

Exploration 3

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Part 1 : Using the parameters of the Low Threshold Spiking (LTS) Izhikevich model ($a=0.02$, $b=0.25$, $c=-65.0$, $d=2$) <http://www.izhikevich.org/publications/spikes.htm>, develop a model of three neurons. All three neurons should have their own controllable input currents. You can use three different TimedArrays or manage the currents through a series of run commands. Use the basic alpha conductance ,g, to connect the neurons with the equations

$$g = dg/dt = g/\tau_{syn} + z(t)$$

$$z = dz/dt = z/\tau_{syn} + g_{syn}u(t)$$

Modify the code LIFwSynSimp.py where all the neurons are in a single group to complete the following.

1. Connect neuron 0 to neuron 1 and neuron 1 to neuron 2 with excitatory connections with a synaptic time constant of 5ms and a reversal potential of 0. Establish a steady state with no input current to any neurons for 200 ms. Apply a suprathreshold stimulus for 20ms neuron 0. Show how the response changes in neurons 1 and 2 as you change g_{peak} from 0.01 to 0.08.

Answer:

The color of neuron 0, 1 ,2 are green, red and blue. And the first curve of each neuron is the curve of v, and the second curve is the curve of g(The conductance represents the ion current caused by post-synaptic spikes.).

As the g_{peak} increases, the post-synaptic spikes become more dense, due to increasing synaptic current caused by growing conductance of alpha synapse equation.

