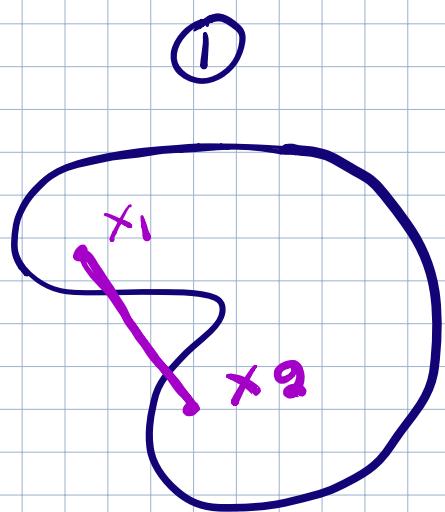


Lecture 5

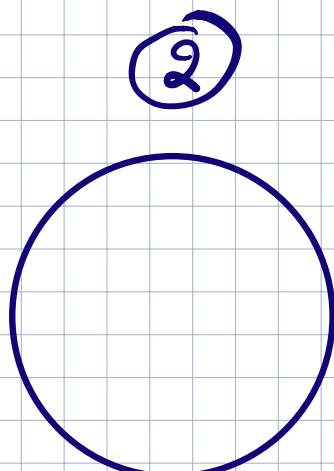
Geometry of LPs

Convex set $\mathcal{C} \subseteq \mathbb{R}^n$

A set is convex iff for any $x_1, x_2 \in \mathcal{C}$
the line that connects them also belongs
in \mathcal{C}



not convex



convex

$$\begin{aligned} & \text{for all } \\ & x_1, x_2 \in \mathcal{C} \\ & \theta_1, \theta_2 \\ & \theta x_1 + (1-\theta) x_2 \in \mathcal{C} \\ & 0 \leq \theta \leq 1 \end{aligned}$$

This definition extends recursively

$\nexists x_1, x_2, \dots, x_k \in \zeta, \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_k x_k \in \zeta^l$

$\theta_i \geq 0, \sum \theta_i = 1$

Example → try to prove this holds

$$k=3 \quad \theta_i \geq 0$$

$$\underbrace{\theta_1 + \theta_2 + \theta_3 = 1}_{\text{, } x_1, x_2, x_3 \in \zeta}$$

$$\theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 = \theta_1 x_1 + \theta_2 x_2 + (1 - \theta_1 - \theta_2) x_3$$

$$= (\theta_1 + \theta_2) \left(\underbrace{\frac{\theta_1}{\theta_1 + \theta_2} x_1 + \frac{\theta_2}{\theta_1 + \theta_2} x_2}_{\theta x_1 + (1 - \theta) x_2} \right) + (1 - \theta_1 - \theta_2) x_3$$

$$\theta x_1 + (1 - \theta) x_2$$

some point

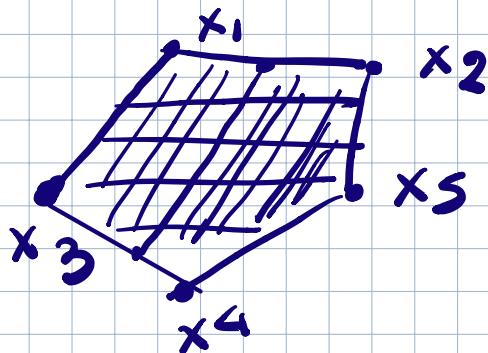
$$x_4 \in \zeta$$

$$\underbrace{(\theta_1 + \theta_2)}_{\theta'} x_4 + \underbrace{(1 - \theta_1 - \theta_2)}_{\theta'} x_3 \in \zeta'$$

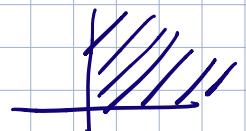
Definition

Given N points x_1, x_2, \dots, x_N , we define the convex hull of these points to be the set:

$$S = \left\{ y = \sum_{i=1}^N \theta_i x_i \mid \theta_i \geq 0, \sum \theta_i = 1 \right\}$$



smallest convex set
that contains
 x_1, \dots, x_N



Examples: are the following sets convex?

