

Exam review

CS 261 Lab #10

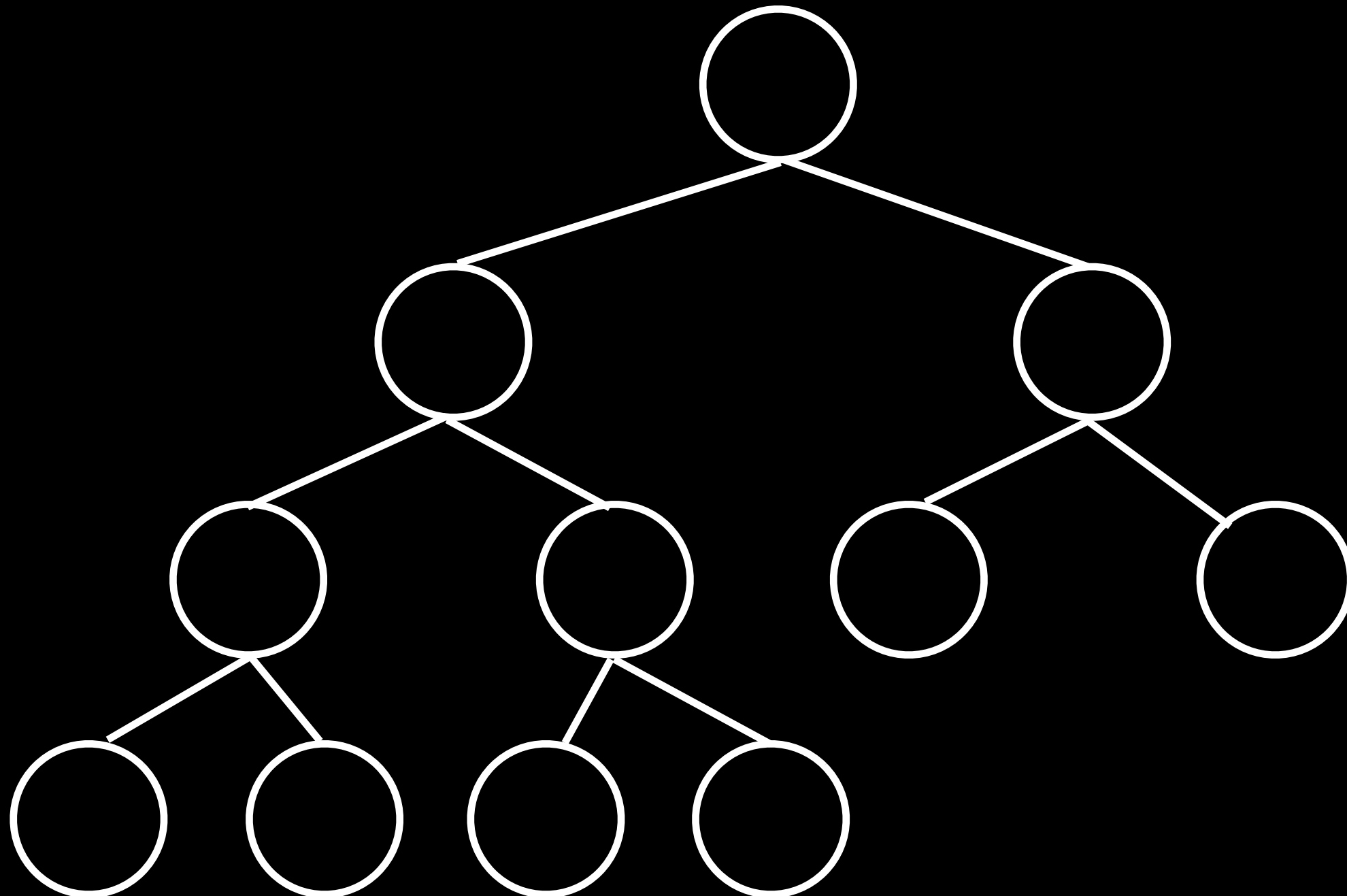
The exam will be **comprehensive**
(so don't forget to review the midterm slides!)

Similar style as midterm
(multiple choice, matching, true/false, code)

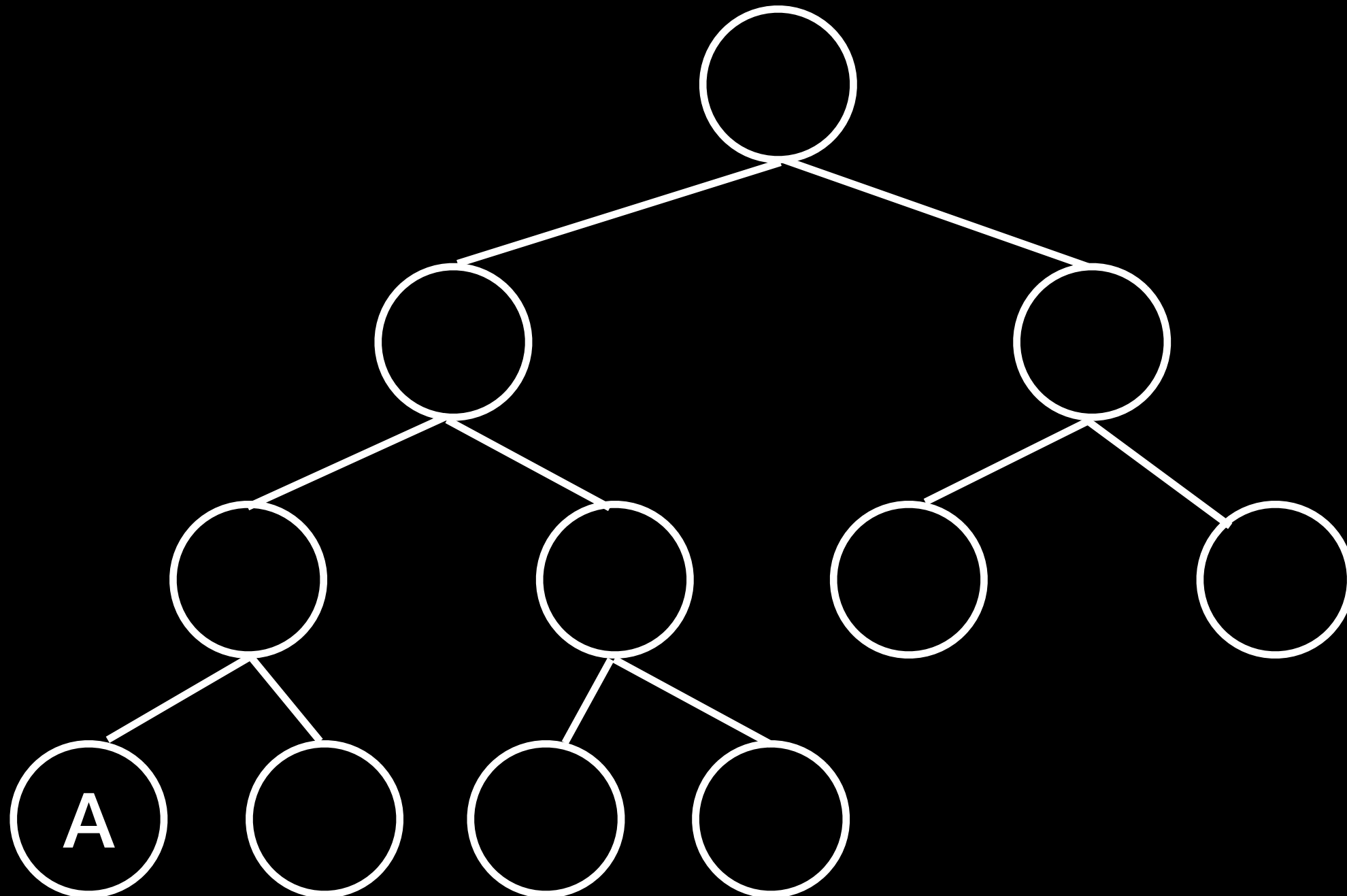
This review will focus on **trees, heaps,**
hash tables, and graphs

Draw a **complete binary search tree**
that contains the following letters:
A, B, C, D, E, F, G, H, I, J, K

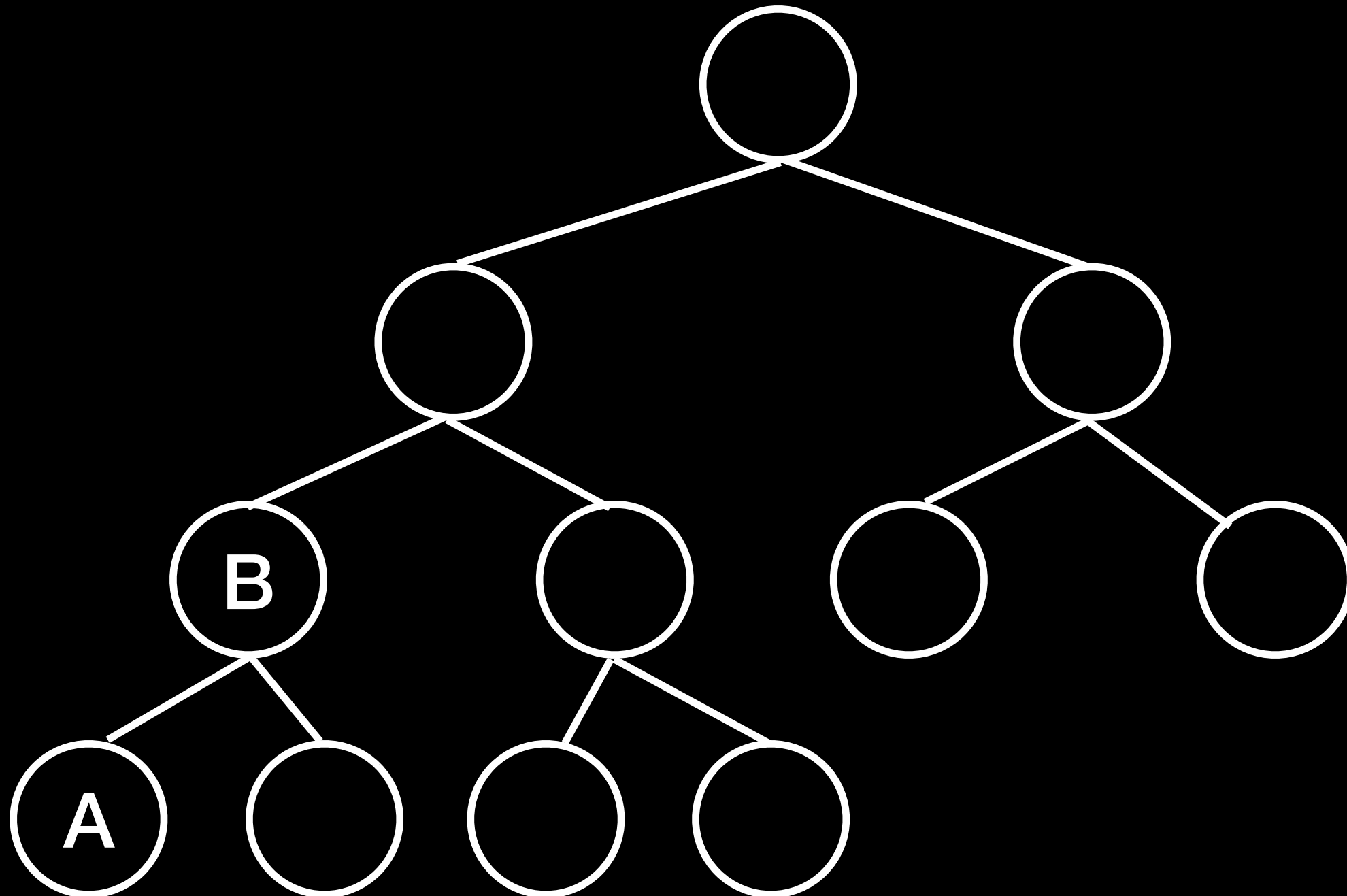
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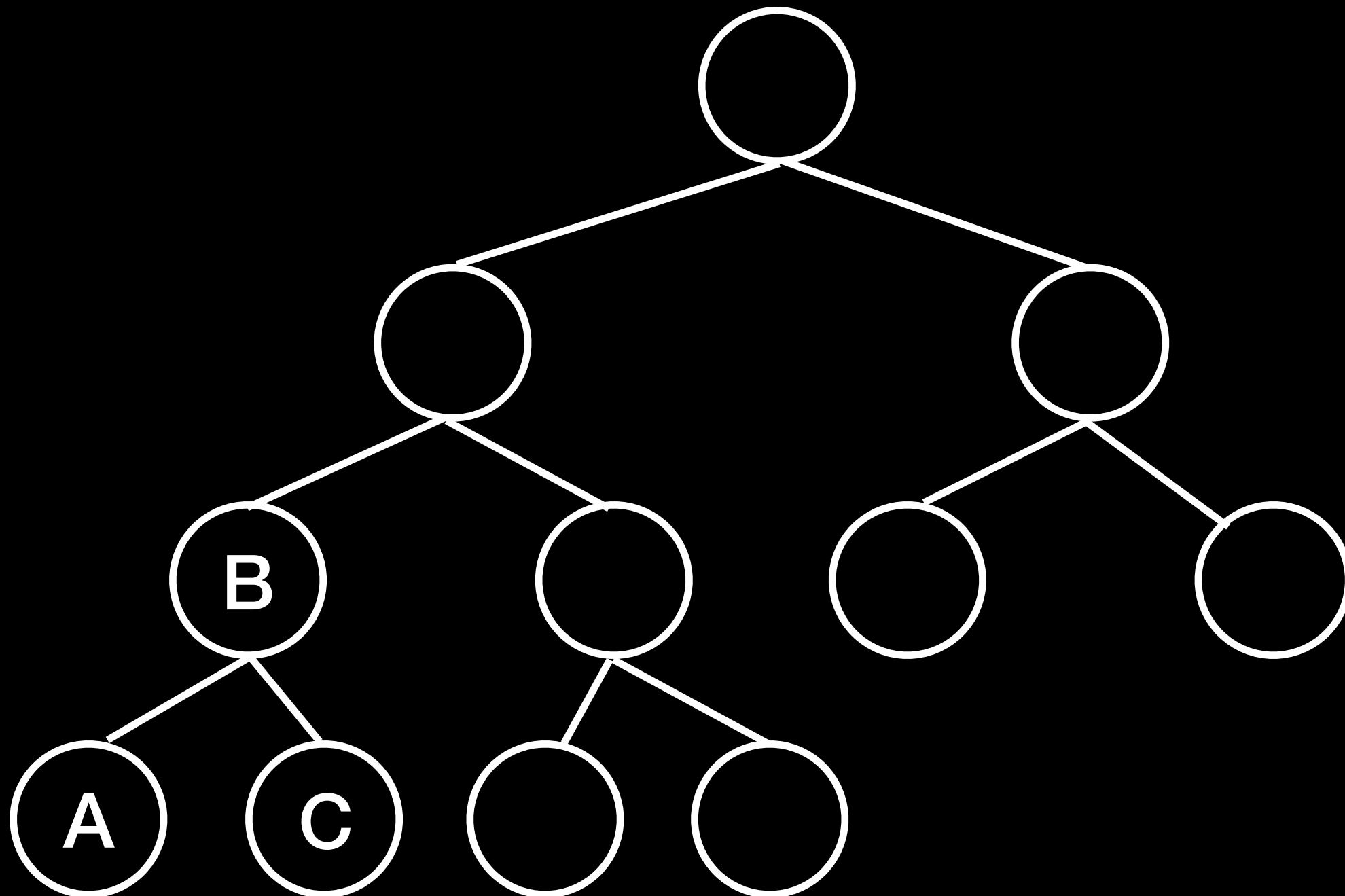
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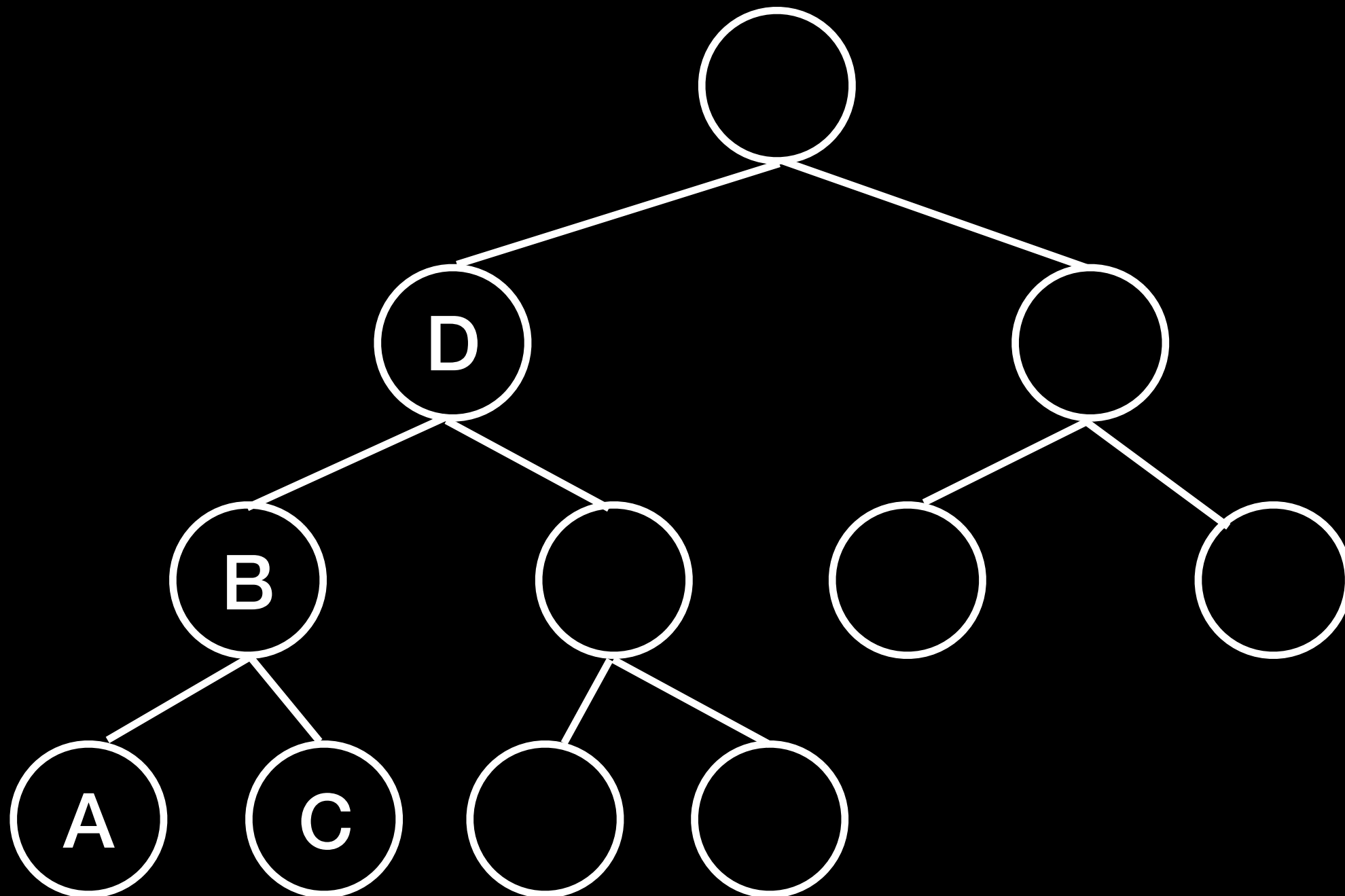
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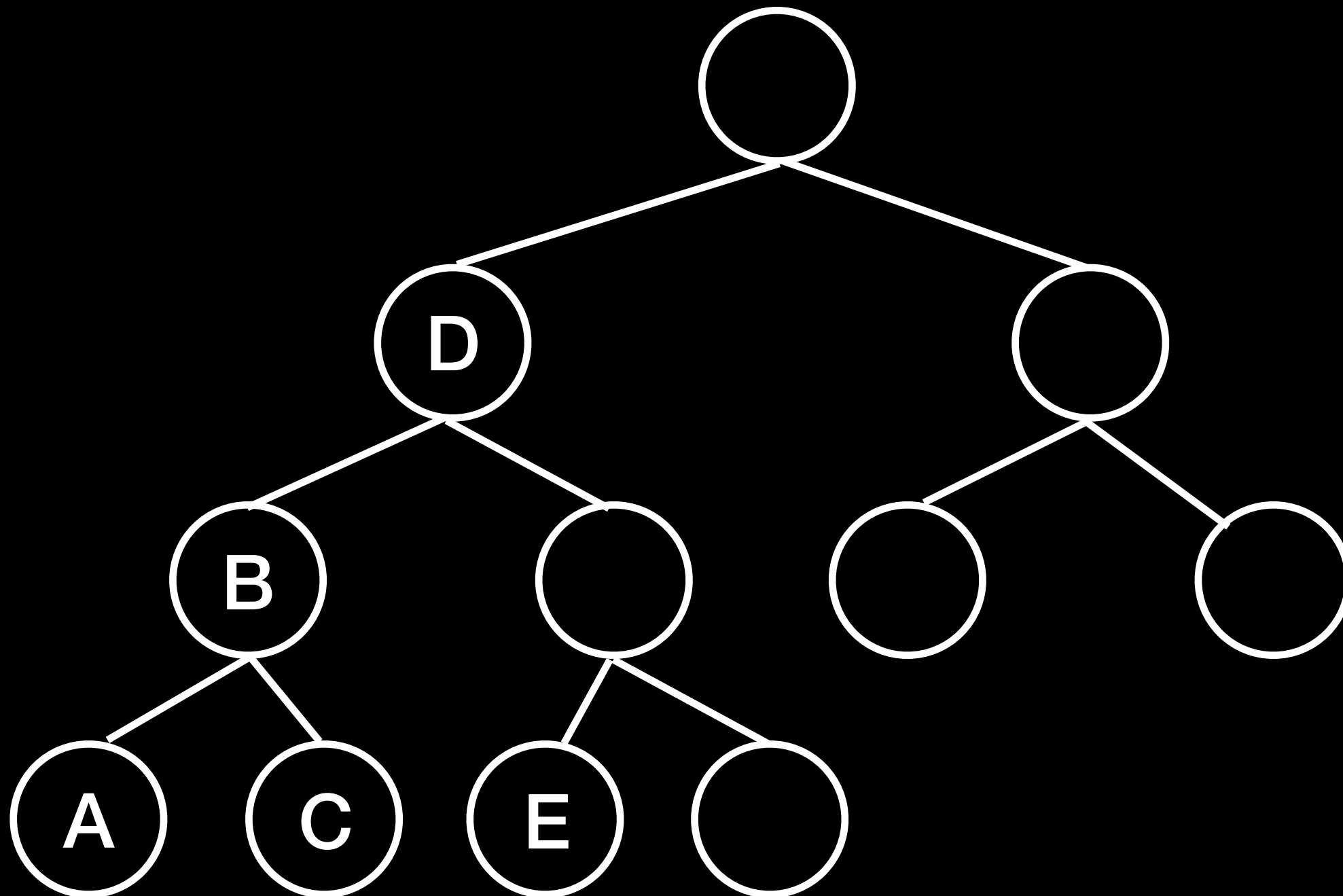
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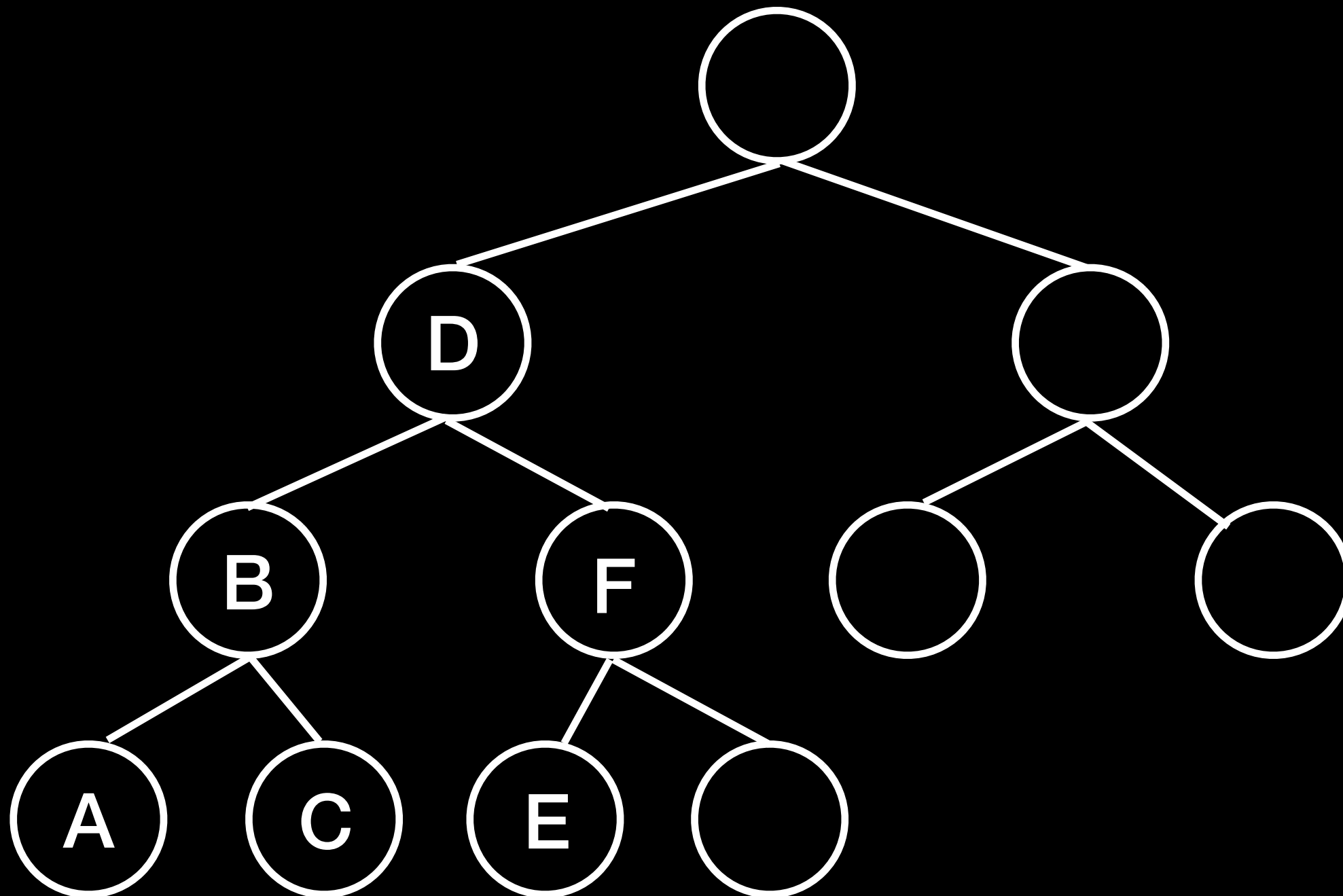
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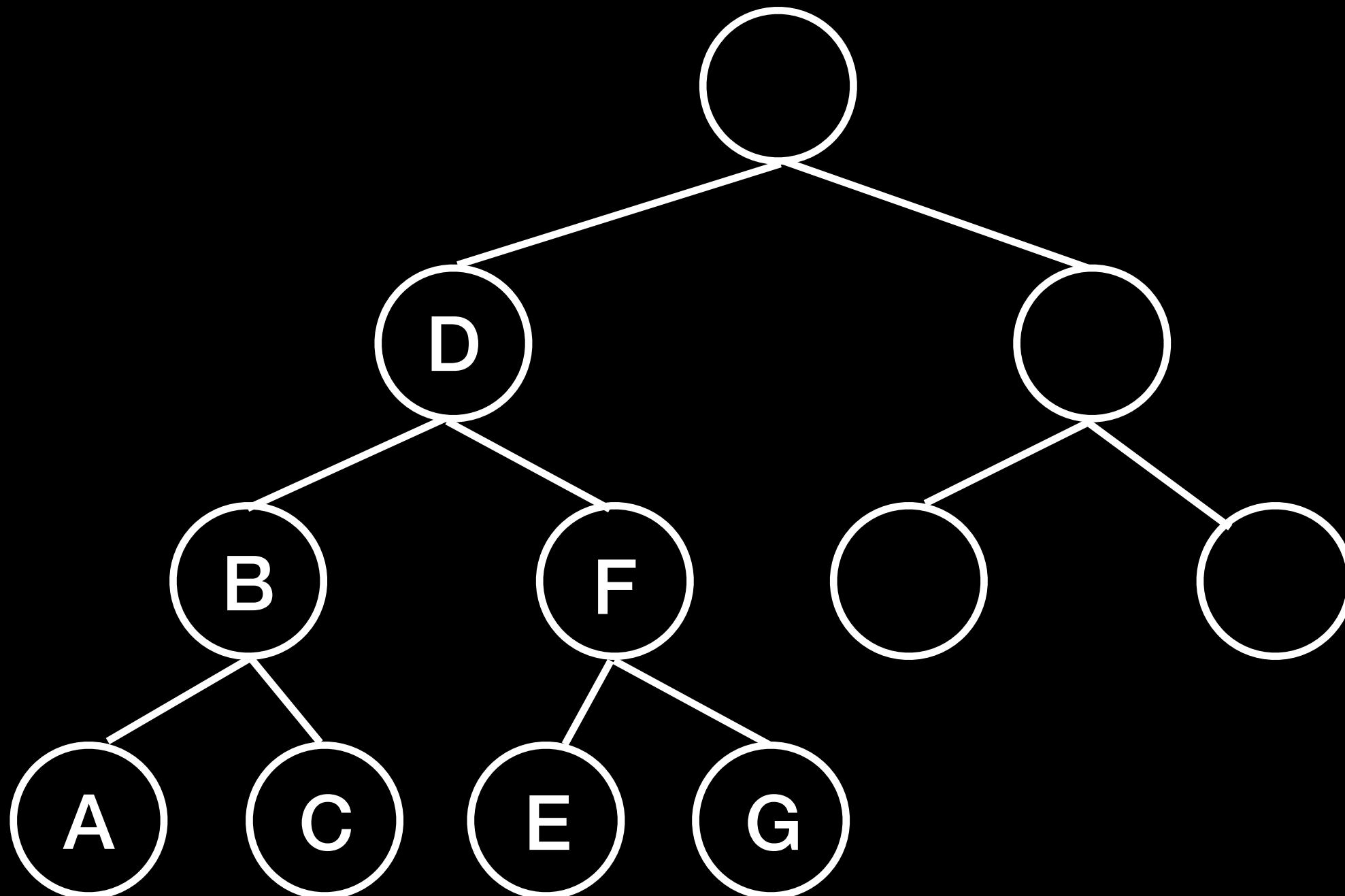
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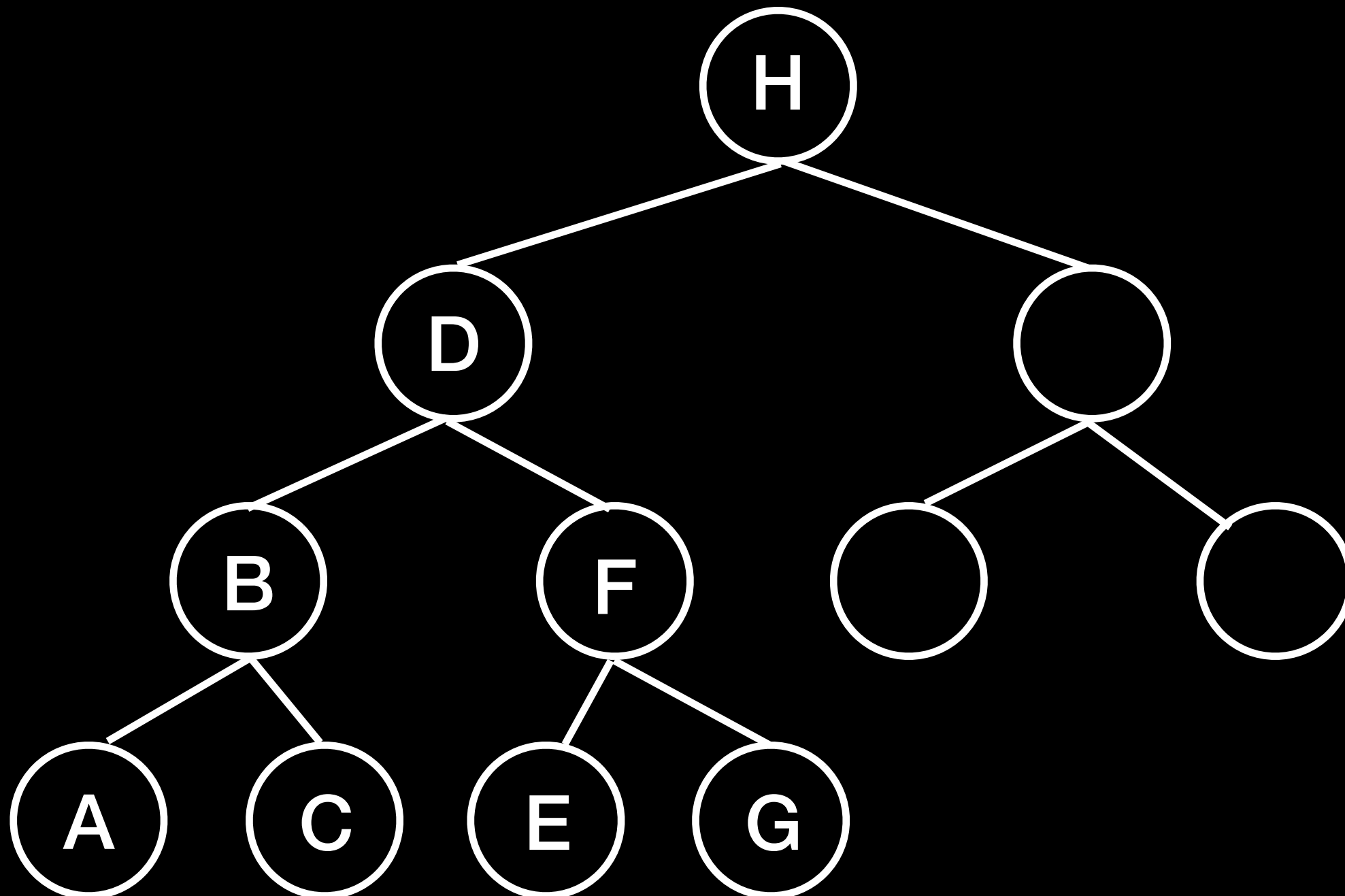
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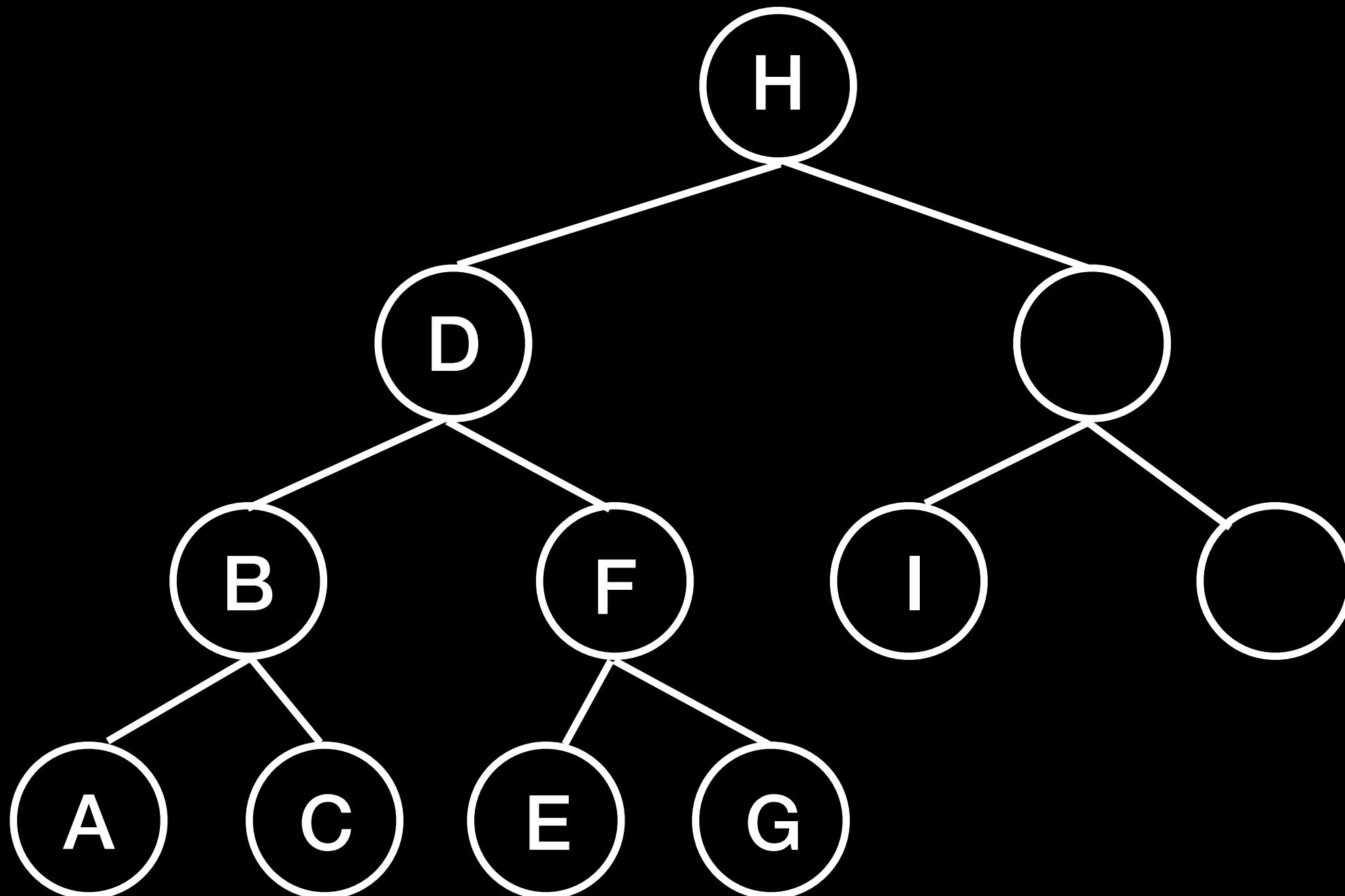
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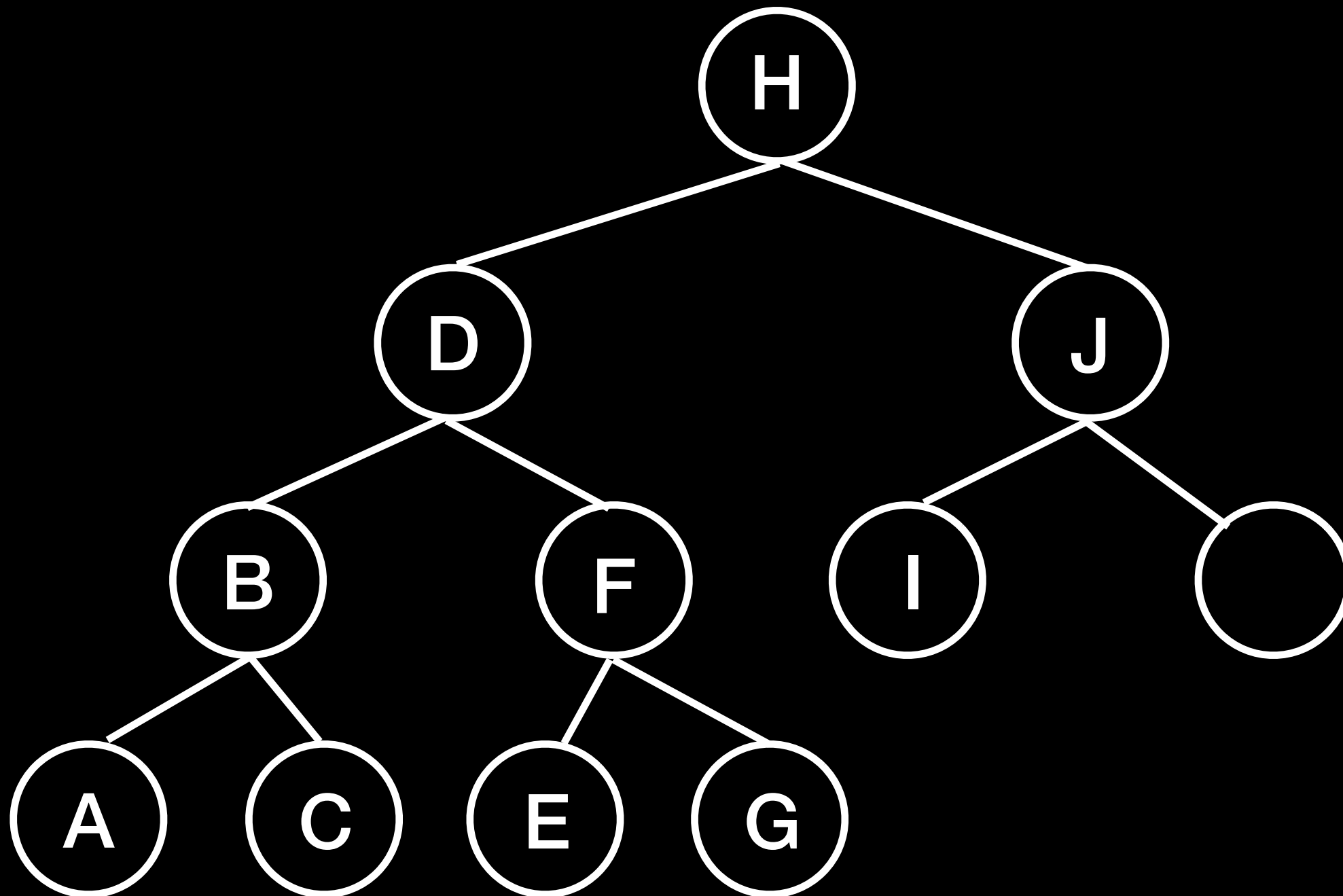
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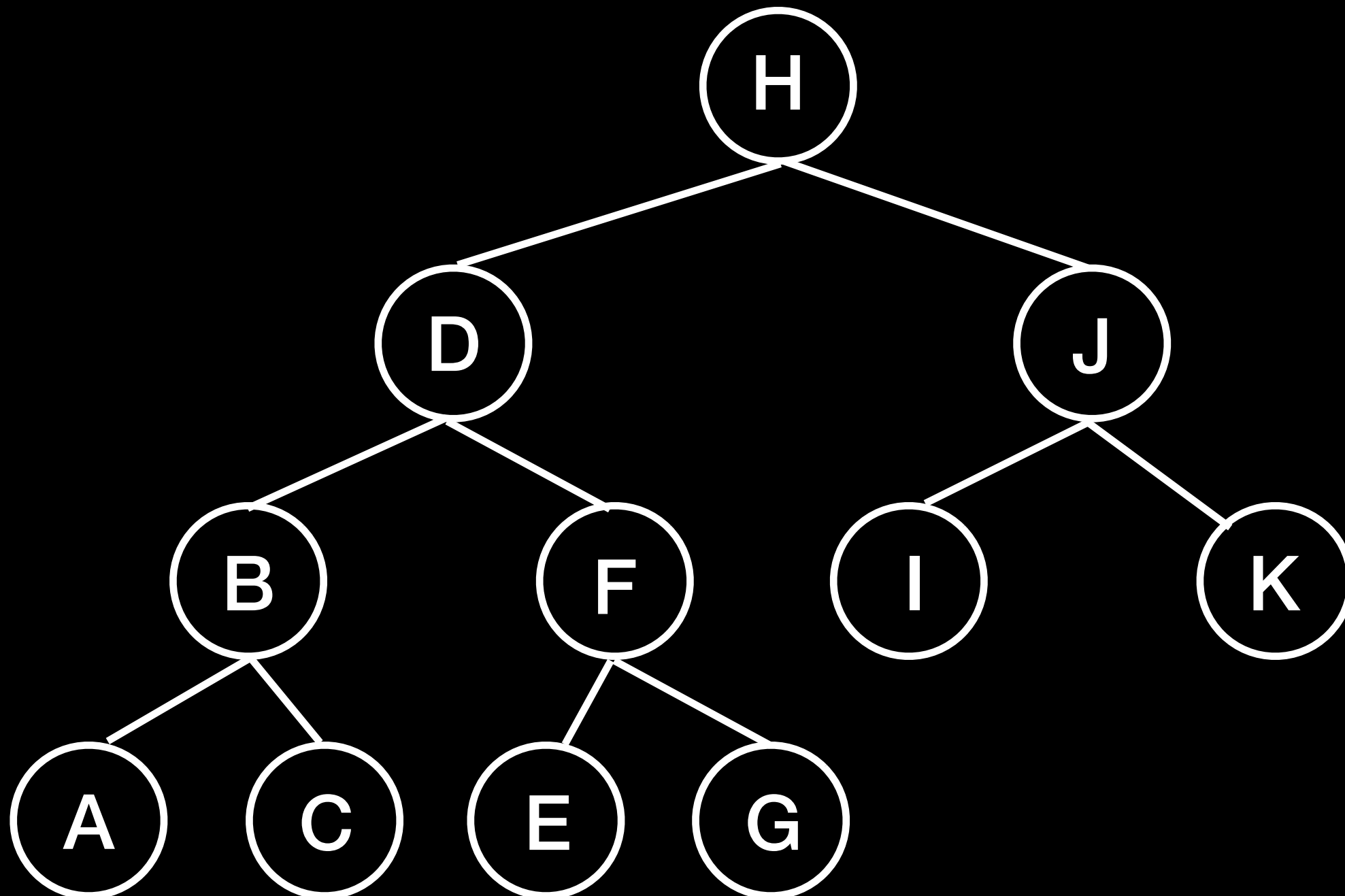
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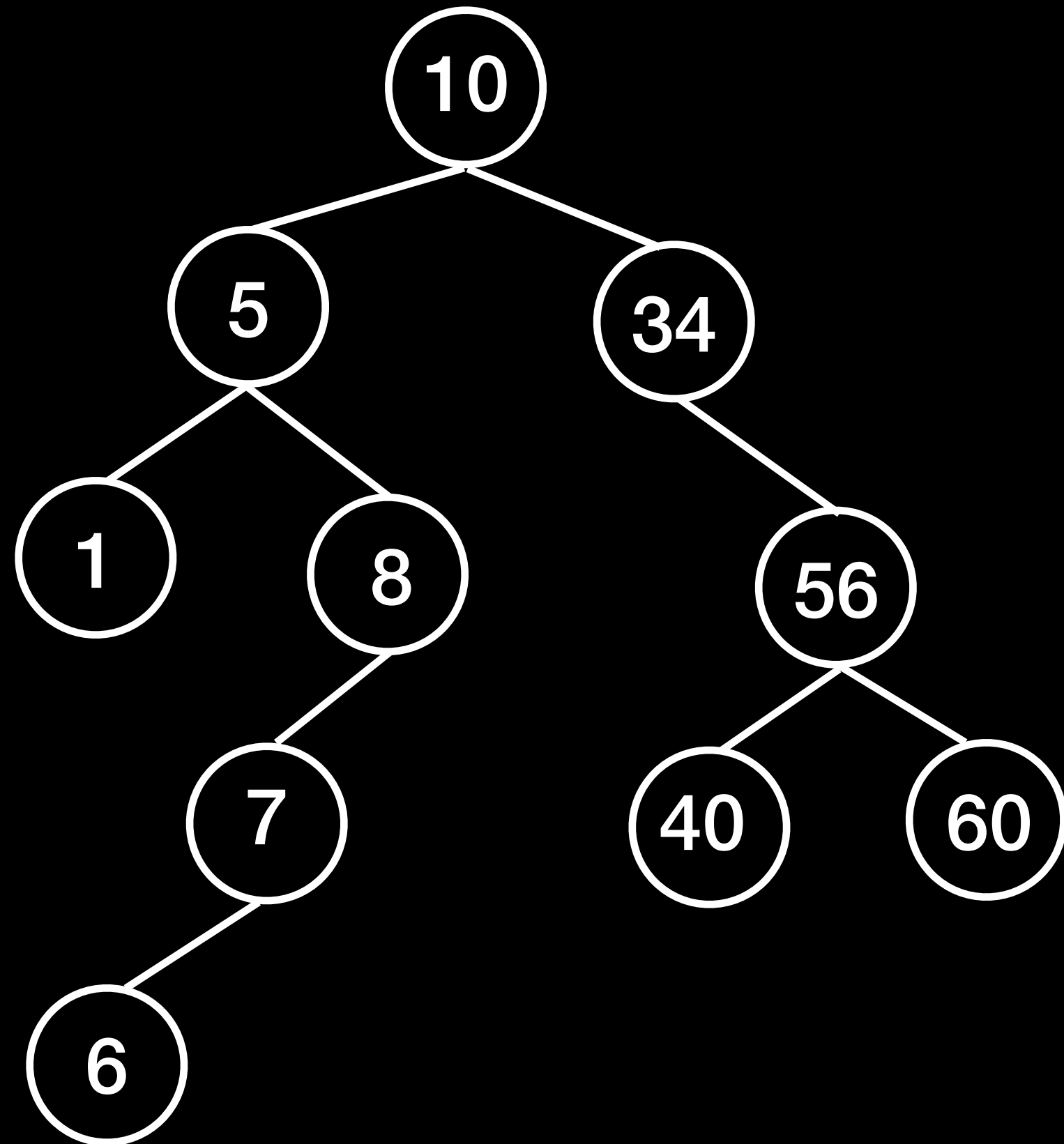
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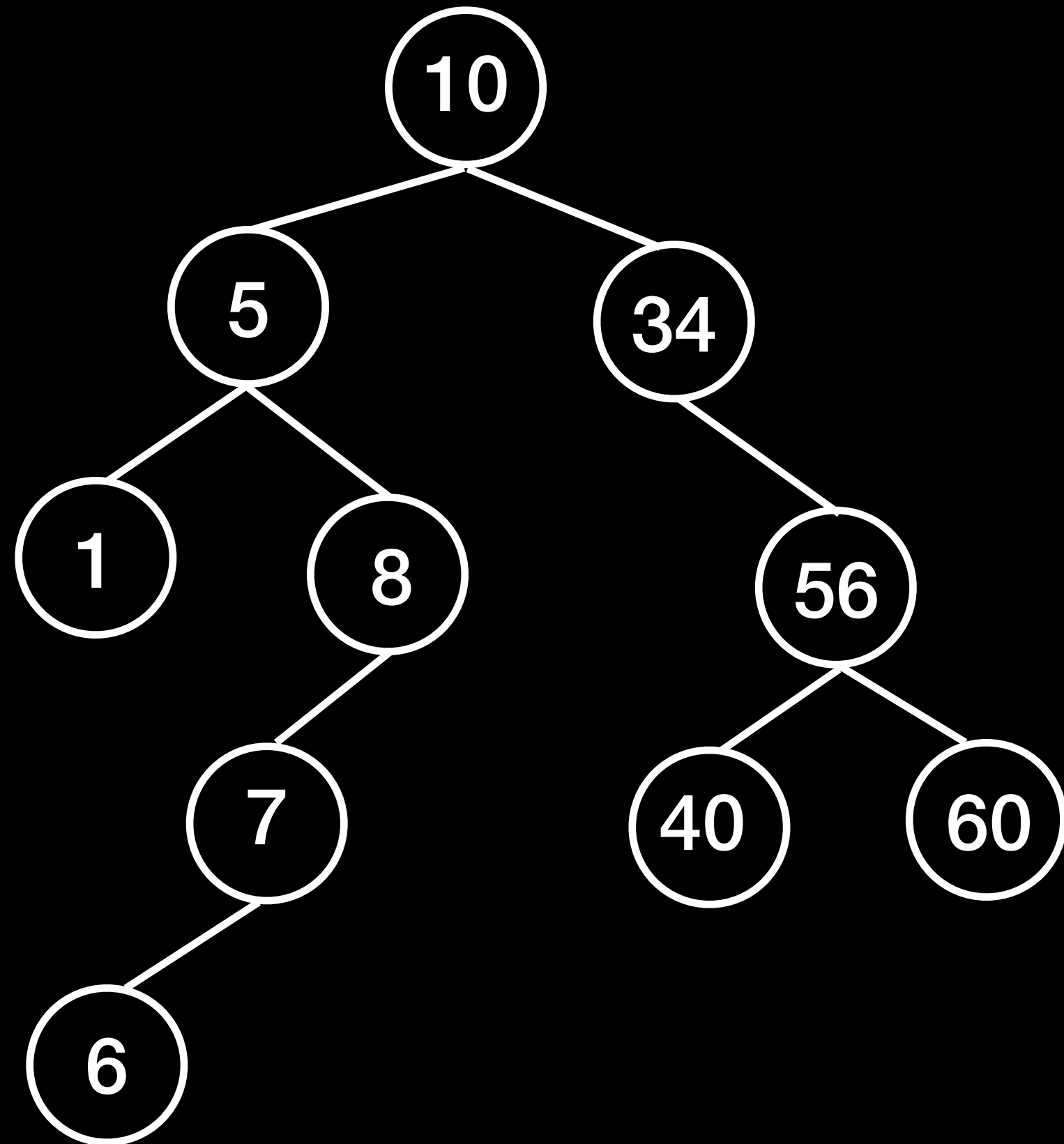


