Tutorial 3 (part 2)

Install these packages first

```
Pkg.add("QuadGK")

Pkg.add("Roots")

Pkg.add("Optim")

Pkg.add("Expectations")
```

Topic 1: Integration and Expectations

Integration

$$\int_0^\infty e^{-\frac{1}{2}x^2} dx$$

Will return two things: value and s.d. for the value. The value is 1.000000000032583.

```
begin
using QuadGK
f1(x) = exp(-x^2 / 2) / sqrt(2*pi)
q = quadgk(f1, -Inf, Inf)

md"Will return two things: value and s.d. for the value.
The value is $(q[1])."
end
```

Expectations

0.99999999999984

```
begin
using Expectations

dist1_1 = Normal(0, 1)
E1_1 = expectation(dist1_1)

f1_1(x) = x^2
exp_value1_1 = E1_1(x -> f1_1(x))
end
```

Comparison between integration and expectation

max(0, X - D)

80.91701244547619

```
begin
dist1_2 = Normal(100, 10^2)
E1_2 = expectation(dist1_2)

D1_2 = 35
f1_2(x) = max(0, x - D1_2)
exp_value1_2 = E1_2(x -> f1_2(x))
end
```

```
(80.5372, 6.3756e-7)

• begin
• f1_3(x) = f1_2(x) * pdf(dist1_2, x)
• quadgk(f1_3, D1_2, Inf)
• end
```

Topic 2: Finding the intersection of two function

```
[-4.0, 1.0]

• begin

• using Roots

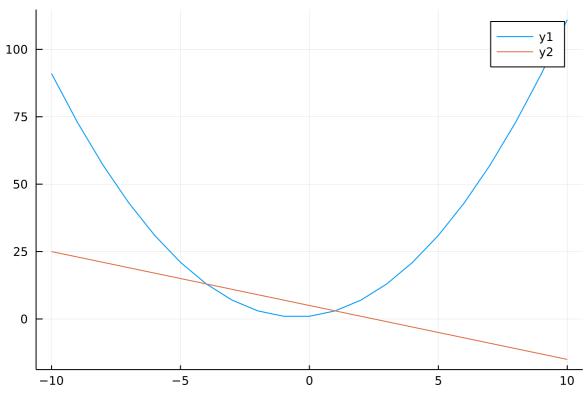
• g1(x) = x^2 + x + 1

• g2(x) = -2*x + 5

• delta(x) = g1(x) - g2(x)

• find_zeros(delta, -30, 30)

• end
```



```
begin
using Plots

x_scale = (-10):10
plot(x_scale, [g1,g2])
end
```

Topic 3: Find The Minimization Point for a Function

Rule:

- (1) Define a function (topic3, here)
- (2) Use "Optimize" function (function, lower bound, upper bound, algorithm)

```
Results of Optimization Algorithm
  * Algorithm: Brent's Method
  * Search Interval: [-20.000000, 20.000000]
  * Minimizer: -5.000000e-01
  * Minimum: 7.500000e-01
  * Iterations: 5
  * Convergence: max(|x - x_upper|, |x - x_lower|) <= 2*(1.5e-08*|x|+2.2e-16): true
  * Objective Function Calls: 6

  begin
     using Optim
     topic3(x) = x^2 + x + 1
     opt = optimize(topic3, -20, 20, Brent())
  end</pre>
```

optimal x = -0.5, optimal f = 0.75

Topic 4: Approximation

(1) Expected-Inventory-Level Approximation

$$egin{aligned} Q &= \sqrt{rac{2\lambda(K+pn(r))}{h}} \ & r = F^{-1}(1-rac{Qh}{p\lambda}) \ & g(r,Q) = h(r-\lambda L + rac{Q}{2}) + rac{K\lambda}{Q} + rac{p\lambda n(r)}{Q} \ & E[(D-r)^+] = \int_r^\infty (d-r)f(d)dd = n(r) \end{aligned}$$

