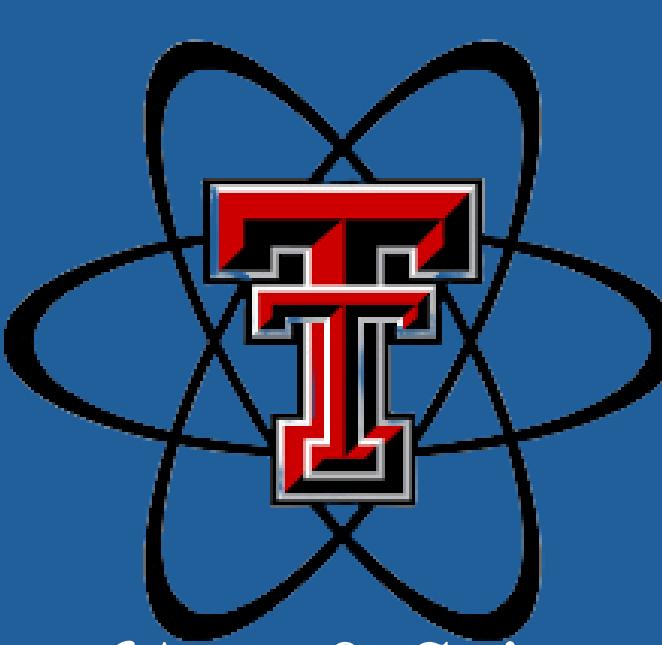


Computational Imaging Methods for CR-39 Alpha Particle Dosimetry

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Background

CR-39 is a widely used solid-state nuclear track detector (SSNTD) for detecting charged particle radiation, particularly alpha particles. When exposed to alpha radiation, CR-39 forms microscopic damage tracks that can be revealed through chemical etching. Traditional dosimetry involves direct irradiation followed by optical or electron microscopy to analyze these tracks.

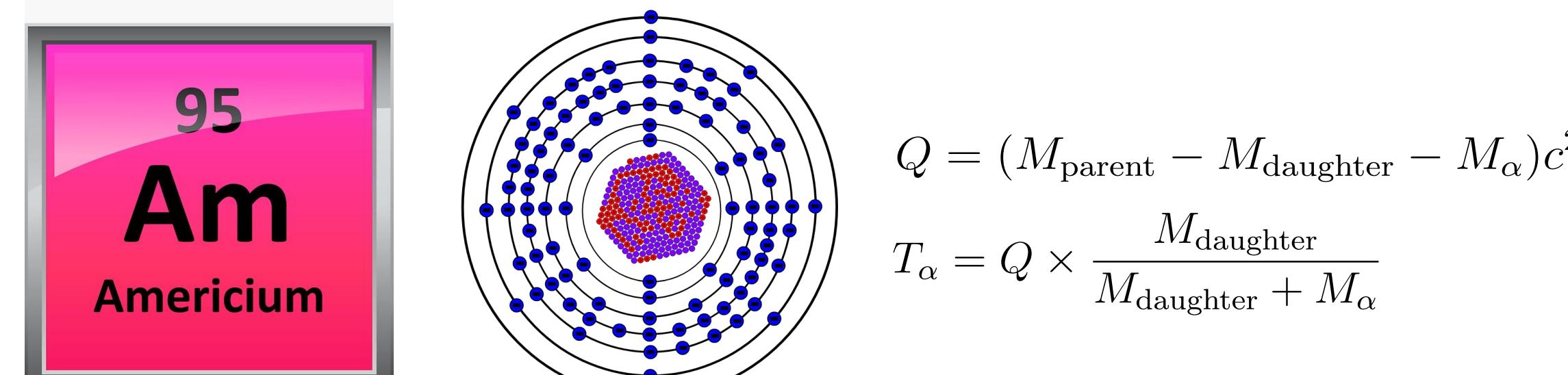


Figure 1. Americium Element

α -decay and Am241

Alpha decay is a type of radioactive decay where an unstable nucleus emits an alpha particle (two protons and two neutrons), reducing its atomic number by 2 and mass number by 4. This process occurs in heavy elements to increase nuclear stability.