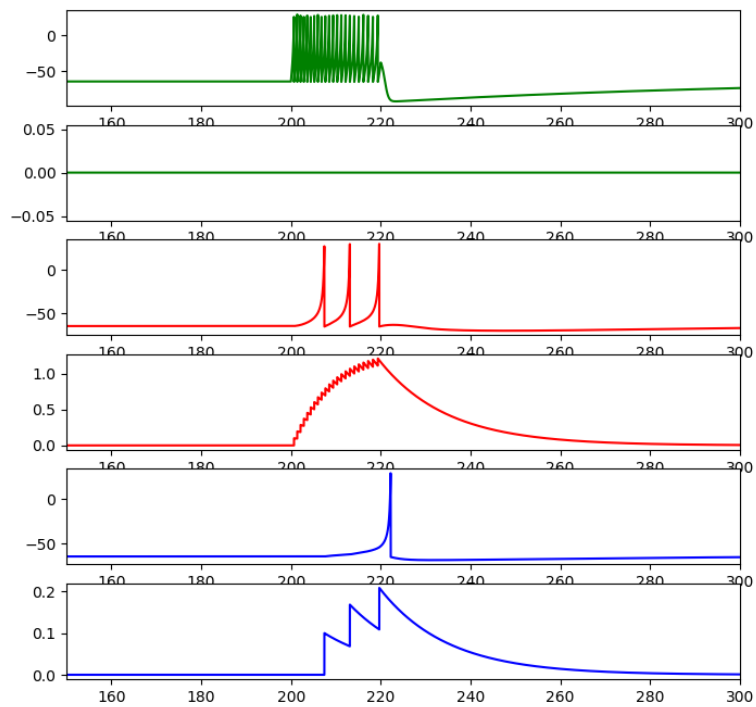


Figure 1: Result $g_{peak} = 0.01$

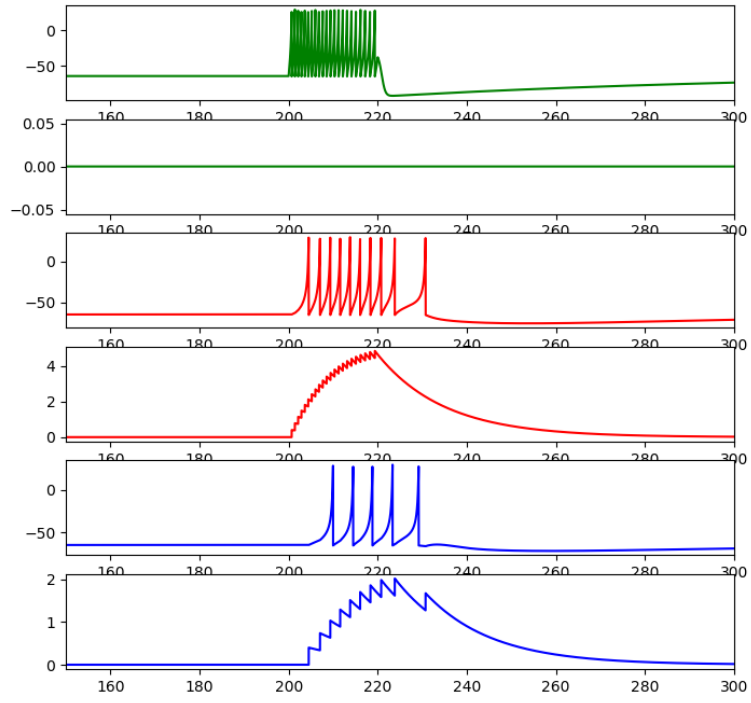


Figure 2: Result $g_{peak} = 0.04$

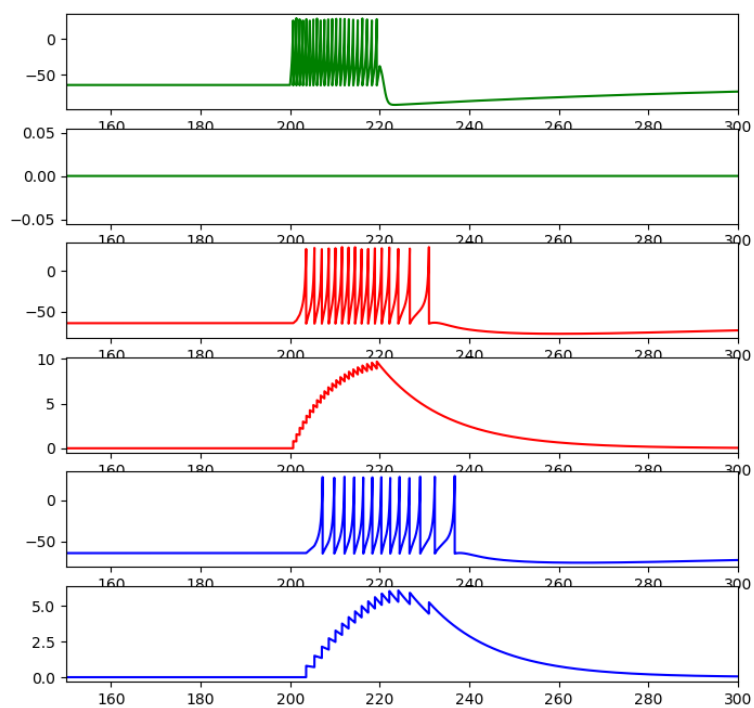


Figure 3: Result $g_{peak} = 0.08$

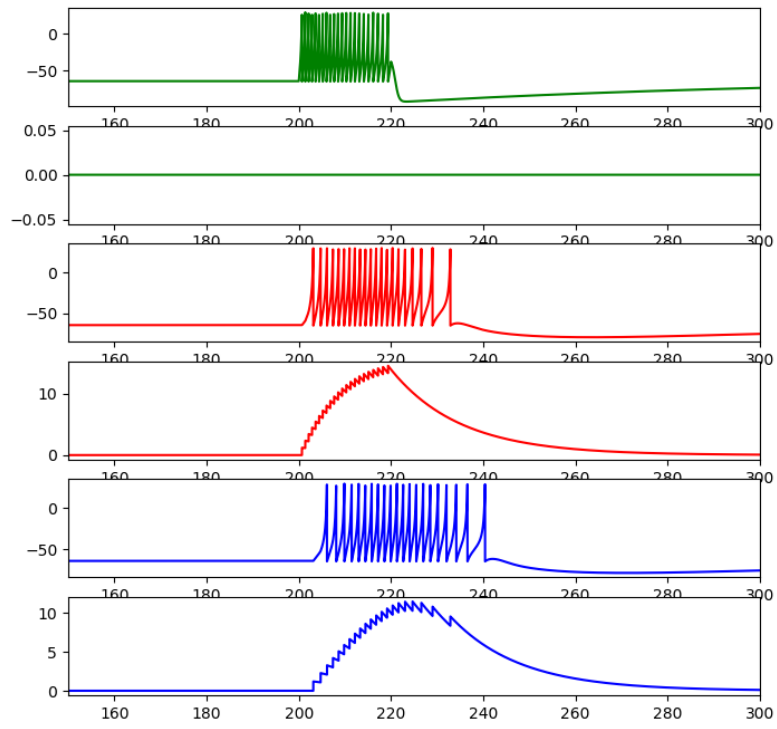


Figure 4: Result $g_{peak} = 0.12$

2. Incorporate synaptic delays to the case above of 5ms. How does the response change?

Answer:

The conductance and voltage response of neuron 1 and 2 will be delayed. The response of neuron 2 will be delayed twice as much as delay time.

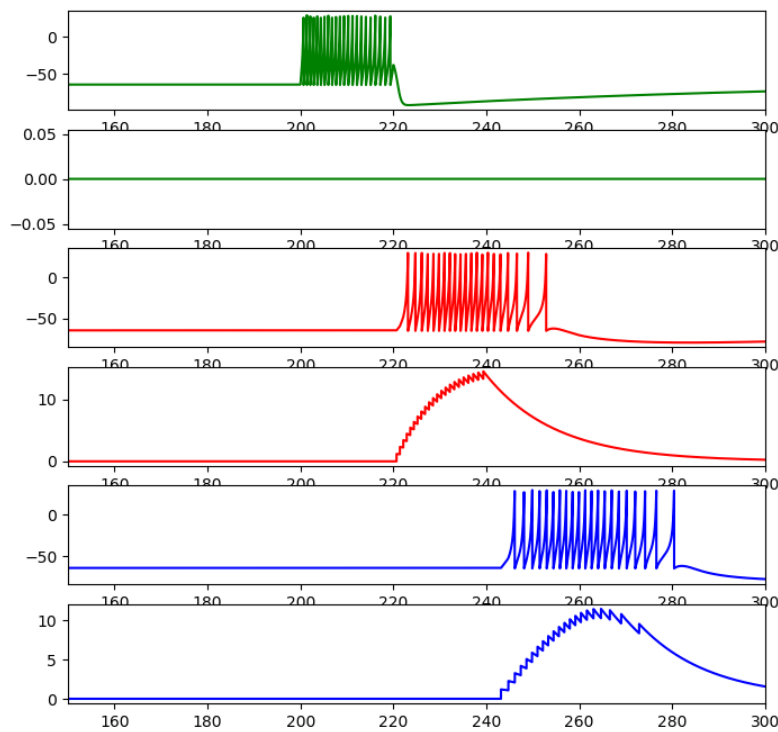


Figure 5: Result $delaytime = 20ms$

3. Connect neuron 0 to neuron 1 with inhibitory connections with a synaptic time constant of 5ms and a reversal potential of -80. Do not connect any cell to neuron 2. Reach steady state at 200ms with no stimulus and apply the same suprathreshold input currents to each cell. Here neuron 0 and 2 should generate the same response. What happens to neuron 1 as g_{peak} is varied from 0.02 to 0.12

Answer:

The voltage response of neuron 1 will be inhibited by the synaptic current. As the g_{peak} increases, the influence becomes more obvious due to higher inhibitory synaptic current. And the spikes of neuron 1 becomes more sparse as the g_{peak} grows.

