

MTH712

# Assignment 1

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I hereby declare that I am the sole author of this work.

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$$\begin{aligned} \text{Given, } \quad \frac{\partial u}{\partial t} &= \frac{\partial^2 u}{\partial x^2} - rx, \quad 0 < x < L \quad t > 0 \\ \text{and BC: } \quad \frac{\partial u}{\partial x}(0, t), \quad \frac{\partial u}{\partial x}(L, t) &= \alpha, \\ \text{Where, } r \text{ and } \alpha &\text{ are constants.} \end{aligned}$$

a)

The corresponding time independent problem is:

$$\begin{aligned} 0 &= \frac{\partial^2 u}{\partial x^2} - rx, \quad 0 < x < L \\ \text{with BC: } \quad \frac{\partial u}{\partial x}(0) &= 0, \quad \frac{\partial u}{\partial x}(L) = \alpha \end{aligned}$$

$$\begin{aligned} \text{Now, } \quad \int rxdx &= \int \frac{\partial^2 u}{\partial x^2} dx \\ \frac{\partial u}{\partial x} &= \frac{rx^2}{2} + K \end{aligned}$$

$$\text{So, } \quad \frac{\partial u}{\partial x}(0) \implies \frac{r(0)^2}{2} + K = 0 \quad \text{ie, } K = 0$$

$$\text{And, } \quad \frac{\partial u}{\partial L} \implies \frac{rL^2}{2} = \alpha$$

$$\text{Now, for a solution to exist, we must have } r = \frac{2\alpha}{L^2}$$

$$\text{Hence, the general solution is, } \quad \frac{\partial u}{\partial x} = \frac{\alpha x^2}{L^2}$$

$$\text{and, } U_E(X) = \int \frac{\partial u}{\partial x} dx = \int \frac{\alpha x^2}{L^2} dx = \frac{\alpha x^3}{3L^2} + K_2$$

b)

From the previous relationship,  $U(x, 0) = f(x)$ ,  $0 < x < L$

$$\begin{aligned}\int_0^L \frac{\partial u}{\partial t} dx &= \int_0^L \frac{\partial^2 u}{\partial x^2} dx - \frac{\alpha x^2}{L^2} \Big|_0^L \quad \text{from } r = \frac{2\alpha}{L^2} \\ &= \left( \frac{\partial u}{\partial x}(L, t) - \frac{\partial u}{\partial x}(0, t) \right) - \left( \frac{\alpha L^2}{L^2} - \frac{\alpha(0)^2}{L^2} \right) \\ &= \alpha - 0 - \alpha - 0 = 0\end{aligned}$$

$$\text{Now, } \frac{d}{dt} \int_0^L U(x, t) dx = 0, \quad t > 0$$

$$\text{So, } \int_0^L U(x, t) dx = P \quad , \text{ where } P \text{ is a constant}$$

$$\begin{aligned}\text{And, } \int_0^L U(x, t) dx &= \int_0^L U_E(X) dx = \int_0^L \left( \frac{\alpha x^3}{3L^2} + K_2 \right) dx \\ &= \left[ \frac{\alpha x^4}{12L^2} + K_2 x \right]_0^L\end{aligned}$$

$$\text{Hence, } \int_0^L f(x) dx = \frac{\alpha L^4}{12L^2} + K_2 L$$

$$\text{And the steady-state solution is } U_E(x) = \frac{\alpha x^3}{3L^2} + \frac{1}{L} \int_0^L f(x) dx - \frac{\alpha}{12}$$

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$$f(x) = \begin{cases} x & \text{if } -2 < x < 0 \\ 1+x & \text{if } 0 < x < 2 \end{cases}$$

$$g(y) \approx a_0 + \sum_{n=1}^{\infty} (a_n \cos \lambda_n(y) + b_n \sin \lambda_n(y))$$

Let  $f(x)$  denote  $g(y)$  in terms of  $x$  and,  $y = \frac{a+b}{2} + \frac{b-a}{2L}x$

$$\text{So, } f(x) \approx a_0 + \sum_{n=1}^{\infty} \left( a_n \cos \left( \frac{n\pi}{L}x \right) + b_n \sin \left( \frac{n\pi}{L}x \right) \right)$$

$$\begin{aligned} \text{Now, } a_0 &= \frac{1}{2L} \int_{-L}^{-L} f(x) dx = \frac{1}{2L} \int_{-L}^L \left( \frac{a+b}{2} + \frac{b-a}{2L}x \right) dx \\ &= \frac{1}{2L} \left[ \frac{a+b}{2}x + \frac{b-a}{4L}x^2 \right]_{x=-L}^{x=L} \\ &= \frac{1}{2L} L(a+b) = \frac{a+b}{2} \end{aligned}$$

$$\begin{aligned} \text{and, } a_n &= \frac{1}{L} \int_{-L}^L \left( \frac{a+b}{2} + \frac{b-a}{2L}x \right) \cos \left( \frac{n\pi}{L}x \right) dx \\ &= \end{aligned}$$