-3 \sin(\frac{3}{2}t) = -2 d$$

$$-3 \cos\left(\frac{3}{2}t\right) - 2d$$

$$->$$
 -3 Sin $(\frac{3}{2}t)$ -3 $(\frac{3}{2}t)$ -0

$$= > -5in\left(\frac{3}{2}t\right) = \cos\left(\frac{3}{2}t\right)$$

$$\frac{Sin(\frac{3}{2}t)}{COS(\frac{3}{2}t)} = -1$$

$$=>$$
 $tan(\frac{3}{2}t)=-1$

$$=>\frac{3}{2}t=ta^{-1}(-1)$$

$$-$$
 > $t = -\frac{1}{6}\pi$

Question 11:

There are multiple ways of doing this: we could eliminate
the parameter, t, and just graph x in terms of x (just need
to be corretal of domain restrictions) or we could construct
o toble of values.

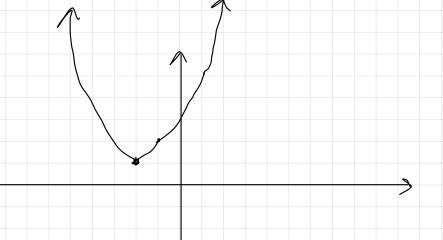
There are't any domain restrictions here so we will eliminate t

$$(x, y) = (t-2, t^2+1)$$

$$=>$$
 $X=t-2$ $Y=t^2+1$

$$\frac{t}{-} > \frac{t^2 + 1}{4}$$

$$=> y - (x+2)^2 + 1$$



Β. $r(t) = \langle t^{-2}, t^2 + 1 \rangle$ $r'(t) = \left(\int_{t}^{d} (t^{-2}), \int_{t}^{d} (t^{2}+1) \right) = \left(1, 2t \right)$ $r(1) = \langle -1, 2 \rangle$ r'(1) = < 1,2> Green vector is r(1) Blue vector is r(2) I copied the blue vector twice but here you can see r'(1) is tongent to the curve at t=1

Question 12:



Let L(t) be the position vector of time to and let & be the time Indy jumps off the cart

 $\vec{L}(t) = \vec{r}(\alpha) + \frac{d}{dt}\vec{r}(\alpha) \cdot (t - \alpha)$

If may seem confusing that we have 2 times here.

Just remember that disa constant and tis

the independent variable. Soon this will reduce to

a system of equations

 $L^{-1}(t) = \langle 2+2, \alpha^3-4 \rangle + \langle 1, 3\alpha^2-1 \rangle (t-\alpha)$ for some t $L^{-1}(t) = (5, -3)$. Hence, $\langle 5, -3 \rangle - \langle 2+2, \alpha^3-4 \rangle + \langle 1, 3\alpha^2-1 \rangle (t-\alpha)$

$$5=2+d+1(t-d)=2+b$$
 $7=3=d^3-d+(t-d)(3d^2-1)$
 $=>t=3$ (we substitute this value into this equation)

 $-3=d^3-d+(3-d)(3d^2-1)$
 $=>-3=d^3-d+(3-d)(3d^2-1)$
 $=>-3=d^3-d+4d^2$
 $=d^2(-2d+4)$
 $=>d=0$ or $4/2$

As all solutions, lets test each point to see if they are logical in the context of the problem $d=0$, $b=3$ makes sense since Indy lets go of time $=0$ and gets the villian $=0$ seconds later $=0$, $=0$, $=0$ doesn't make sense since the villian at time $=0$ and reaches the villian at time $=0$.

Go of time $=0$, $=0$