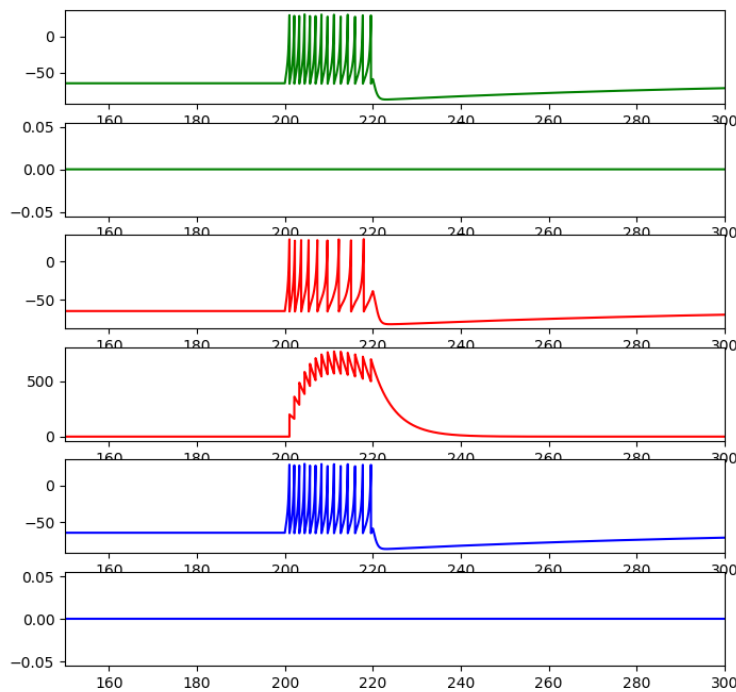


Figure 6: Result $g_{peak} = 0.02$

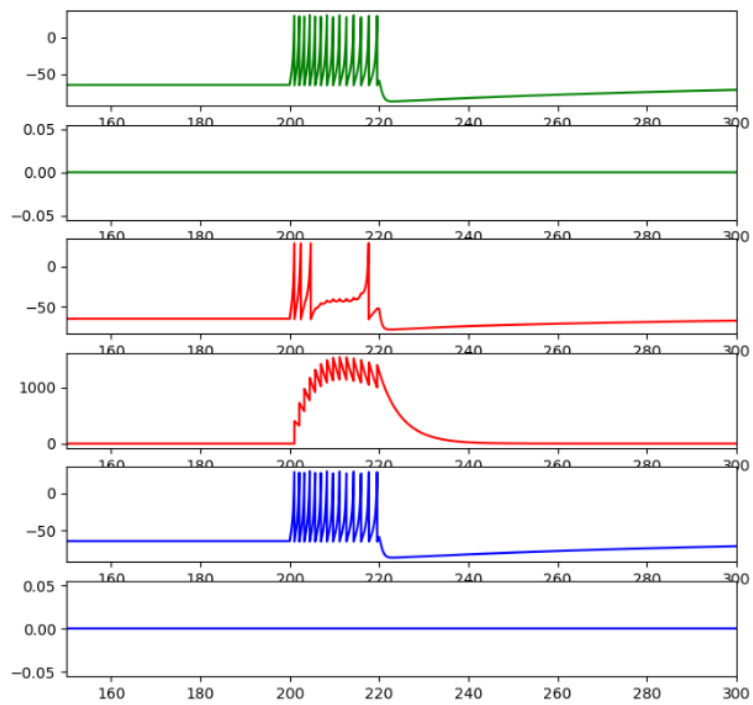


Figure 7: Result $g_{peak} = 0.04$

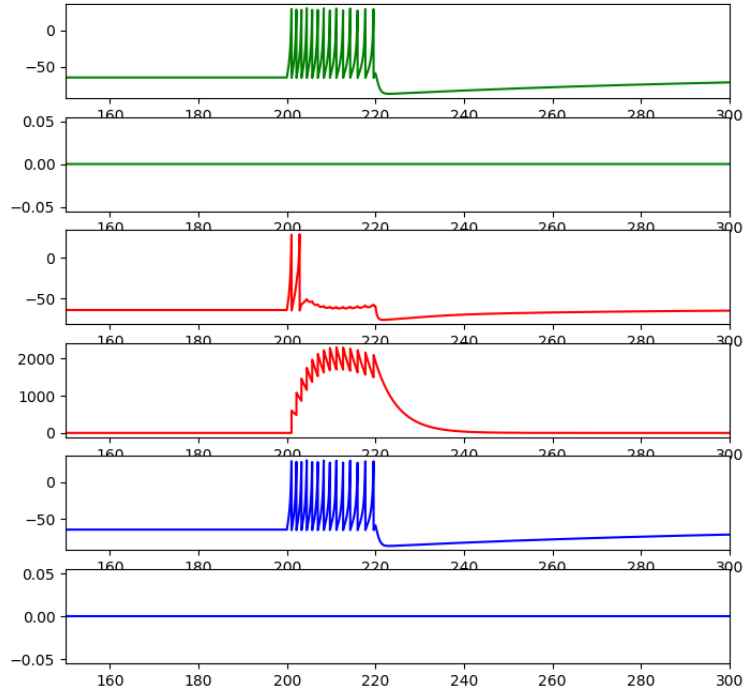


Figure 8: Result $g_{peak} = 0.06$

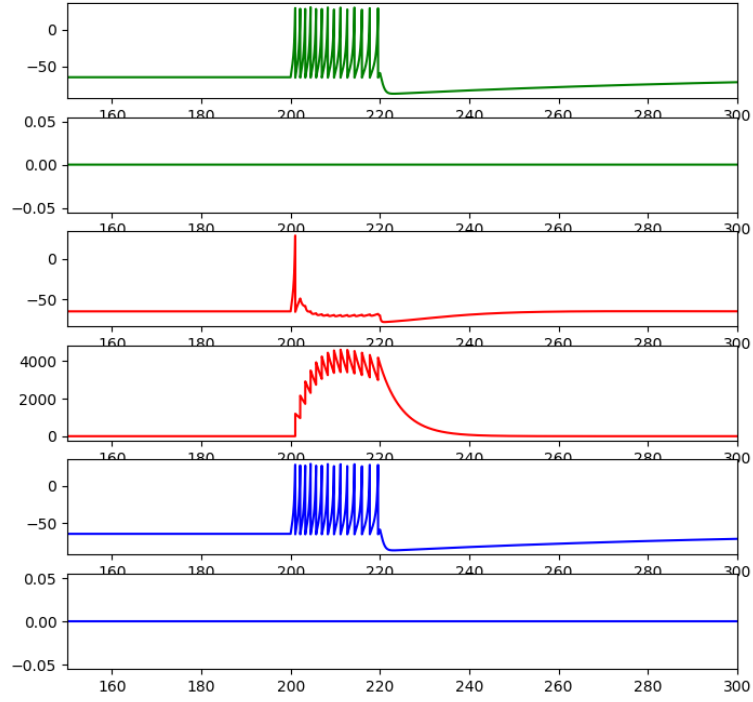


Figure 9: Result $g_{peak} = 0.12$

4. Incorporate synaptic delays to the case above of 5ms. How does the response change?

Answer:

The inhibitory impact on neuron 1 will be delayed due to the delay of synaptic current.