Tree traversals

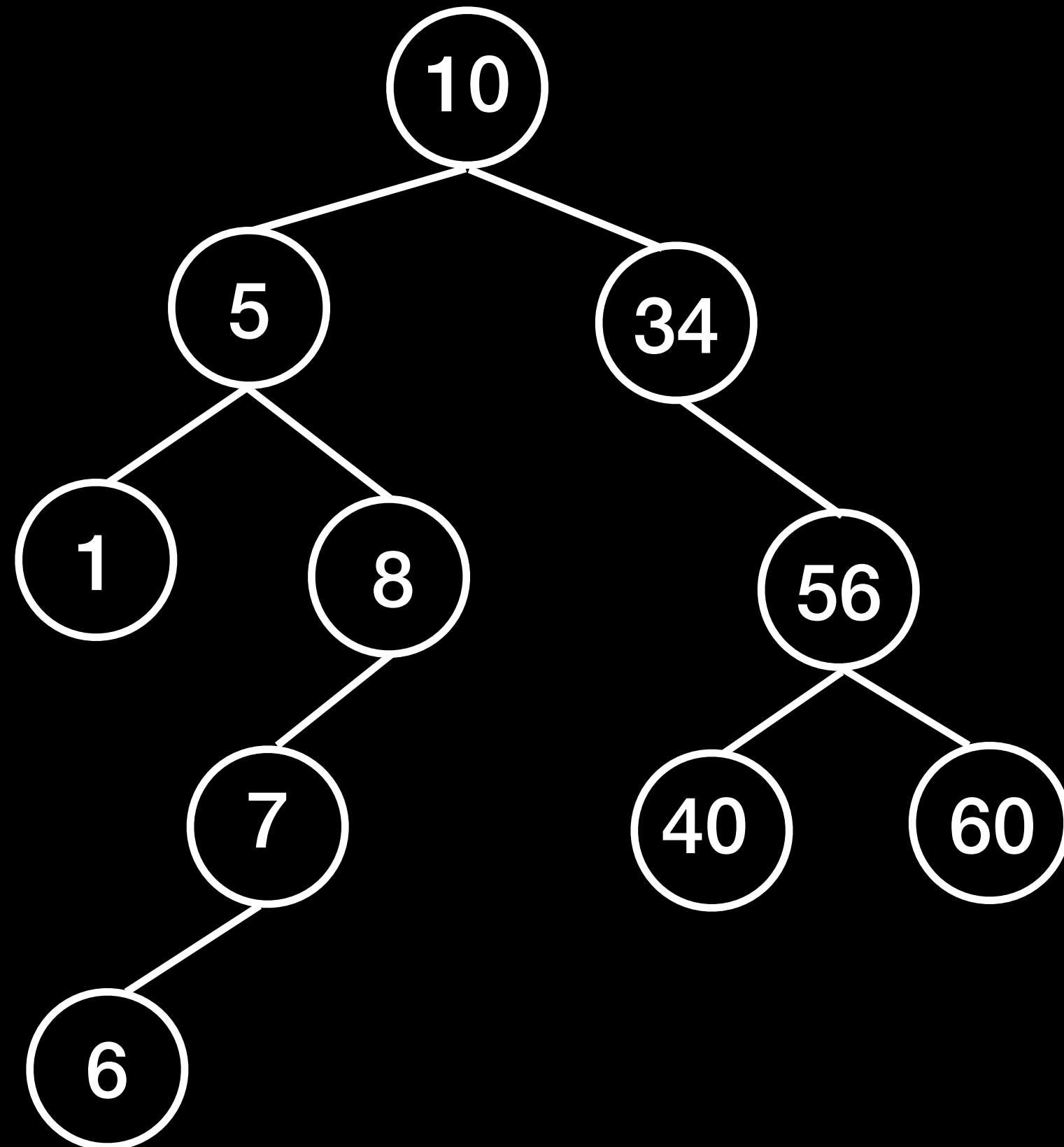


Tree traversals

Pre-order



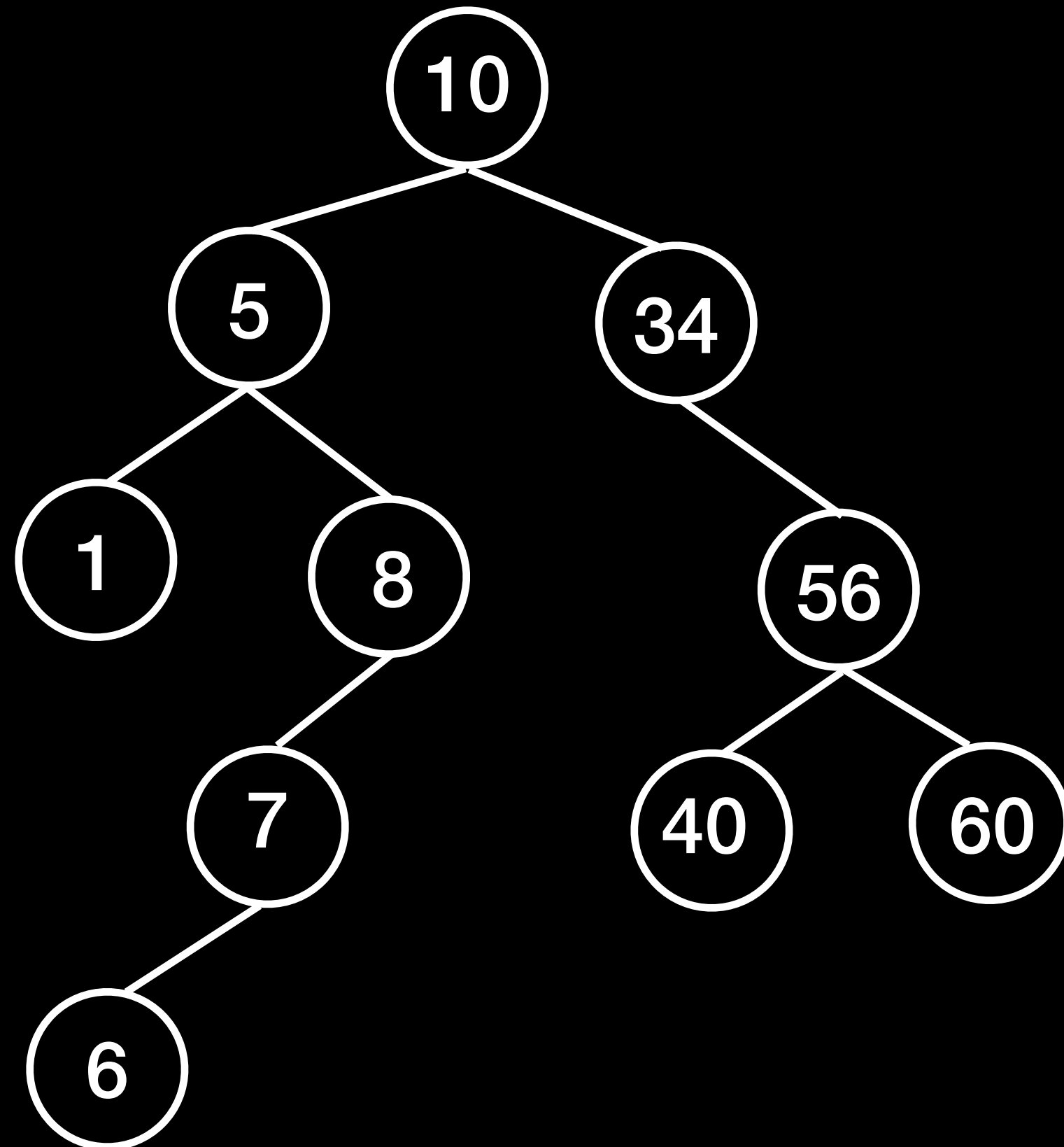
Tree traversals



Pre-order

10, 5, 1, 8, 7, 6, 34, 56,
40, 60

Tree traversals

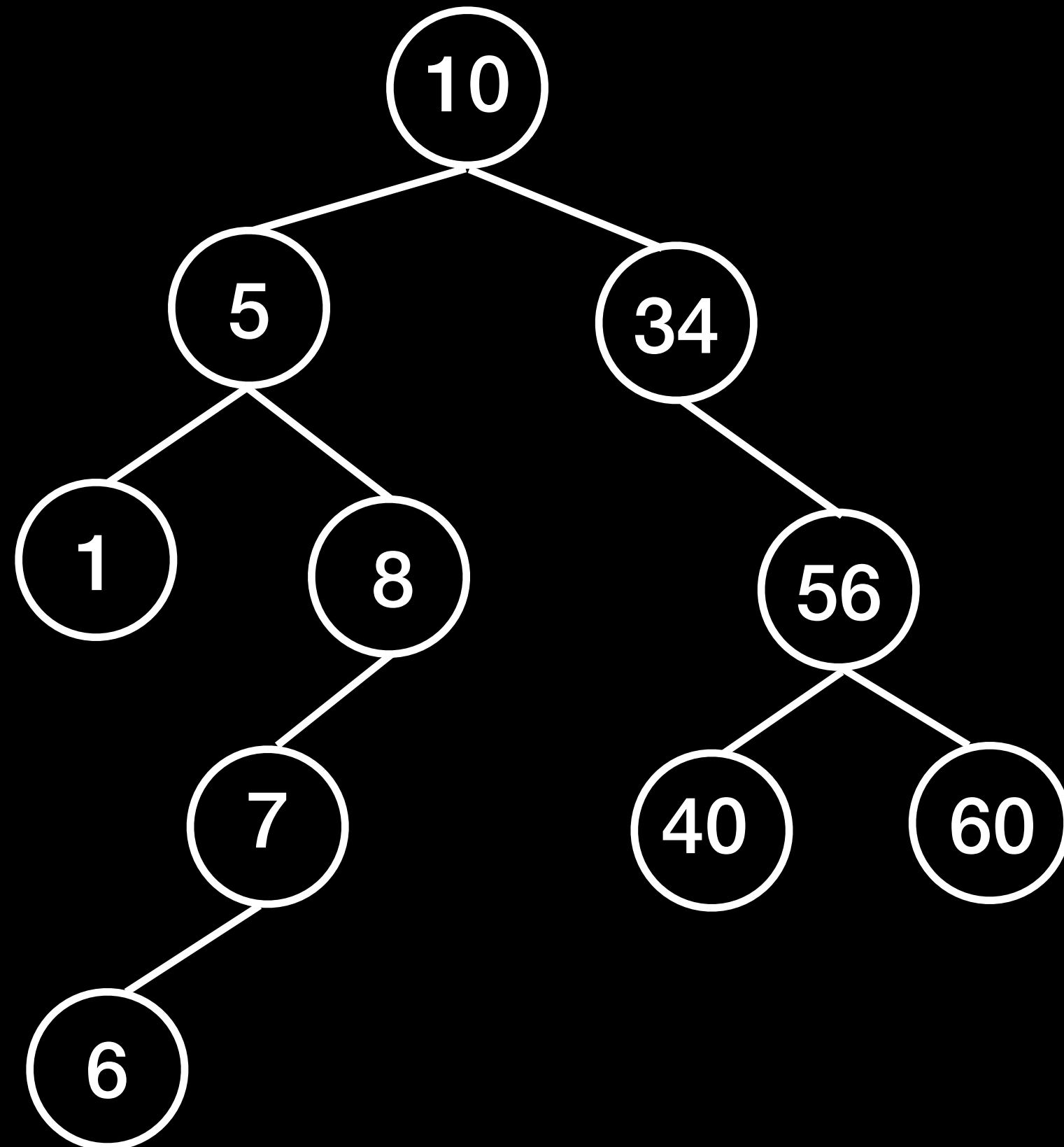


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In-order

Tree traversals



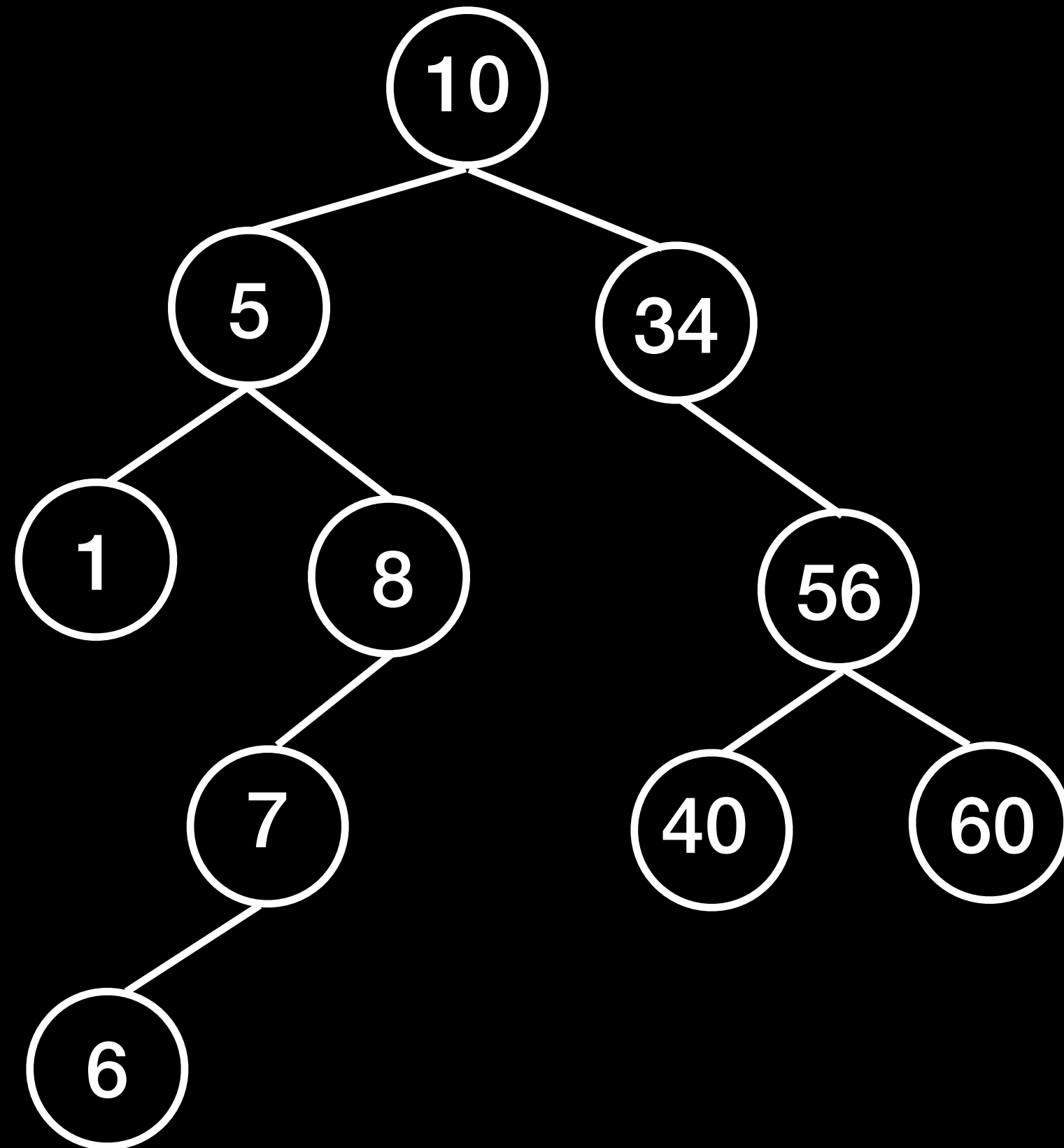
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Tree traversals