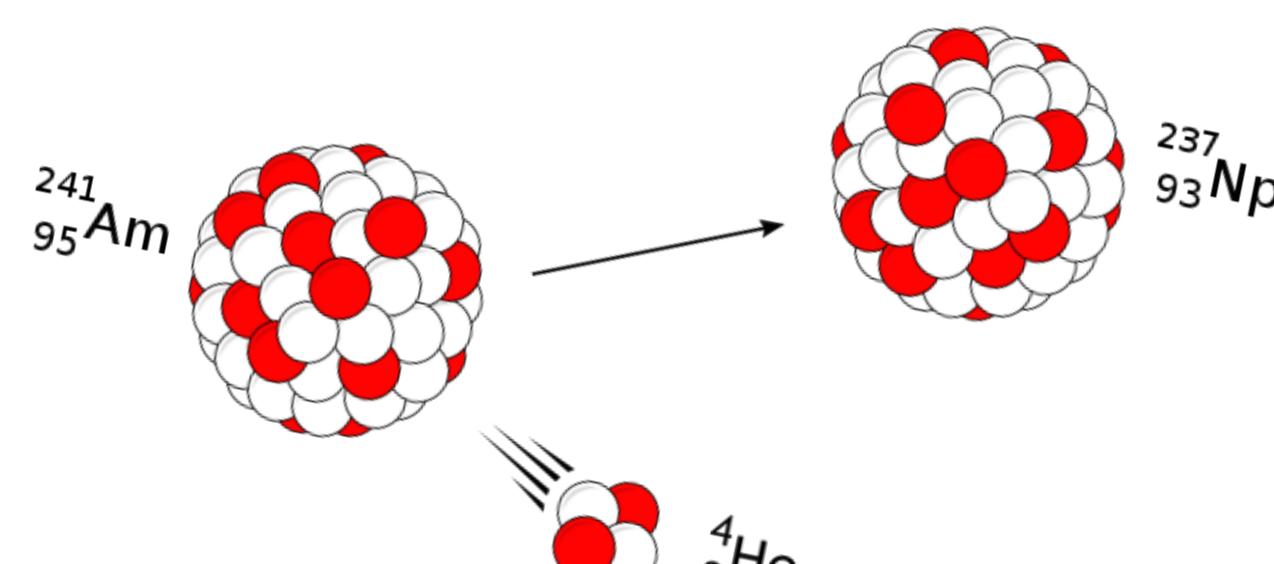
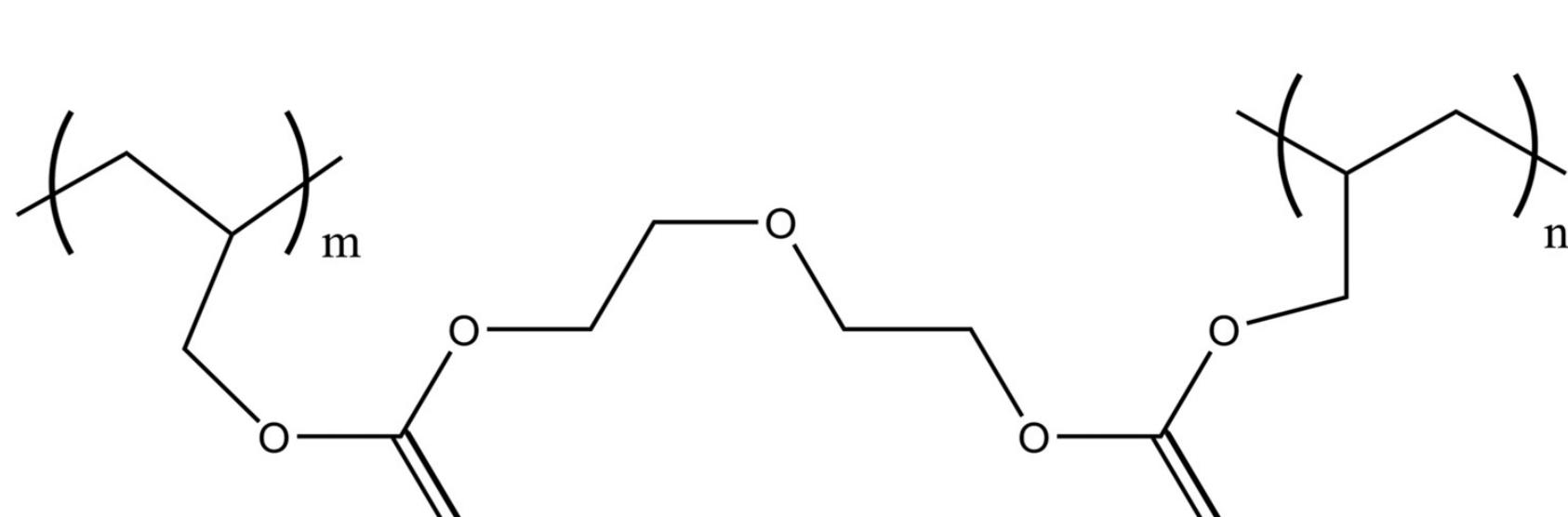
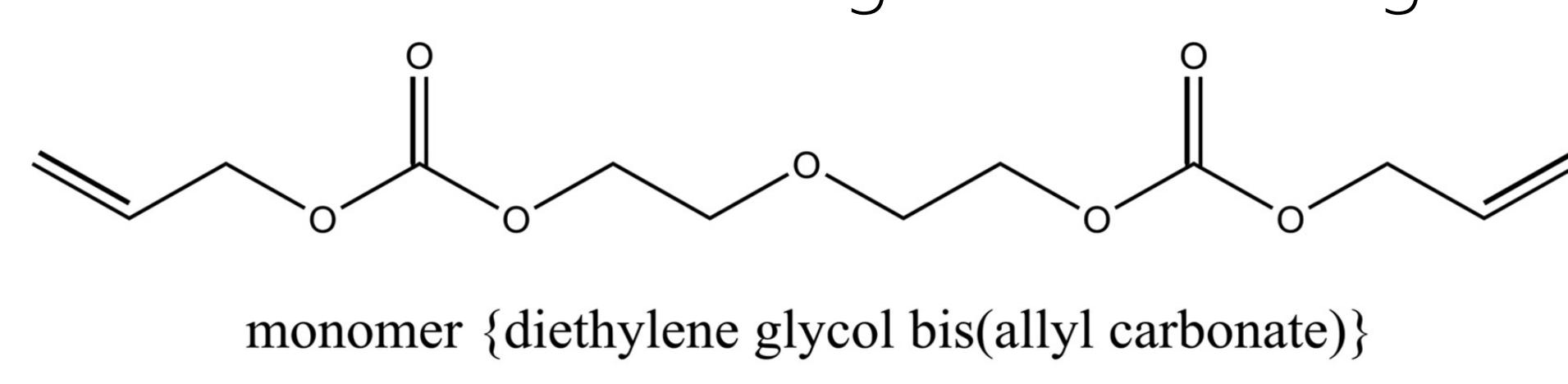