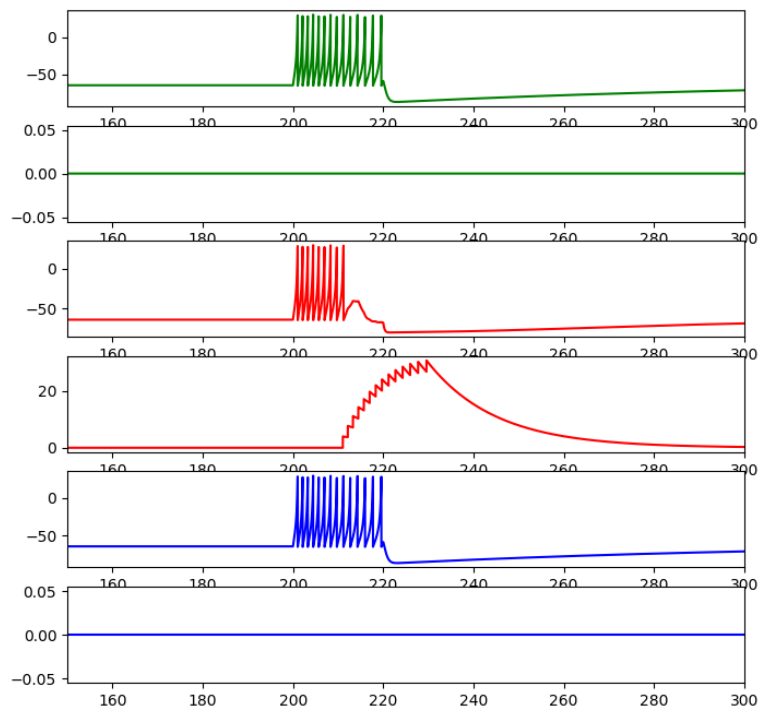


Figure 10: Result $delaytime = 10ms$

5. Design several interesting circuits using excitatory AND inhibitory connections with 4 neurons. Note that one cell type should be able to produce only one type of synapse (inhibitory or excitatory) but a cell can receive both types. Explain the output based on your design.

Answer:

The connection of neuron 0 and 1 is excitatory. The connection of neuron 1 and 2 is inhibitory. The connection of neuron 2 and 3 is excitatory.

Now I apply the suprathreshold current on neuron 0 and neuron 2. The outcome is that the spikes of neuron 2 will be inhibited by the influence of neuron 0 and 1, thus inhibiting the spikes of neuron 3.

And then I cancel the current on neuron 0. Neuron 2 can generate spikes without obstacle to stimulate neuron 3.

And I find the interesting phenomenon that there is a spike after the inhibitory influence. I think it is because low 'v' causes low 'u' according to $du/dt = a(bv - u)$. Thus in this situation, the neuron is easy to fire.

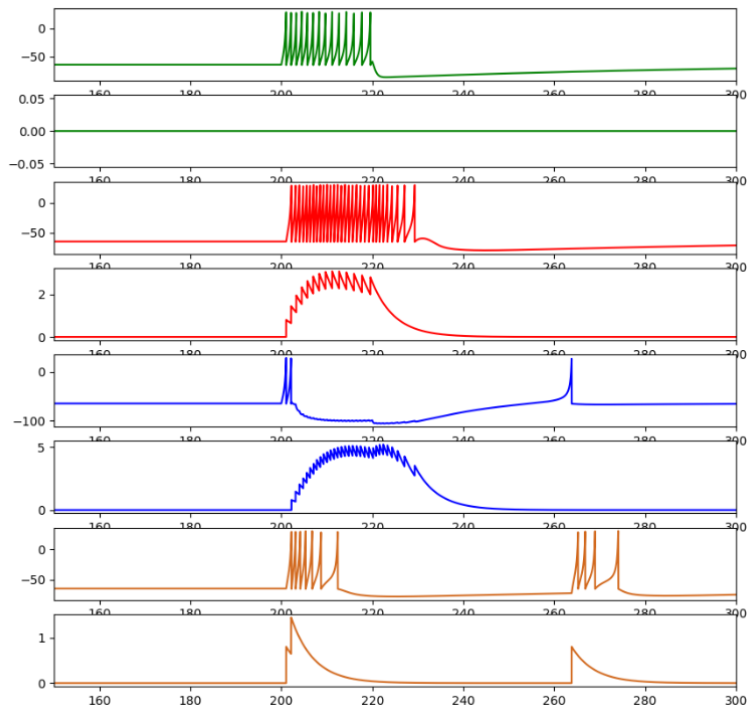


Figure 11: Apply current to neuron 0 and 2

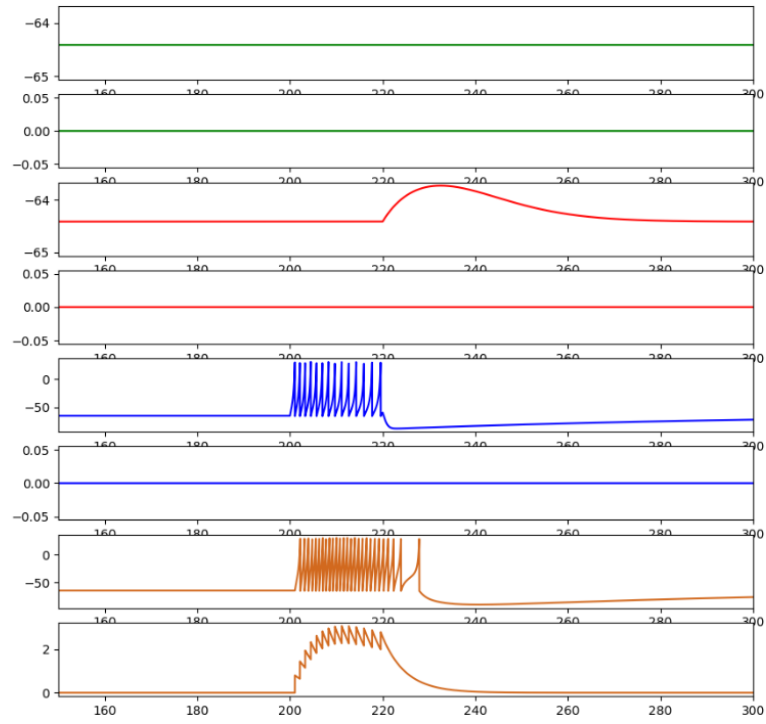


Figure 12: Apply current just to neuron 2

Part 2

Use the framework of synaptic connections to form a network of 4 neurons to actuate the bug as a coward. Modify LIFwSynSimp to have 4 different groups with 1 neuron in each group. Find synaptic conductances that give you a large dynamic range.