1) $\mathbb{R}^+ = \{ x \in \mathbb{R}^n \mid x \geq 0 \}$ non negative orthant.
convex

2) Sphere $S = \{ x \mid \|x - x_c\| \leq r \}$

To prove, consider $x_1, x_2 \in S$, we want to show $\theta x_1 + (1-\theta)x_2, \theta \geq 0 \in S'$

$$\|\theta x_1 + (1-\theta)x_2 - x_c\| = \|\theta x_1 + (1-\theta)x_2 - \theta x_c - (1-\theta)x_c\|$$

$$= \|\theta(x_1 - x_c) + (1-\theta)(x_2 - x_c)\| \leq$$

$$\leq \theta \|x_1 - x_c\| + (1-\theta) \|x_2 - x_c\| \leq \theta r + (1-\theta)r = r$$

convex

3) Halfspace. $\{x \mid a^T x \leq b\}$ convex

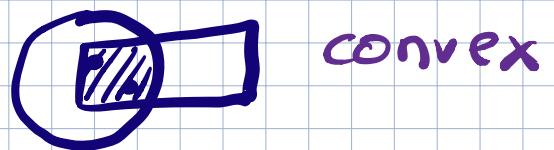
Hyperplane $\{x \mid a^T x = b\}$ convex.

4) Intersection of convex sets

S_1 is convex

S_2 is convex

$S_1 \cap S_2$



$S_1 \cup S_2$ not convex

5) Polyhedron:

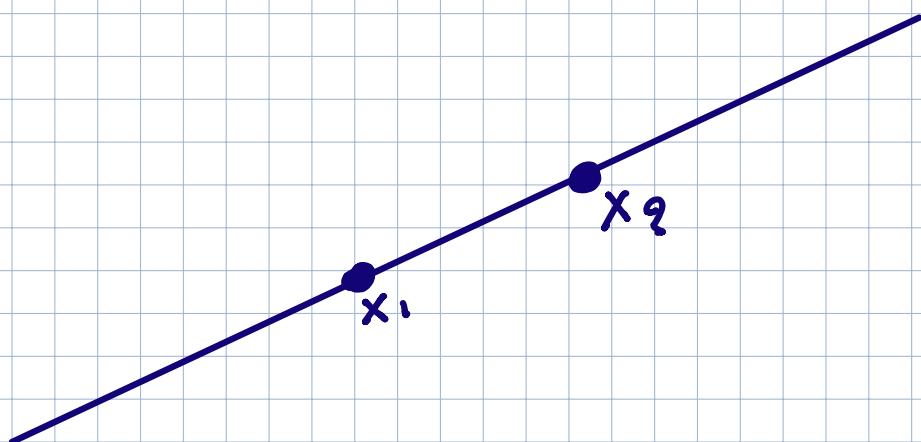
$P = \{x \mid a_i^T x \leq b_i, c_i^T x = d_i\}$

convex because
intersection of
convex sets.

Affine Sets S

A subset $S \subseteq \mathbb{R}^n$ is an affine set iff
the line that connects any 2 points
 $x_1, x_2 \in S$ also belongs in S

$\forall x_1, x_2 \in S, \theta x_1 + (1-\theta)x_2 \in S$



Extends recursively

S is an affine set iff $x_1, \dots, x_k \in S$

$$a_1 x_1 + a_2 x_2 + \dots + a_k x_k \in S$$

$$a_1 + a_2 + \dots + a_k = 1$$

affine combination

Affine hull

$$\{a_1 x_1 + \dots + a_k x_k \mid \sum a_i = 1\}$$

Example

1) hyperplane $\{x \mid a^T x = b\}$ ✓

2) halfspace $\{x \mid a^T x \leq b\}$

hyperplane:

$$x = \theta x_1 + (1-\theta)x_2$$

$$a^T(\theta x_1 + (1-\theta)x_2) = \\ \theta \underbrace{a^T x_1}_b + (1-\theta) \underbrace{a^T x_2}_b = b$$

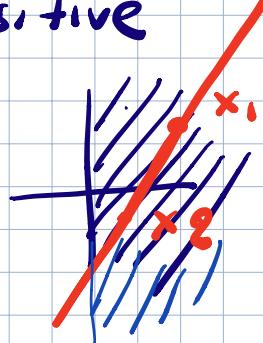
halfspace?

$$x = \theta x_1 + (1-\theta)x_2$$

$$a^T(\theta x_1 + (1-\theta)x_2)$$

θ is not positive

$$= \theta \underbrace{a^T x_1}_{\leq b} + (1-\theta) \underbrace{a^T x_2}_{\leq b}$$