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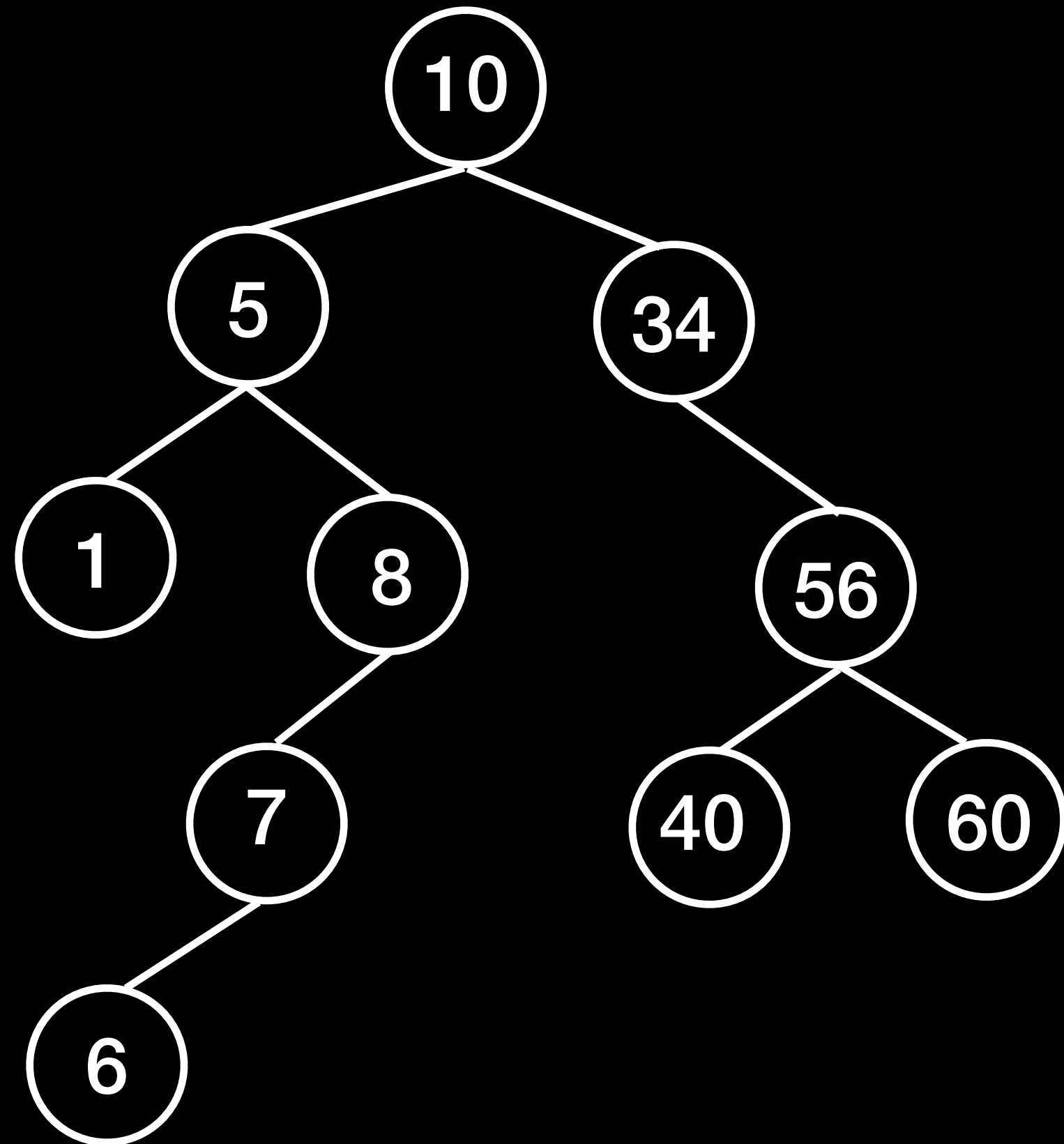
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Tree traversals



Pre-order

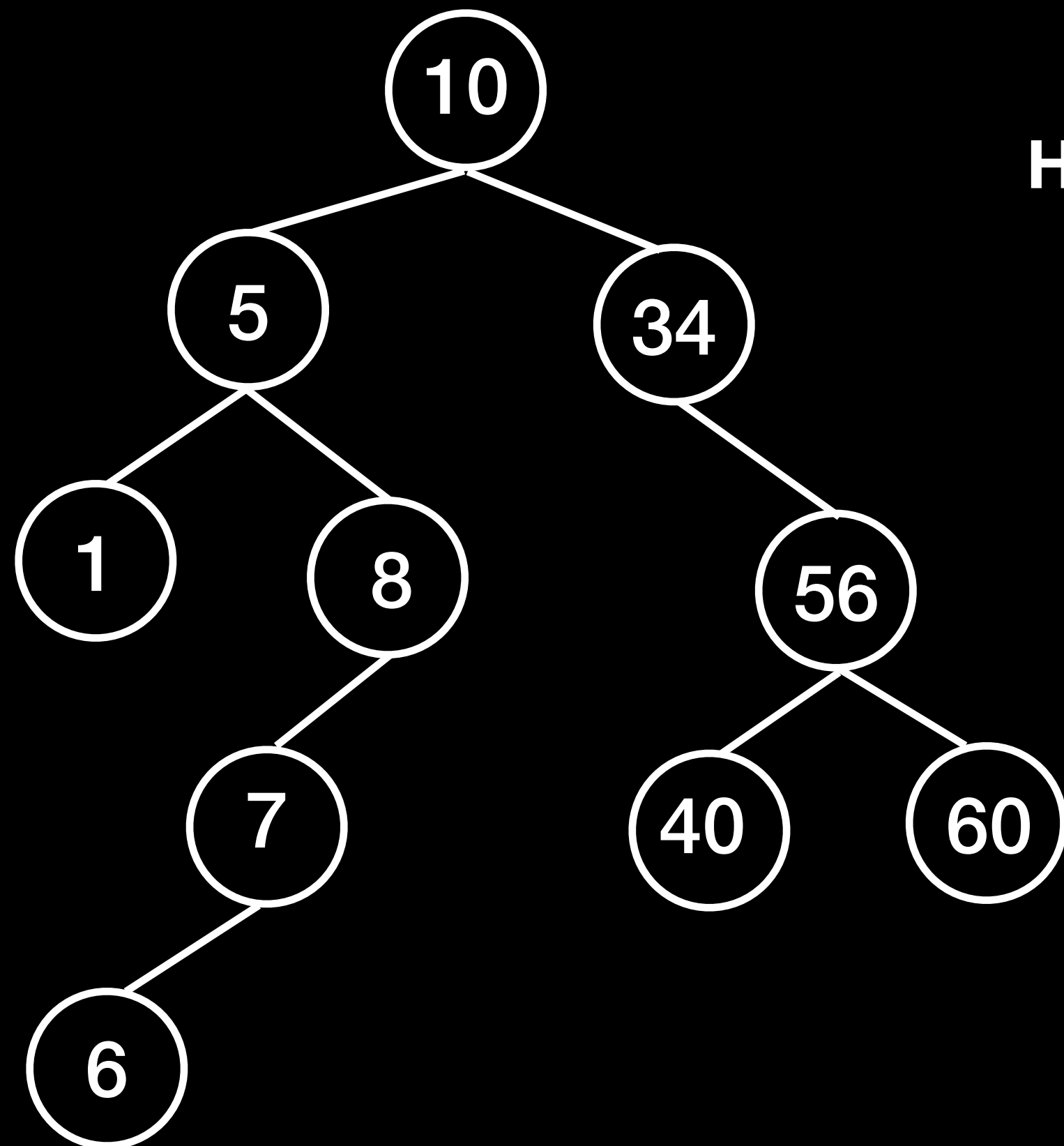
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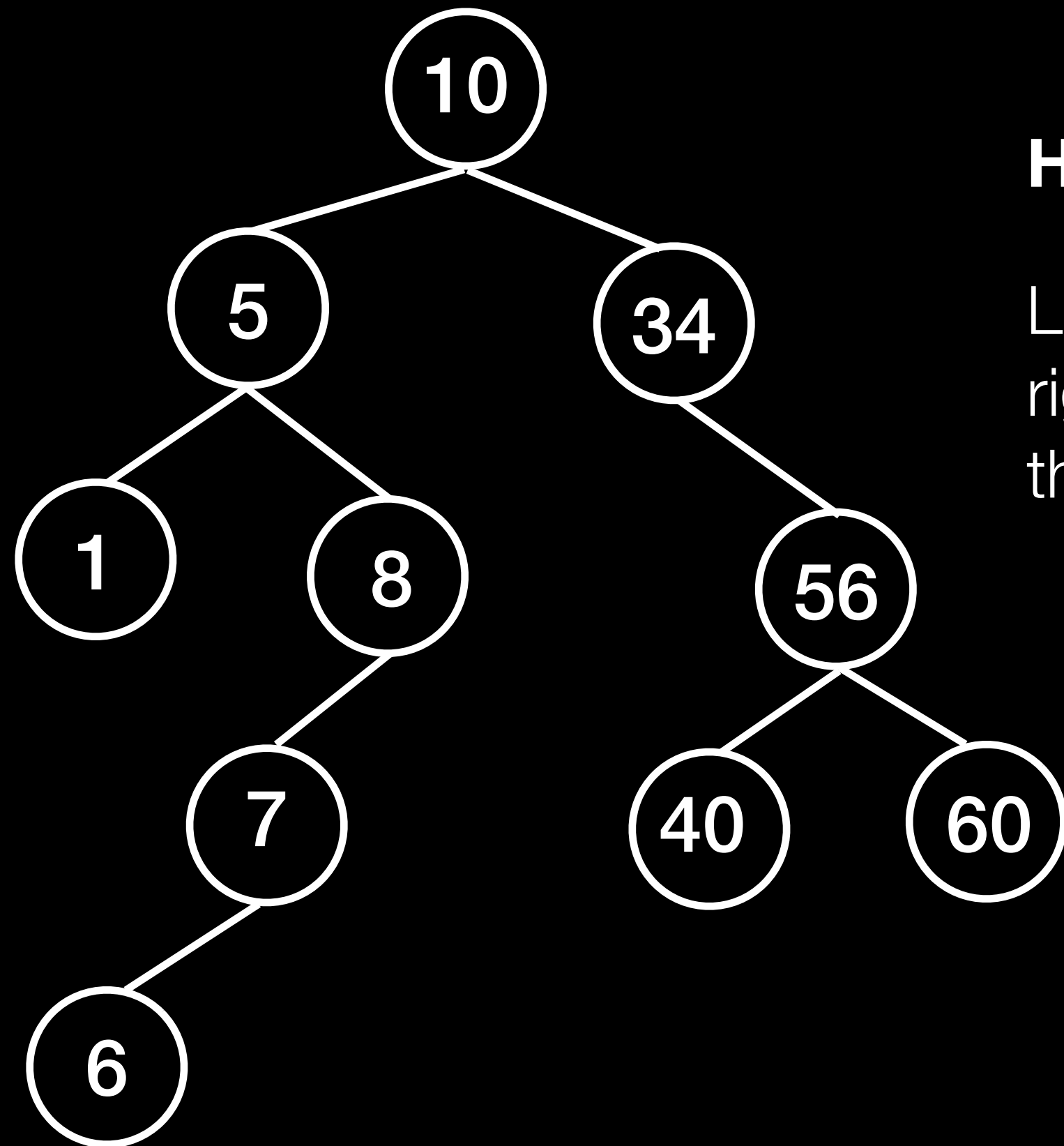
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Post-order

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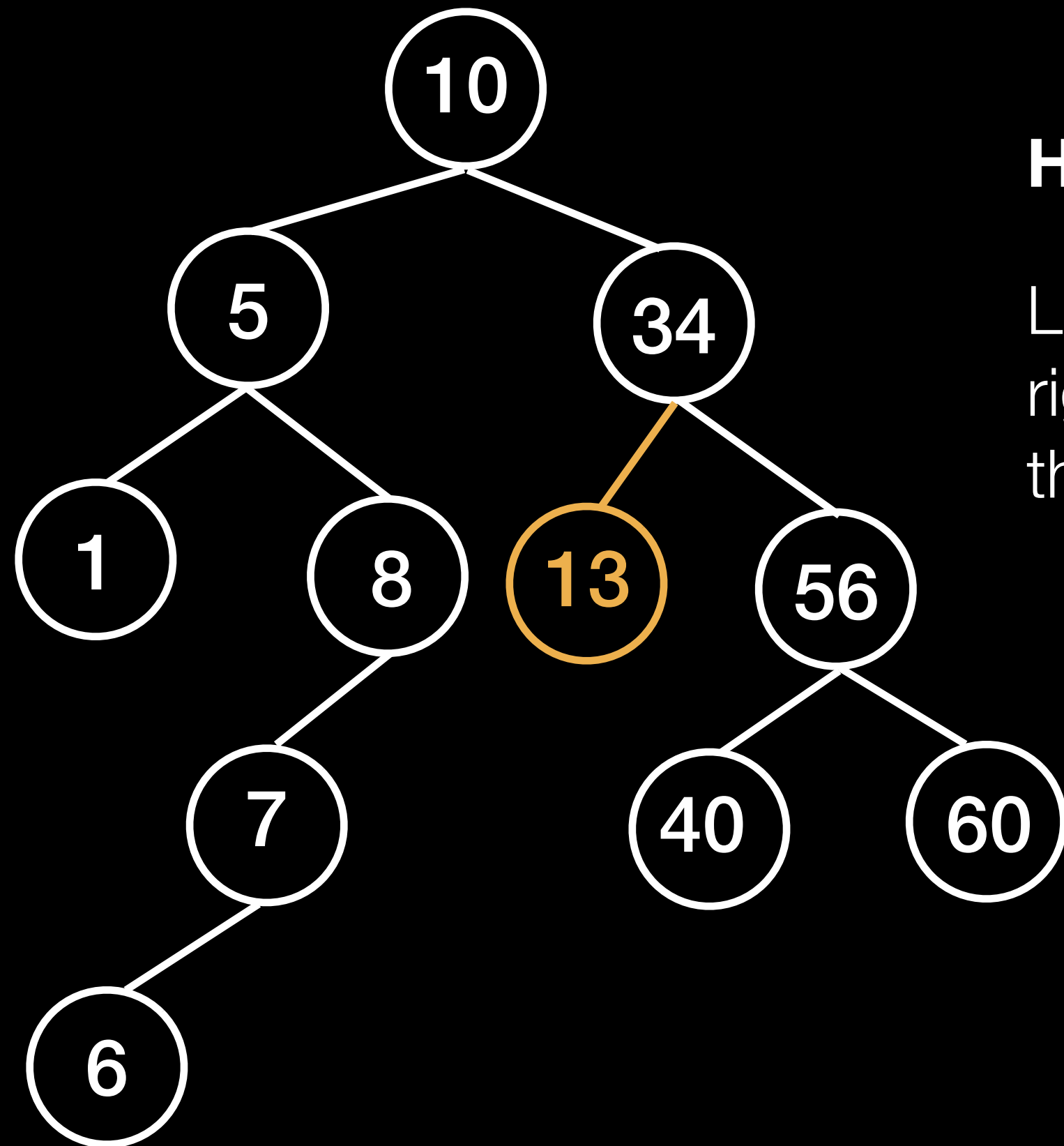


How would we add 13?



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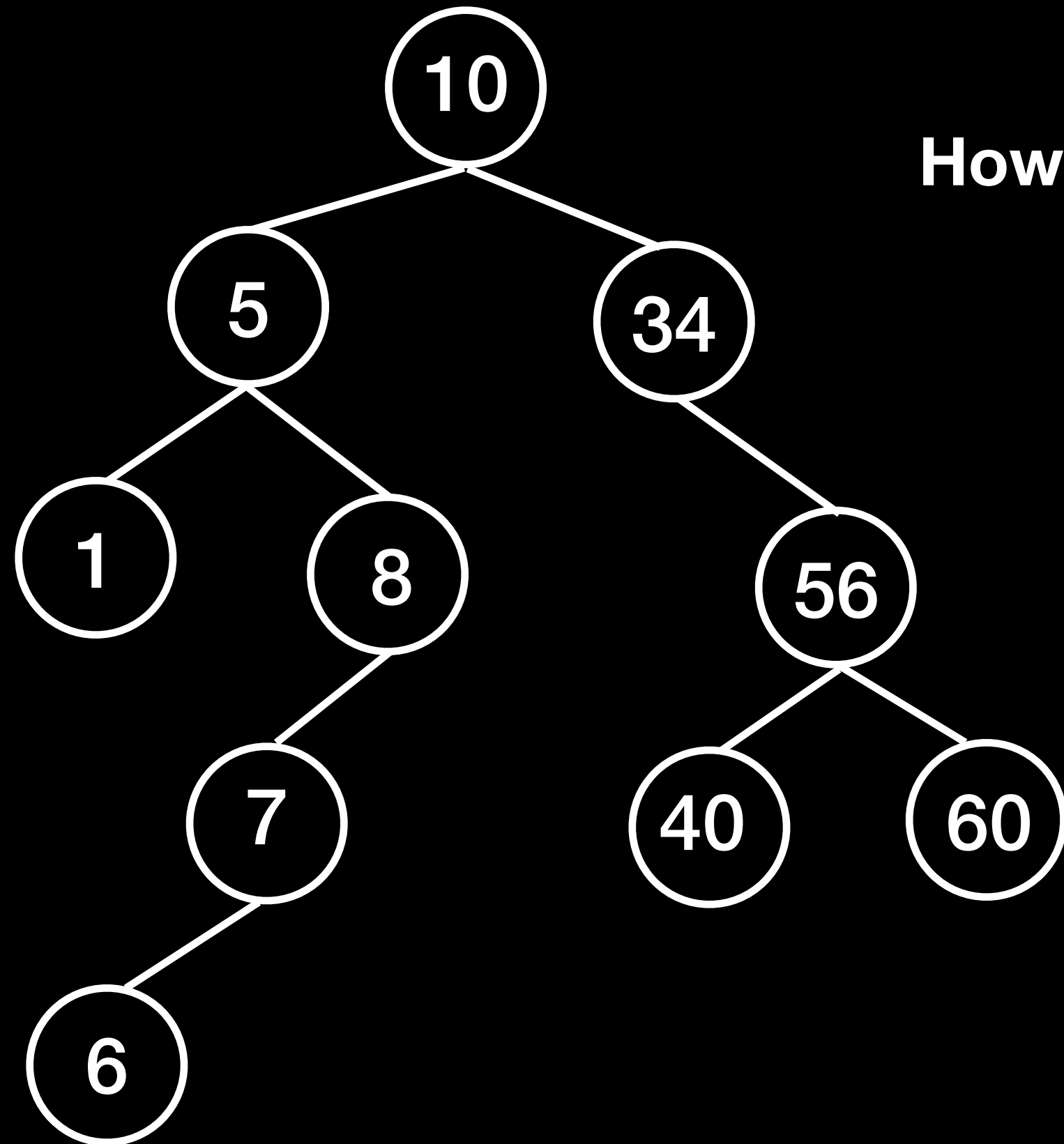
Larger values go to the right, smaller values go to the left

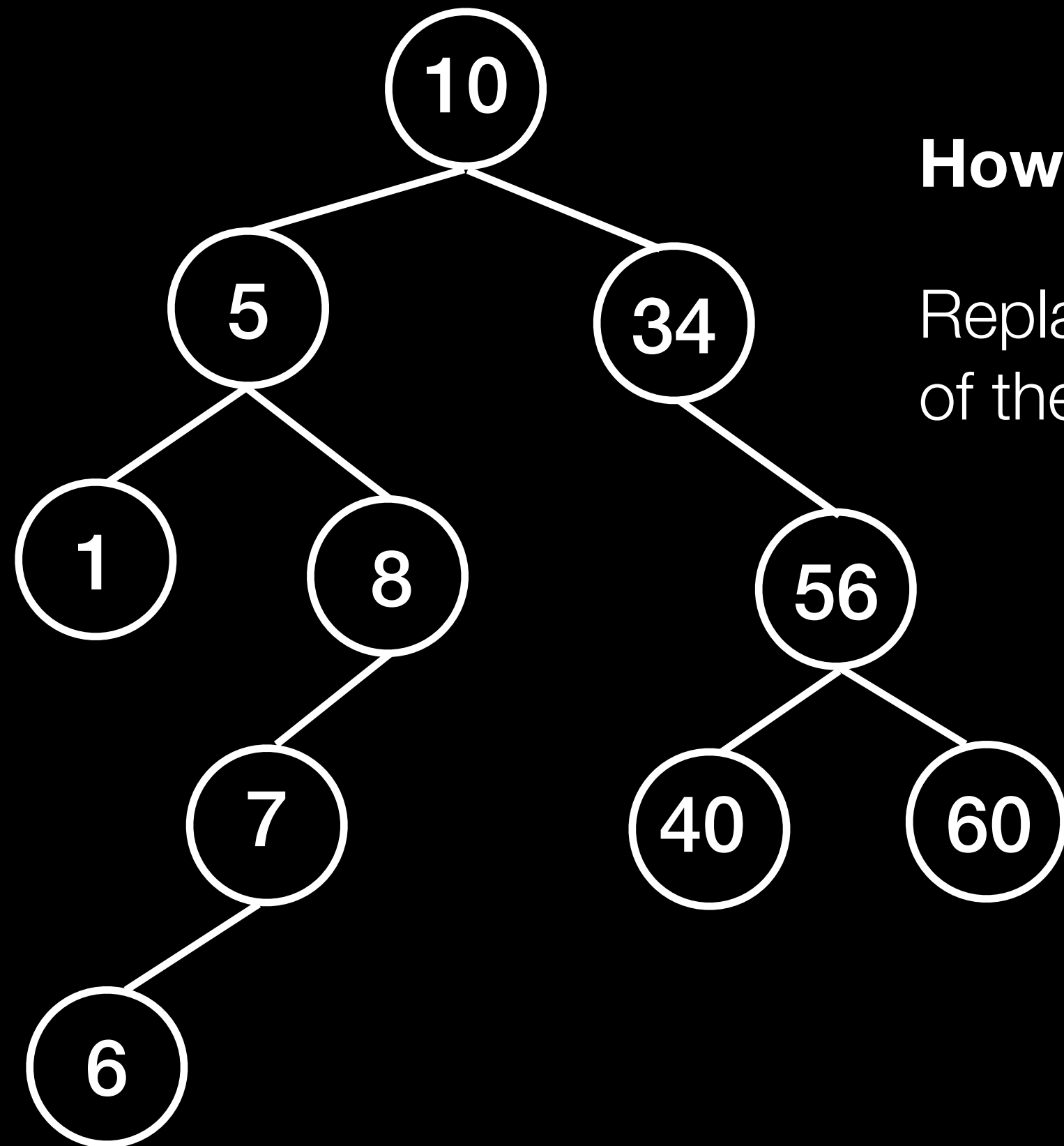


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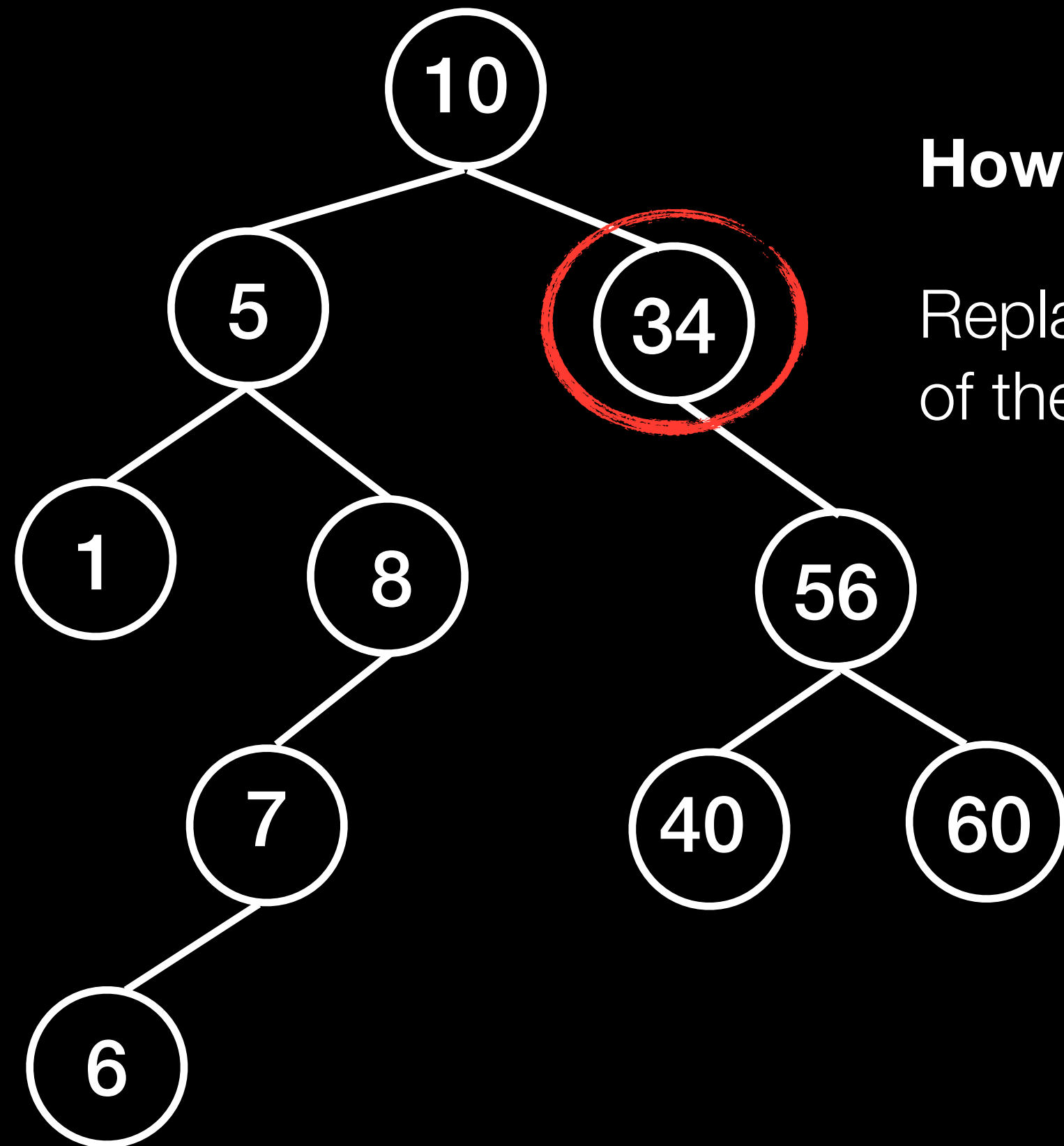
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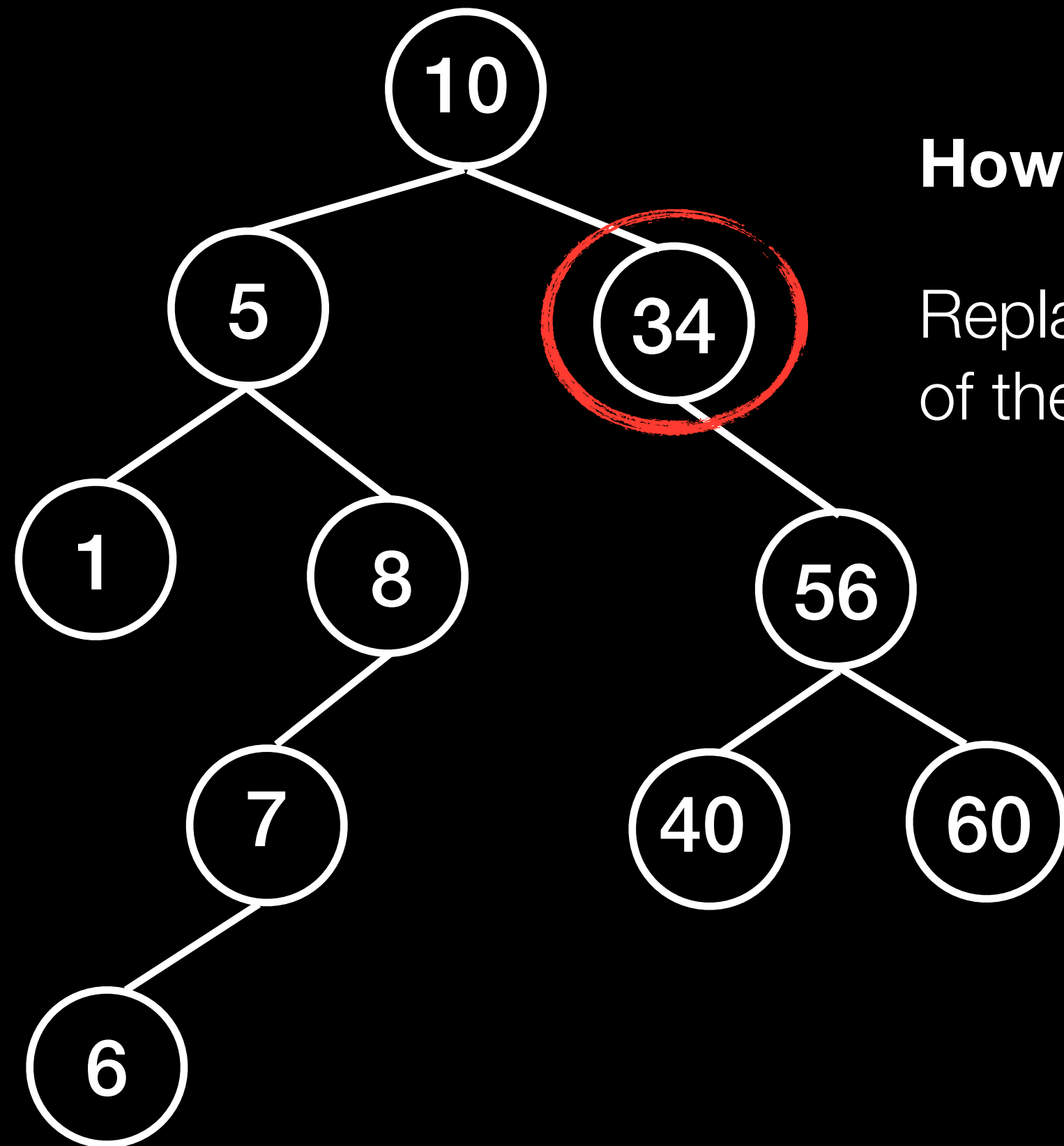
How would we remove 10?

Replace with the left-most item
of the right-subtree!



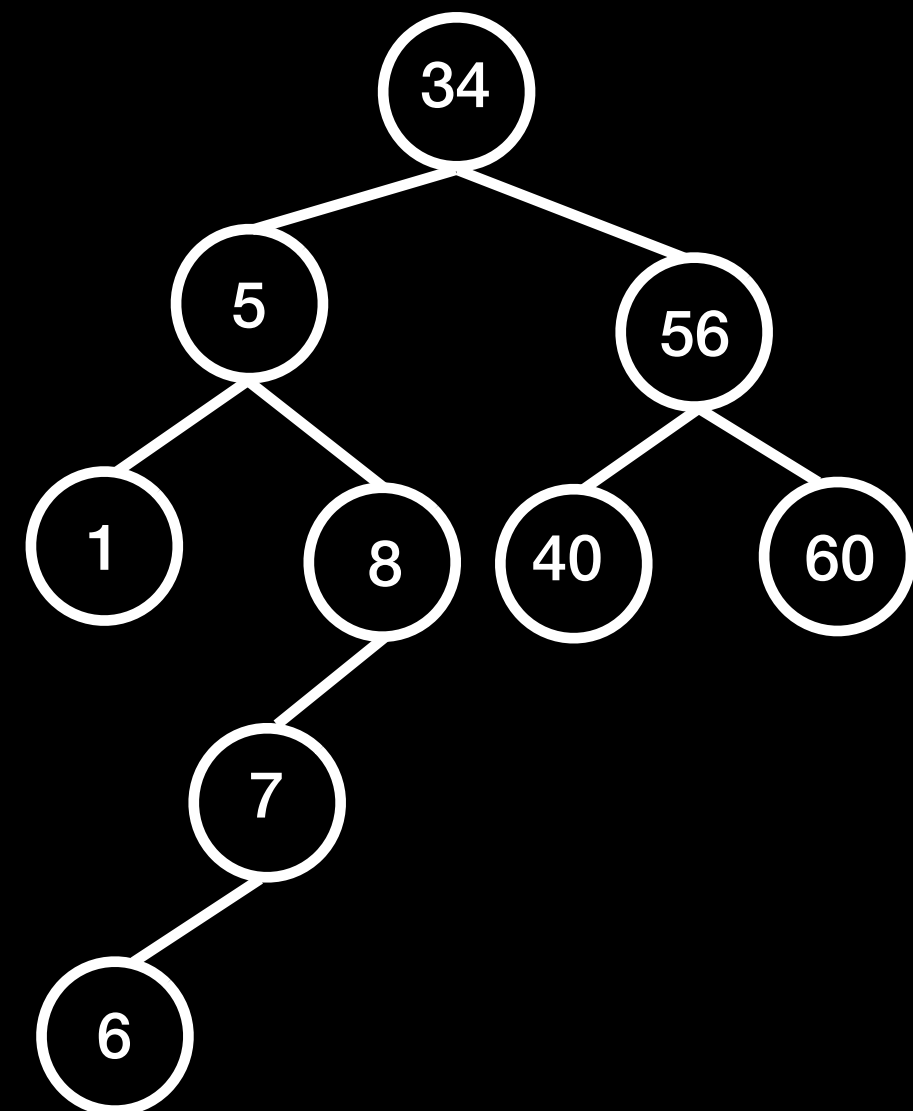
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Write a **treeSort** function that takes an array of elements and returns those elements in sorted order. Assume you do not have an iterator (your approach **must be recursive**). You will need a helper function.