EIL (generic function with 1 method)

```
begin
      function EIL(K, lambda, h, p, L, eplison, dist)
          theo_Q = sqrt(2 * K * lambda / h)
         pre_0 = 0
         new_Q = theo_Q
         pre_r = 0
          new_r = quantile(dist, 1 - theo_Q*h / (p*lambda))
          # when the difference between previous Q and new Q or the difference
          # between previous r and new Q is not larger than eplison, the loop should
          # stop and return the best_Q and best_r
          while((abs(new_Q - pre_Q) >= eplison) & (abs(new_r - pre_r) >= eplison))
             pre_Q = new_Q
             pre_r = new_r
              f(d) = (d - new_r) * pdf(dist, d)
             n_r = quadgk(f, new_r, Inf)[1]
             new_Q = sqrt(2 * lambda * (K + p*n_r) / h)
             new_r = quantile(dist, 1 - new_Q*h / (p*lambda) )
              if new_r < 0
                  new_r = 0
              end
          end
         cost = h * (new_r - lambda*L + new_Q/2) + K * lambda / new_Q + p * lambda *
 n_r / new_Q
          return new_Q, new_r, cost
     end
 end
```

```
beginusing Distributions
```

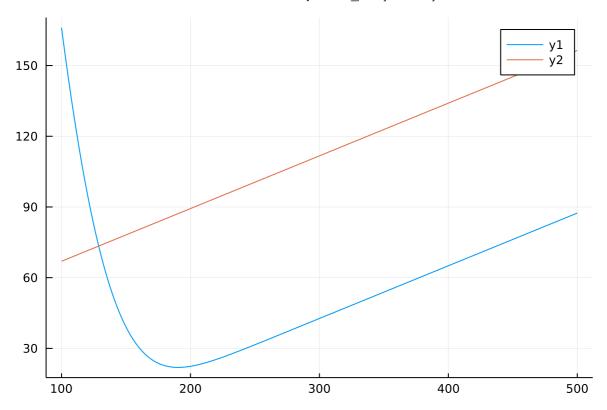
```
K1 = 8
lambda1 = 1300
h1 = 0.225
p1 = 7.5
L1 = 1/12
eplison1 = 0.05
mu1 = 1300/12
sigma1 = 150/sqrt(12)
dist1 = Normal(mu1, sigma1)
end
```

(318.555, 213.972, 95.4436)

(2) EOQ with Backorder Approximation

$$Q^* = \sqrt{rac{2K\lambda(h+p)}{hp}}$$
 $x^* = rac{h}{h+p}$ $g(S) = h\int_0^S (S-d)f(d)dd + p\int_S^\infty (d-S)f(d)dd$

To get the reorder point, we need to solve the equation g(r)=g(Q+r)



EOQB (generic function with 1 method)

```
begin
    function EOQB(K, lambda, h, p, dist)
        theo_Q = sqrt(2 * K * lambda * (h + p) / (h * p))

function g(s)
    f1(x) = (s - x) * pdf(dist, x)
    f2(x) = (x - s) * pdf(dist, x)

return h*quadgk(f1, 0, s)[1] + p*quadgk(f2, s, Inf)[1]
end

delta(r) = g(theo_Q + r) - g(r)

r_star = find_zeros(delta, 100, 500)

return theo_Q, r_star
end
end
```

EOQB2 (generic function with 1 method)

end

Distributions.Normal{Float64}(μ =108.333333333333, σ =43.30127018922194)

```
begin
    K2 = 8
    lambda2 = 1300
    p2 = 7.5
    h2 = 0.225
    mu2 = 1300/12
    sigma2 = 150/sqrt(12)
    dist2 = Normal(mu2, sigma2)
end
```

```
(308.574, [128.812])
• EOQB(K2, lambda2, h2, p2, dist2)

(308.574, [129.049])
```

EOQB2(K2, lambda2, h2, p2, dist2)