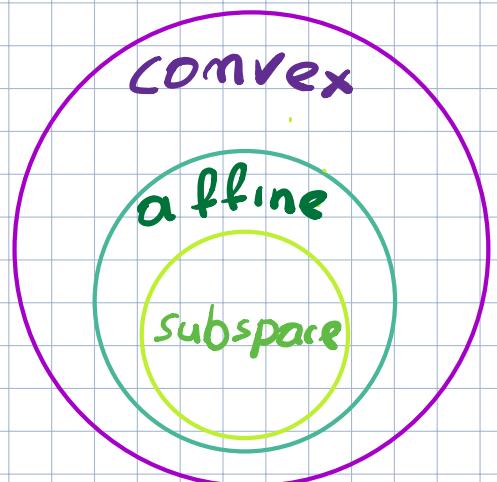
$$a^T x_1 \leq b$$

$$\theta < 0 \quad \theta a^T x_1 > \theta b$$

Subspace. V a set $V \subseteq \mathbb{R}^n$ is a subspace if $x_1, x_2 \in V, \alpha x_1 + \beta x_2 \in V$

subspace always contains the origin

$$x = 0$$



Example Let A be an $m \times n$ matrix.

1) $R(A) = \{x \mid x = Ay, y \in \mathbb{R}^n\}$ subspace ✓

$$\begin{aligned} x_1, x_2 \in R(A), \quad \alpha x_1 + \beta x_2 &= \alpha Ay_1 + \beta Ay_2 \\ &= A(\underbrace{\alpha y_1 + \beta y_2}_y) \end{aligned}$$

2) $N(A) = \{x \mid Ax = 0\}$

$$x_1, x_2 \in N(A) \quad A(\alpha x_1 + \beta x_2) =$$

$$\underbrace{\alpha Ax_1}_{0} + \underbrace{\beta Ax_2}_{0} = 0$$

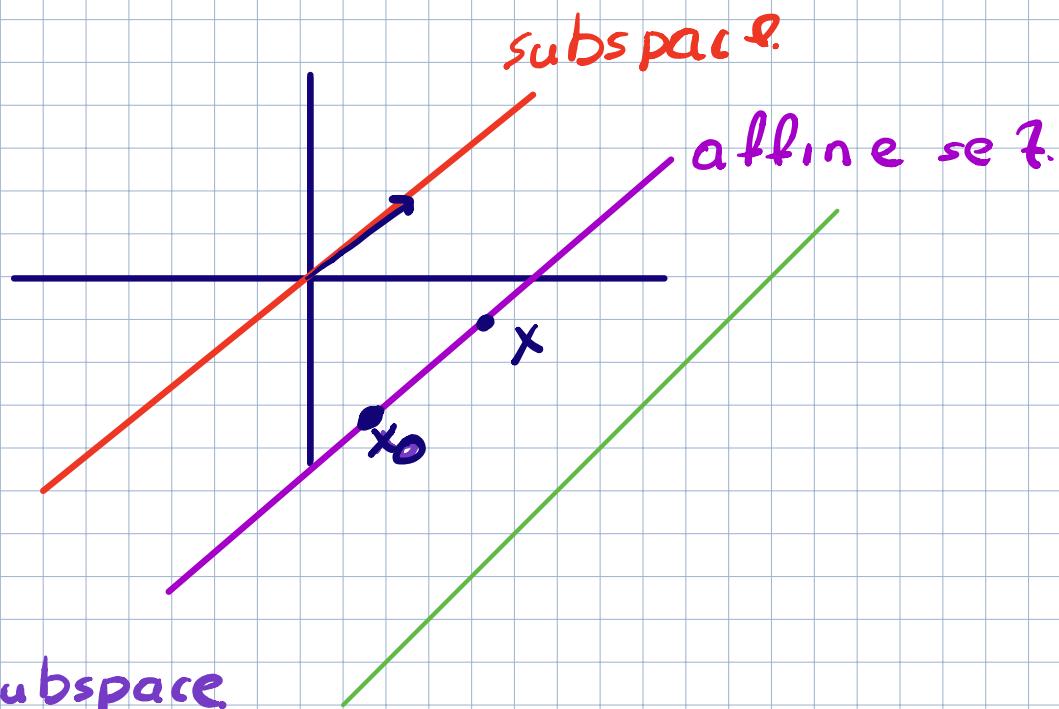
3) Set of solutions of linear equations

$$G = \{x \mid Ax = b\}$$

affine set
(not a subspace)

$$A(\alpha x_1 + \beta x_2) = \alpha Ax_1 + \beta Ax_2 = \underbrace{(\alpha + \beta)}_1 b$$

Why are we interested in affine sets?
allow us to deal with sets independently
of the coordinate system.



Parallel subspace

Let G be an affine set
and let $x_0 \in G$

$\left. \begin{array}{l} \text{the set} \\ V = \{v = x - x_0 \mid x, x_0 \in G\} \end{array} \right\}$
 is a subspace called
the parallel subspace.