Answer:

The value of synaptic conductance will have impact on the post-synaptic spikes. As the synaptic conductance increases, the post-synaptic spikes become more dense. However, when the conductance is excessively high like 0.2, the membrane potential of post-synaptic will keep depolarization and there are no spikes during this time.

When the synaptic conductance is about 0.12, it will have the large dynamic range as shown in figure.

What is more, The meaning of the parameters I find is that the magnitude of velocity is directly dependent on the parameter η . τ_{motor} can control the decay rate of the velocity.

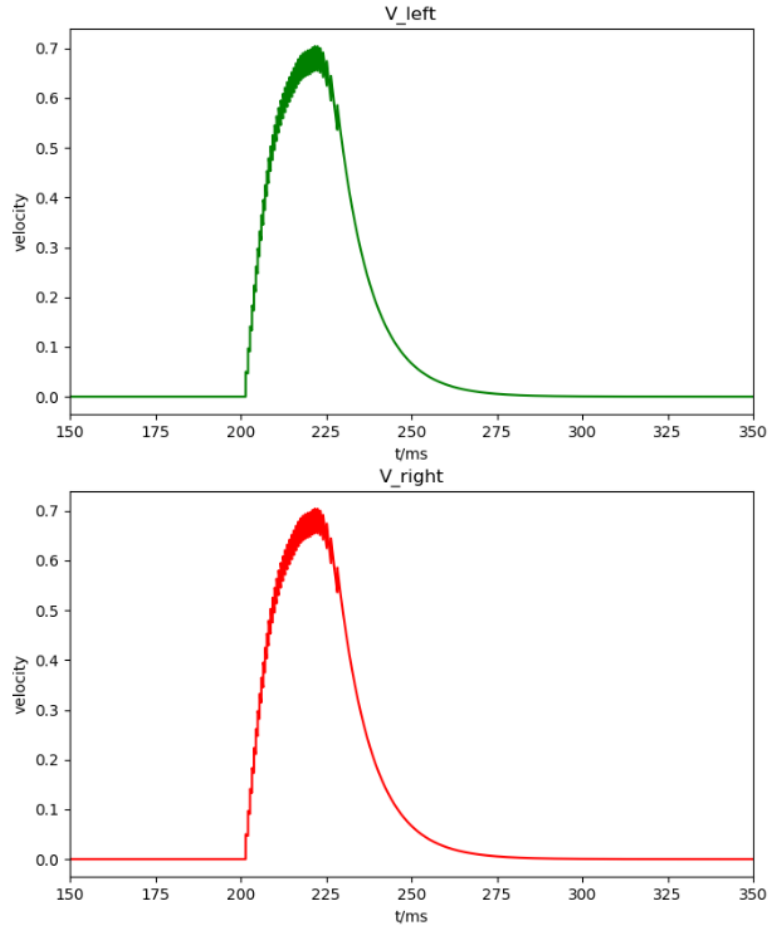


Figure 13: The large dynamic range of velocity when $g_{peak} = 0.12$

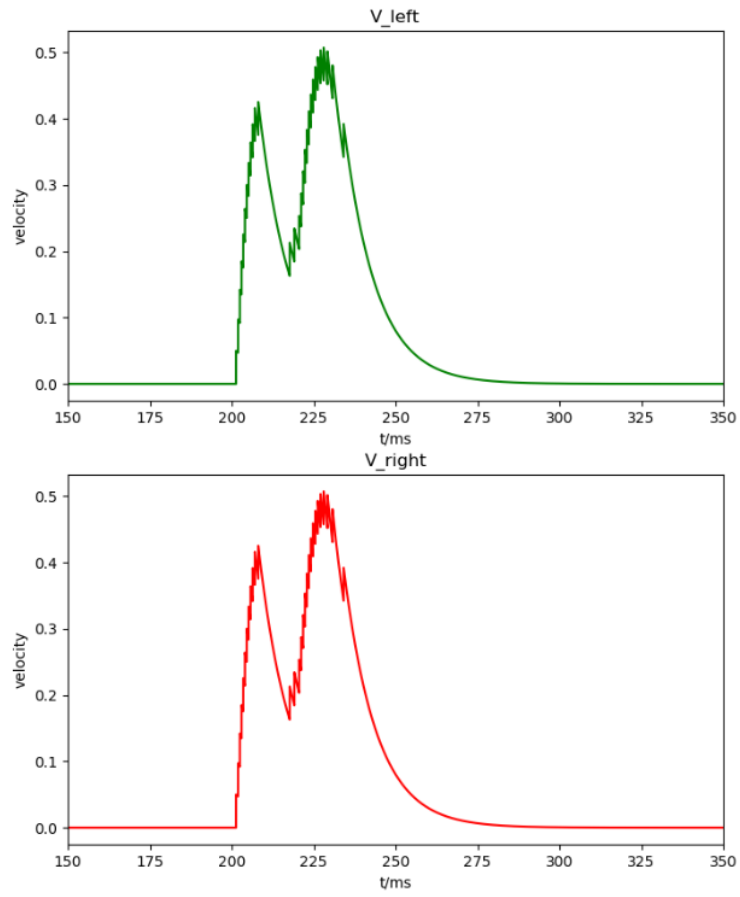


Figure 14: $g_{peak} = 0.2$

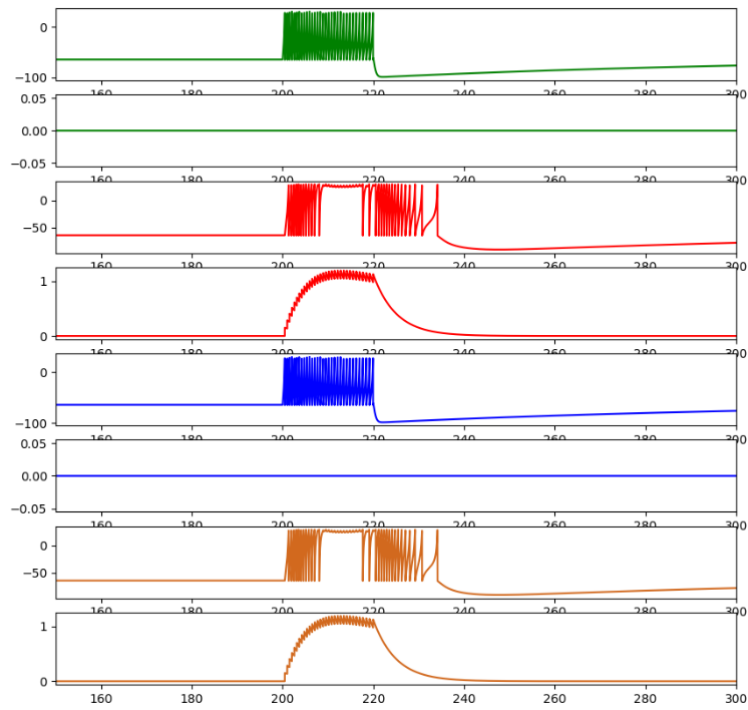


Figure 15: The membrane potential of neuron and post-synaptic conductance when $g_{peak} = 0.2$