Figure 2. α -decay of Americium-241

Americium-241 (Am-241) undergoes alpha decay, emitting 5.486 MeV alpha particles and transforming into neptunium-237 (Np-237).

CR39

Polyallyl diglycol carbonate (PADC) or CR39, a transparent polymer widely used for detecting charged particles. When an alpha particle strikes CR-39, it ionizes the polymer along its path, breaking molecular bonds and creating a latent damage track.



CR-39 polymer (polyallyl diglycol carbonate)

Figure 3. PADC molecular structure

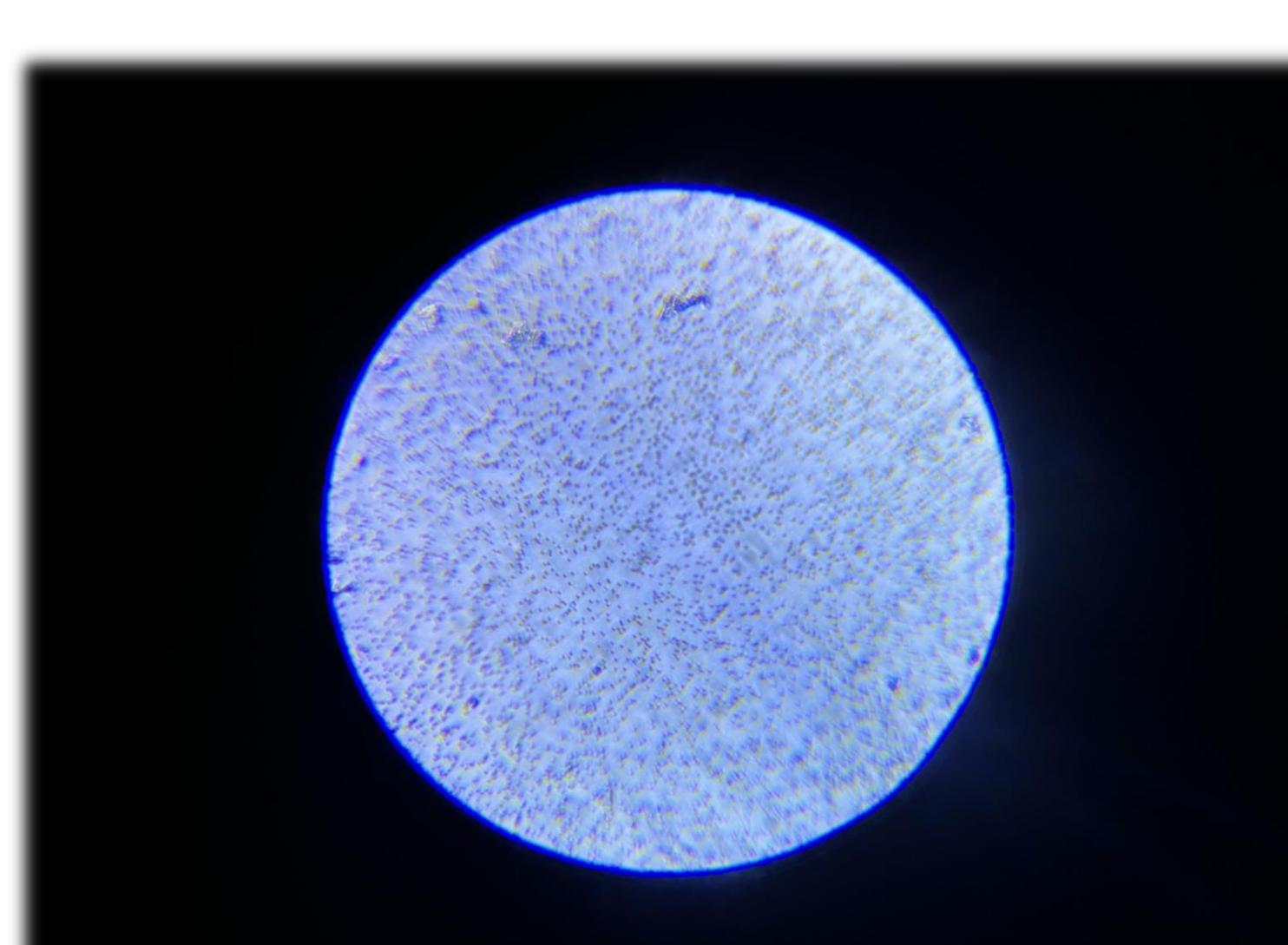


Figure 4. CR39 implementation of iPhone pocket dosimeter

