Final: Nov 18, 2:30 –4:45. Note the time!

## Mid-term Stuff

- 1. There will be **no MatLab** coding
- 2. Material from this part of course is covered in the text.
- 3. The exam will be *closed book* and *no notes* will be allowed
  - i. I will provide a *sheet with formulae*
- 4. You will be asked to solve numerical problems by *hand*.
  - i. Please use a calculator, not your phone.
- 5. There may be interpretation or conceptual problems
  - For example, why does a particular numerical method fail and why does it fail
- 6. You may be asked to apply a particular numerical technique graphically.
- 7. There may be some derivations, but they will not be too involved.
- 8. You may be asked to explain the advantage/disadvantage of one numerical technique over another.
- 9. Make sure you can apply numerical methods by hand.

#### Since Mid Term

#### 1. PDEs

$$A\frac{\partial^2 u}{\partial x^2} + B\frac{\partial^2 u}{\partial x \partial t} + C\frac{\partial^2 u}{\partial t^2} + D\left(x, t, u, \frac{\partial u}{\partial x}, \frac{\partial u}{\partial t}\right) = 0$$

The functions A,B,C, can be used to characterize some types of PDEs

- If  $B^2(x_o, t_o) 4A(x_o, t_o)C(x_o, t_o) > 0$  for all **x**,**t** the equation is called *hyperbolic*
- If  $B^2(x_o,t_o)-4A(x_o,t_o)C(x_o,t_o)=0$  for all **x**,**t** the equation is called *parabolic*
- If  $B^2(x_o, t_o) 4A(x_o, t_o)C(x_o, t_o) < 0$  for all x,t the equation is called *elliptic*.

Notation: 
$$\frac{\partial u}{\partial x} = u_x$$
;  $\frac{\partial^2 u}{\partial x^2} = u_{xx}$ ;  $\frac{\partial^2 u}{\partial x \partial t} = u_{xt}$ .

## 2. Finite Differences

$$u_t \equiv u_i^j \approx \frac{u_i^{j+1} - u_i^j}{\Delta t}$$
$$u_{xx} \approx \frac{u_i^{j+1} - 2u_i^j + u_i^{j-1}}{h_x^2}$$

Example: Set up a finite difference scheme for the 1-D heat equation:

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{c^2} \frac{\partial u}{\partial t}; \qquad u(0,t) = 0 \qquad u(L,t) = 100$$
$$u_t(x,0) = g(x)$$

You have to apply both boundary and initial conditions correctly.

Make sure you fully understand the notation so you can implement algorithm

3. *Implicit Schemes*. These solve for *all* the points simultaneously. Eventually you must solve *tri-diagonal* system of equations.

### Stuff since mid-term

#### 4. Fourier Series.

$$f(x) = a_o(1) + \sum_n a_n \cos(nx) + \sum_m b_m \sin(mx)$$

$$\int_{-\pi}^{\pi} \cos(nt) \cos(mt) = \begin{cases} \pi \delta_{m,n}, & m \neq n \\ 2\pi, & m = n = 0 \end{cases}$$

$$\int_{-\pi}^{\pi} \cos(nt) \sin(mt) = 0$$

$$\int_{-\pi}^{\pi} \sin(nt) \sin(mt) = \begin{cases} 1 & n = m \neq 0 \\ 0 & n \neq m \end{cases}$$

$$a_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(t) \cos nt dt$$

$$b_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(t) \sin nt dt$$

Function must be periodic on  $-\pi$  to  $\pi$ . How would you change expressions for a function that is periodic on -T to T

## 5. Fourier Transform.

When dealing with *non-periodic*, or functions over infinite extant, we move to *Fourier Transform* 

**Inverse Fourier Transform** 

$$f(t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(\omega) e^{i\omega t} d\omega \tag{1}$$

$$g(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(t)e^{-i\omega t}dt$$
 (2)

**Fourier Transform** 

## 6. Discrete Fourier Transform

- 1. In physical applications, the underlying function is only sampled
  - i. No instrument has *infinite resolution*
  - ii. No experiment has *infinite time to run*

#### Discrete Fourier Transform

$$g(n\Delta\omega) = \sum_{0}^{N-1} f(m\Delta t)e^{-in\Delta\omega m\Delta t} = \sum_{0}^{N-1} f(m\Delta t)e^{-i2\pi mn/N}$$

Inverse Discrete Fourier Transform

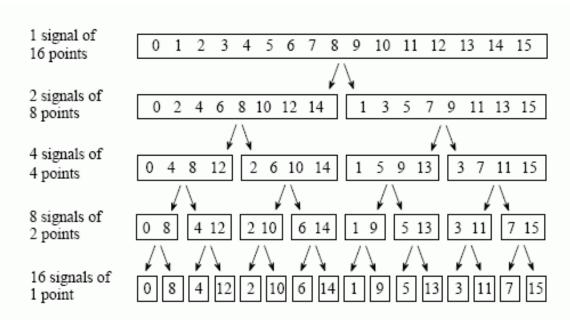
$$f(m\Delta t) = \frac{1}{N} \sum_{n=0}^{N-1} g(n\Delta\omega) e^{i2\pi mn/N}$$

Make sure you fully understand the notation so you can apply it.