(3) EOQ+SS Approximation

For the parameter setting, check Example 5.5

$$Q=\sqrt{rac{2K\lambda}{h}}$$
 $r=\mu+z_{lpha}\sigma$ $lpha=rac{p}{p+h}$

EOQ_SS (generic function with 1 method)

```
function EOQ_SS(K, lambda, h, p, mu, sigma)
    theo_Q = sqrt(2 * K * lambda / h)

alpha = p / (p + h)
    r = mu + sigma * quantile(Normal(0, 1), alpha)

function g(s)
    dist = Normal(mu, sigma)
    f1(x) = (s - x) * pdf(dist, x)
    f2(x) = (x - s) * pdf(dist, x)

return h*quadgk(f1, 0, s)[1] + p*quadgk(f2, s, Inf)[1]
end

return theo_Q, r
end
```

```
begin

K3 = 8

lambda3 = 1300

p3 = 7.5

h3 = 0.225

mu3 = 1300/12

sigma3 = 150/sqrt(12)

end
```

```
(304.047, 190.337)
• EOQ_SS(K3, lambda3, h3, p3, mu3, sigma3)
```

(4) Loss Function Approximation

For the parameter setting, check Example 5.6

$$g(r,Q) = rac{K\lambda}{Q} + h(rac{Q}{2} + r - \lambda L) + (h+p)B(r,Q)$$
 $B(r,Q) = rac{1}{Q}[n^{(2)}(r) - n^{(2)}(r+Q)]$
 $Q = \sqrt{rac{2[K\lambda + (h+p)n^{(2)}(r)]}{h}}$
 $n^{(2)}(x) = rac{1}{2}E[([X-x]^+)^2] = \int_x^\infty n(y)dy$
 $n(r) = \int_r^\infty (d-r)f(d)dd$

And to solve r, you need to solve the equation $n(r)=rac{hQ}{h+v}$

Loss_Approximation (generic function with 1 method)

```
function Loss_Approximation(K, lambda, h, p, L, dist, eplison)
theo_Q = sqrt(2 * K * lambda / h)

function n(r)
    f(d) = (d - r) * pdf(dist, d)
    return quadgk(f, r, Inf)[1]
end

# to solve r
pre_r = 0
lambda_out(x) = n(x) - h*theo_Q/(h+p)
new_r = find_zeros(lambda_out, 100, 500)[1]

# to solve Q
n_2 = quadgk(n, new_r, Inf)[1]
pre_Q = 0
```

```
new_Q = sqrt(2 * (K * lambda + (h + p) * n_2) / h)

while((abs(new_Q - pre_Q) >= eplison) & (abs(new_r - pre_r) >= eplison))

pre_Q = new_Q

pre_r = new_r

lambda_inside(x) = n(x) - h*new_Q/(h+p)

new_r = find_zeros(lambda_inside, 100, 500)[1]

n_2 = quadgk(n, new_r, Inf)[1]

new_Q = sqrt(2 * (K * lambda + (h + p) * n_2) / h)

end

#cost = K*lambda/new_Q + h*(new_Q/2 + new_r - lambda*L) + (h+p)/new_Q*n_2

return new_Q, new_r

end
```

Distributions.Normal{Float64}(μ =108.333333333333, σ =43.30127018922194)

```
begin

K4 = 8
lambda4 = 1300
h4 = 0.225
p4 = 7.5
L4 = 1/12
eplison4 = 0.05
mu4 = 1300/12
sigma4 = 150/sqrt(12)
dist4 = Normal(mu4, sigma4)
end
```

```
(328.448, 126.868)

• Loss_Approximation(K4, lambda4, h4, p4, L4, dist4, eplison4)
```

Algorithm 5.2

For detailed algorithm, check it on p.172 of your textbook

$$g(r,Q) = rac{K\lambda}{Q} + h(rac{Q}{2} + r - \lambda L) + (h+p)B(r,Q)$$
 $B(r,Q) = rac{1}{Q} \int_r^{r+Q} E[(D-y)^+] dy$
 $H(Q) = g(r(Q)) = g(r(Q) + Q)$
 $A(Q) = QH(Q) - \int_0^Q H(y) dy$
 $Q_d^* = \sqrt{rac{2K\lambda(h+p)}{hp}}$
 $H_0(Q) = H(Q) - g(S^*)$

```
\mathbb{Q} tutorial3_part2.jl - Pluto.jl g(y) = hE[(y-D)^+] + pE[(D-y)^+]
```