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```
struct AVLTree* newAVLTree();
void addAVLTree(struct AVLTree *tree, TYPE val);

void treeSort (TYPE data[], int n) {
    // WRITE ME
}

void _treeSortHelper(AVLNode *cur, TYPE *data,
int *count) {
    // WRITE ME
}
```

```
void treeSort(TYPE data[], int size){
    int i;
    int sortIdx = 0;

}

```



```
void treeSort(TYPE data[], int size){  
    int i;  
    int sortIdx = 0;  
  
    /* declare an AVL tree */  
    struct AVLTree *tree = newAVLtree();  
    assert(data != NULL && size > 0);  
  
}
```

```
void treeSort(TYPE data[], int size){  
    int i;  
    int sortIdx = 0;  
  
    /* declare an AVL tree */  
    struct AVLTree *tree = newAVLtree();  
    assert(data != NULL && size > 0);  
  
    /* add elements to the tree */  
    for (i = 0; i < size; i++)  
        addAVLTree(tree, data[i]);  
  
}
```

```
void treeSort(TYPE data[], int size){
    int i;
    int sortIdx = 0;

    /* declare an AVL tree */
    struct AVLTree *tree = newAVLtree();
    assert(data != NULL && size > 0);

    /* add elements to the tree */
    for (i = 0; i < size; i++)
        addAVLTree(tree, data[i]);

    /* call the helper function on the root */
    _treeSortHelper(tree->root, data, &sortIdx);
}
```

```
/* *index goes from 0 to size-1 */
```

```
void _treeSortHelper(AVLNode *cur, TYPE *data,  
                     int *index){
```