Example. Find the discrete Fourier transform for the data vector  $A = (1 \ 2 \ 3 \ 4)$  Assume the data is evenly sampled once every second.

Answer: 
$$g(0) = 10$$
;  $g(1) = -2 + 2i$ ;  $g(2) = -2$ ;  $g(3) = -2 - 2i$ 

## 7. Fast Fourier Transform.



#### FIGURE 12-2

The FFT decomposition. An N point signal is decomposed into N signals each containing a single point. Each stage uses an *interlace decomposition*, separating the even and odd numbered samples.

$$g(n\Delta\omega) = \sum_{0}^{N-1} f(m\Delta t)e^{-in\Delta\omega m\Delta t} = \sum_{0}^{N-1} f(m\Delta t)e^{-i2\pi mn/N}$$
$$g(n\Delta\omega) = g_{even}(n\Delta\omega) + e^{-i2\pi n/N}g_{odd}(n\Delta\omega).$$

Understand how/why only first N/2 terms correspond to positive frequencies, the latter half of the terms correspond to negative frequencies.

# Detailed example, N = 4

$$g(n\Delta\omega) = \sum_{j=0}^{N/2-1} f(2j\Delta t)e^{-i2\pi jn/(N/2)} + W_N^n \sum_{j=0}^{N/2-1} f((2j+1)\Delta t)e^{-i2\pi jn/(N/2)}$$

$$E = EE + E0 \qquad O = OE + OO.$$

$$EE = \sum_{j=0}^{N/(2\cdot2)-1} f(2(2j\Delta t))e^{-i2\pi(2j)n/(N/2)} \qquad OE = W_N^n \sum_{j=0}^{N/(2\cdot2)-1} f((2(2j)+1)\Delta t)e^{\frac{-i2\pi(2j)n}{(N/2)}}$$

$$= \sum_{j=0}^{N/(2\cdot2)-1} f(2(2j+1)\Delta t)e^{\frac{-i2\pi jn}{(N/2)}}$$

$$= V_N^{N/(2\cdot2)-1} \int_{j=0}^{N/(2\cdot2)-1} f((2(2j+1)\Delta t)e^{\frac{-i2\pi jn}{(N/2)}}$$

$$= W_N^n \sum_{j=0}^{N/(2\cdot2)-1} f((2(2j+1)\Delta t)e^{\frac{-i2\pi jn}{(N/2)}}$$

$$= W_N^{N/(2\cdot2)-1} \int_{j=0}^{N/(2\cdot2)-1} f((2(2j+2)+1)\Delta t)e^{\frac{-i2\pi jn}{(N/2)}}$$

$$g(n\Delta\omega) = f(0\Delta t) + W_2^n f(2\Delta t) + W_4^n f(1\Delta t) + W_4^n W_2^n f(3\Delta t). \quad W_N^n = e^{-i2\pi n/N}$$

Find the Fast Fourier transform for f(0) = 0; f(1) = 1; f(2) = 4; f(3) = 9

Answer: 14; -4.0 + 8.0 i; -6.0; -4.0 - 8.0 i

#### 8. Convolution and Correlation

Convolution:

$$\mathcal{F}(p) = \frac{\mathcal{F}(p \otimes q)}{\mathcal{F}(q)}$$

or that

$$p(t) = \mathcal{F}^{-1}\left(\frac{\mathcal{F}(p\otimes q)}{\mathcal{F}(q)}\right)$$

Correlation

$$p \odot p = s \odot s + n \odot n = s \odot s + |\langle n(t) \rangle|^2$$
.

## 9. Spectrum Analysis

Energy of each frequency = Fourier coefficient squared

Example. Find the spectrum of data f(0) = 0; f(1) = 1; f(2) = 4; f(3) = 9

Write the second order ODE as 2 coupled first order and use Runge-Kutta to solve.

$$\frac{d^2y}{dt^2} - 3\frac{dy}{dt} - 6 = 0$$

$$f_o = f(t_o, y_o)$$

$$f_1 = f(t_o + \frac{h}{2}, y_o + \frac{h}{2}f_o)$$

$$f_2 = f(t_o + \frac{h}{2}, y_o + \frac{h}{2}f_1)$$

$$f_3 = f(t_o + h, y_o + f_2)$$

$$y_{i+1} = y_i + \frac{h}{6}(f_o + 2f_1 + 2f_2 + f_3)$$

$$S = \begin{pmatrix} y \\ v \end{pmatrix}$$

$$\frac{dy}{dt} = v$$

$$\frac{dv}{dt} = 3v + 6$$

$$S = \begin{pmatrix} y \\ v \end{pmatrix}$$

$$F = \begin{pmatrix} v \\ 3v + 6 \end{pmatrix}$$

$$\frac{dS}{dt} = F$$