Proof (that V is a subspace)

Assume $v_1, v_2 \in V$, we need to show that
 $a v_1 + b v_2 \in V$, $\forall a, b$.

$$v_1 = x_1 - x_0 \rightsquigarrow x_1 = v_1 + x_0 \quad x_1, x_2 \in G$$

$$v_2 = x_2 - x_0 \rightsquigarrow x_2 = v_2 + x_0$$

$$v_3 = a v_1 + b v_2 \rightsquigarrow x_3 - x_0$$

equivalently, it is sufficient to show
that $\exists x_3 \in G : x_3 = a v_1 + b v_2 + x_0$

$$= a(\underbrace{v_1 + x_0}_{x_1 \in G}) + b(\underbrace{v_2 + x_0}_{x_2 \in G}) + (1-a-b)x_0 \in G$$

affine combination $\Rightarrow \in G$

Summary

For every affine set G } parallel subspace $V = \left\{ x - x_0, \frac{x-x_0}{\in G} \right\}$

If G is affine, $G - x_0$ is a subspace.

If V is a subspace, $V + x_0$ is an affine set.

Set of solutions of linear equations

$$G = \left\{ x \mid \underbrace{\begin{matrix} Ax = b \\ m \times n \end{matrix}}_{A \in \mathbb{R}^{m \times n}} \right\} \text{ affine set}$$

① ζ' is an affine set

② Consider $x_0 \in \zeta'$

$$V = \left\{ \underbrace{x - x_0}_y \mid x \in \zeta' \right\} = N(A)$$

$$A(x - x_0) = Ax - Ax_0 = b - b = 0$$

If x_0 is any solution ($\in \zeta'$) then

any other solution can be expressed
as $x_0 + z$, $z \in N(A)$.

$$A(x_0 + z) = Ax_0 + Az^0 = b$$

③ Every affine set can be expressed
as a set of solutions of linear equations.

Procedure Given an affine set ζ'

i) construct the parallel subspace V

ii) find a matrix A , $N(A) = V$

iii) Select any $x_0 \in \zeta'$, and set

$$b = Ax_0$$

$$\zeta' = \{x \mid Ax = b\}$$

Trigonometry

$$P = \{ x \mid a_i^T x \leq b_i, \\ i=1, \dots, m \}$$

$c_i^T x = d_i \quad \left\{ \begin{array}{l} \text{intersection of} \\ \text{a finite number} \\ \text{of subspaces} \\ \text{and hyperplanes} \end{array} \right.$

$$P = \{ x \mid Ax \leq b, Cx = d \} \text{ convex}$$

$m \times n$ $k \times n$

Linearity Space

We define the linearity space of P

$\mathcal{L} = \text{nullspace} \begin{pmatrix} A \\ C \end{pmatrix} \approx \text{subspace of } \mathbb{R}^n.$

If $x \in P$, then $x + v \in P$, for all $v \in L$

$$A(x+v) = Ax + Av \in A\mathbb{R}^n = Ax \leq b$$

$$C(x+r) = Cx + Cr = Cx = d.$$

The opposite does not hold, we cannot express every point in P as $x_0 + v$, $v \in L$, $x_0 \in \underline{P}$.

the linearly space may be "empty," $\{0\}$
but the polyhedron is not empty.

Pointed Polyhedron : linearity space is $\{0\}$

it does not contain an entire line.

1) $\{x \in \mathbb{R}^2 \mid x_1 \geq 0, x_2 \geq 0\}$

$$Ax \leq b \Rightarrow \underbrace{\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}}_A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

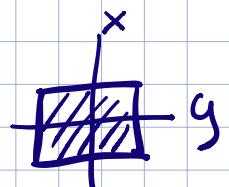
$L(A) = \{0\}$, pointed polyhedron

2) Halfspace $\{x \mid a^T x \leq b\}$

$L = \{x \in \mathbb{R}^n \mid a^T x = 0\}$ for $n \geq 2$, not a pointed polyhedron.

3) $\left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mid \underbrace{|x| \leq 1}_{x \leq 1, -x \leq 1}, \underbrace{|y| \leq 1}_{y \leq 1, -y \leq 1}, |z| \leq 1 \right\}$

$$\underbrace{\begin{pmatrix} 1 & 0 & 0 \\ -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{pmatrix}}_A \begin{pmatrix} x \\ y \\ z \end{pmatrix} \leq \begin{pmatrix} 1 \\ 1 \\ 1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$$



$N(A) = \{0\}$, pointed polyhedron

4) $\left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mid |x| \leq 1, |y| \leq 1 \right\}$

not pointed

contains $\{(0, 0, z) \mid z \in \mathbb{R}\}$

