## Lecture 8 - Tagging

## Goals

- 1. Generative Tagging
  - a. Parameterization
  - b. Estimation
  - c. Inference
- 2. Discriminative tagging
  - a. Max Entropy
  - b. Simple RNN
  - c. Bidirectional RNN

## **Generative Tagging**

- Sentence: I love white dogs
- Tags: Pr, Vb Adj, N
- Baseline: most frequent tag already gets 90%+ accuracy
- We are given
  - $\circ$   $S = w_1, \dots, w_n$
  - $\circ \quad T = y_1, \dots, y_n$
- Parameterization
  - $P(S,T) = p(w_1, ..., w_n, y_1, ..., y_n) =$   $\prod p(w_i|w_1, ..., w_n, y_1, ..., y_i) p(y_i|w_1, ..., w_n, y_1, ..., y_{i-1})$
- Markov Assumption
  - $P(S,T) = \prod p(w_i|y_i)p(y_i|y_{i-1})$ 
    - $p(w_i|y_i)$  called the emission probability
    - $p(y_i|y_{i-1})$  called the transition probability
  - Number of parameters:  $VT + T^2$
- Estimation
  - MLE of transition probability:  $p(Vb|Pr) = \frac{count(Pr,Vb)}{count(Pr)}$
  - MLE of emission probability:  $p(I|Pr) = \frac{count(I,Pr)}{count(Pr)}$
  - o Remember there are smoothing issues
  - Want to use EM...but
- Inference Problem
  - We are looking for  $T^* = argmax_T(P(S,T))$ 
    - Assume  $p(t_i|t_{i-1})$  and  $p(w_i|t_i)$  are given
  - Solution: Viterbi Algorithm
    - Let *n* be the length of the sequence
    - $\blacksquare \quad \pi[i,t] \rightarrow$ 
      - $\max \log(probability \ of \ a \ sequence \ that \ ends \ at \ position \ i \ with \ tag \ t)$
    - Goal:  $\max_{t \in T} \pi[n, t]$
    - Base Case:  $\pi[0,*] = \log(1), \pi[0,t] = \log(0) = -\infty$

Recursive Case

• 
$$\pi[i,t] = \max_{t_{prev}} \pi[i_{prev}, t_{prev}] + \log(p(t|t_{prev})) + \log(p(i|t))$$

- Complexity:  $O(nT^2)$
- Now we can do estimation with EM
  - Take a random guess of the parameters, and compute the MLE efficiently with the Viterbi algorithm
  - o Bad results with random initialization
  - o Can get good results with good initialization

## **Discriminative Tagging**

- Now we estimate

$$o \quad p(T|S) = p(y_1, ..., y_n | w_1, ..., w_n) = \prod_i p(y_i | w_1, ..., w_n, y_1, ..., y_{i-1})$$

- Max Entropy

$$o \quad p(y|w) = \frac{1}{z(\theta,w)} e^{\theta f(y,w)}$$

• Indicator function f(y, w) of features  $1 \dots K$ 

• i.e. 
$$f_1(y, w) = \begin{cases} 1, & \text{if } y = noun, w \text{ is capitalized} \\ 0, & \text{o. } w. \end{cases}$$

- NN Structure for Max Entropy
  - Final layer: softmax, each unit represents  $p(y_t = k|w)$
  - Vector representing indicator function for y, w