

# Joonkyu Min

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## Research Interest

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My goal is to build safe and reliable AI agent that can interact with the real world.

I believe that safety is the key component for practical tasks of robots. Safety guarantees would also enable easier and scalable real world data collection and training, enabling more robust deployment!

## Education

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KAIST, MS in Kim Jaechul School of Artificial Intelligence	Mar 2026 –
Seoul National University, BS in Electrical and Computer Engineering	Mar 2020 – Feb 2026

## Experience

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Research Intern, CLVR lab	June 2025 – Current
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- Working on robot learning with Prof. Joseph J. Lim

Research Intern, SNU VGI lab	June 2024 – Mar 2025
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- Worked on 3D gaussian splatting for feature field with Prof. Jaesik Park

Duty of National Defense, Auxiliary Police	May 2021 – Nov 2022
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## Publications

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### CF3: Compact and Fast Feature Field

- Hyunjoon Lee, Joonkyu Min, Jaesik Park
- *Int. Conf. on Computer Vision (ICCV)*, 2025
- Proposed an approach for constructing a compact 3D feature representation from given 3D Gaussian Splatting

## Projects

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### Can Zero-shot RL enable test time safety?

- Course Project on Robot Learning at SNU
- Explored the potential of zero-shot RL method to enable safe decision making. Extended FB representations with safety constraints, enabling test-time adaptation to both rewards and costs without retraining.

### KL-regularized FB representation for offline zero-shot RL

- Undergraduate Project with Prof. Insoon Yang
- Applied KL-divergence regularization approach to zero shot RL method

### Gaussian Splatting in the Dark

- Course project of 3D Computer Vision at SNU
- Learn robust gaussian splatting to render realistic novel views from dark and blurry scenes by initializing gaussians based on dense point tracking method instead of keypoint matching

### SNU Autonomous Driving Student Club (ZERO)

- Worked on synthetic generating domain randomization data for autonomous vehicles with gazebo

## Skills

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**Languages:** Korean: Native, English: TOEFL 102 (test date: 03/2024)

**Technologies:** C/C++, Python, Pytorch, CUDA