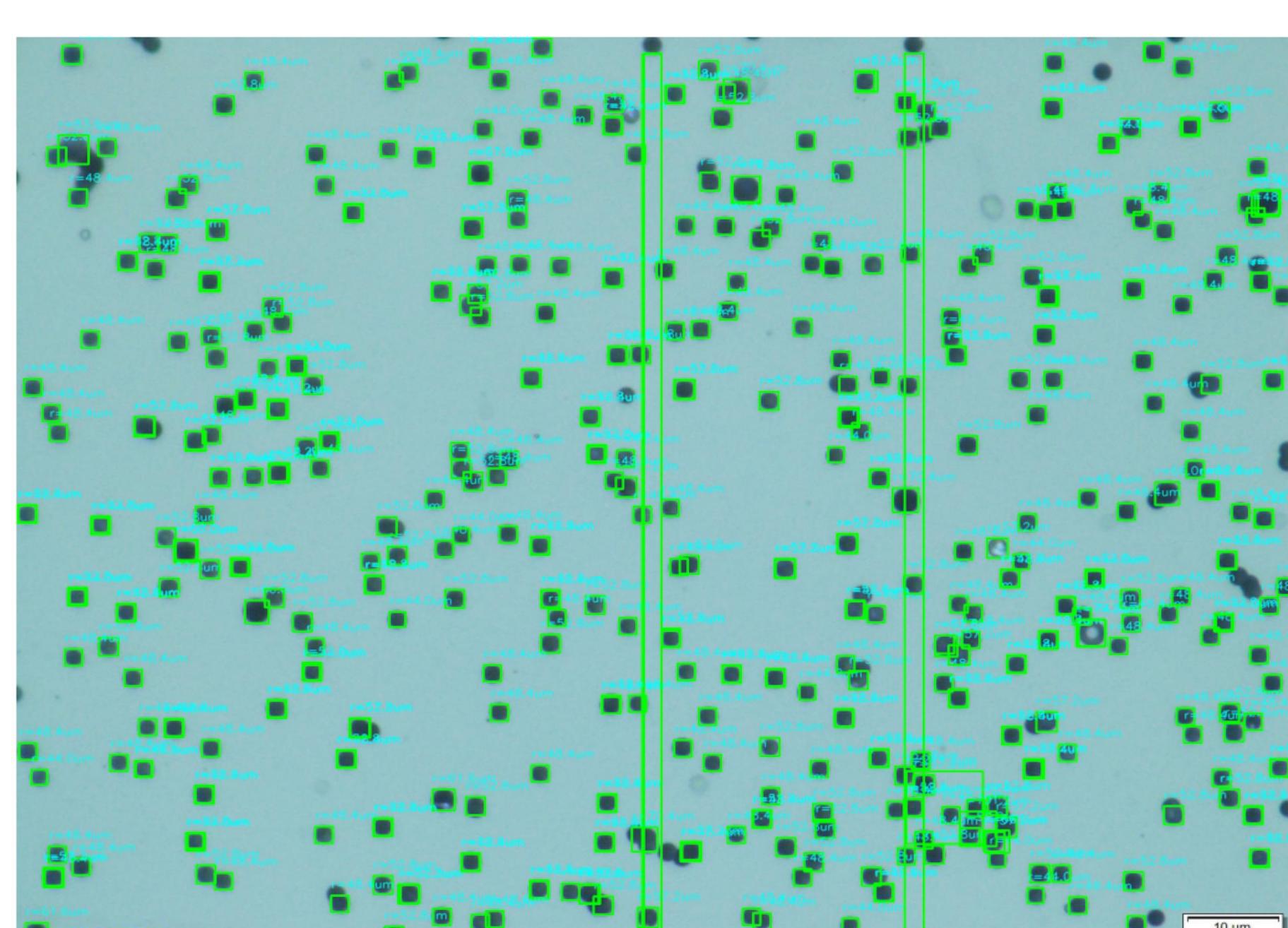
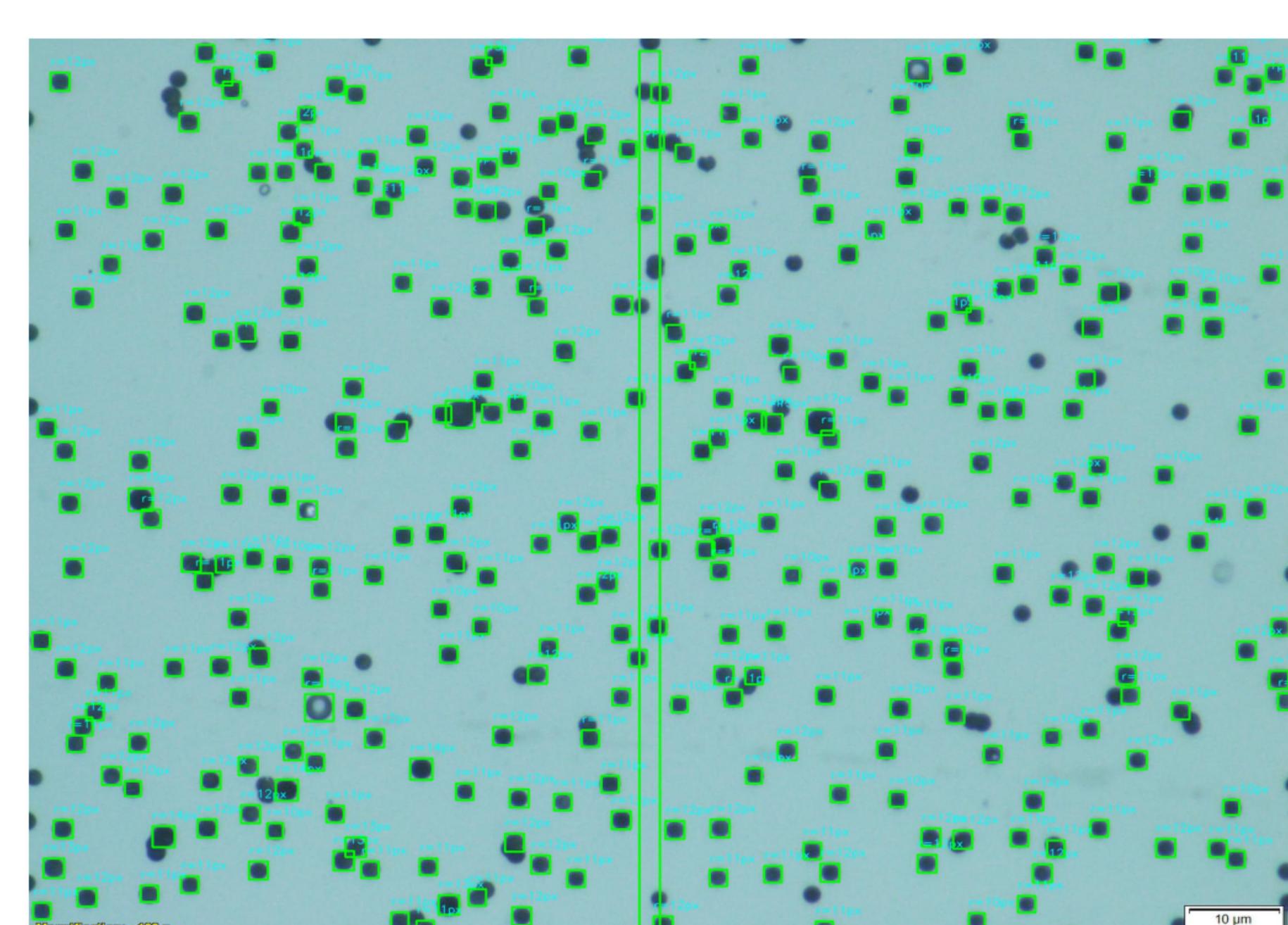
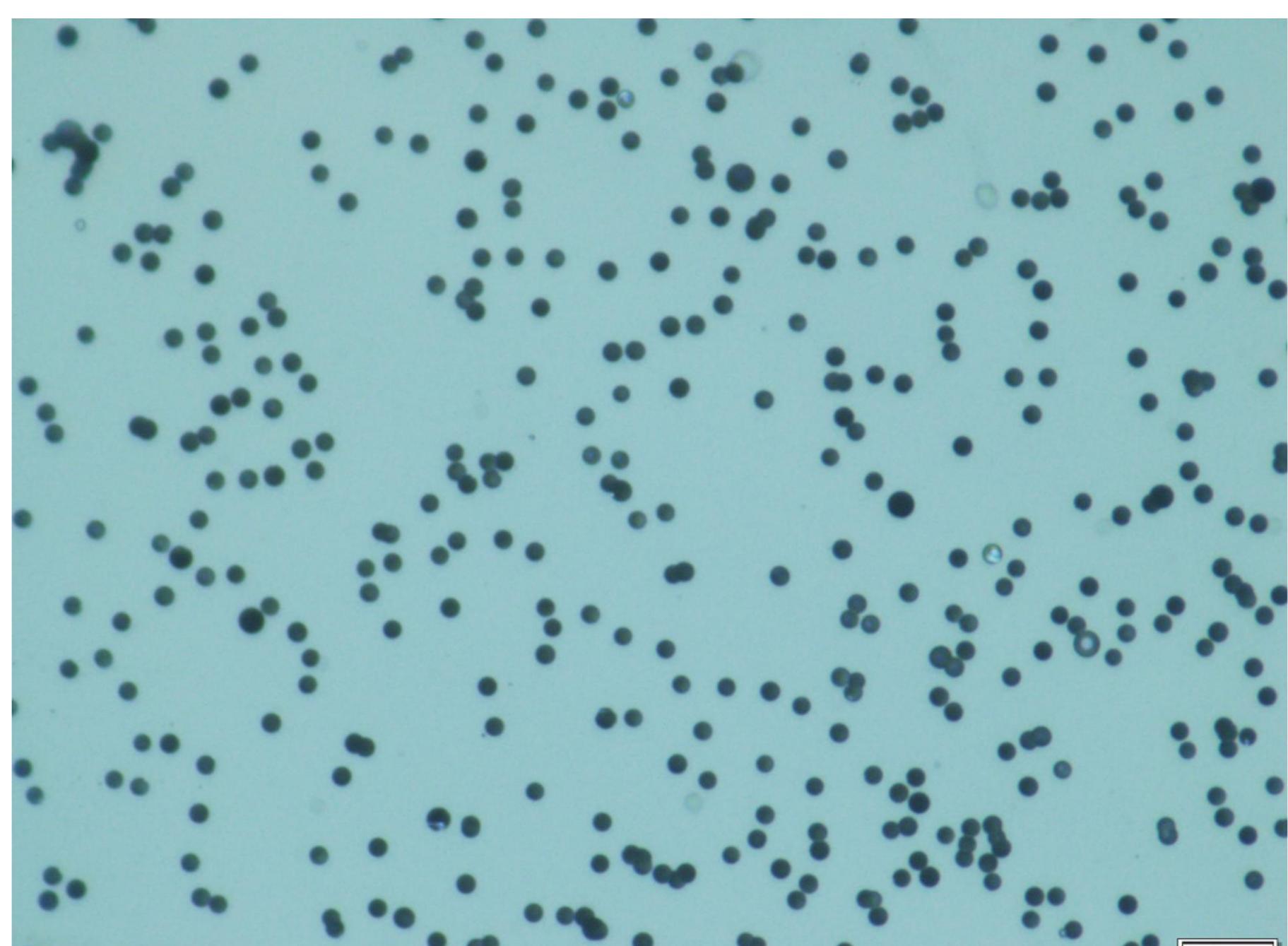
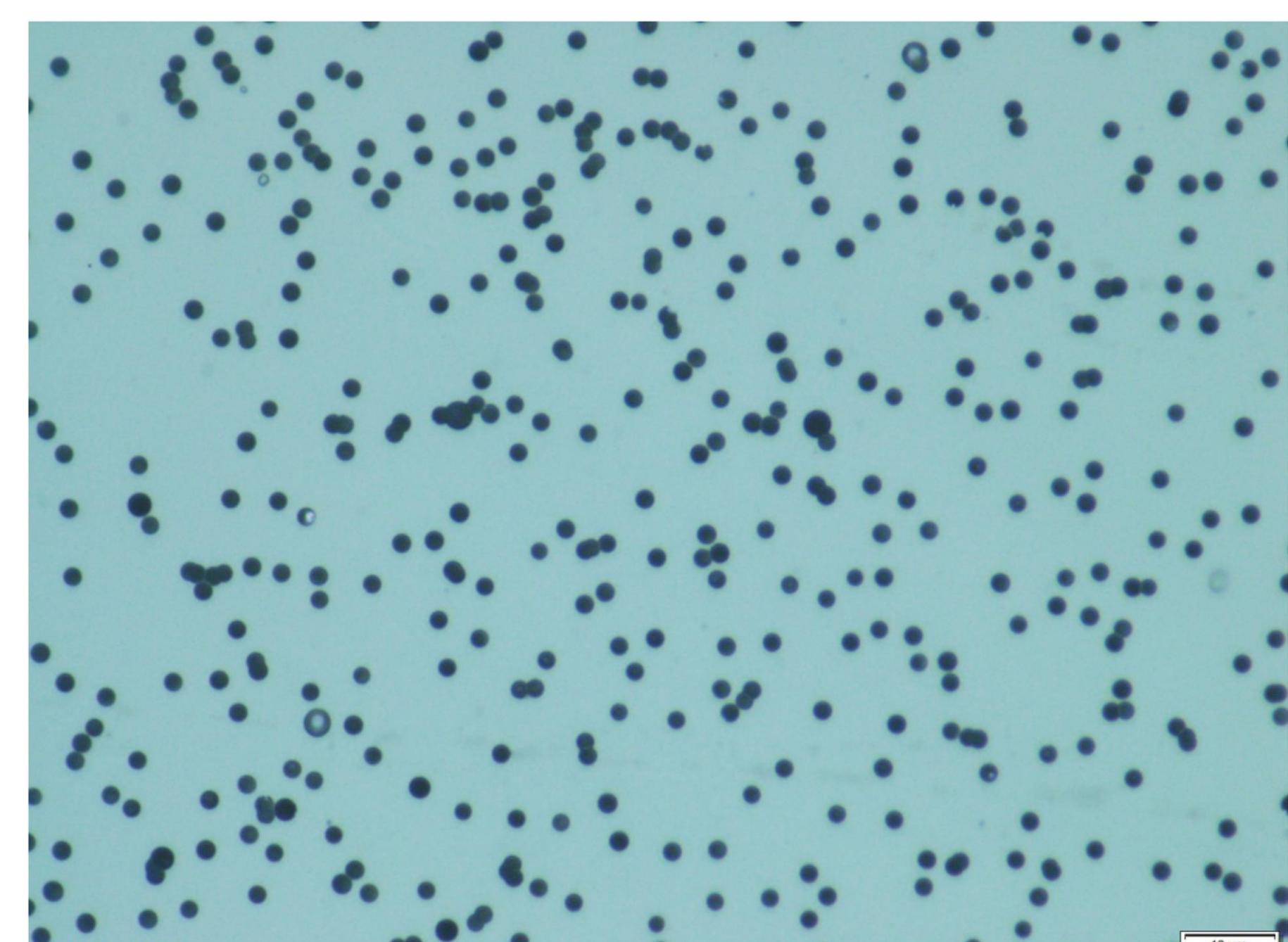