```
}
```

```
/* *index goes from 0 to size-1 */  
  
void _treeSortHelper(AVLNode *cur, TYPE *data,  
                     int *index){  
    /* In-order traversal: get the left subtree,  
       then this node, then the right subtree */  
    if (cur != NULL) {  
        _treeSortHelper(cur->left, data, index);  
        data[*index] = cur->val;  
        (*index)++;  
        _treeSortHelper(cur->right, data, index);  
    }  
}
```

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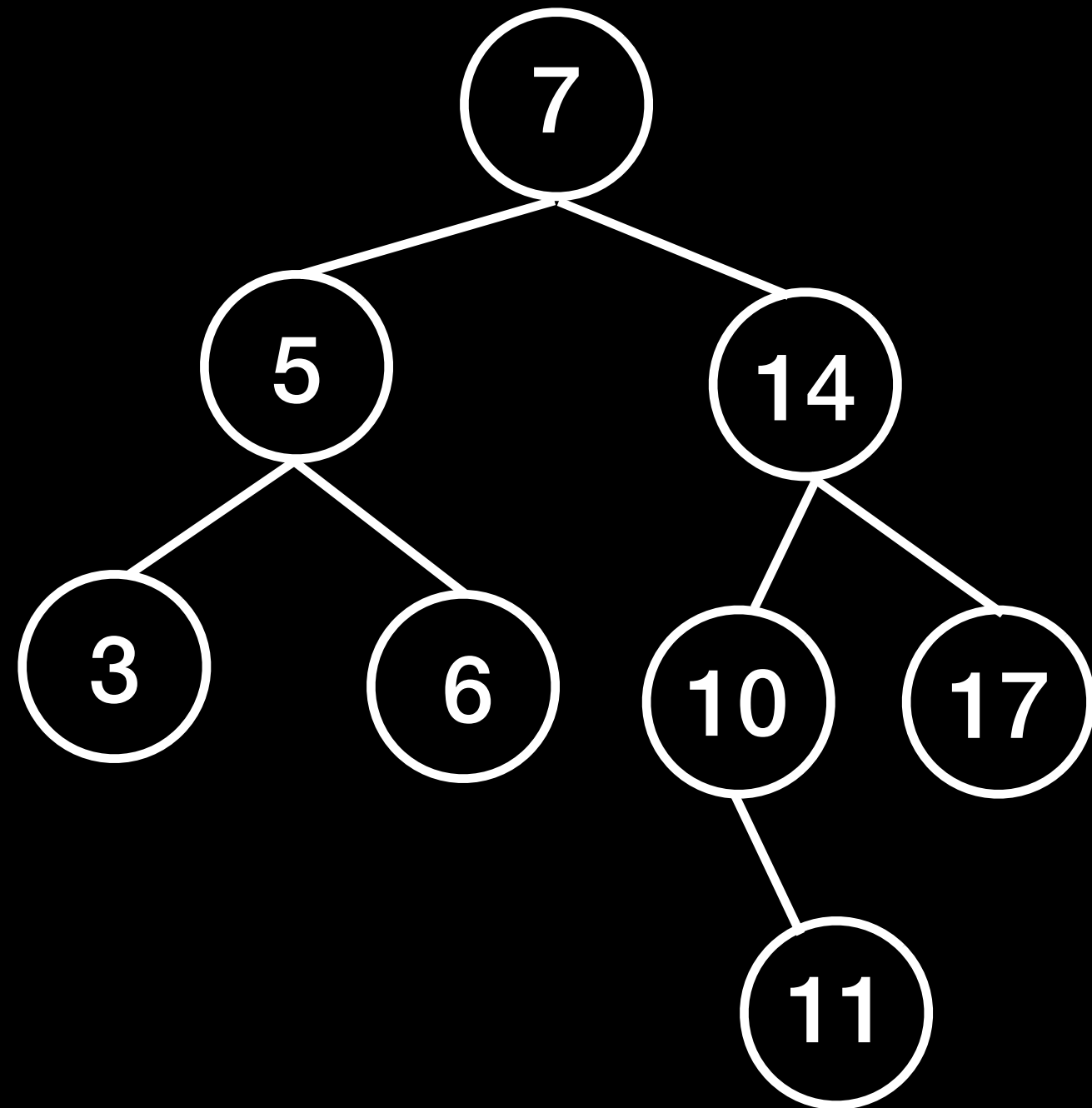
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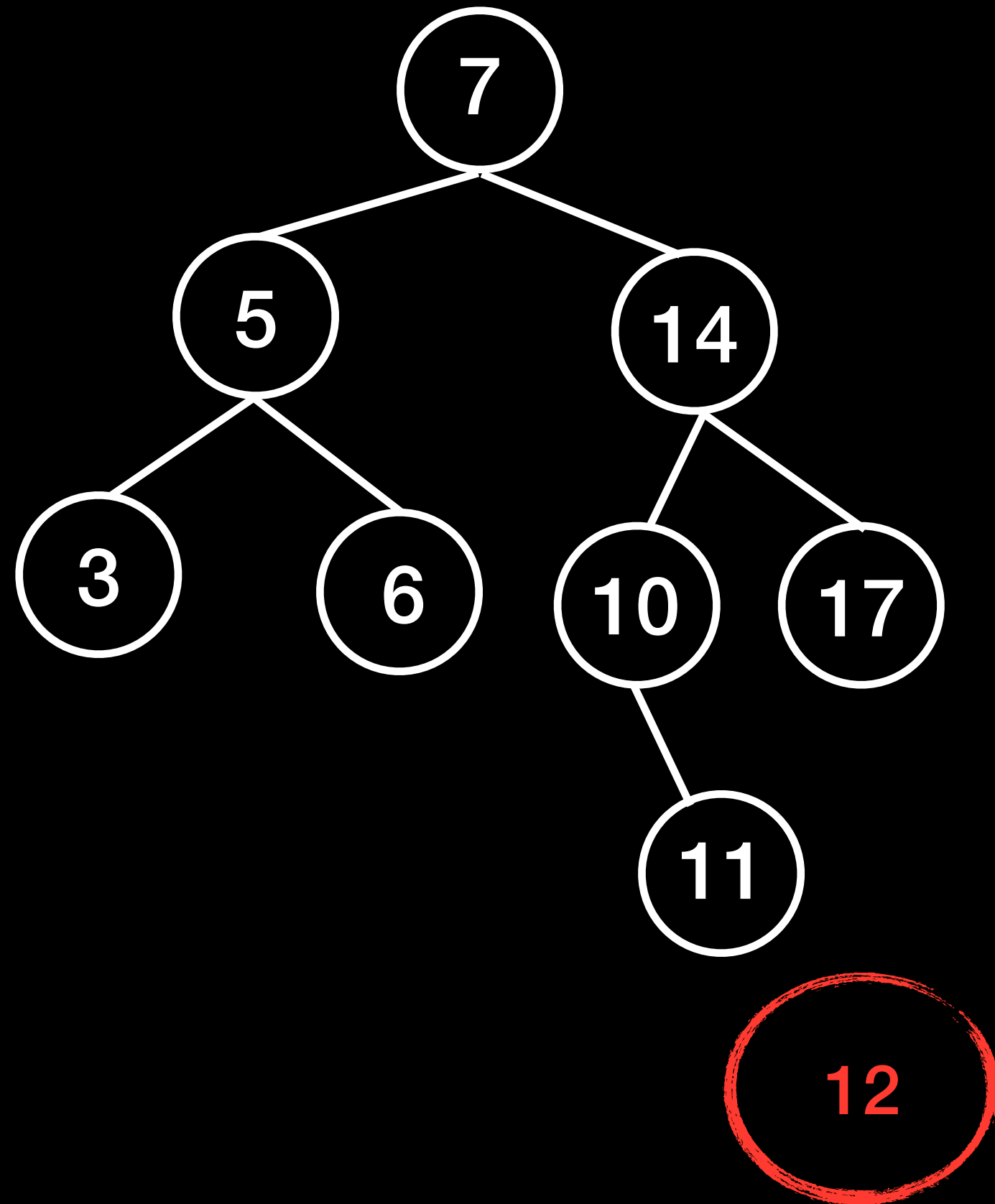
Does inserting into an AVL tree with n nodes require $O(\log n)$ rotations?

No, we need at most 2 rotations

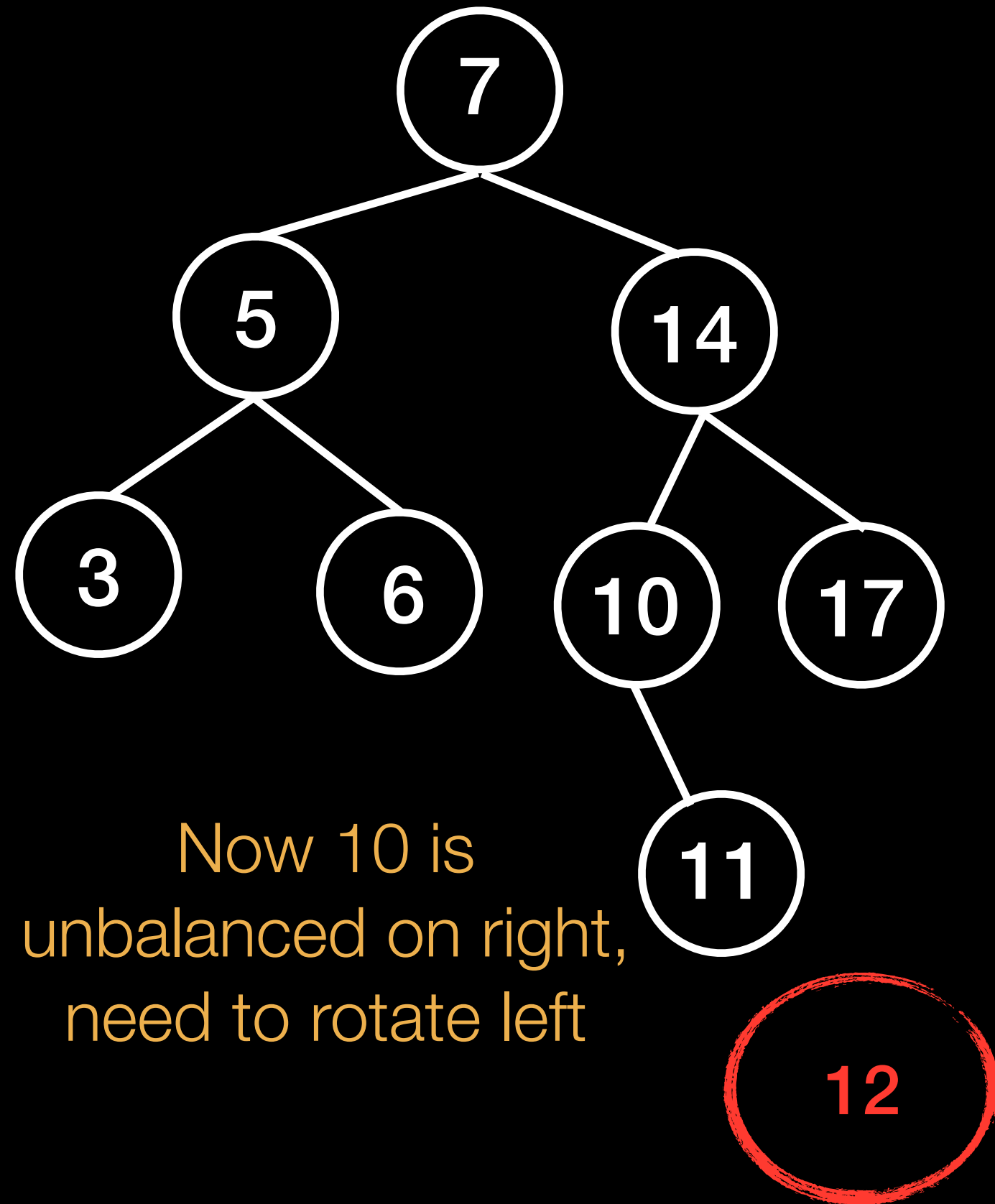
Add 12 to this AVL tree



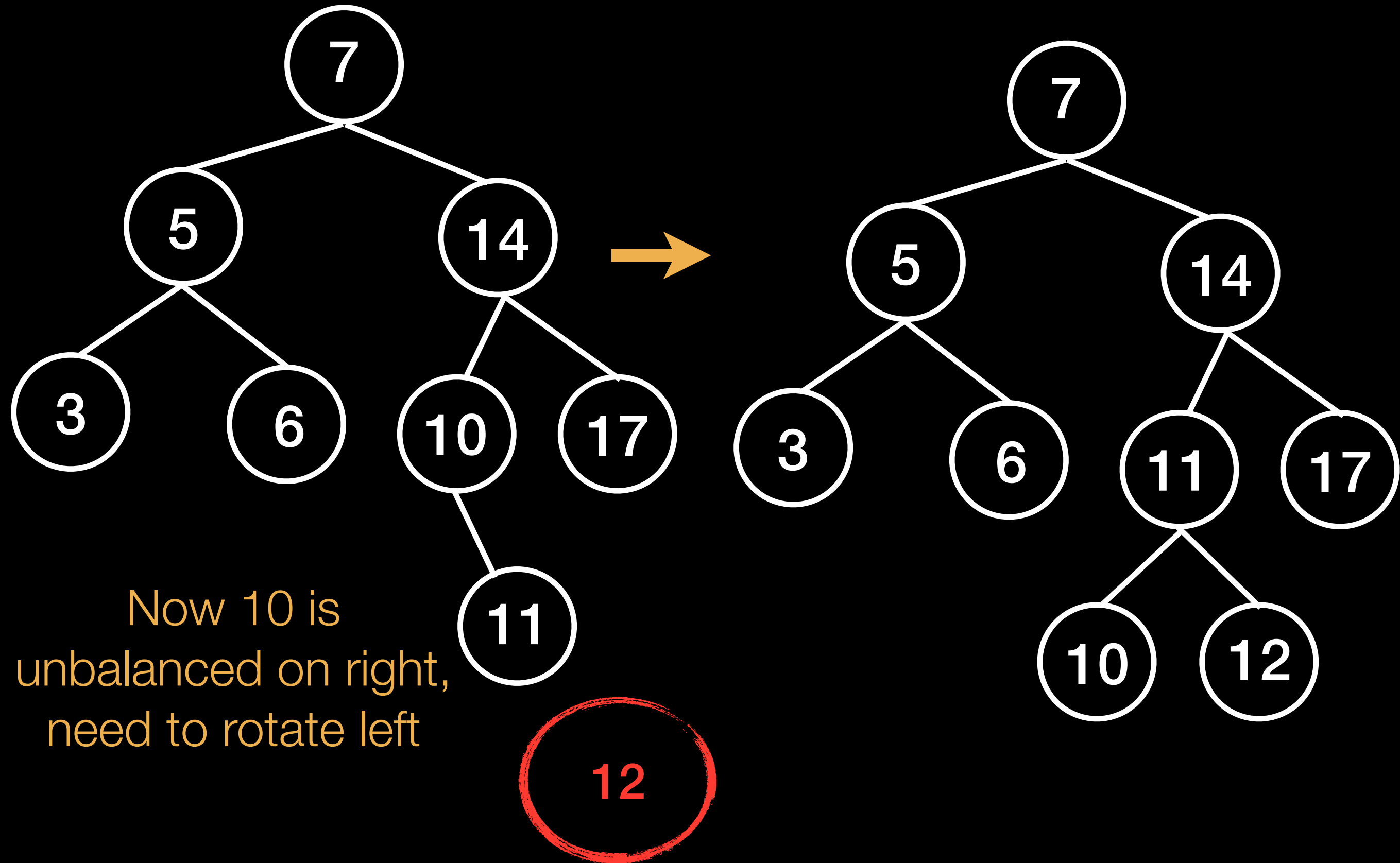
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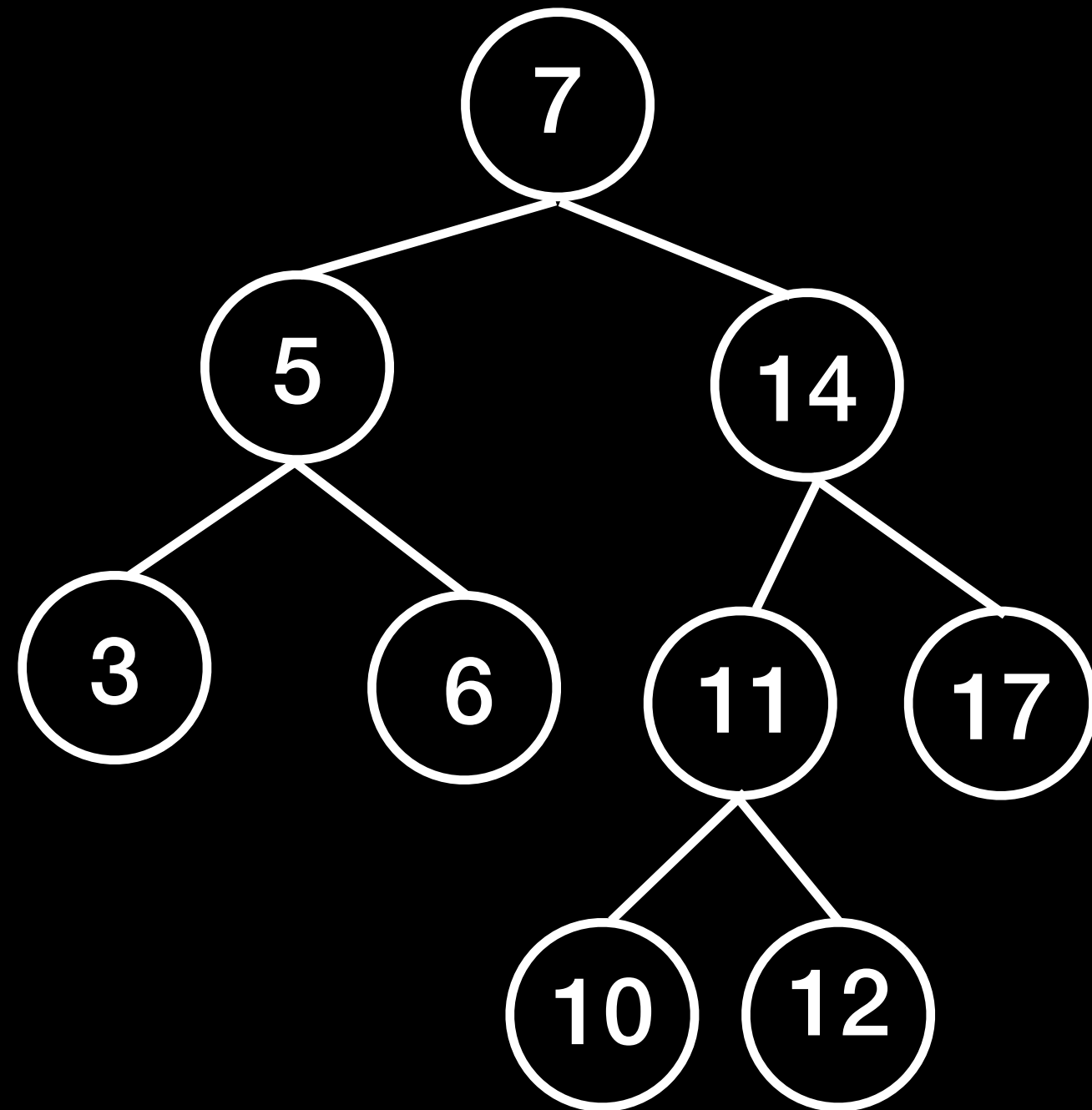
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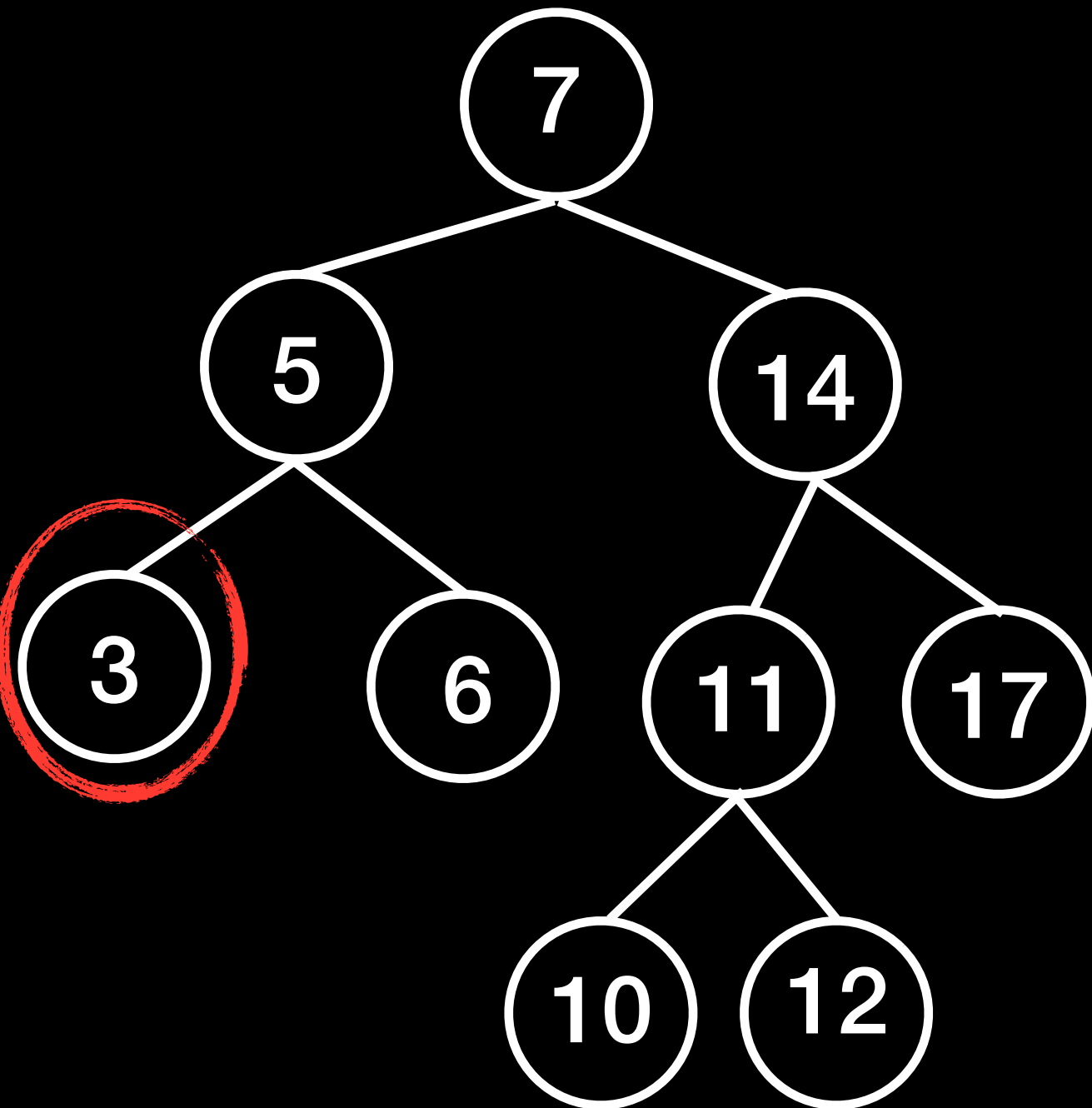
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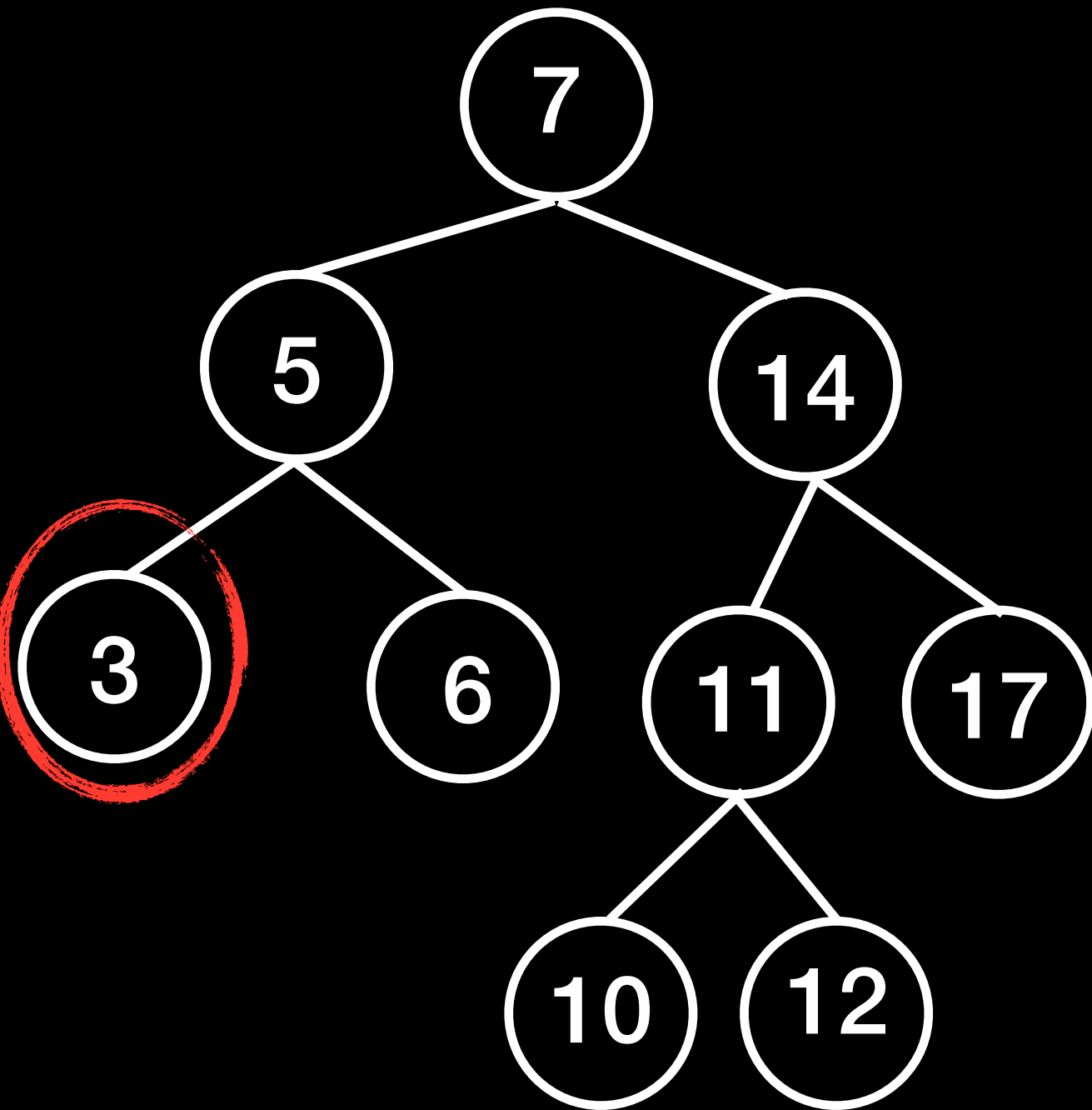
Remove 3



Remove 3

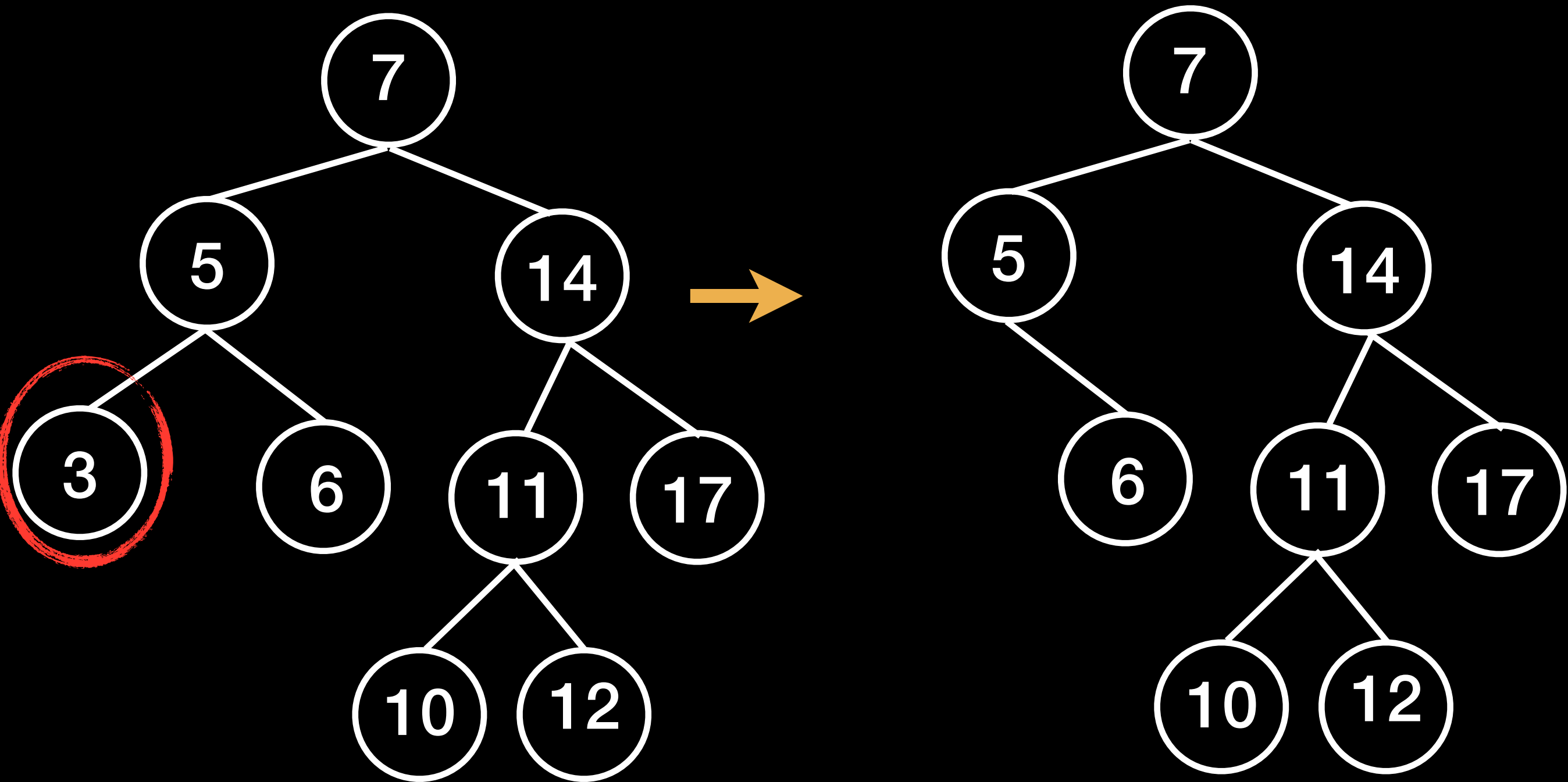


Remove 3



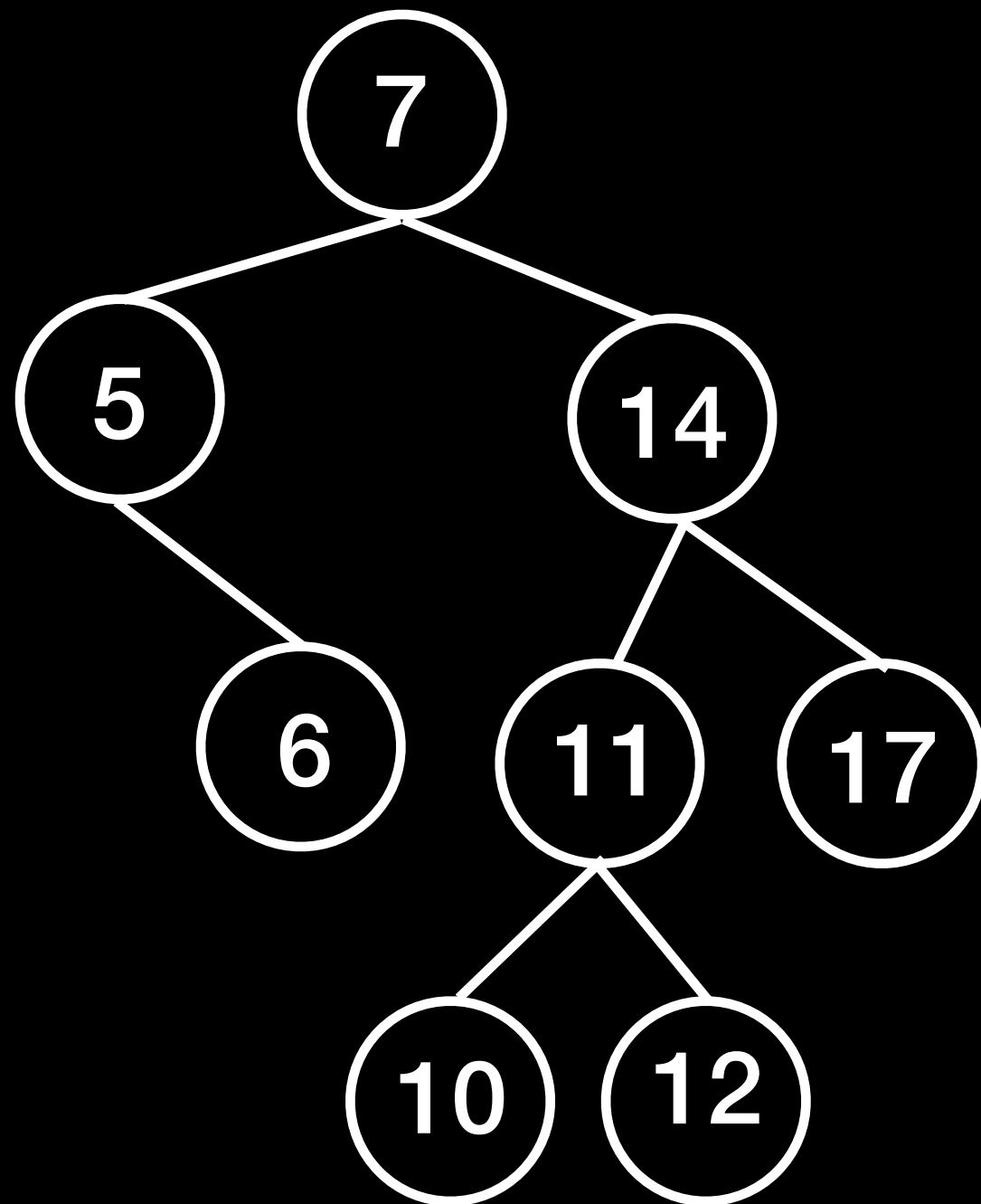
Still balanced, no
rotations needed

Remove 3

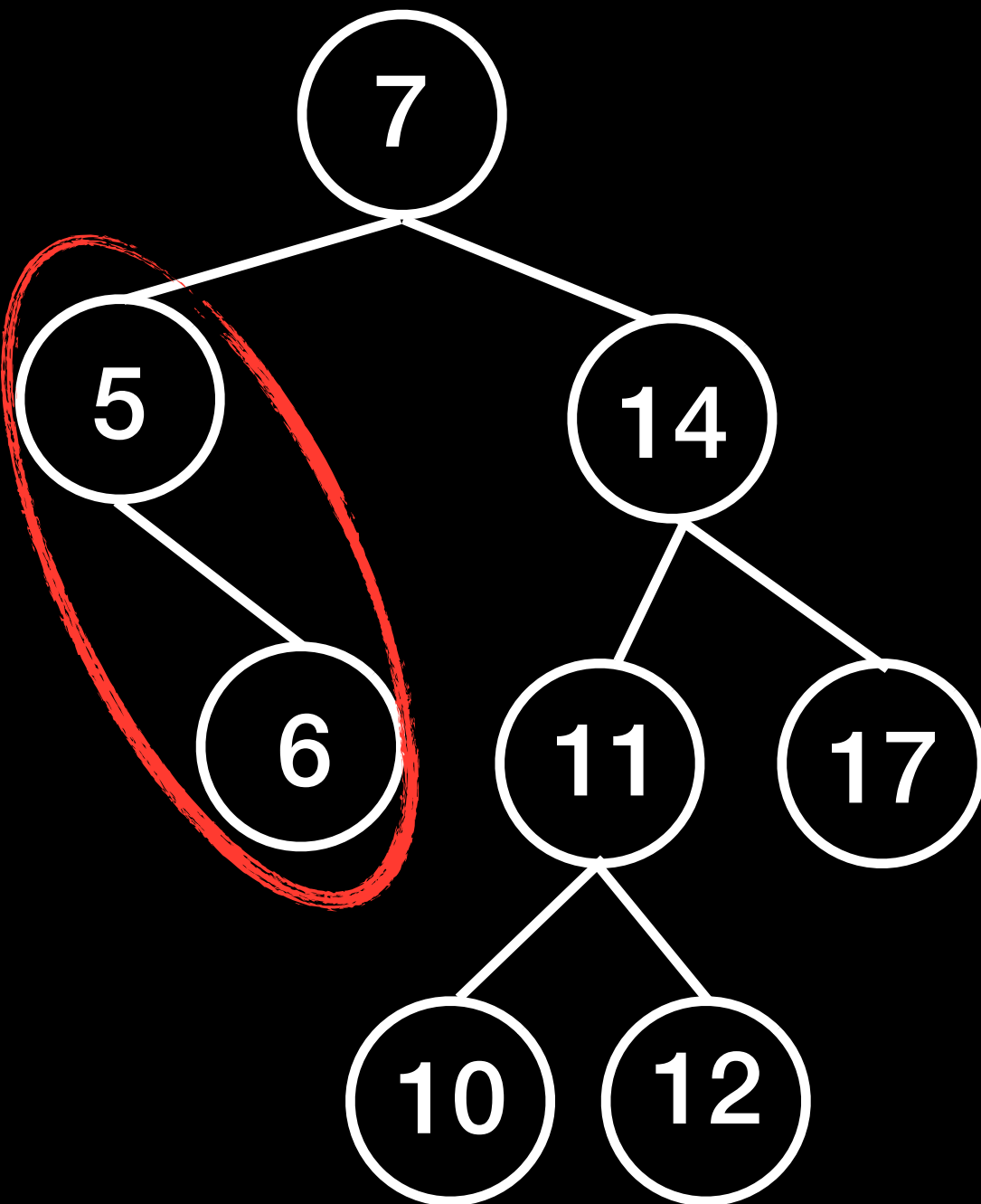


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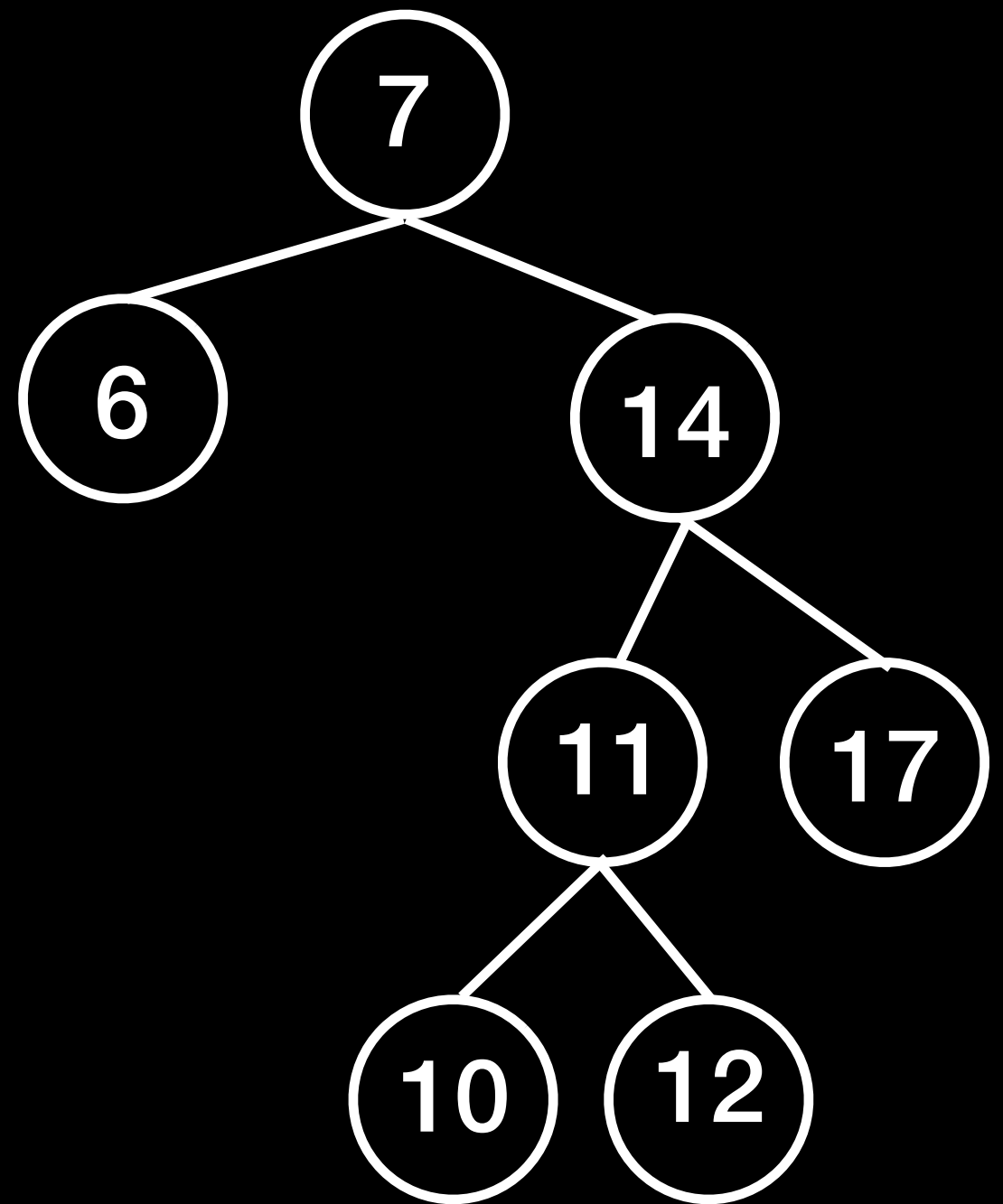
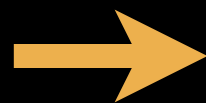
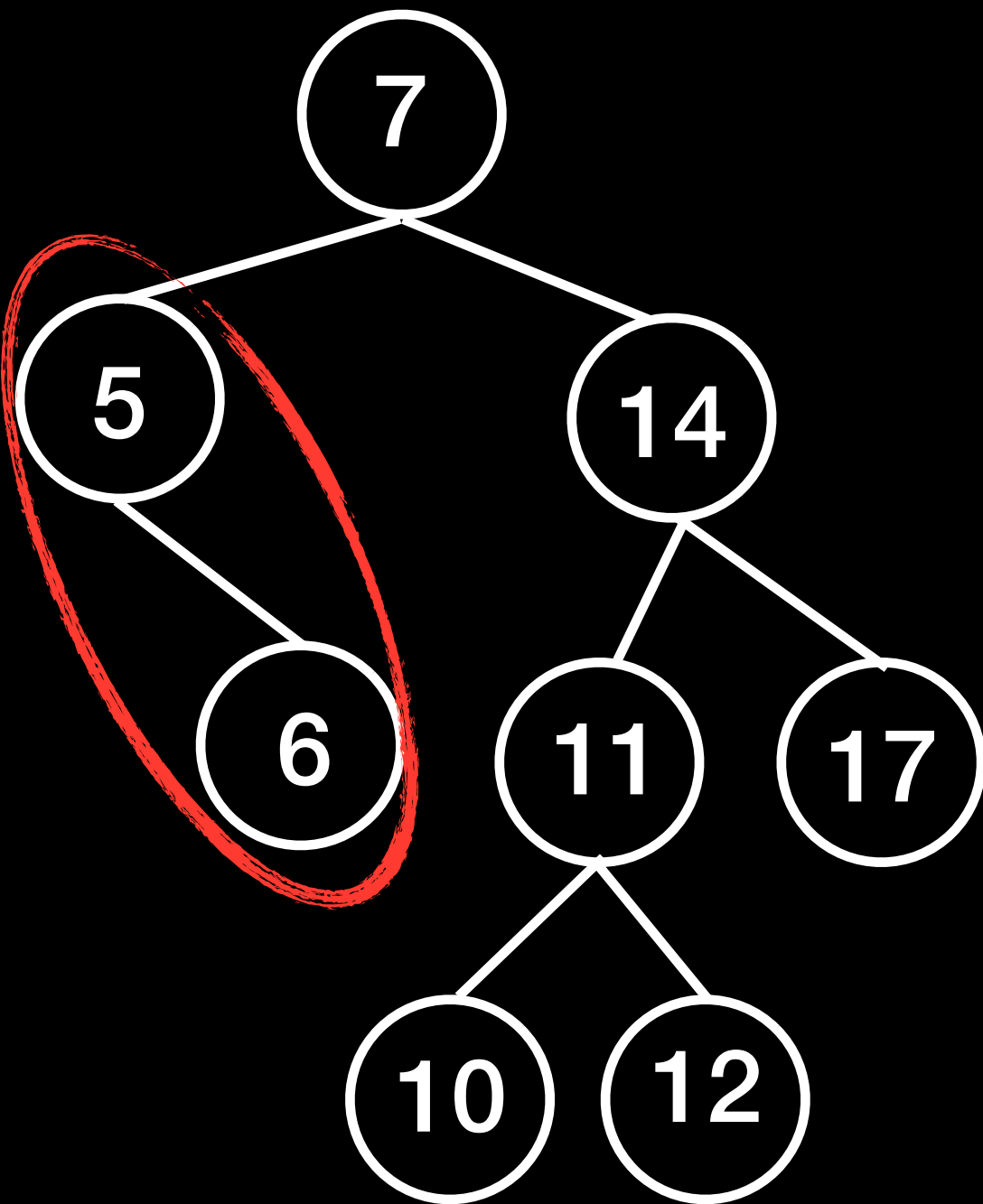
Remove 5



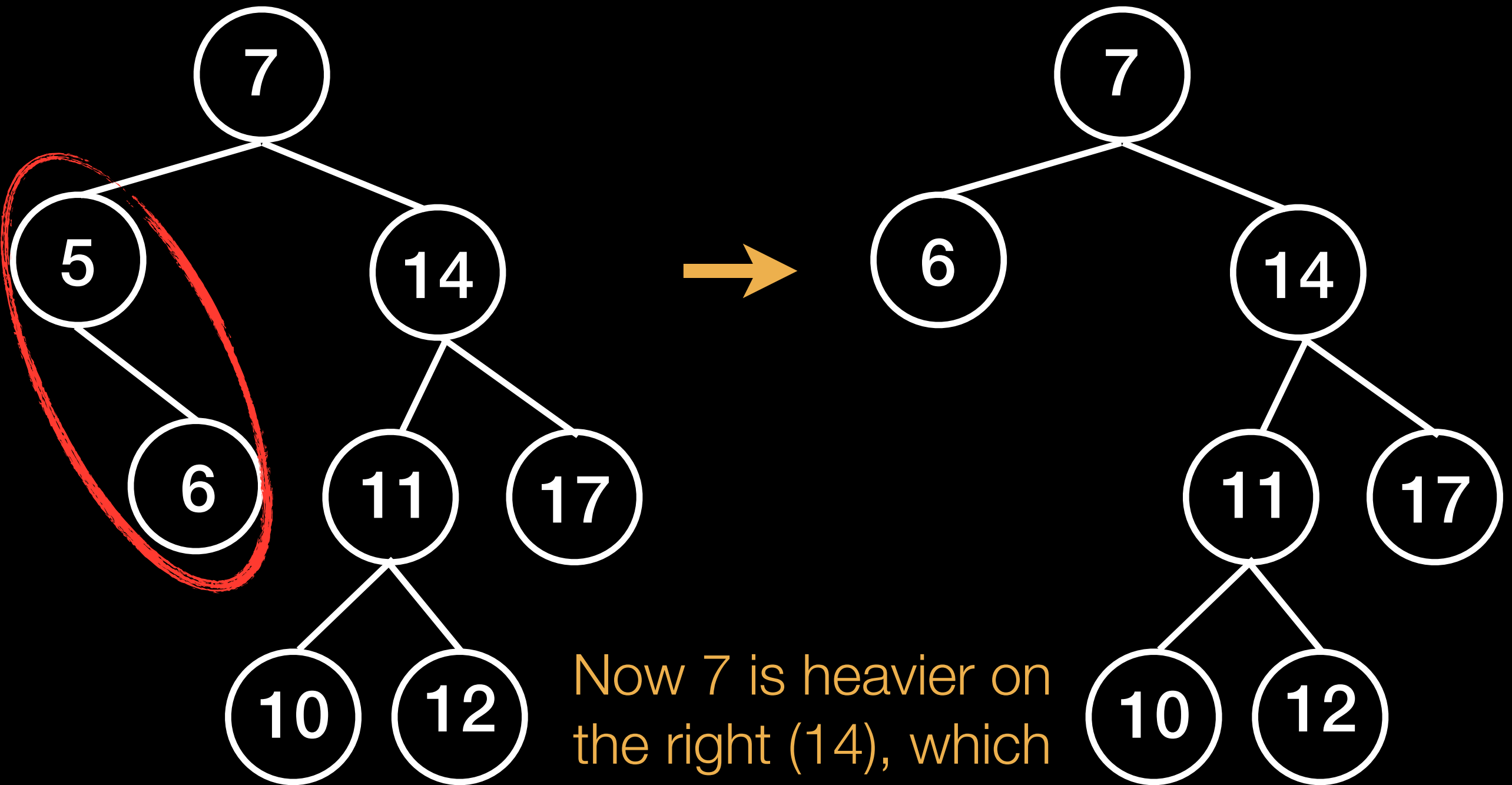
Remove 5



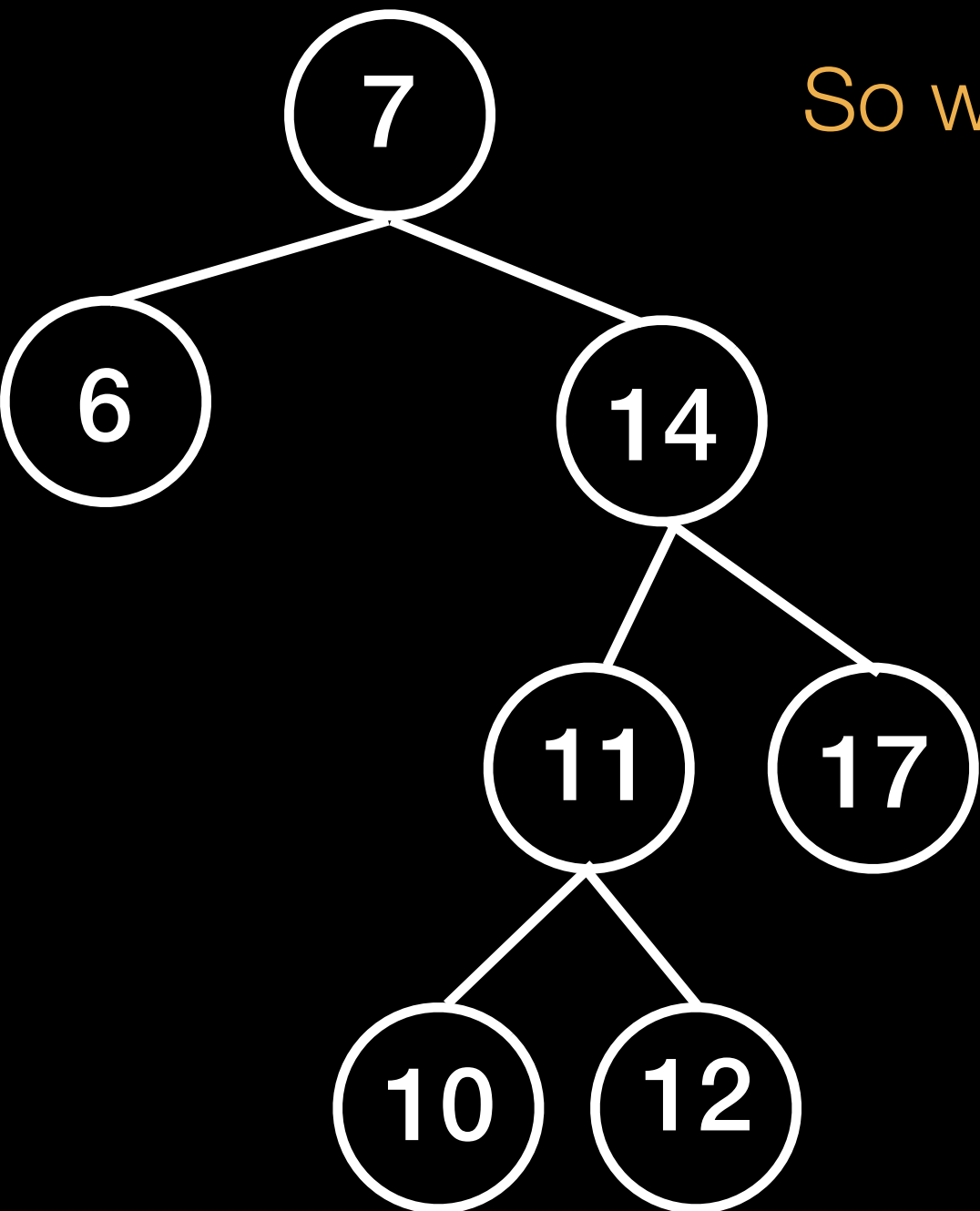
Remove 5



Remove 5

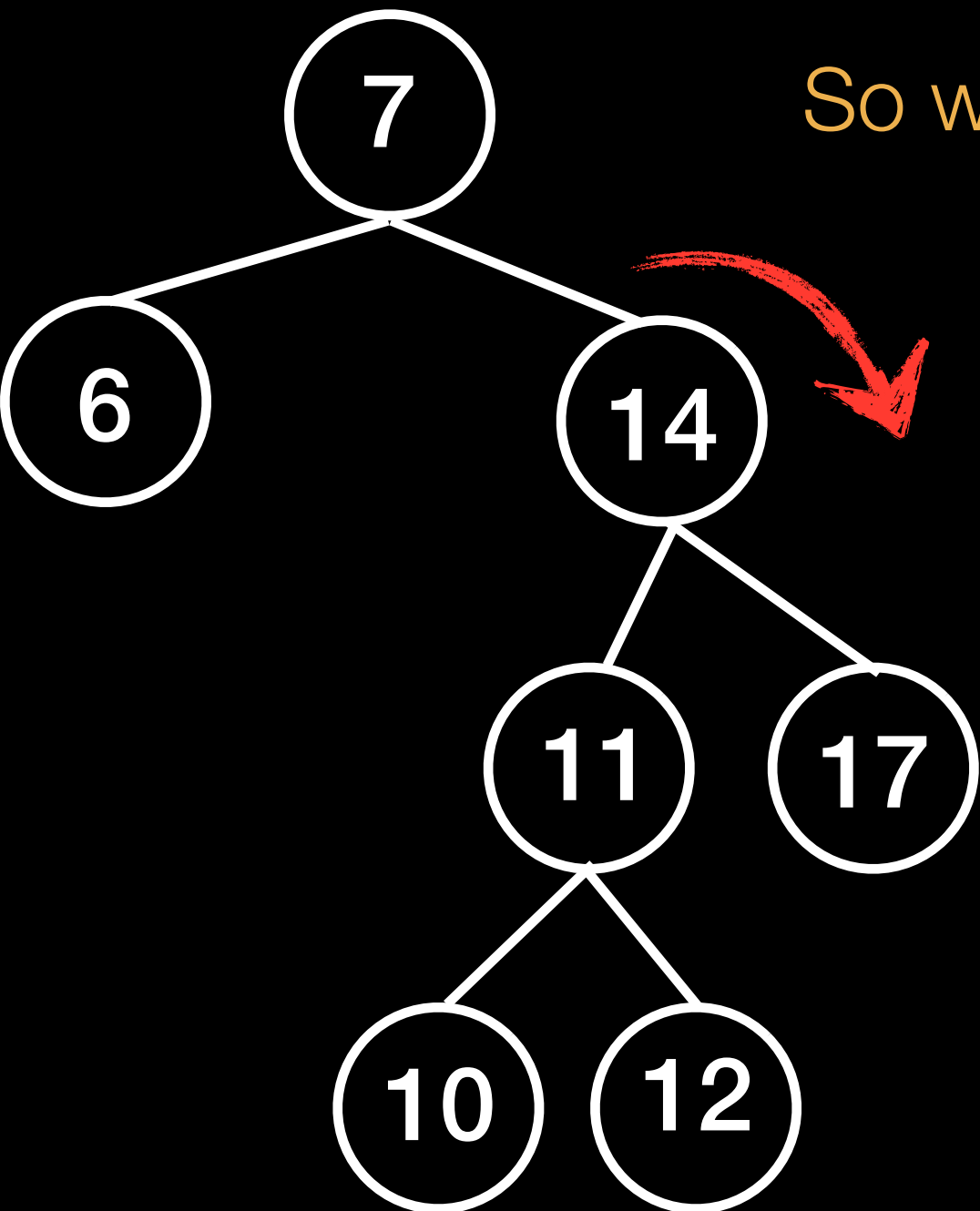


Remove 5 (continued)

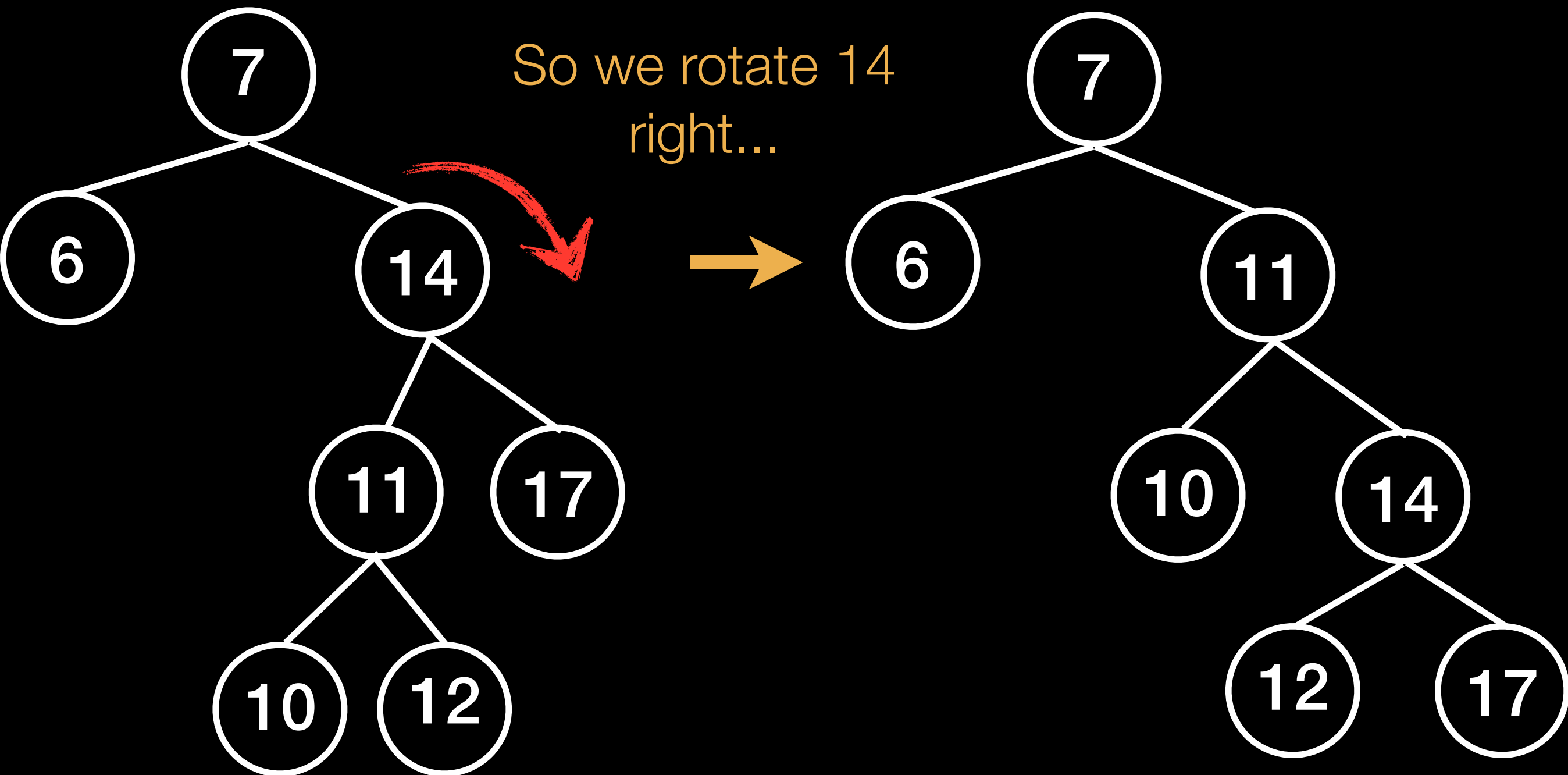


So we rotate 14
right...

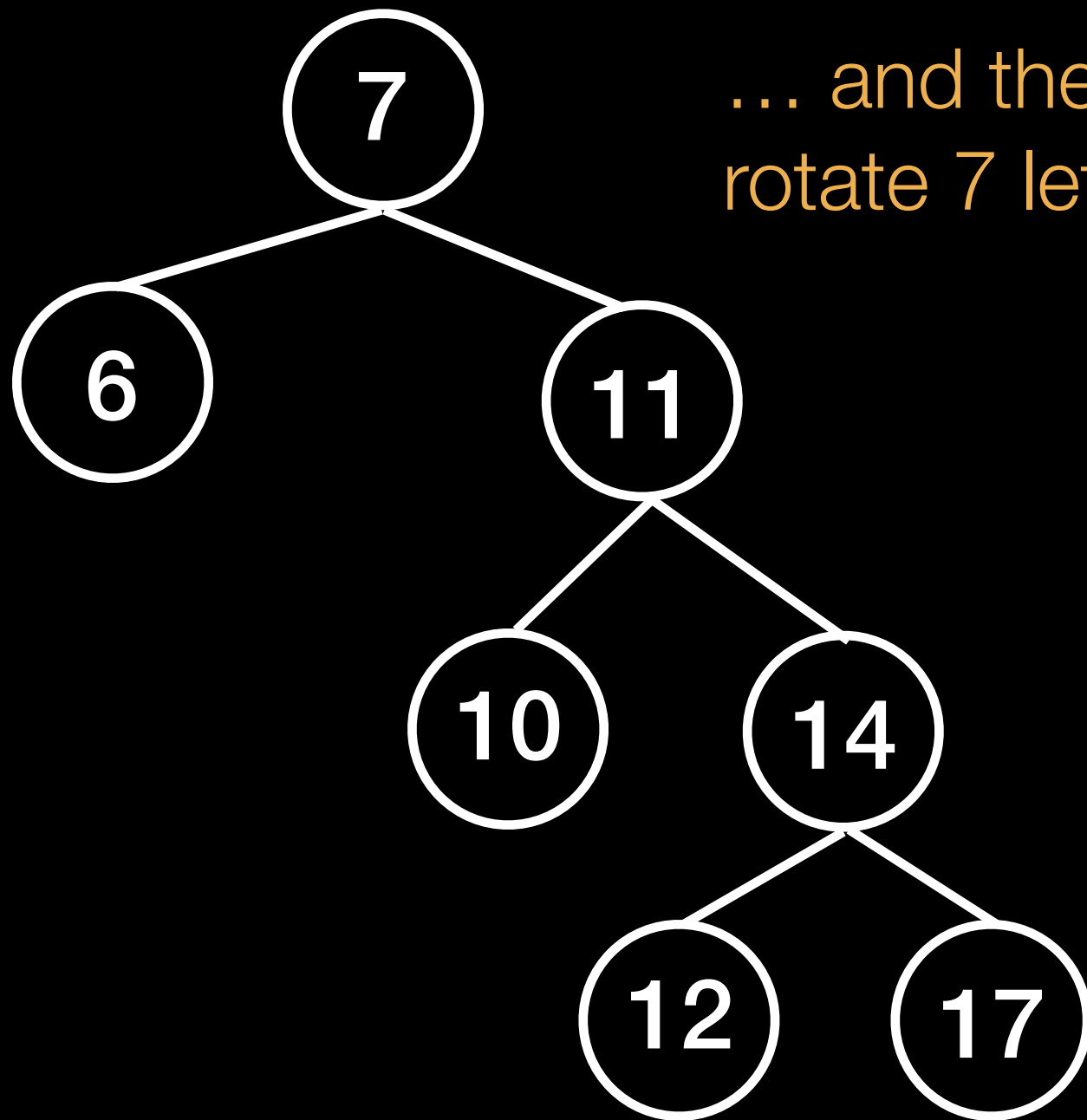
Remove 5 (continued)



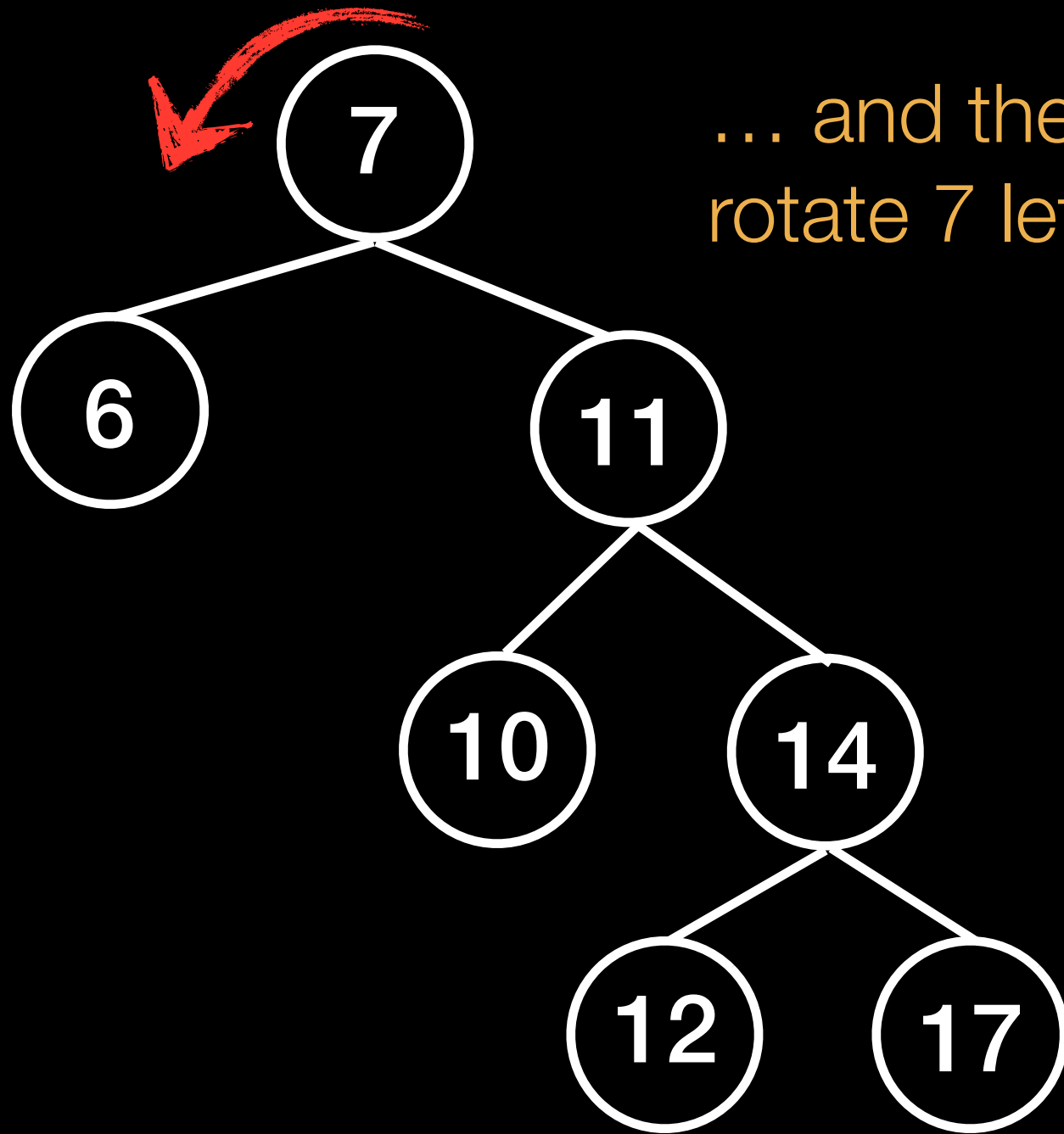
Remove 5 (continued)



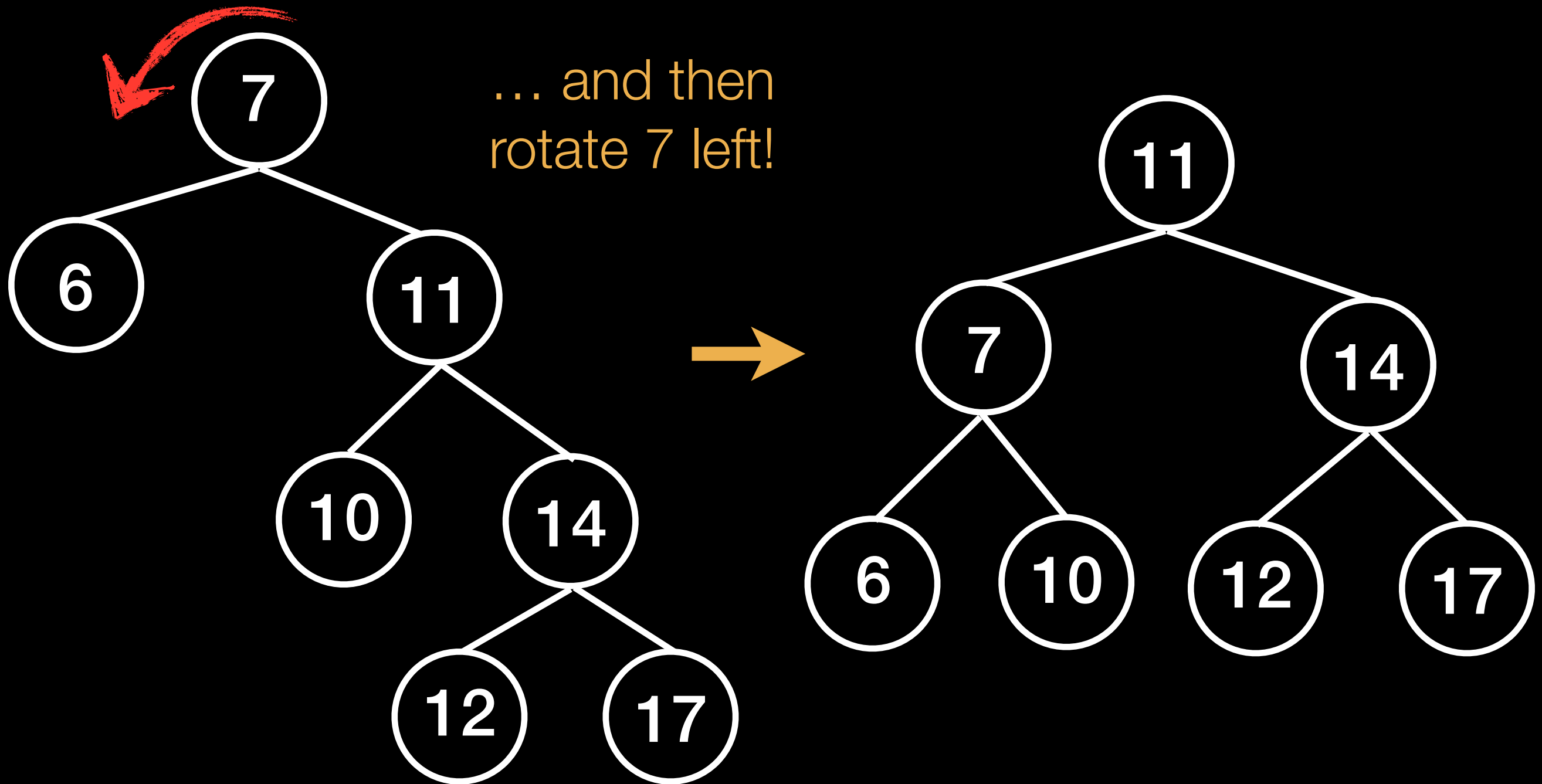
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and

2) The node's balance factor is positive, but
its right subtree's balance factor is negative,
or

The node's balance factor is negative, but its
left subtree's balance factor is positive

Balance factor = height(right subtree) -
height(left subtree)

How do we represent a binary heap?

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An array

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$2 * i + 1$ and $2 * i + 2$

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How do we add a node to a heap?

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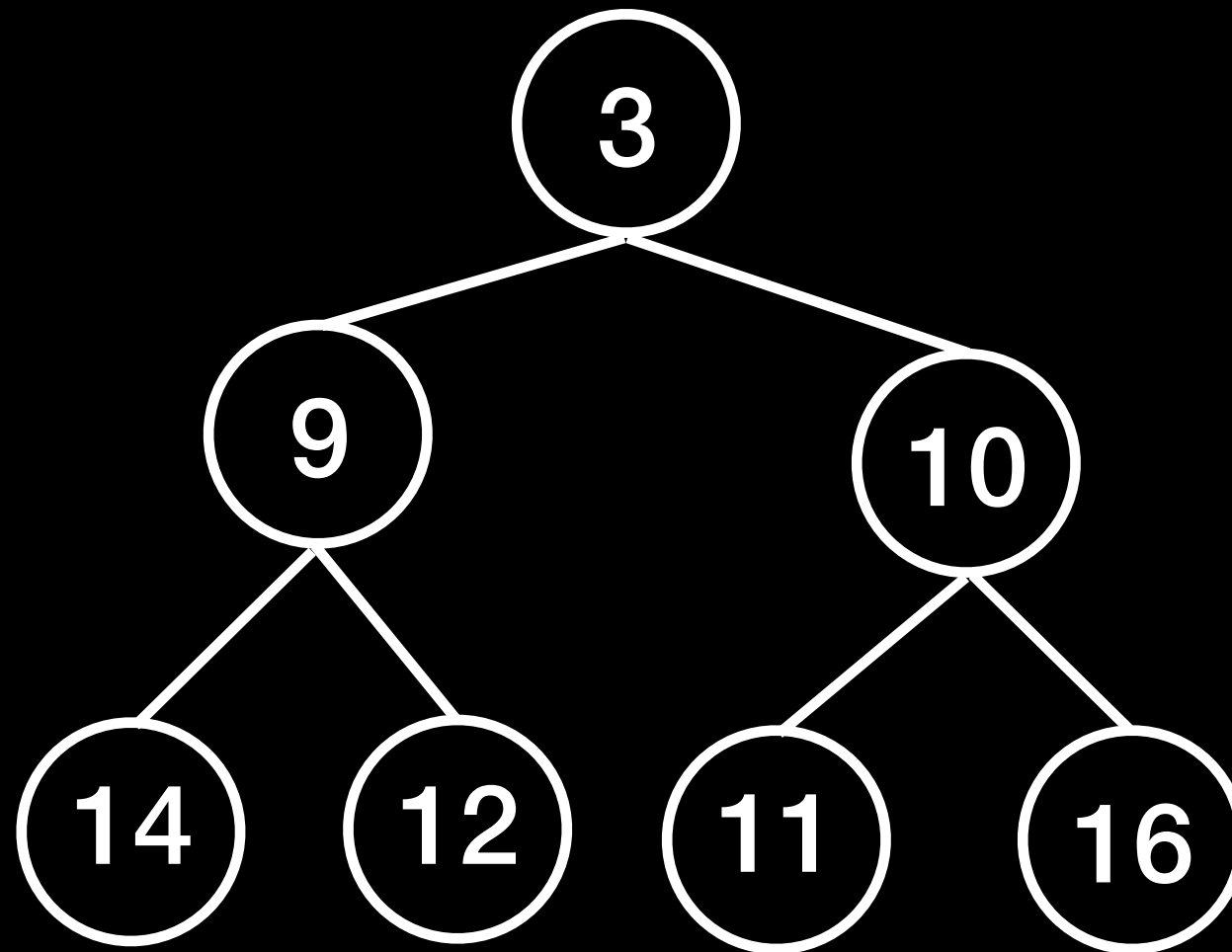
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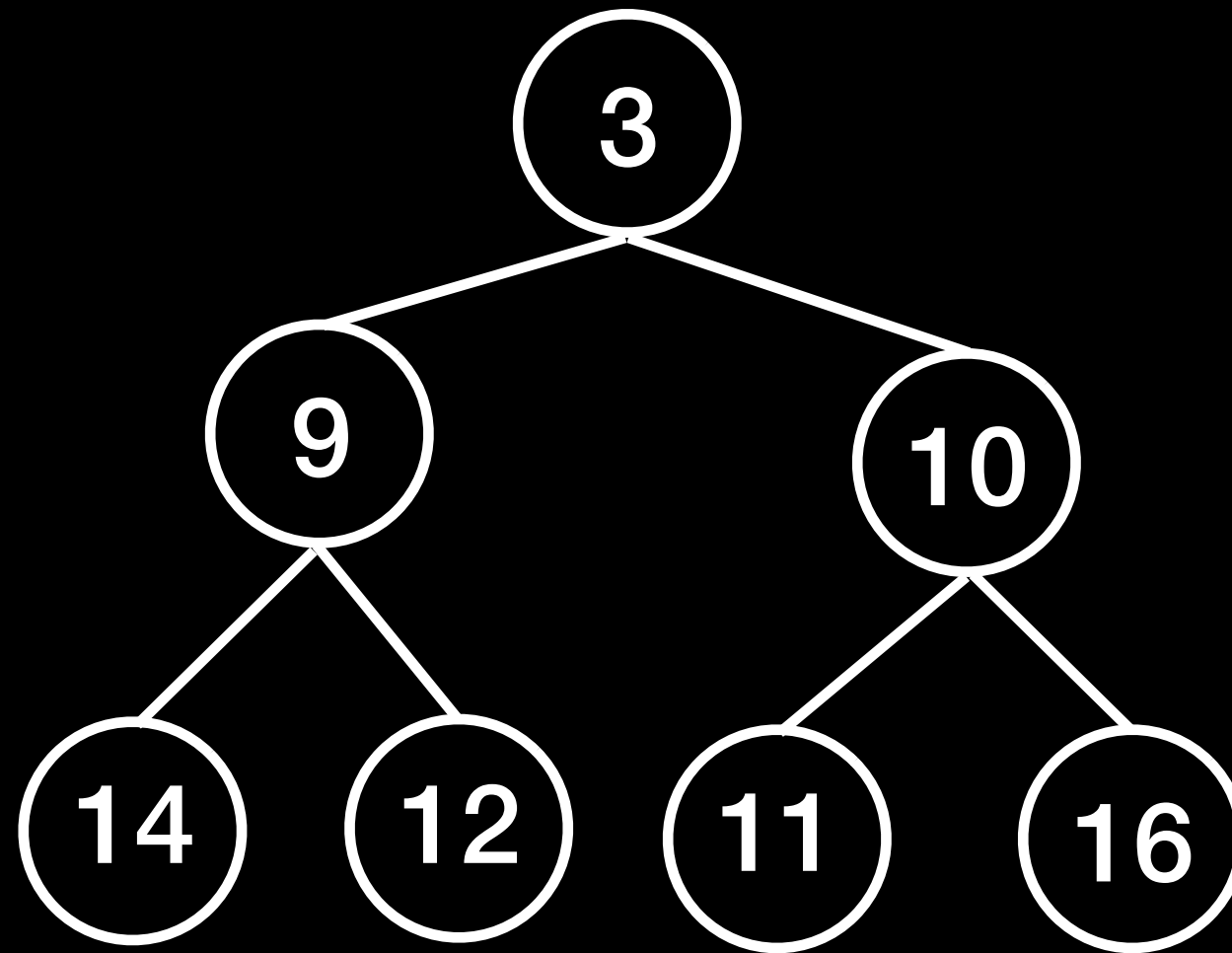
How do we add a node to a heap?