and Q_0 is the Q that satisfies $QH_0(Q)=2K\lambda$, S^* is the minimizer of g(y)

algorithm5_2 (generic function with 1 method)

```
begin
      function algorithm5_2(K, lambda, h, p, dist, eplison)
          Q_l = sqrt(2 * K * lambda * (h + p) / (h * p))
          function g(s)
              f1(x) = (s - x) * pdf(dist, x)
              f2(x) = (x - s) * pdf(dist, x)
              return h*quadgk(f1, 0, s)[1] + p*quadgk(f2, s, Inf)[1]
          end
          function H(q0)
              diff(r) = g(r) - g(r + q0)
              r_value = find_zeros(diff, -500, 500)[1]
              return g(r_value)
          g_star = optimize(g, -500, 500, Brent()).minimum
          H_0(q1) = H(q1) - g_star
          H_eq(q2) = q2 * H_0(q2) - 2 * K * lambda
          Q_u = find_zeros(H_eq, 0.1, 800)[1]
          A = typemax(Int64)
          Q = typemax(Int64)
          r = typemax(Int64)
          while(abs(A - K*lambda) > eplison)
              Q = (Q_u + Q_l) / 2
              diff2(x) = g(x) - g(Q + x)
              r = find_zeros( diff2, -500, 500)[1]
              A = Q * H(Q) - quadgk(H, 0.001, Q)[1]
              if A > K * lambda
                  Q_u = Q
              else
                  Q_l = Q
              end
          end
          return Q, r
      end
 end
```

Distributions.Normal{Float64}(μ =108.333333333333, σ =43.30127018922194)

```
begin
K5 = 8
lambda5 = 1300
h5 = 0.225
p5 = 7.5
eplison5 = 2
mu5 = 1300/12
sigma5 = 150/sqrt(12)
dist5 = Normal(mu5, sigma5)
```

```
(329.384, 126.963)

• algorithm5_2(K5, lambda5, h5, p5, dist5, eplison5)
```

Algorithm 5.3

For detailed algorithm, check it on p.179 of your textbook

And the for the parameter setting you can check Example 5.8

$$g(r,Q) = rac{K\lambda + \sum_{y=r+1}^{r+Q} g(y)}{Q}$$
 $g(y) = hE[(y-D)^+] + pE[(D-y)^+]$

where S^* minimizes g(y)

algorithm5_3 (generic function with 1 method)

```
function algorithm5_3(K, lambda, h, p, dist)
      Q = 1
      S_star = 0
      while(cdf(dist, S_star) < (p/(p+h)))</pre>
          S_star = S_star + 1
      end
      r = S_star - 1
      function g(x)
          appro_bound = 10
          n = h * sum((x .- [j for j in 0:x]) .*
          pdf.(dist, [j for j in 0:x]))
          n_bar = p * sum(([j for j in x:(appro_bound*lambda)] .- x) .*
          pdf.(dist, [j for j in x:(appro_bound*lambda)]))
          return n + n_bar
      end
      function f(\mathbf{r}, \mathbf{Q})
          sum = 0
          for i in (r+1):(r+Q)
              sum = sum + g(i)
          return sum
      end
      g_pre = K*lambda/Q + f(r, Q)/Q
      r_pre = r
      while(true)
          if g(r_pre) < g(r_pre + Q + 1)
              r_new = r_pre - 1
              r_new = r_pre
          g_new = (f(r_new, Q+1) + K*lambda)/(Q+1)
          if g_new > g_pre
              break
              Q = Q + 1
```

```
g_pre = g_new
r_pre = r_new
end

return r_pre, Q, g_pre
end
```

Distributions.Poisson{Float64}(λ =3.0)

```
begin
K6 = 100
lambda6 = 1.5
h6 = 20
p6 = 150
L6 = 2
dist6 = Poisson(lambda6*L6)
end
```

```
(3, 5, 107.923)
- algorithm5_3(K6, lambda6, h6, p6, dist6)
```