Figure 5. 100x surface image: pixel diameter estimation (right), um diameter estimation (left)

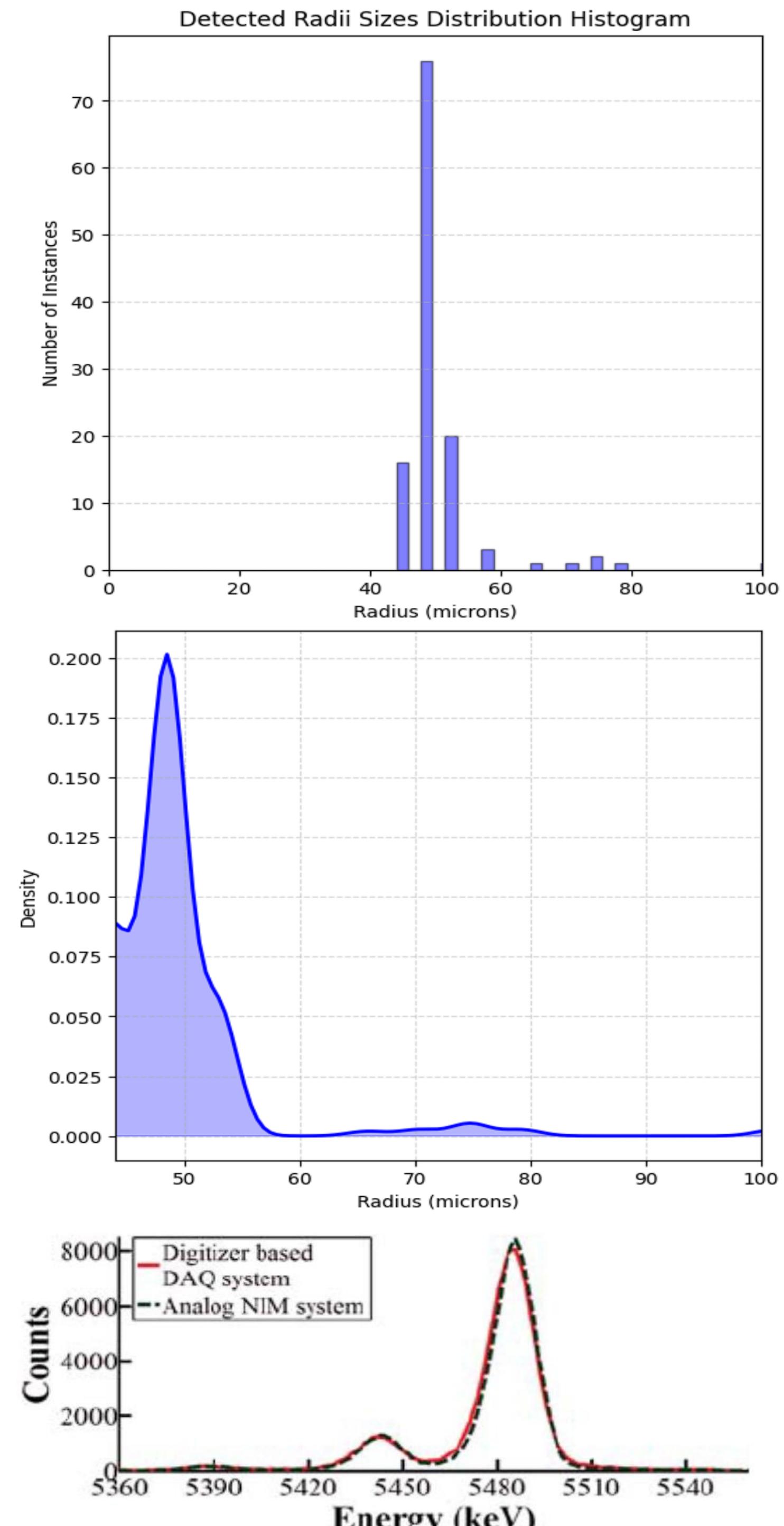


Figure 7. Observed distribution vs. experimentally confirmed [3]

Methods

1. Microscopic Imaging of CR-39 Tracks

To analyze α -induced damage, high-magnification microscope images of etched CR-39 tiles are captured. These images are processed to enhance contrast and minimize noise.

2. Image Processing & Feature Extraction

- Edge detection and adaptive thresholding techniques are applied to segment track craters
- Morphological features such as diameter, shape, and depth indicators
- Automated measurements of track radii

3. Machine Learning-Based Track Identification

- A supervised classification model is trained on detected craters to differentiate projectile-induced features from background noise