Insert it after the last item, then percolate it up

Simulate **heap sort** on this heap



Simulate **heap sort** on this heap



We'll work this out on the
chalk board

If we have a hash table with 11 buckets and the silly hash function $hash(x) = x$, what will the hash table look like after inserting 3, 43, 8, 11, 14, 25, 23, 44 using **open addressing**?

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0	
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	

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If 'bucket' is in use, try the next one

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2	
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0	11
1	
2	
3	3
4	
5	
6	
7	
8	8
9	
10	43

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0	11
1	
2	
3	3 14
4	
5	
6	
7	
8	8
9	
10	43

If we have a hash table with 11 buckets and the silly hash function $hash(x) = x$, what will the hash table look like after inserting 3, 43, 8, 11, 14, 25, 23, 44 using **open addressing**?

$bucket = hash(x) \% 11$

If 'bucket' is in use, try the next one

0	11
1	
2	
3	3
4	14
5	
6	
7	
8	8
9	
10	43

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If 'bucket' is in use, add the item to the chain

0
1
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4
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9
10

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What is the **table load**?

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2			
3	3	14	25
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What is the **table load**?

8 items / 11 buckets

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1	23		
2			
3	3	14	25
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5			
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8	8		
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10	43		

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Does hash table performance increase or decrease as the number of buckets increases?

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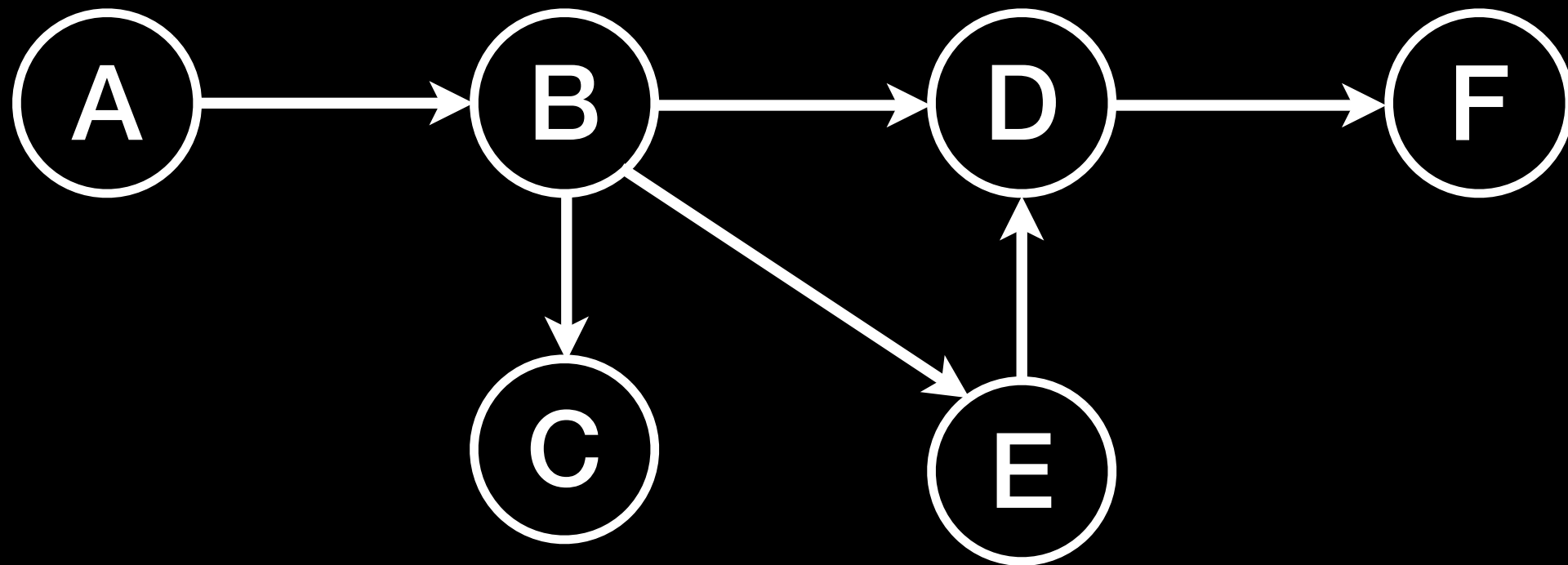
Does each key in a hash table need to hash to a unique value?

No, but we should use a hash function with as few collisions as possible

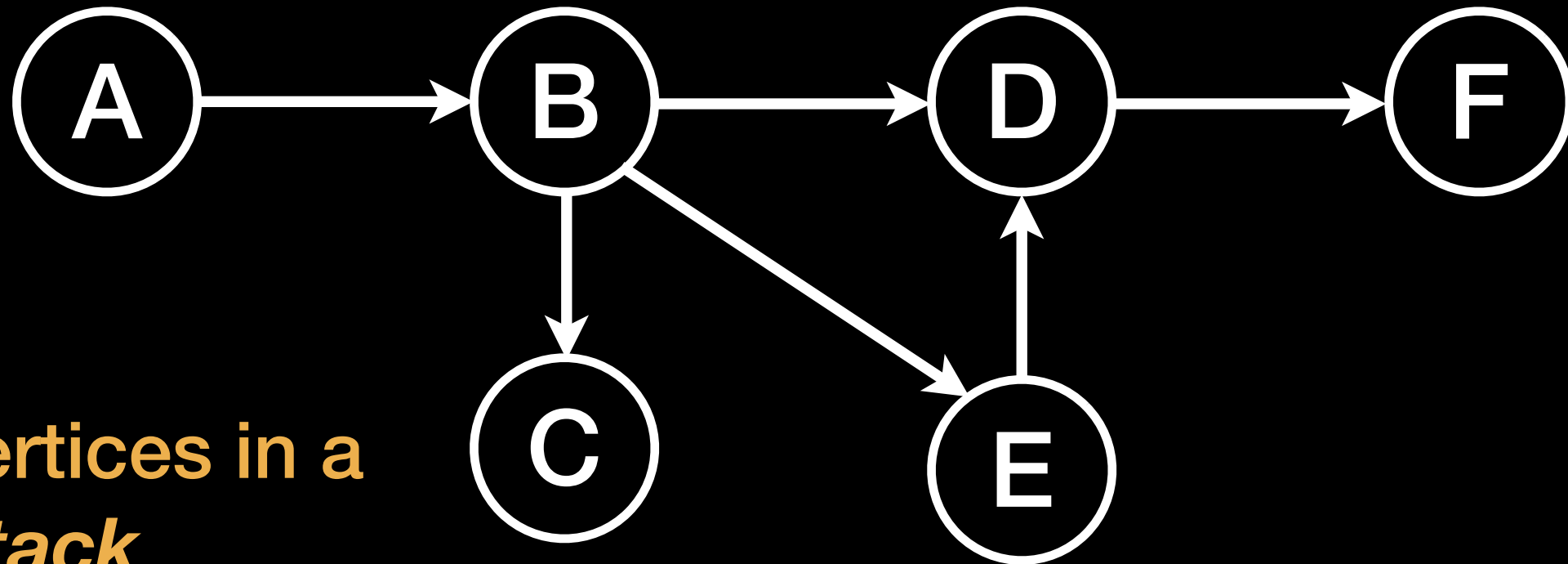
Does hash table performance increase or decrease as the number of buckets increases?

It should increase

Simulate **depth-first search** on this graph

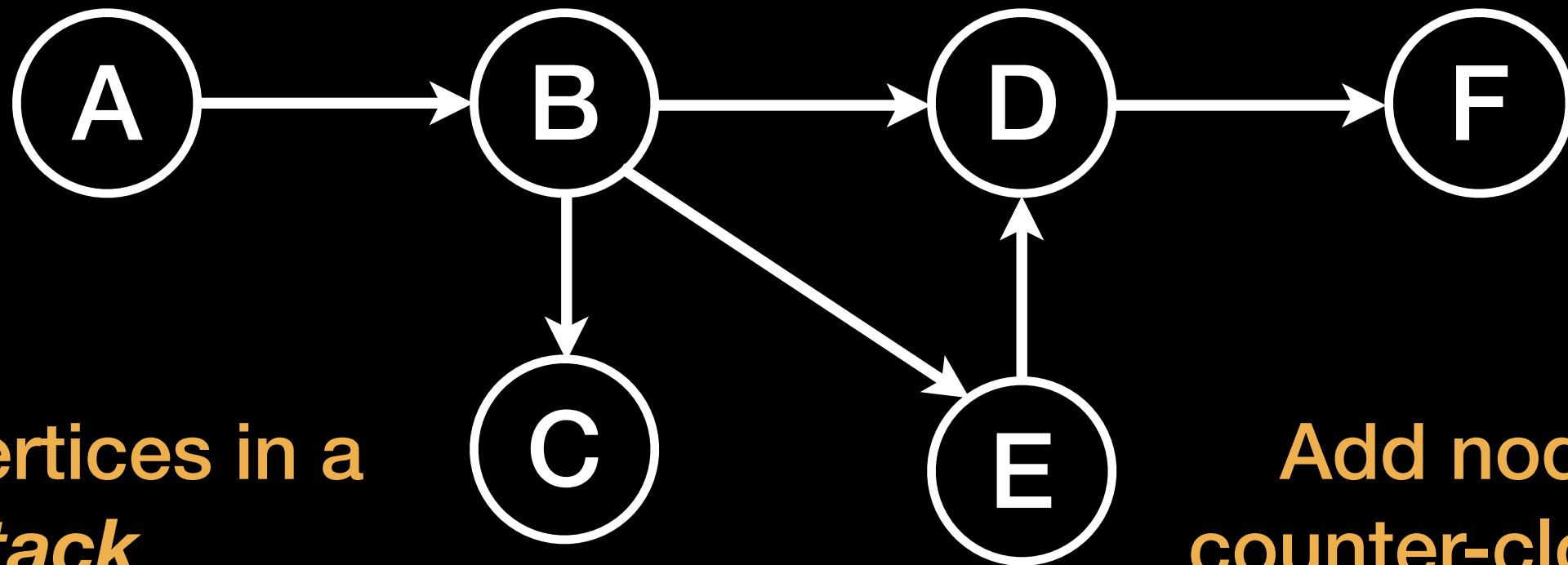


Simulate **depth-first search** on this graph



Store vertices in a
stack
(last in, first out)

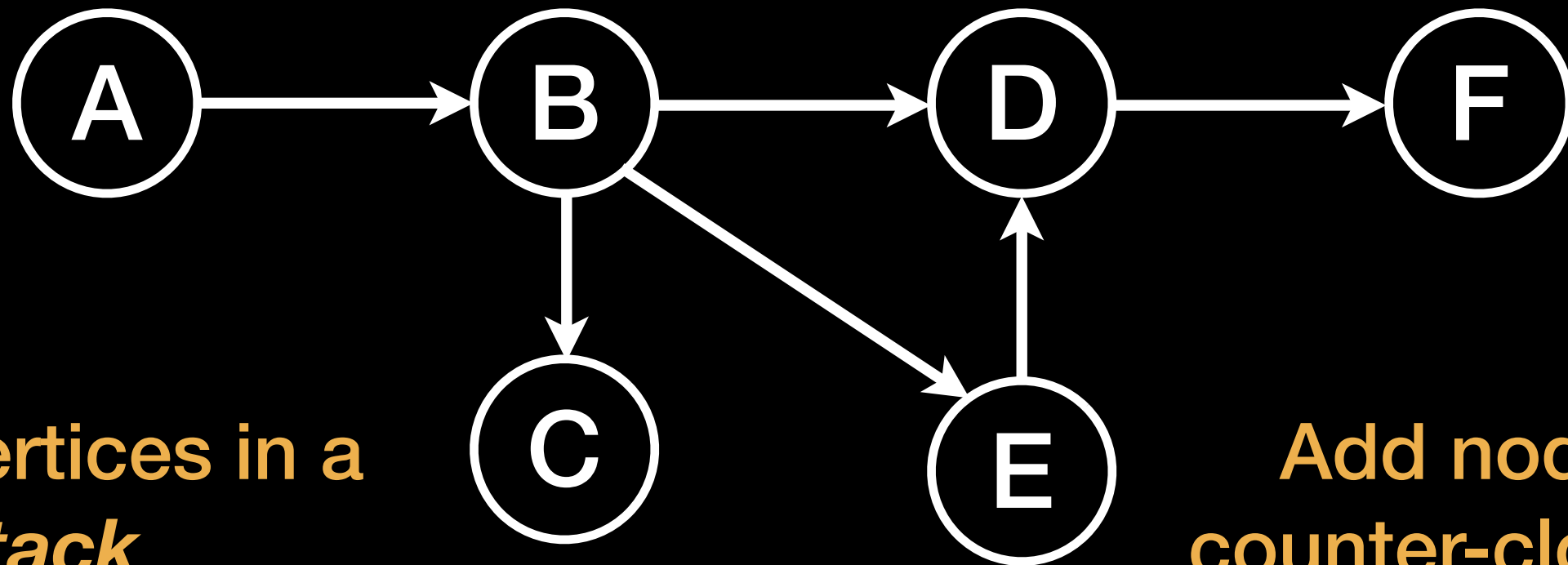
Simulate **depth-first search** on this graph



Store vertices in a
stack
(last in, first out)

Add nodes in
counter-clockwise
order

Simulate **depth-first search** on this graph