Appendix

Part1 problem 1 & problem 2

```
from brian2 import *
defaultclock.dt=.01*ms
num_neurons = 2
duration = 2*second

# Parameters
area = 20000*umetre**2
Cm = 1*ufarad*cm**-2
El = -60*mV
gl = 0.7*msiemens/cm**2

tau_ampa=0.3*ms
g_synpk= 120 * siemens
g_synmaxval=(g_synpk)
E_syn = 0*mV
tau_m = 15*ms
# Parameters for LTS model
a = 0.02
b = 0.25
c = -65*mV
d = 2.0 * mV
R = 1*ohm
v0 = -65*mV
u0 = 4*mV

#The model
eqs_fv = '''
fv = 0.04*v**2 / mV + 5*v + 140*mV : volt
'''

eqs_u = '''
du/dt = a*(b*v - u) * metre ** 2 * kilogram * second ** -4 * amp
      ** -1 /mV: volt
'''

eqs = '''
dv/dt = ((fv - u + R*I)* metre ** 2 * kilogram * second ** -4 *
```

```

        amp ** -1 /mV) + (g*(E_syn-v)*metre ** 2 * kilogram * second **
        -4 * amp ** -1/amp) : volt
I : amp
'''

eqs_syn = '''
# The conductance of the alpha model
dz/dt = (-z/tau_m) : siemens
dg/dt = -g/tau_m + z/ms : siemens
'''

eqs += eqs_fv + eqs_u + eqs_syn
# Threshold and refractoriness are only used for spike counting
neuron1 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler',
                      refractory='v > 0*mV')
neuron2 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler',
                      refractory='v > 0*mV'
                      )
neuron3 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler',
                      refractory='v > 0*mV'
                      )

syn1 = Synapses(neuron1, neuron2, clock=neuron1.clock, on_pre=''g
               += g_synpk'')
syn2 = Synapses(neuron2, neuron3, clock=neuron2.clock, on_pre=''g
               += g_synpk'')
syn1.connect('i == j')
syn2.connect('i == j')
syn1.delay=20*ms
syn2.delay=20*ms

monitor1=StateMonitor(neuron1, ('v', 'g'), record=True)

```

```

monitor2=StateMonitor(neuron2, ('v', 'g'), record=True)
monitor3=StateMonitor(neuron3, ('v', 'g'), record=True)
neuron1.v= -65*mV
neuron1.u= b*(-65*mV)
neuron2.v= -65*mV
neuron2.u= b*(-65*mV)
neuron3.v= -65*mV
neuron3.u= b*(-65*mV)

neuron1.g= 0*nsiemens
neuron2.g = 0*nsiemens
neuron3.g = 0*nsiemens
run(200.0*ms, report='text')
neuron1.I = 75*mA
neuron2.I = 0*nA
neuron3.I = 0*nA
run(20.0*ms, report='text')
neuron1.I = 0*mA
neuron2.I = 0*nA
neuron3.I = 0*nA
run(400.0*ms, report='text')

figure(1, figsize=(8, 8))
subplot(6, 1, 1)
plot(monitor1.t/ms, monitor1.v[0]/mV, 'g')
xlim(150, 300)
subplot(6, 1, 2)
plot(monitor1.t/ms, monitor1.g[0], 'g')
xlim(150, 300)
subplot(6, 1, 3)
plot(monitor2.t/ms, monitor2.v[0]/mV, 'r')
xlim(150, 300)
subplot(6, 1, 4)
plot(monitor2.t/ms, monitor2.g[0]/100, 'r')
xlim(150, 300)
subplot(6, 1, 5)
plot(monitor3.t/ms, monitor3.v[0]/mV, 'b')
xlim(150, 300)
subplot(6, 1, 6)

```

```
plot(monitor3.t/ms, monitor3.g[0]/100, 'b')  
xlim(150, 300)  
show()
```

Part1 problem 3 & problem 4

```
from brian2 import *
defaultclock.dt=.01*ms
num_neurons = 2
duration = 2*second

# Parameters
area = 20000*umetre**2
Cm = 1*ufarad*cm**-2
El = -60*mV
gl = 0.7*msiemens/cm**2

tau_ampa=0.3*ms
g_synpk= 400 * siemens
g_synmaxval=(g_synpk)
E_syn = -80*mV
tau_m = 15*ms

# Parameters for LTS model
a = 0.02
b = 0.25
c = -65*mV
d = 2.0 * mV
R = 1*ohm
v0 = -65*mV
u0 = 4*mV

#The model
eqs_fv = '''
fv = 0.04*v**2 / mV + 5*v + 140*mV : volt
'''

eqs_u = '''
du/dt = a*(b*v - u) * metre ** 2 * kilogram * second ** -4 * amp
      ** -1 /mV: volt
'''

eqs = '''
dv/dt = ((fv - u + R*I)* metre ** 2 * kilogram * second ** -4 *
      amp ** -1 /mV) + (g*(E_syn-v)*metre ** 2 * kilogram * second **
      -4 * amp ** -1/amp) : volt
```



```

I : amp
'''

eqs_syn = '''
# The conductance of the alpha model
dz/dt = (-z/tau_m) : siemens
dg/dt = -g/tau_m + z/ms : siemens
'''

eqs += eqs_fv + eqs_u + eqs_syn
# Threshold and refractoriness are only used for spike counting
neuron1 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron2 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron3 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron4 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
syn1 = Synapses(neuron1, neuron2, clock=neuron1.clock, on_pre='''g
+= g_synpk''')
# syn2 = Synapses(neuron2, neuron3, clock=neuron2.clock,
#                 on_pre='''g += g_synpk''')
syn1.connect('i == j')
syn1.delay=10*ms
# syn2.delay=15*ms

monitor1=StateMonitor(neuron1, ('v', 'g'), record=True)
monitor2=StateMonitor(neuron2, ('v', 'g'), record=True)

