

Students must check the number of pages in this examination paper before beginning to write, and report any discrepancy immediately.

Total marks: 75

Time allowed: 2 hours

Section A (30 marks): For each question in this section, place an X beside all answers that apply. Each question is worth 6 marks. Partial marks are not given for incomplete answers.

Question 1: For a 7-bit two's complement number in AVR:

- ☒ The maximum positive value is 0b0111111
- ☒ The most negative value is 0b1000000
- ☐ Zero can be represented as 0b0000000 or 0b1000000
- ☒ The range of values is -64 to +63
- ☐ None of the above

Question 2: Regarding AVR memory addressing:

- ☒ The Z register can be used for indirect jumps
- ☒ The Y register consists of r29:r28
- ☒ Post-increment addressing updates the pointer after accessing memory
- ☒ ld and st instructions can only use X, Y, or Z registers
- ☐ None of the above

Question 3: In the context of AVR I/O ports:

- ☐ Writing 1 to a DDRD bit makes that pin an input
- ☐ Pull-up resistors are enabled by default
- ☒ The PORTD register can be read and written
- ☒ Pin states can be read regardless of direction setting
- ☐ None of the above

Question 4: The AVR status register:

- ☒ Is automatically saved during interrupt handling
- ☒ Contains the global interrupt enable bit
- ☒ Is modified by arithmetic and logic instructions
- ☒ Can be directly copied to a general-purpose register
- ☐ None of the above

Question 5: For AVR branch instructions:

- ☒ Branch targets must be within -64 to +63 words of the branch
- ☐ Multiple conditions can be tested in a single branch
- ☒ rjmp has a greater range than breq
- ☒ Branch instructions are two bytes long
- ☐ None of the above

## Section B (25 marks): Short Answer Questions

Question 6 (5 marks):

Explain how the AVR hardware stack operates during an interrupt service routine, including register preservation and return address handling.

*When an interrupt occurs:*

1. Program counter pushed onto stack
2. Global interrupt flag cleared
3. Status register automatically pushed
4. Jump to interrupt vector
5. ISR must save/restore used registers

Question 7 (5 marks):

Describe the purpose of the AVR status register's H (half-carry) flag and when it becomes relevant in arithmetic operations.

*H flag indicates carry from bit 3 to bit 4. Used in BCD arithmetic operations. Set when carry occurs from lower nibble to upper nibble during addition, or when borrow occurs during subtraction. Essential for decimal arithmetic adjustments.*

Question 8 (5 marks):

Compare direct and indirect addressing modes in AVR assembly, explaining their advantages and typical use cases.

*Direct addressing: Immediate operand access, fixed memory locations, simple and fast.*

*Indirect addressing: Flexible pointer-based access, arrays/data structures, dynamic memory access.*

*X/Y/Z registers enable pre/post increment/decrement modes.*

*Direct for static data, indirect for arrays and dynamic structures.*

Question 9 (5 marks):

Explain how the AVR processor handles the overflow flag (V) in signed arithmetic operations. Provide specific examples.

*V flag set when signed overflow occurs:*

- *Addition: operands same sign, result opposite sign*
- *Subtraction: operand signs different, result same sign as subtrahend*

*Used with signed branch instructions (BRLT, BRGE)*

*Critical for signed arithmetic validity checking*

Question 10 (5 marks):

Describe the function and importance of the linker command file in AVR program development.

*Linker command file*

- *Defines memory layout and sections*
- *Maps program sections to memory regions*
- *Specifies start address and stack location*
- *Controls placement of code and data segments*
- *Essential for proper memory allocation*

## **Section C (20 marks): Assembly Programming Problems**

Question 11 (4 marks):

Write AVR assembly code to swap the contents of two memory locations without using any general-purpose registers.

```
lds r16, ADDR1      ; Load first value  
lds r17, ADDR2      ; Load second value  
sts ADDR1, r17      ; Store second value to first address  
sts ADDR2, r16      ; Store first value to second address
```

Question 12 (4 marks):

Write code to configure Timer1 for PWM operation on OC1A (Port B, pin 1) with a frequency of 50Hz.

```
ldi r16, (1<<WGM11)|(1<<COM1A1)
sts TCCR1A, r16
ldi r16, (1<<WGM12)|(1<<CS11)|(1<<CS10)
sts TCCR1B, r16
ldi r16, HIGH(ICR1_VALUE)
sts ICR1H, r16
ldi r16, LOW(ICR1_VALUE)
sts ICR1L, r16
```

Question 13 (4 marks):

Write an interrupt service routine for External Interrupt 0 that toggles all bits in PORTB while preserving all register values.

```
ISR_INT0:
    push r16
    in r16, SREG
    push r16
    in r16, PORTB
    com r16
    out PORTB, r16
    pop r16
    out SREG, r16
    pop r16
    reti
```

Question 14 (4 marks):

Write assembly code to perform a 16-bit addition of values stored in SRAM at addresses DATA1 and DATA2, storing the result at address RESULT.

```
lds r16, DATA1
lds r17, DATA1+1
lds r18, DATA2
lds r19, DATA2+1
add r16, r18
adc r17, r19
sts RESULT, r16
sts RESULT+1, r17
```

Question 15 (4 marks):

Write code to rotate an 8-bit value in r16 right by the number of positions specified in r17, preserving the original value in r16.

```
mov r18, r16      ; Save original value  
loop:  
    tst r17        ; Check count  
    breq done      ; Exit if zero  
    lsr r16        ; Rotate right  
    dec r17        ; Decrement count  
    rjmp loop      ; Repeat  
done:  
    nop
```