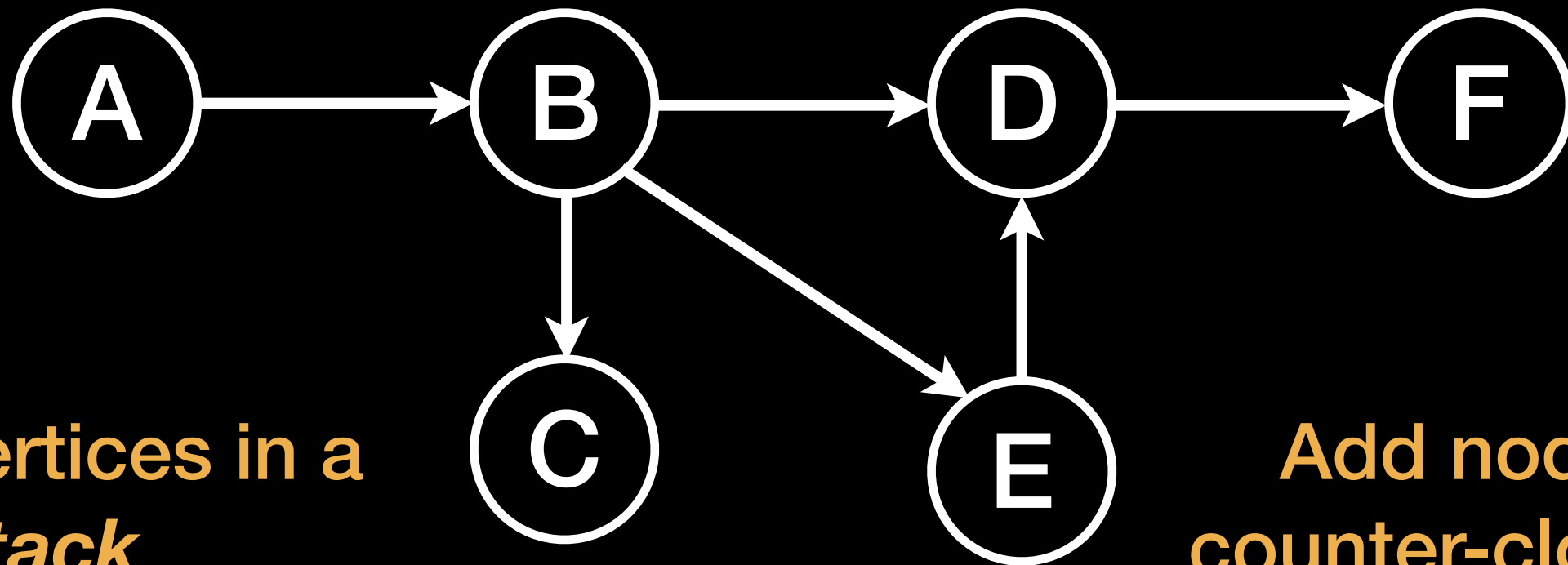
Store vertices in a
stack
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Add nodes in
counter-clockwise
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Reachable:

Known:

Simulate **depth-first search** on this graph



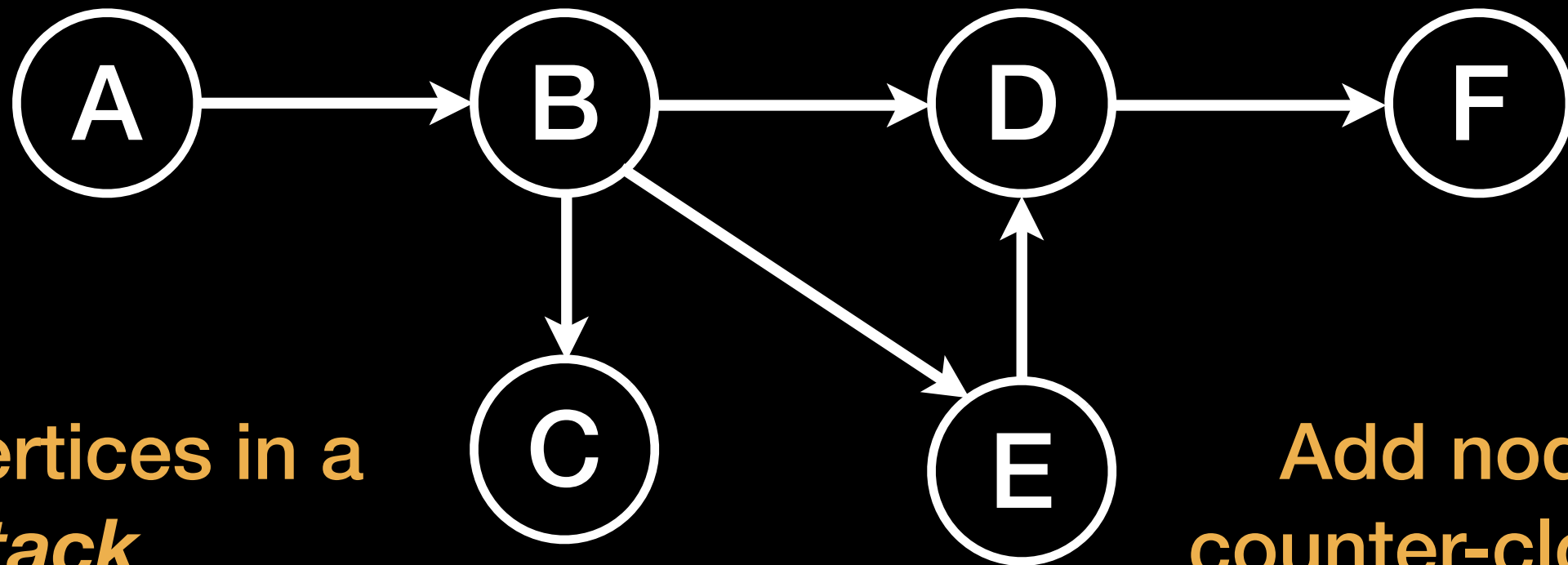
Store vertices in a
stack
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Add nodes in
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Reachable:

Known: **A**

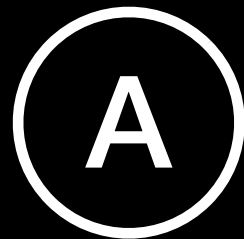
Simulate **depth-first search** on this graph



Store vertices in a
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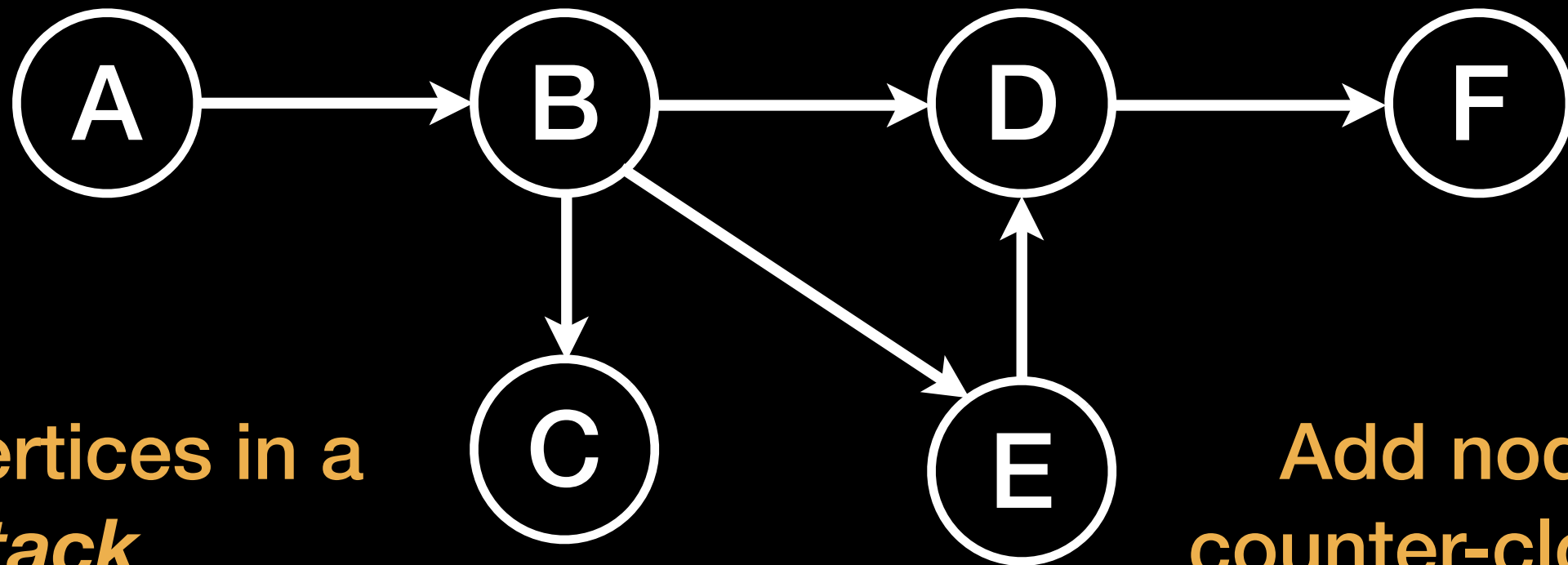
Add nodes in
counter-clockwise
order

Reachable:



Known:

Simulate **depth-first search** on this graph



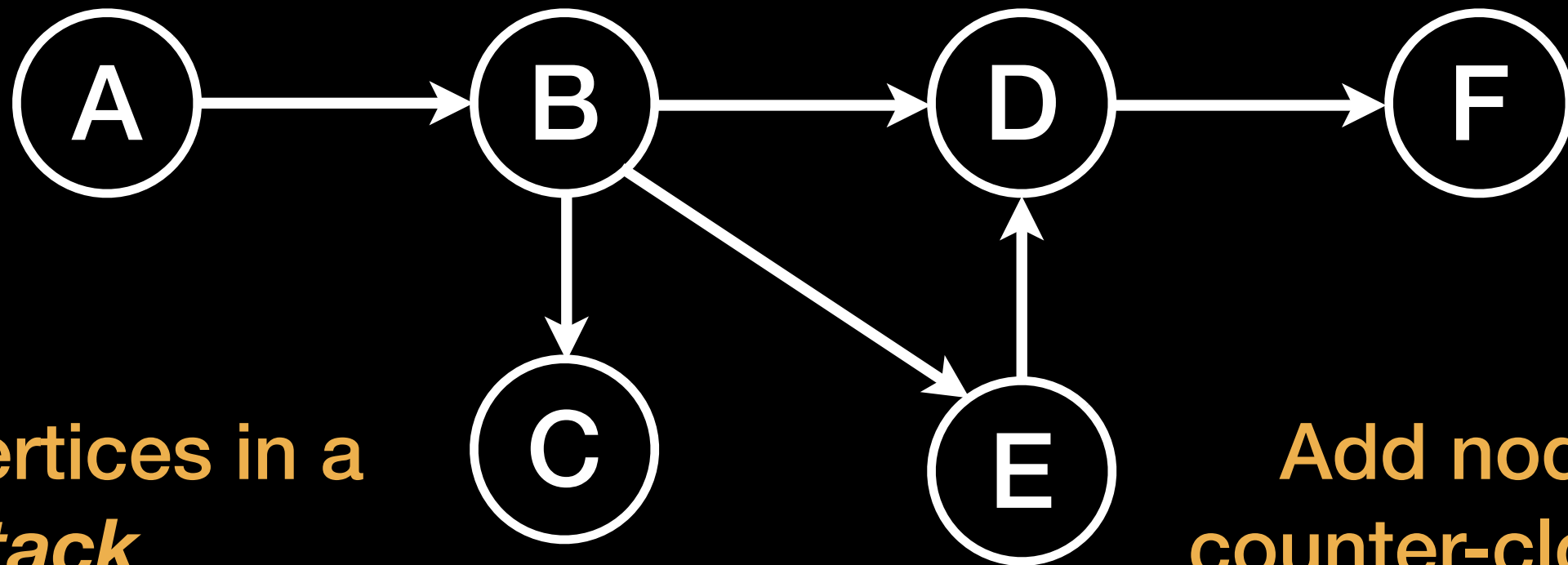
Store vertices in a
stack
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Add nodes in
counter-clockwise
order

Reachable: **A**

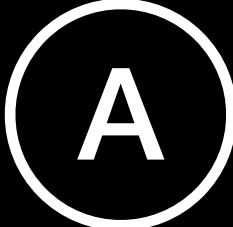
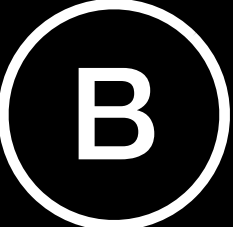
Known: **B**

Simulate **depth-first search** on this graph



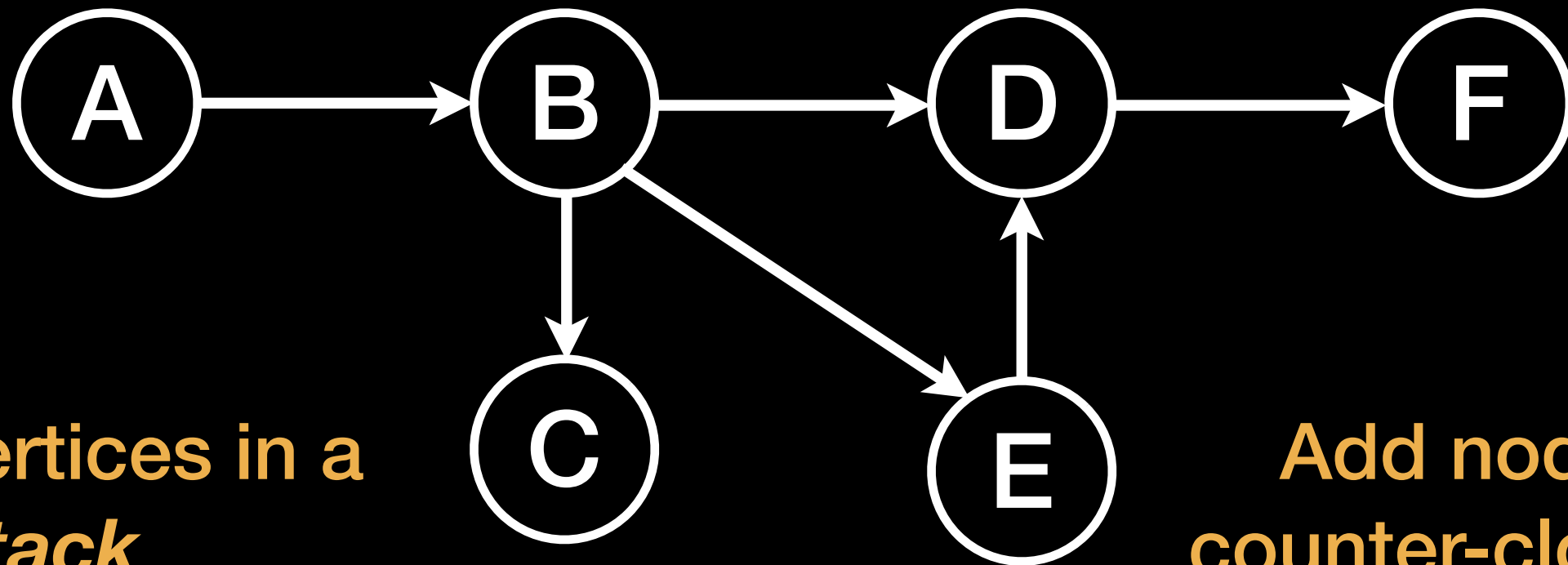
Store vertices in a
stack
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Add nodes in
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order

Reachable:  

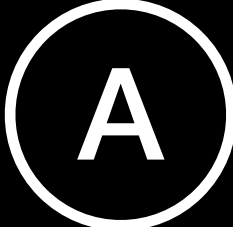
Known:

Simulate **depth-first search** on this graph



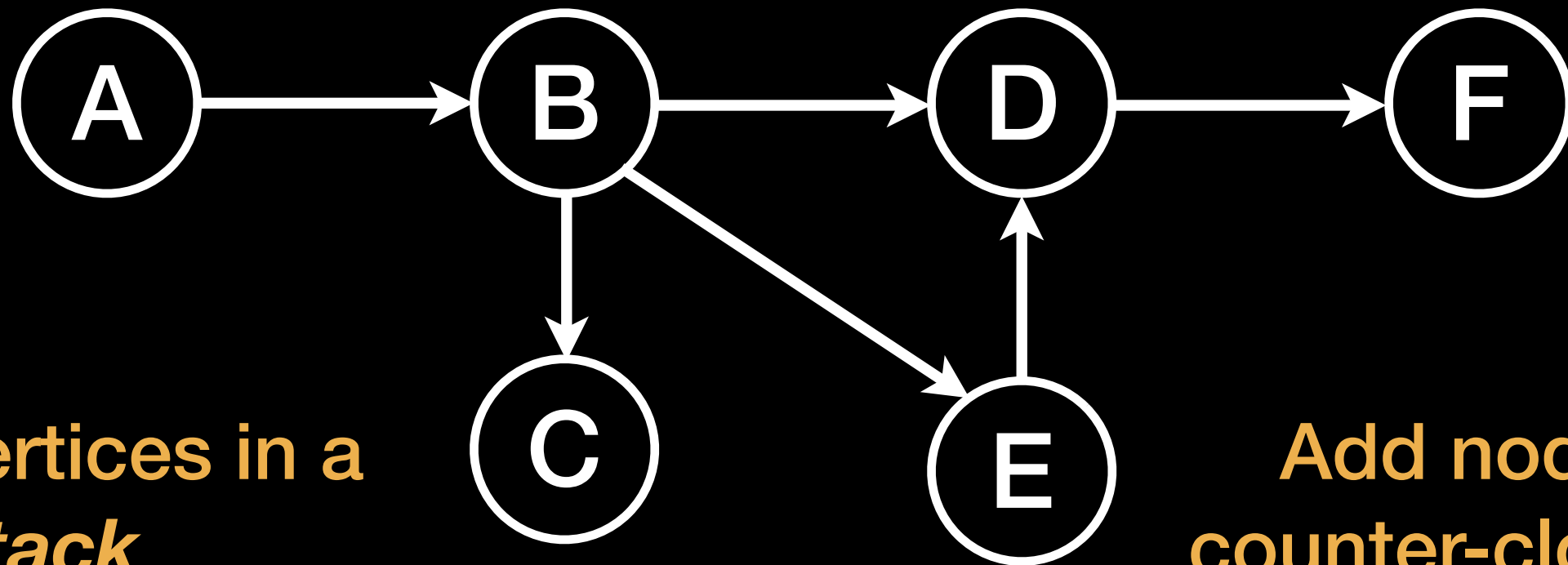
Store vertices in a
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Add nodes in
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Reachable:  

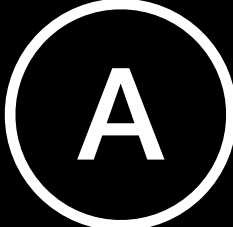
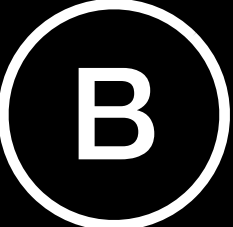
Known: 

Simulate **depth-first search** on this graph



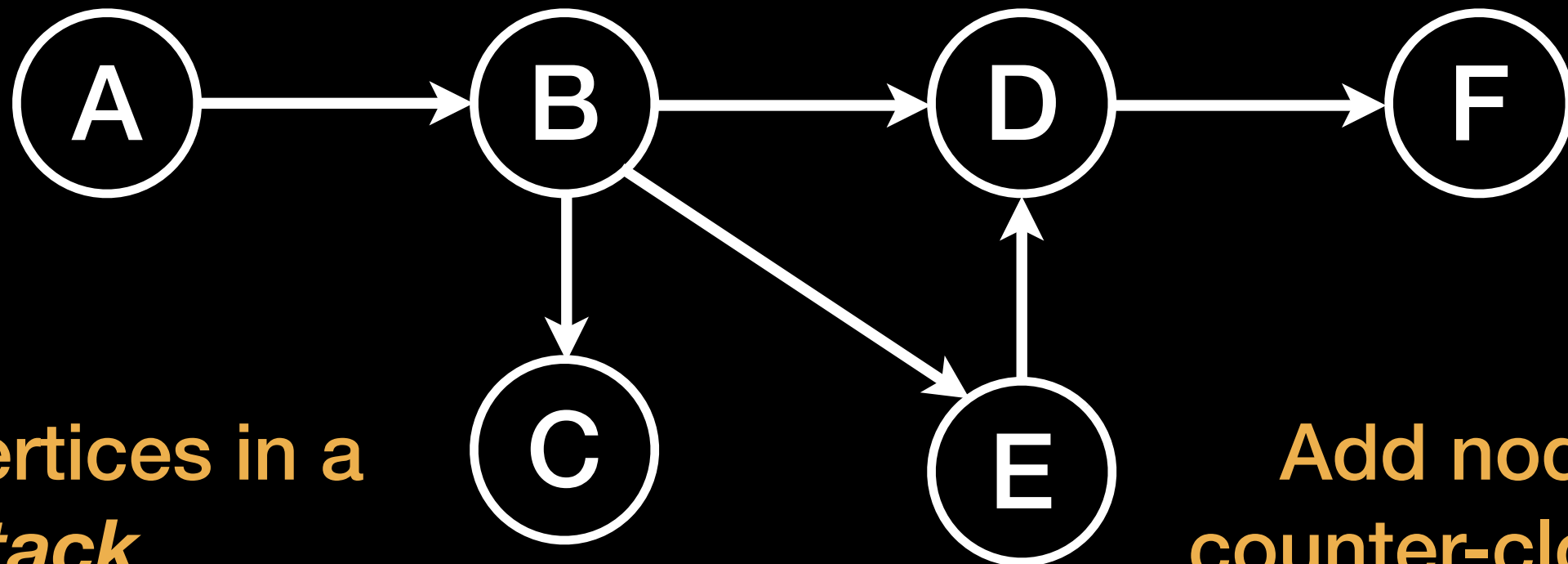
Store vertices in a
stack
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Add nodes in
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Reachable:  

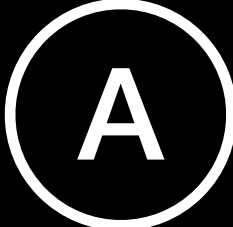
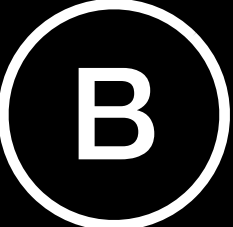
Known:  

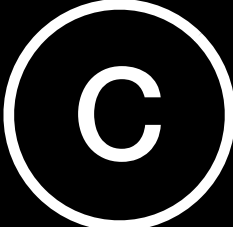
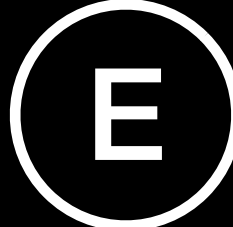
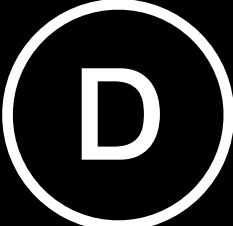
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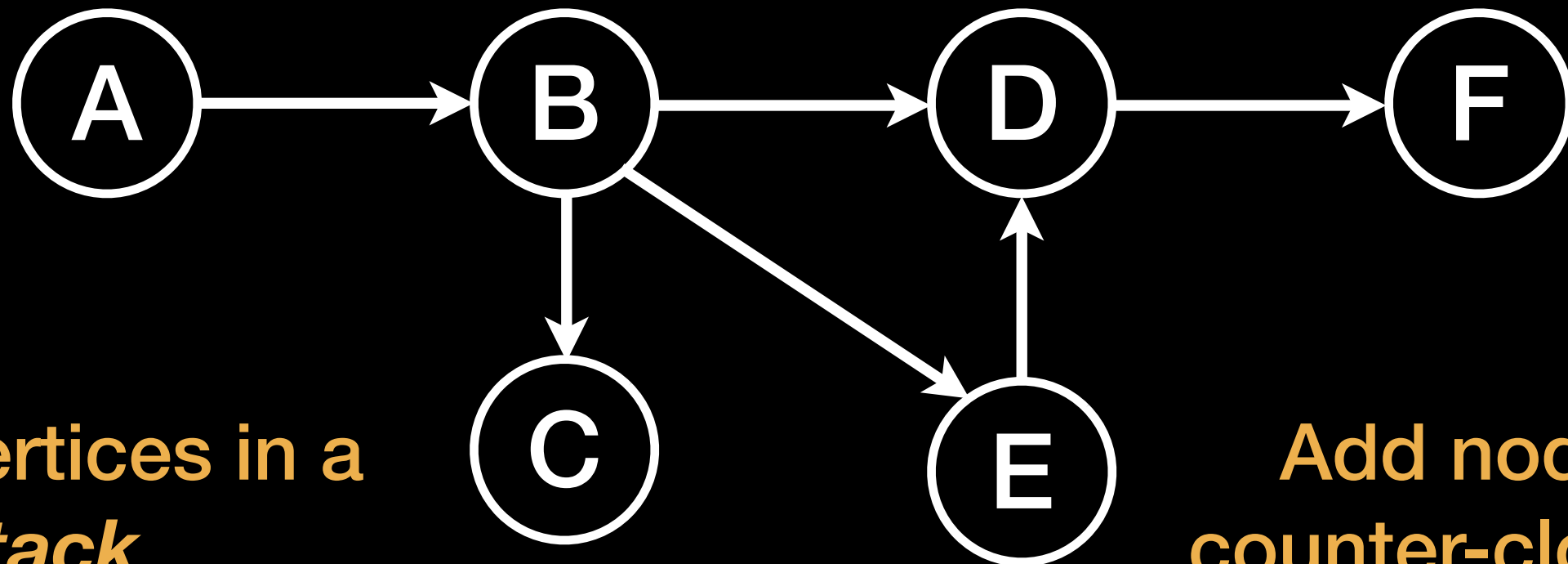
Store vertices in a
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Add nodes in
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Reachable:  

Known:   

Simulate **depth-first search** on this graph



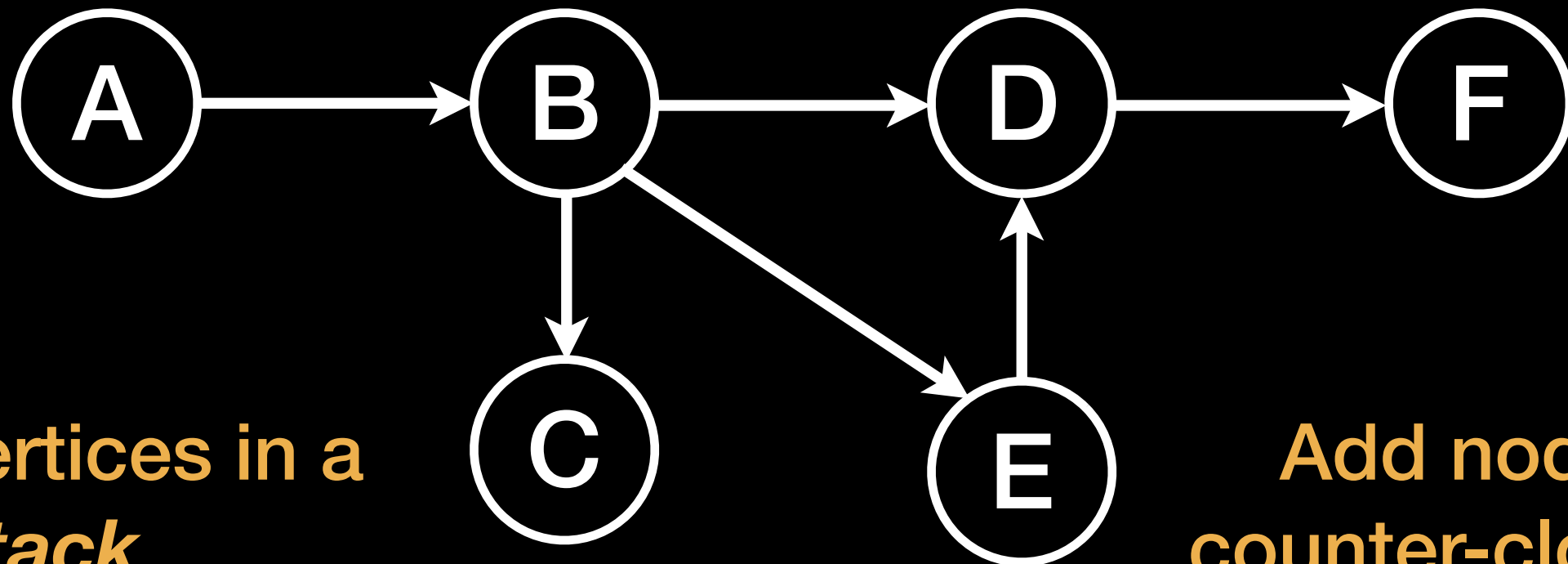
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Add nodes in
counter-clockwise
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Reachable: A B D

Known: C E

Simulate **depth-first search** on this graph