```

```

monitor3=StateMonitor(neuron3, ('v', 'g'), record=True)
monitor4=StateMonitor(neuron4, ('v', 'g'), record=True)

neuron1.v= -65*mV
neuron1.u= b*(-65*mV)
neuron2.v= -65*mV
neuron2.u= b*(-65*mV)
neuron3.v= -65*mV
neuron3.u= b*(-65*mV)
neuron4.v= -65*mV
neuron4.u= b*(-65*mV)

neuron1.g= 0*nsiemens
neuron2.g = 0*nsiemens
neuron3.g = 0*nsiemens
run(200.0*ms, report='text')
neuron1.I = 40*mA
neuron2.I = 40*mA
neuron3.I = 40*mA
run(20.0*ms, report='text')
neuron1.I = 0*mA
neuron2.I = 0*nA
neuron3.I = 0*nA
run(200.0*ms, report='text')

figure(1, figsize=(8, 8))
subplot(6, 1, 1)
plot(monitor1.t/ms, monitor1.v[0]/mV, 'g')
xlim(150, 300)
subplot(6, 1, 2)
plot(monitor1.t/ms, monitor1.g[0], 'g')
xlim(150, 300)
subplot(6, 1, 3)
plot(monitor2.t/ms, monitor2.v[0]/mV, 'r')
xlim(150, 300)
subplot(6, 1, 4)
plot(monitor2.t/ms, monitor2.g[0]/100, 'r')
xlim(150, 300)

```

```
subplot(6, 1, 5)
plot(monitor3.t/ms, monitor3.v[0]/mV, 'b')
xlim(150, 300)
subplot(6, 1, 6)
plot(monitor3.t/ms, monitor3.g[0]/100, 'b')
xlim(150, 300)
show()
```

Part1 problem 5

```
from brian2 import *
defaultclock.dt=.01*ms
num_neurons = 2
duration = 2*second

# Parameters
area = 20000*umetre**2
Cm = 1*ufarad*cm**-2
El = -60*mV
gl = 0.7*msiemens/cm**2

tau_ampa=0.3*ms
g_synpk= 800 * siemens
g_synmaxval=(g_synpk)
E_syn_in = -80*mV
E_syn_ex = 0*mV
tau_m = 5*ms
# Parameters for LTS model
a = 0.02
b = 0.25
c = -65*mV
d = 2.0 * mV
R = 1*ohm
v0 = -65*mV
u0 = 4*mV

#The model
eqs_fv = '''
fv = 0.04*v**2 / mV + 5*v + 140*mV : volt
'''
eqs_u = '''
du/dt = a*(b*v - u) * metre ** 2 * kilogram * second ** -4 * amp
      ** -1 /mV: volt
'''
eqs = '''
dv/dt = ((fv - u + R*I)* metre ** 2 * kilogram * second ** -4 *
      amp ** -1 /mV) + (g*(E_syn-v)*metre ** 2 * kilogram * second **
```

```

        -4 * amp ** -1/amp) : volt
I : amp
E_syn : volt
'''

eqs_syn = '''
# The conductance of the alpha model
dz/dt = (-z/tau_m) : siemens
dg/dt = -g/tau_m + z/ms : siemens
'''

eqs += eqs_fv + eqs_u + eqs_syn
# Threshold and refractoriness are only used for spike counting
neuron1 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron2 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron3 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron4 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
syn1 = Synapses(neuron1, neuron2, clock=neuron1.clock, on_pre='''g
+= g_synpk''')
syn2 = Synapses(neuron2, neuron3, clock=neuron2.clock, on_pre='''g
+= g_synpk''')
syn3 = Synapses(neuron3, neuron4, clock=neuron2.clock, on_pre='''g
+= g_synpk''')

syn1.connect('i == j')
```

```

syn2.connect('i == j')
syn3.connect('i == j')
# syn1.delay=10*ms
# syn2.delay=20*ms
syn3.delay = 0*ms

monitor1=StateMonitor(neuron1, ('v', 'g'), record=True)
monitor2=StateMonitor(neuron2, ('v', 'g'), record=True)
monitor3=StateMonitor(neuron3, ('v', 'g'), record=True)
monitor4=StateMonitor(neuron4, ('v', 'g'), record=True)

neuron1.v= -65*mV
neuron1.u= b*(-65*mV)
neuron2.v= -65*mV
neuron2.u= b*(-65*mV)
neuron3.v= -65*mV
neuron3.u= b*(-65*mV)
neuron4.v= -65*mV
neuron4.u= b*(-65*mV)

neuron1.g= 0*nsiemens
neuron2.g = 0*nsiemens
neuron3.g = 0*nsiemens
neuron4.g = 0*nsiemens

run(200.0*ms, report='text')
# Define the type of neuron
neuron1.E_syn = E_syn_ex
neuron2.E_syn = E_syn_ex
neuron3.E_syn = 1.5 * E_syn_in
neuron4.E_syn = E_syn_ex

neuron1.I = 0*mA
neuron2.I = 0*mA
neuron3.I = 40*mA
neuron4.I = 0*mA
run(20.0*ms, report='text')
neuron2.u= b*(-65*mV)
neuron1.I = 0*mA

```

```

neuron2.I = 0*nA
neuron3.I = 0*nA
neuron4.I = 0*mA
run(200.0*ms, report='text')

figure(1, figsize=(10, 10))
subplot(8, 1, 1)
plot(monitor1.t/ms, monitor1.v[0]/mV, 'g')
xlim(150, 300)
subplot(8, 1, 2)
plot(monitor1.t/ms, monitor1.g[0]/1000, 'g')
xlim(150, 300)
subplot(8, 1, 3)
plot(monitor2.t/ms, monitor2.v[0]/mV, 'r')
xlim(150, 300)
subplot(8, 1, 4)
plot(monitor2.t/ms, monitor2.g[0]/1000, 'r')
xlim(150, 300)
subplot(8, 1, 5)
plot(monitor3.t/ms, monitor3.v[0]/mV, 'b')
xlim(150, 300)
subplot(8, 1, 6)
plot(monitor3.t/ms, monitor3.g[0]/1000, 'b')
xlim(150, 300)
subplot(8, 1, 7)
plot(monitor4.t/ms, monitor4.v[0]/mV, 'chocolate')
xlim(150, 300)
subplot(8, 1, 8)
plot(monitor4.t/ms, monitor4.g[0]/1000, 'chocolate')
xlim(150, 300)
show()