- A regression model is implemented to predict crater size distributions, which correlate with the energy of the impacting alpha particles

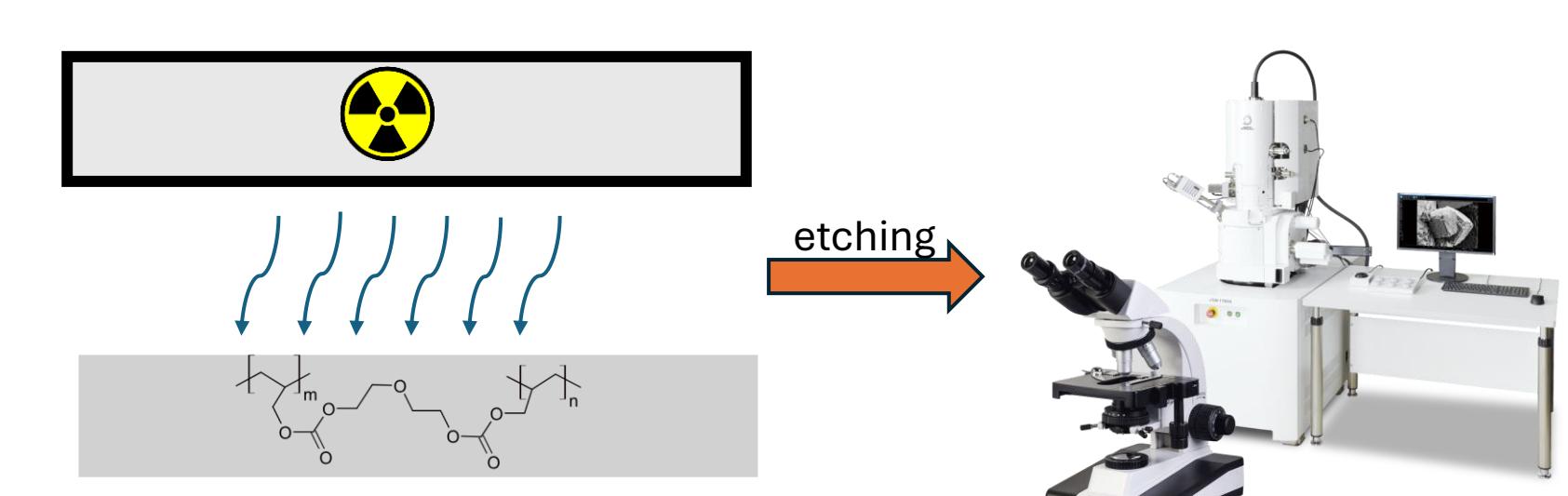


Figure 8. Experimental Setup

$$\text{1. Grayscale Conversion: } I_{\text{gray}} = 0.2989R + 0.5870G + 0.1140B$$

$$\text{2. Gaussian blur: } G(x, y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

$$\text{3a. Circle Equation: } (x - a)^2 + (y - b)^2 = r^2$$

$$\text{3b. Edge Detection Gradient: } G_x = \frac{\partial I}{\partial x}, \quad G_y = \frac{\partial I}{\partial y}$$

$$\text{Magnitude and Direction: } G = \sqrt{G_x^2 + G_y^2}, \quad \theta = \tan^{-1}\left(\frac{G_y}{G_x}\right)$$

$$\text{4. For each edge pixel}(x,y)\text{, the possible circle centers}(a,b)\text{satisfy: } a = x + r \cos \theta, \quad b = y + r \sin \theta$$

Acknowledgements

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References

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