```

Part2

```
from brian2 import *
defaultclock.dt=.01*ms
num_neurons = 2
duration = 2*second

# Parameters
area = 20000*umetre**2
Cm = 1*ufarad*cm**-2
El = -60*mV
gl = 0.7*msiemens/cm**2

tau_ampa=0.3*ms
g_synpk= 1500 * siemens
g_synmaxval=(g_synpk)
E_syn_in = -80*mV
E_syn_ex = 0*mV
tau_m = 5*ms
# Parameters for LTS model
a = 0.02
b = 0.25
c = -65*mV
d = 2.0 * mV
R = 1*ohm
v0 = -65*mV
u0 = 4*mV
# parameters for motor
tau_motor = 10*ms
eta = 0.05
#The model
eqs_fv = '''
fv = 0.04*v**2 / mV + 5*v + 140*mV : volt
'''
eqs_u = '''
du/dt = a*(b*v - u) * metre ** 2 * kilogram * second ** -4 * amp
      ** -1 /mV: volt
'''
eqs = '''
```



```

dv/dt = ((fv - u + R*I)* metre ** 2 * kilogram * second ** -4 *
          amp ** -1 /mV) + (g*(E_syn-v)*metre ** 2 * kilogram * second **
          -4 * amp ** -1/amp) : volt
I : amp
E_syn : volt
'''

eqs_syn = '''
# The conductance of the alpha model
dz/dt = (-z/tau_m) : siemens
dg/dt = -g/tau_m + z/ms : siemens
'''

eqs += eqs_fv + eqs_u + eqs_syn
# Threshold and refractoriness are only used for spike counting
neuron1 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron2 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron3 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron4 = NeuronGroup(1, eqs,
                      threshold='v >= 30*mV',
                      reset='v = c;u = u + d',
                      method='euler'
                      )
neuron_L = NeuronGroup(1, '''
dvl/dt = -(vl/tau_motor) : 1
''')
neuron_R = NeuronGroup(1, '''
dvr/dt = -(vr/tau_motor) : 1
''')

```

```

syn1 = Synapses(neuron1, neuron2, clock=neuron1.clock, on_pre='''g
    += g_synpk ''',
                method='euler')

syn2 = Synapses(neuron3, neuron4, clock=neuron3.clock, on_pre='''g
    += g_synpk ''',
                method='euler')
synl = Synapses(neuron2, neuron_L, clock=neuron2.clock,
    on_pre='''v1 += eta''')
synr = Synapses(neuron4, neuron_R, clock=neuron4.clock,
    on_pre='''vr += eta''')

syn1.connect('i == j')
syn2.connect('i == j')
synl.connect('i == j')
synr.connect('i == j')
# syn1.delay=10*ms
# syn2.delay=20*ms

monitor1=StateMonitor(neuron1, ('v', 'g'), record=True)
monitor2=StateMonitor(neuron2, ('v', 'g'), record=True)
monitor3=StateMonitor(neuron3, ('v', 'g'), record=True)
monitor4=StateMonitor(neuron4, ('v', 'g'), record=True)
monitor_syn1 = StateMonitor(neuron_L, 'v1', record=True)
monitor_syn2 = StateMonitor(neuron_R, 'vr', record=True)

neuron1.v= -65*mV
neuron1.u= b*(-65*mV)
neuron2.v= -65*mV
neuron2.u= b*(-65*mV)
neuron3.v= -65*mV
neuron3.u= b*(-65*mV)
neuron4.v= -65*mV
neuron4.u= b*(-65*mV)

neuron1.g= 0*nsiemens
neuron2.g = 0*nsiemens
neuron3.g = 0*nsiemens

```

```

neuron4.g = 0*nsiemens

run(200.0*ms, report='text')
# Define the type of neuron
neuron1.E_syn = E_syn_ex
neuron2.E_syn = E_syn_ex
neuron3.E_syn = E_syn_ex
neuron4.E_syn = E_syn_ex

neuron1.I = 120*mA
neuron2.I = 0*mA
neuron3.I = 120*mA
neuron4.I = 0*mA
run(20.0*ms, report='text')
neuron1.I = 0*mA
neuron2.I = 0*nA
neuron3.I = 0*nA
neuron4.I = 0*mA
run(200.0*ms, report='text')

figure(1, figsize=(8, 10))
subplot(2, 1, 1)
plot(monitorsyn1.t/ms, monitorsyn1.vl[0], 'g')
xlabel('t/ms')
ylabel('velocity')
title("V_left")
xlim(150, 350)
subplot(2, 1, 2)
plot(monitorsyn2.t/ms, monitorsyn2.vr[0], 'r')
xlabel('t/ms')
ylabel('velocity')
title("V_right")
xlim(150, 350)

figure(2, figsize=(10, 10))
subplot(8, 1, 1)
plot(monitorsyn1.t/ms, monitorsyn1.v[0]/mV, 'g')
xlim(150, 300)

```

```
subplot(8, 1, 2)
plot(monitor1.t/ms, monitor1.g[0], 'g')
xlim(150, 300)
subplot(8, 1, 3)
plot(monitor2.t/ms, monitor2.v[0]/mV, 'r')
xlim(150, 300)
subplot(8, 1, 4)
plot(monitor2.t/ms, monitor2.g[0]/10000, 'r')
xlim(150, 300)
subplot(8, 1, 5)
plot(monitor3.t/ms, monitor3.v[0]/mV, 'b')
xlim(150, 300)
subplot(8, 1, 6)
plot(monitor3.t/ms, monitor3.g[0], 'b')
xlim(150, 300)
subplot(8, 1, 7)
plot(monitor4.t/ms, monitor4.v[0]/mV, 'chocolate')
xlim(150, 300)
subplot(8, 1, 8)
plot(monitor4.t/ms, monitor4.g[0]/10000, 'chocolate')
xlim(150, 300)
show()
```