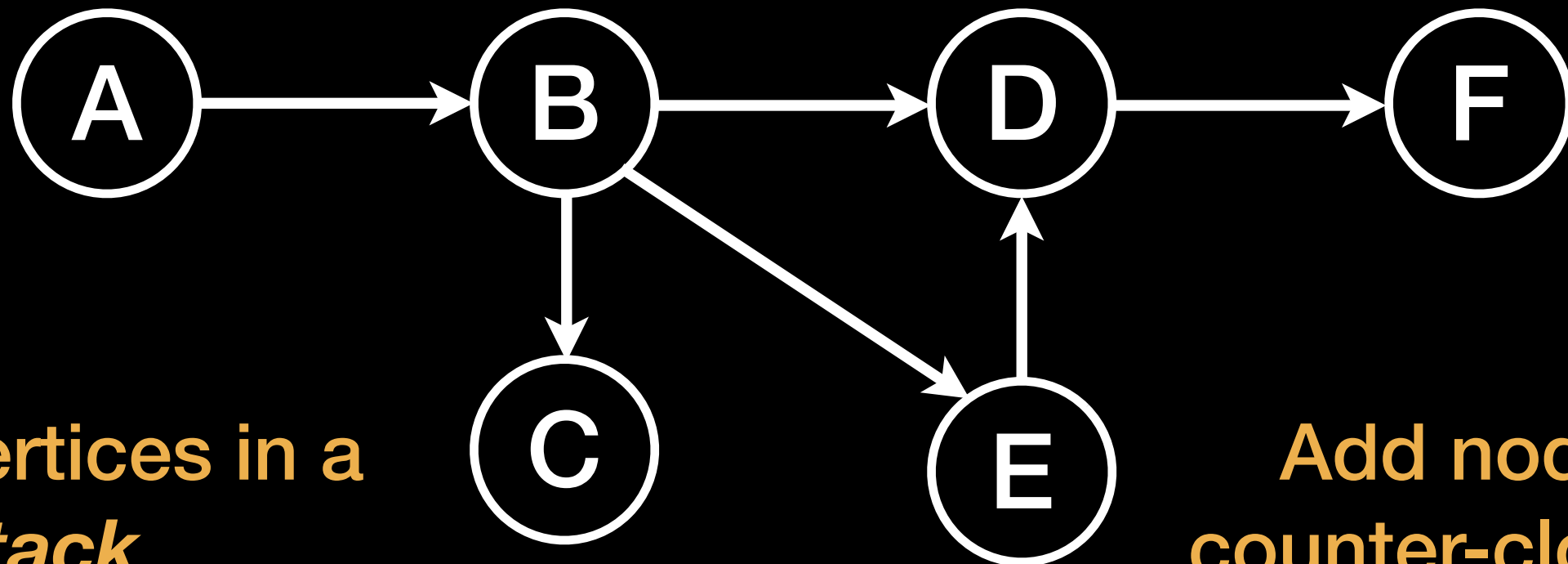
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Reachable: A B D

Known: C E F

Simulate **depth-first search** on this graph



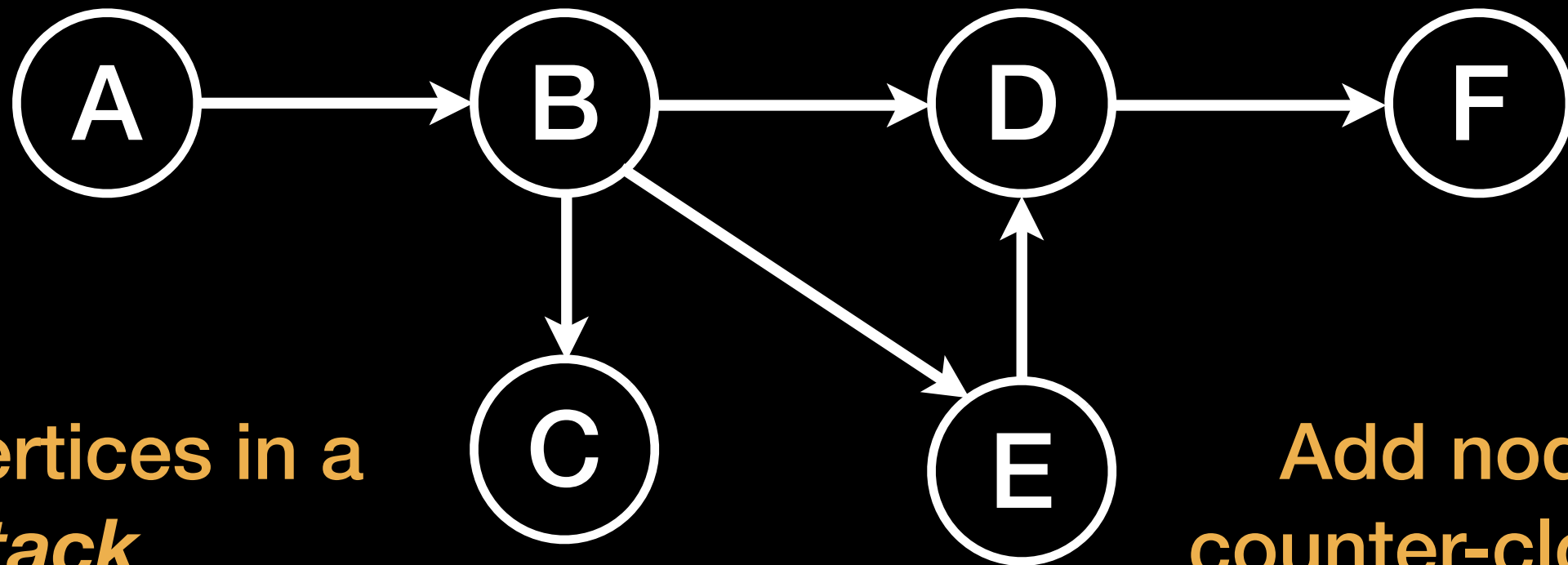
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Reachable: A B D F

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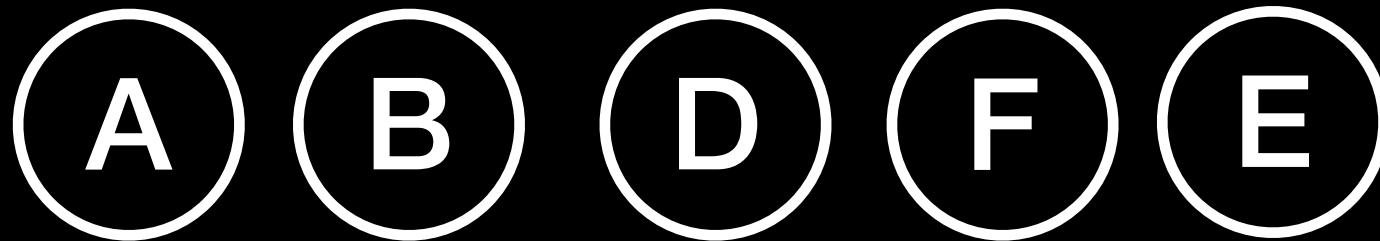
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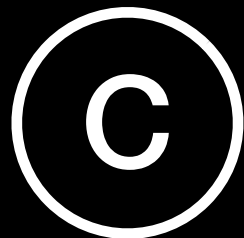
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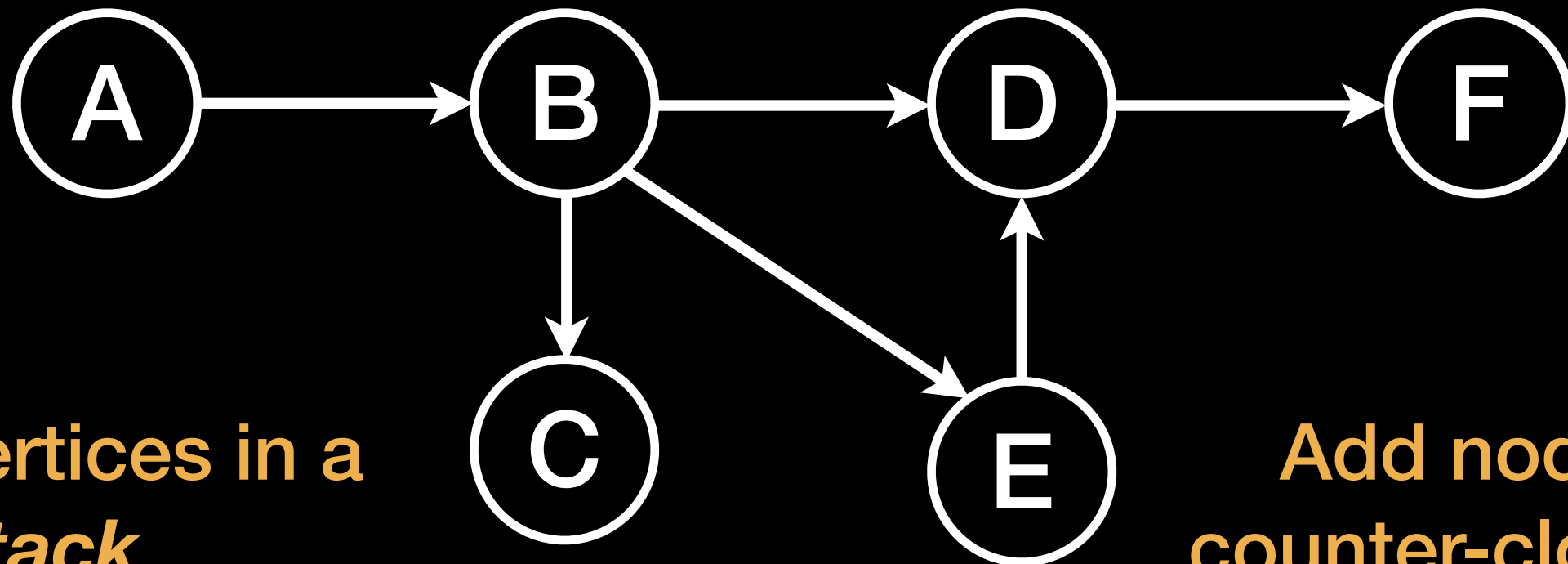
Reachable:



Known:



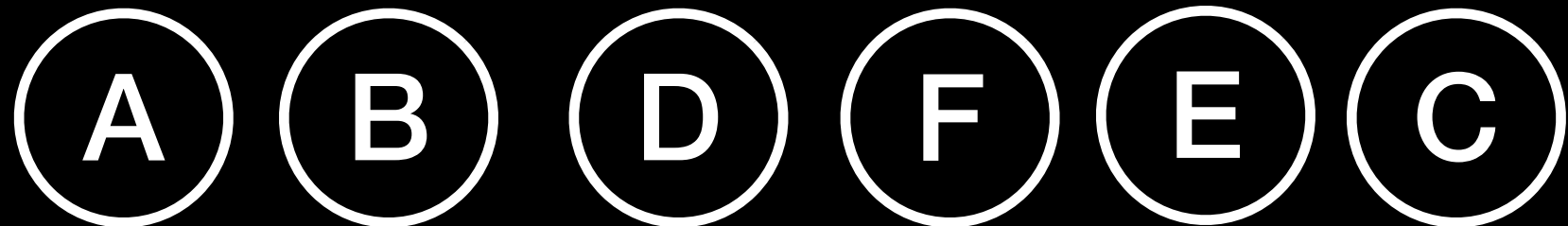
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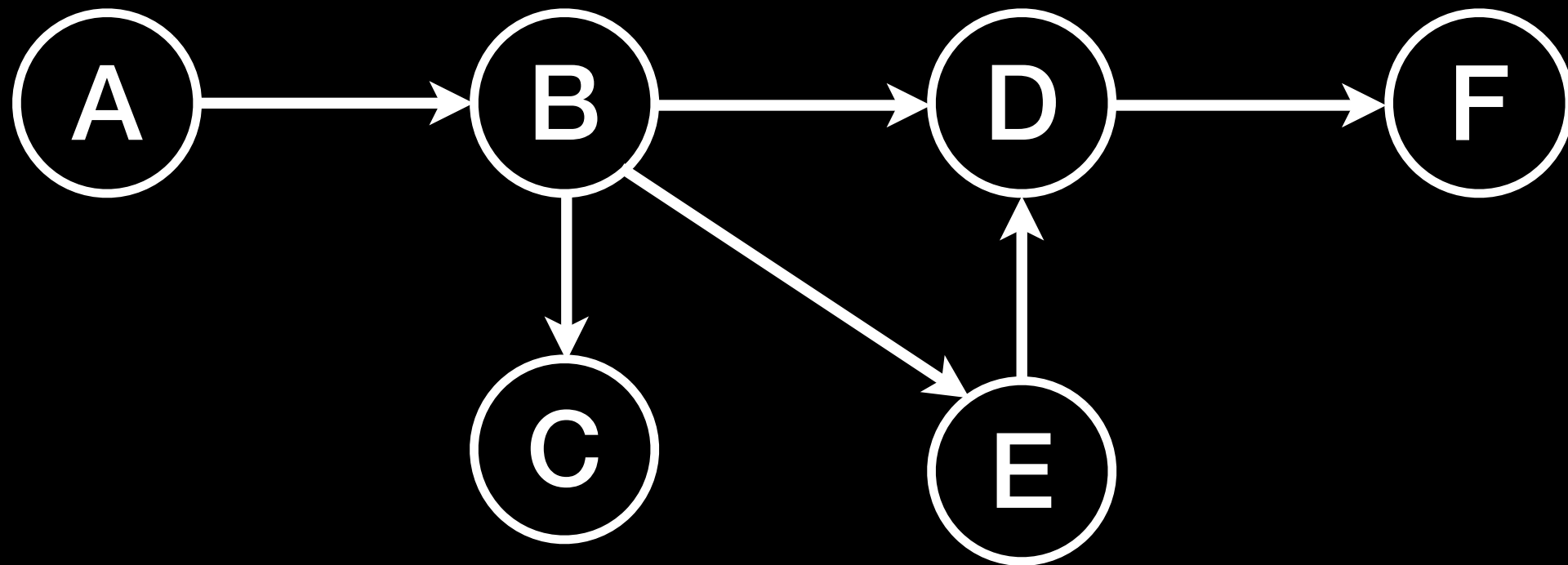
Add nodes in
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Reachable:

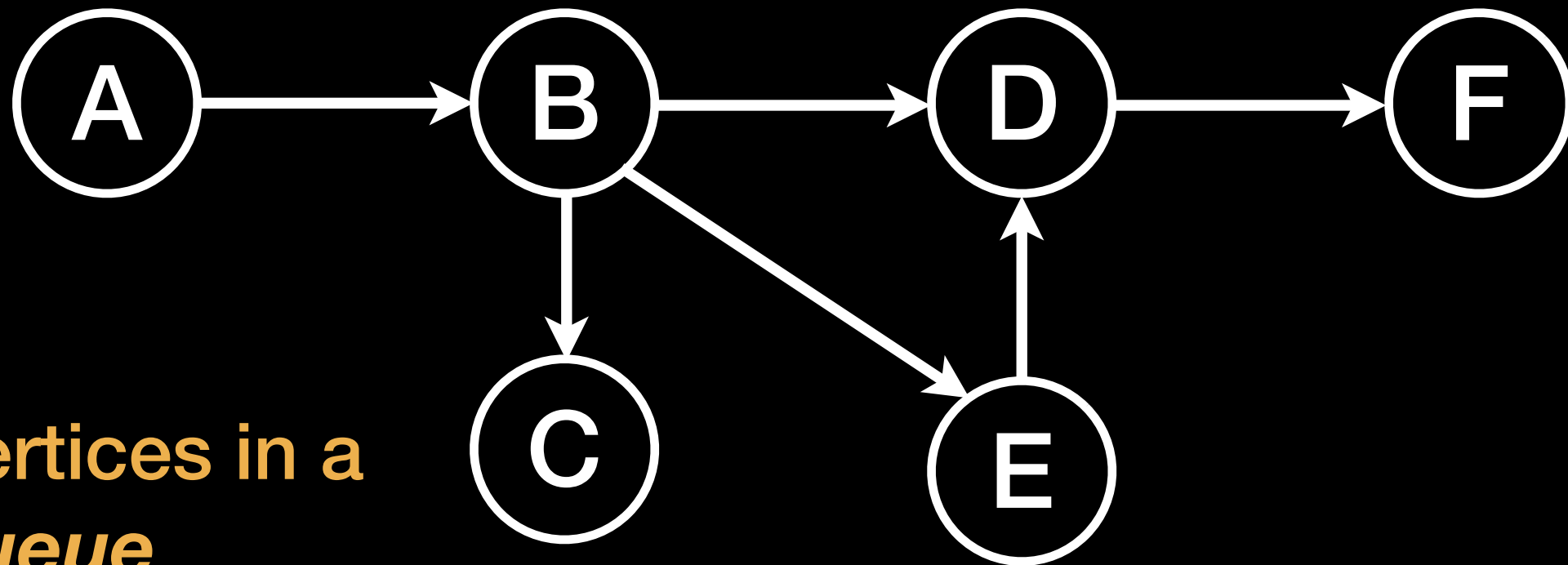


Known:

Simulate **breadth-first search** on this graph

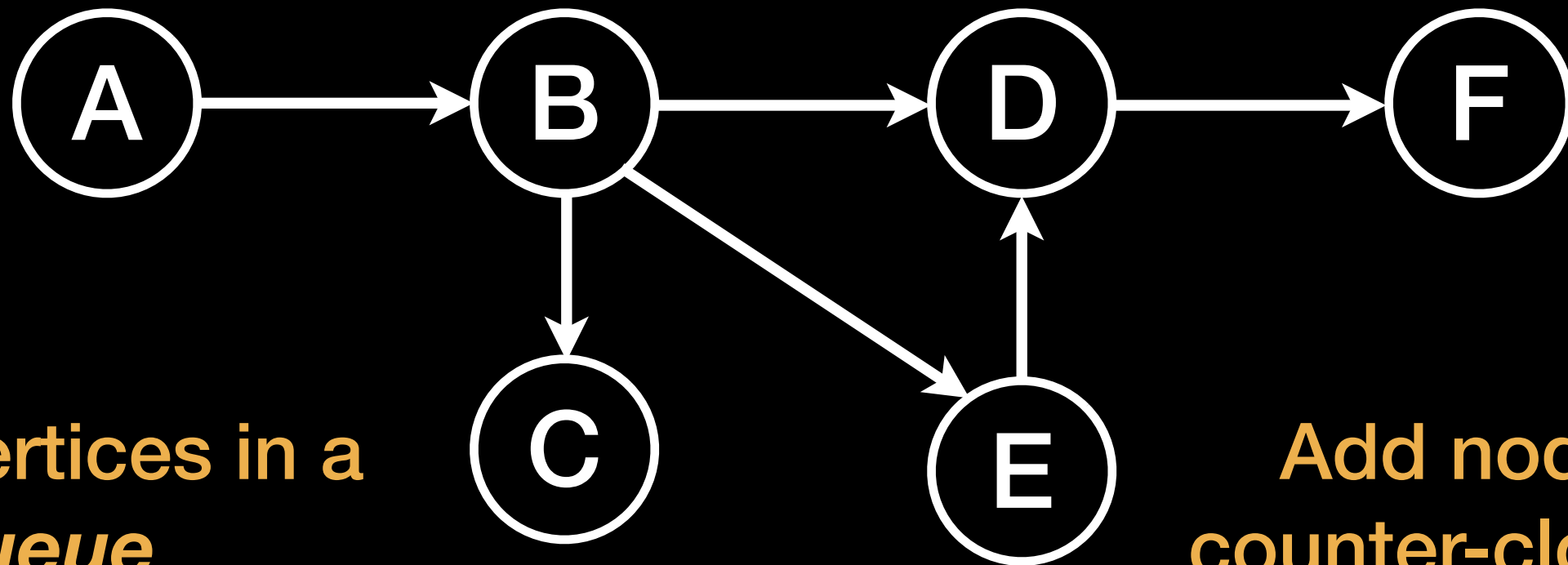


Simulate **breadth-first search** on this graph



Store vertices in a
queue
(first in, first out)

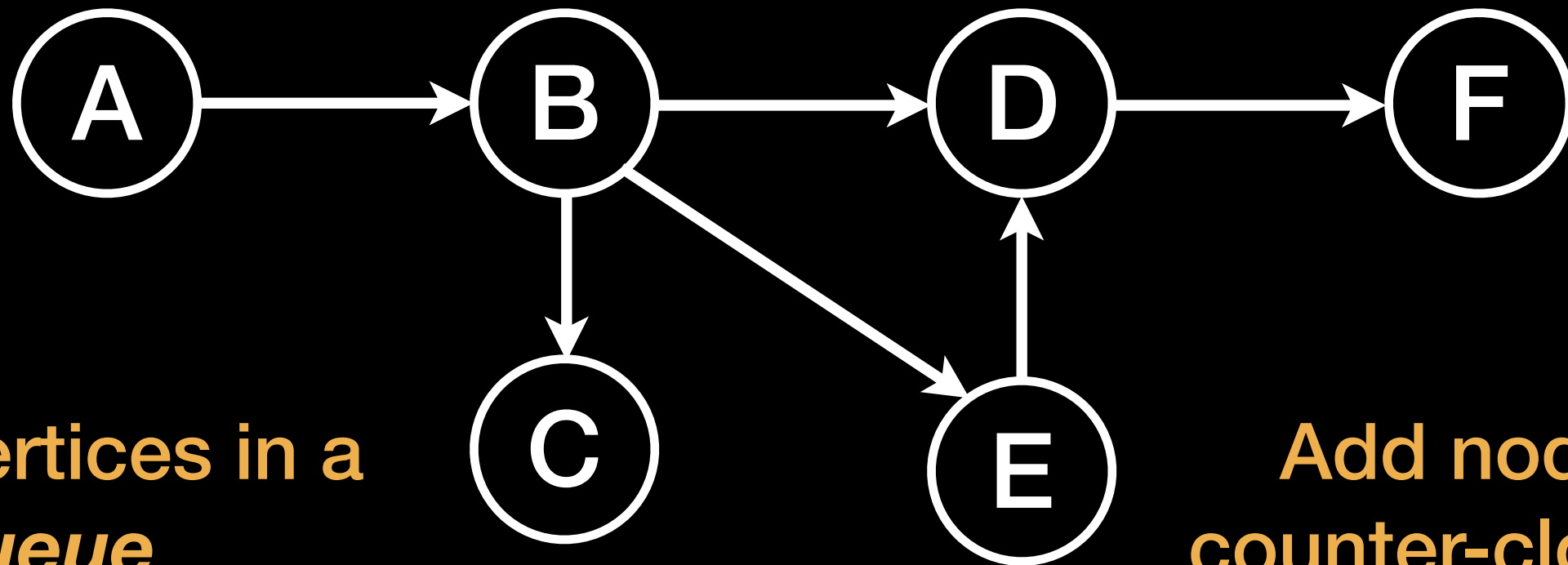
Simulate **breadth-first search** on this graph



Store vertices in a
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Simulate **breadth-first search** on this graph



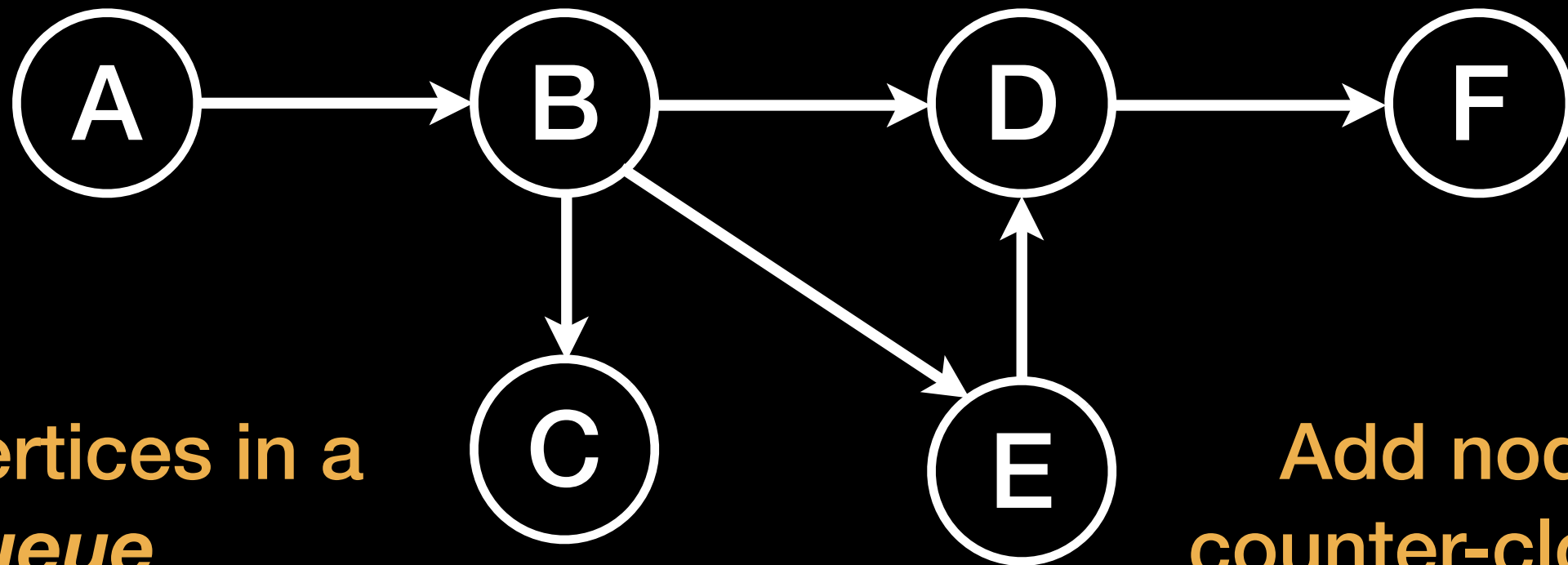
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Reachable:

Known:

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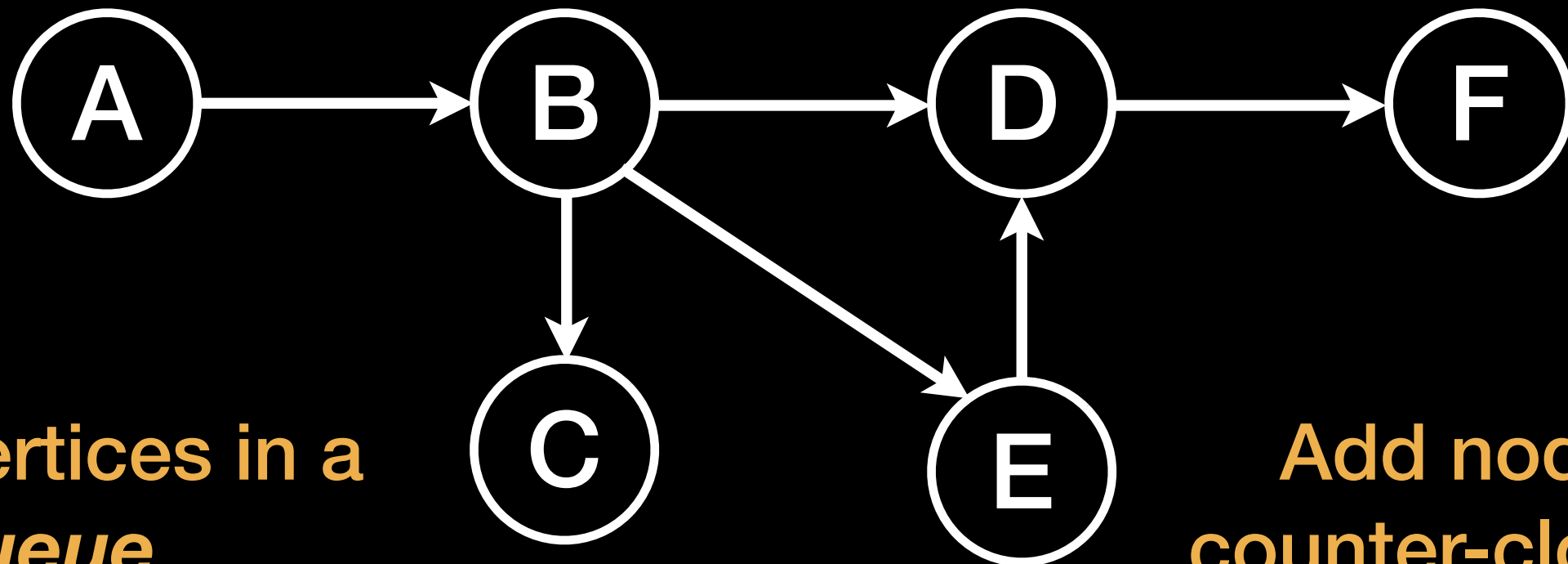
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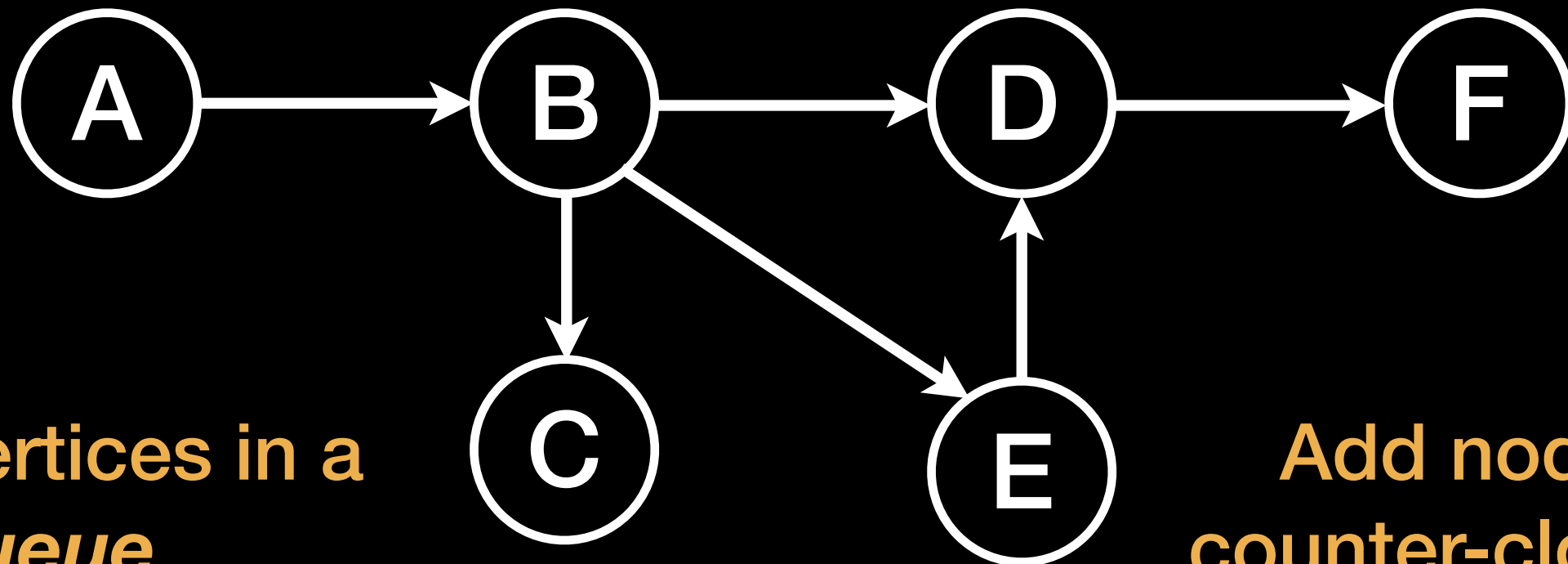
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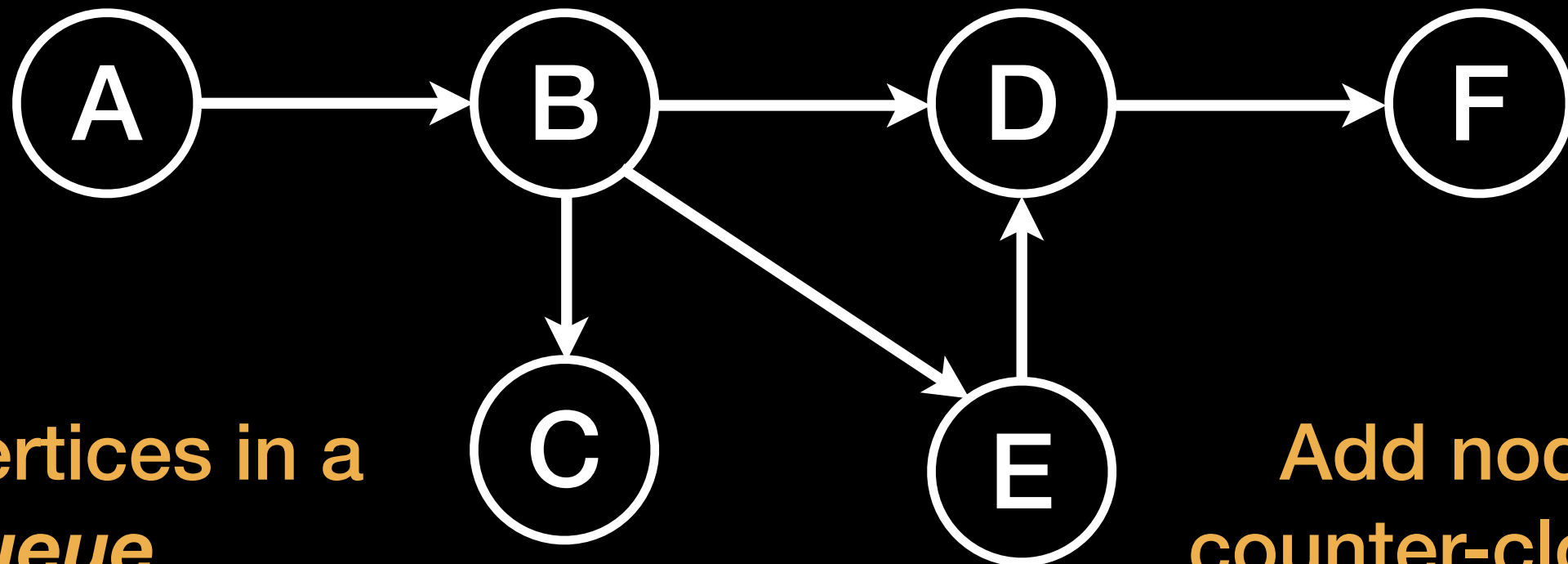
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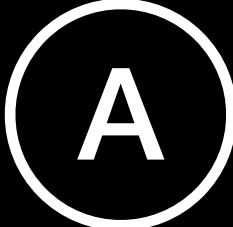
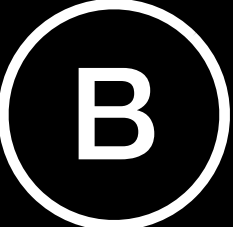
Known: 

Simulate **breadth-first search** on this graph



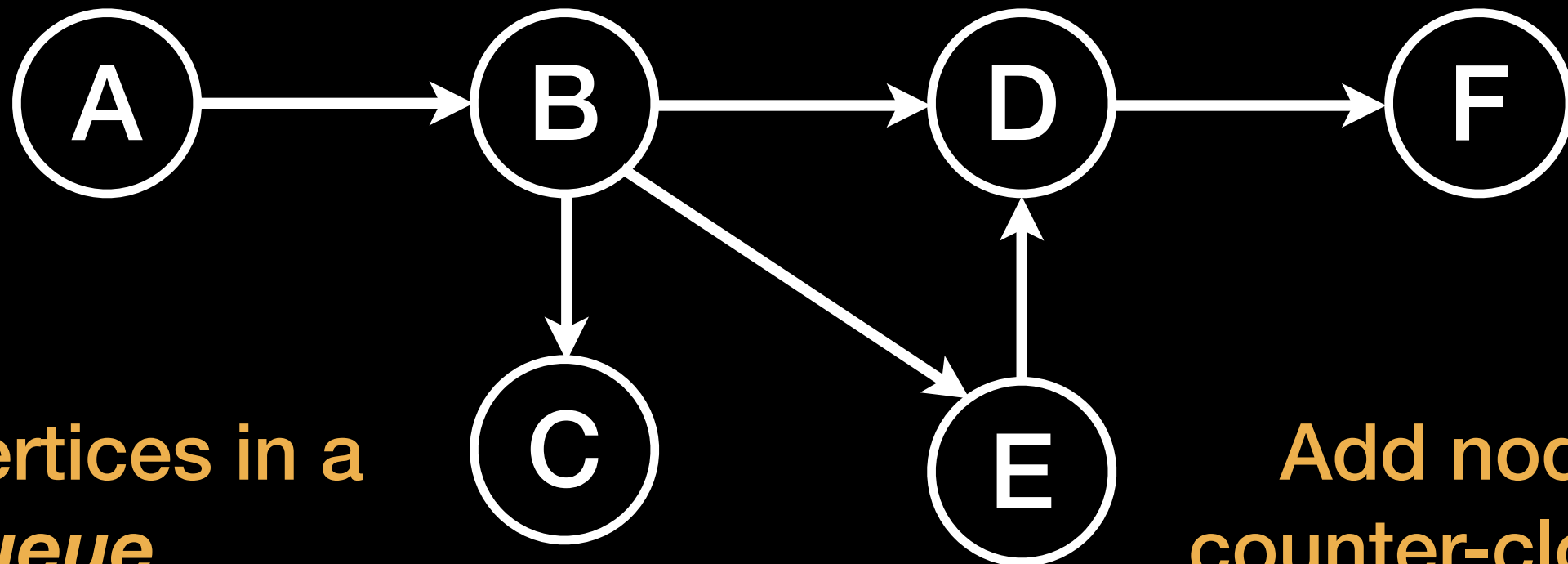
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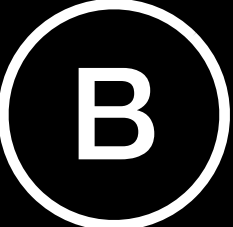
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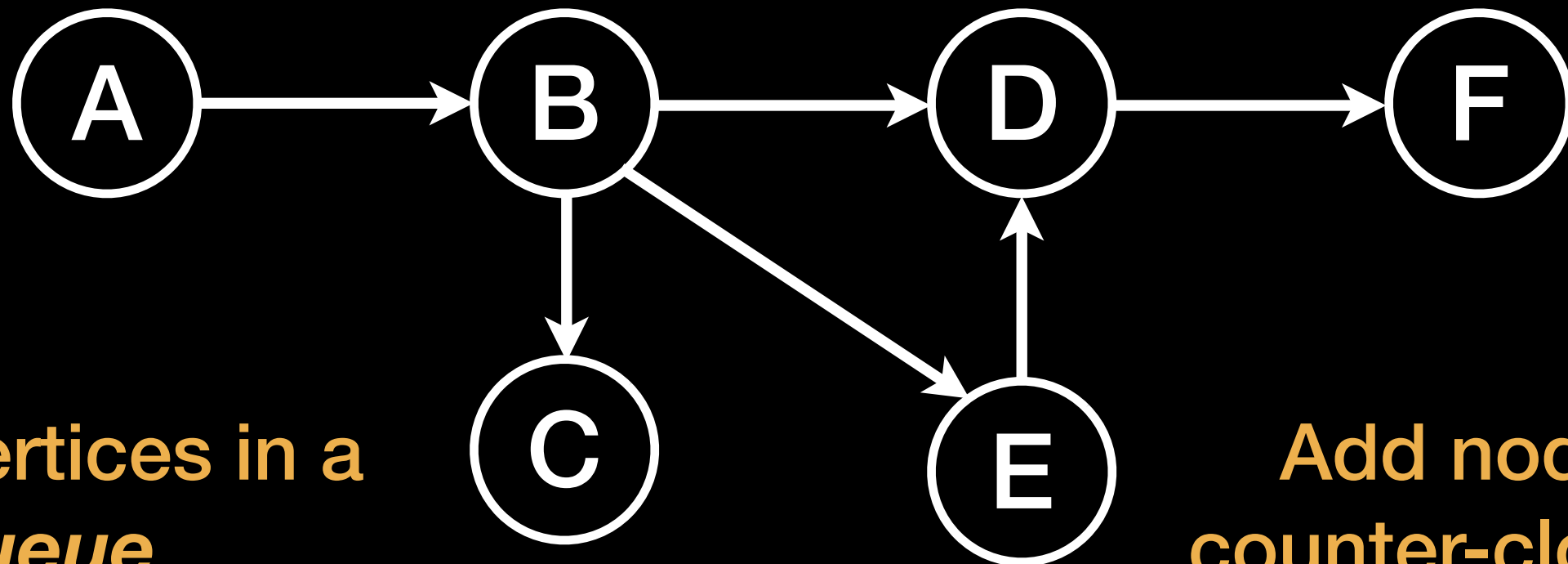
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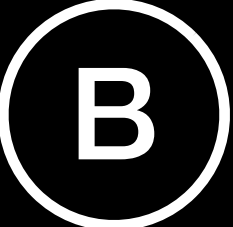
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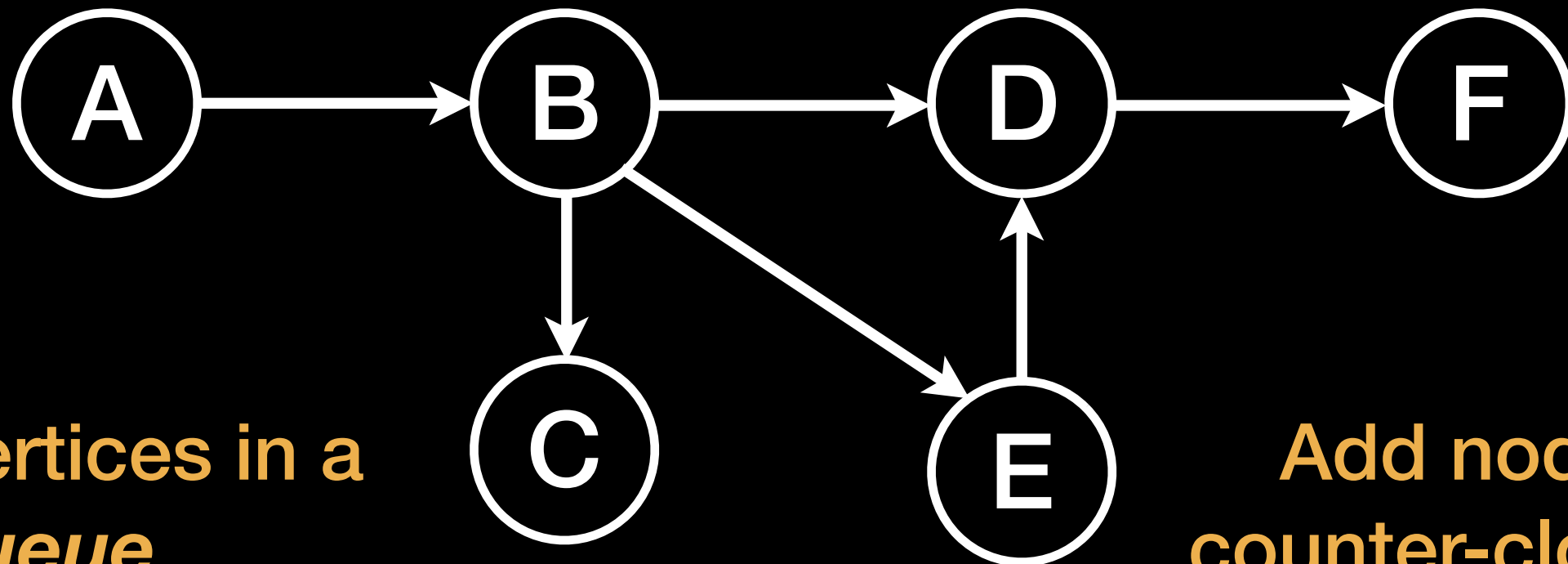
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Reachable:  

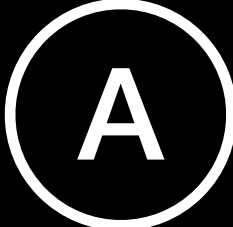
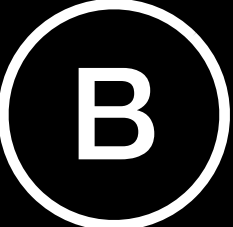
Known:  

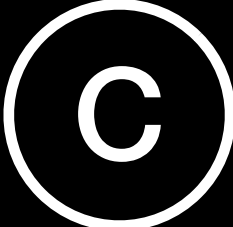
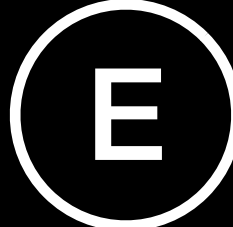
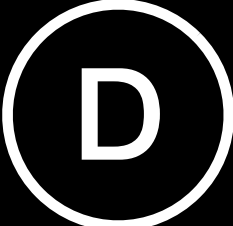
Simulate **breadth-first search** on this graph



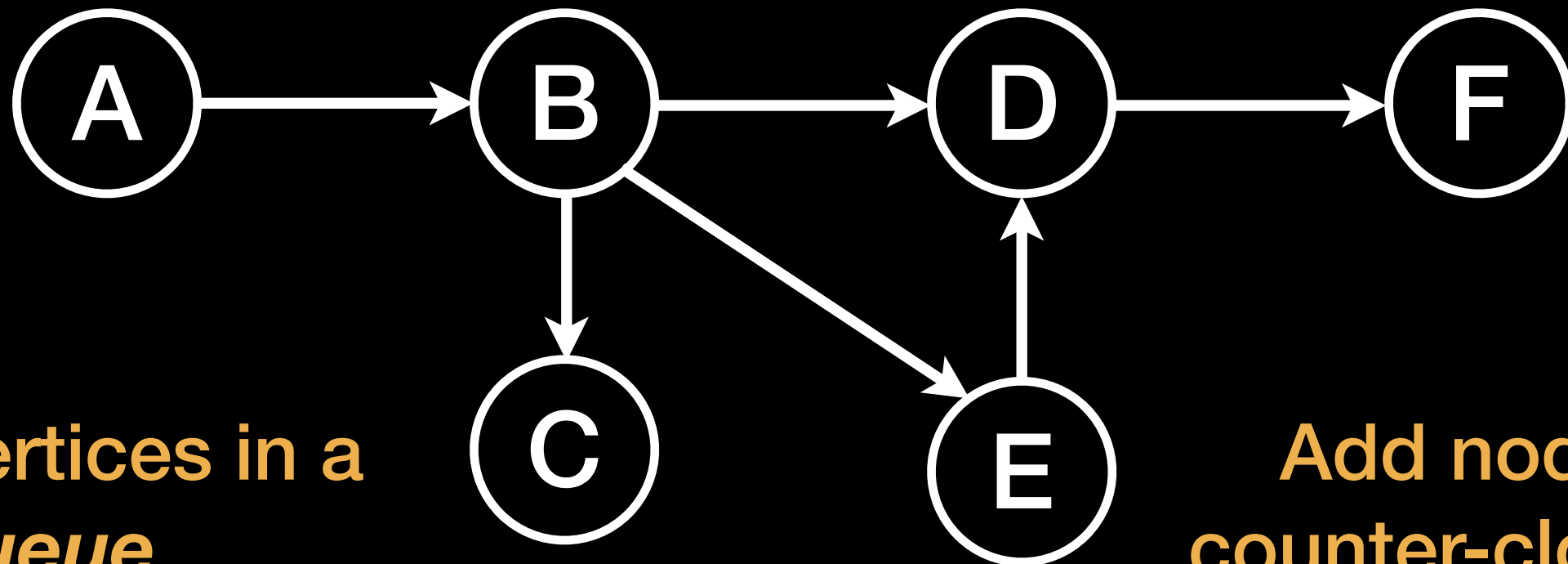
Store vertices in a
queue
(first in, first out)

Add nodes in
counter-clockwise
order

Reachable:  

Known:   

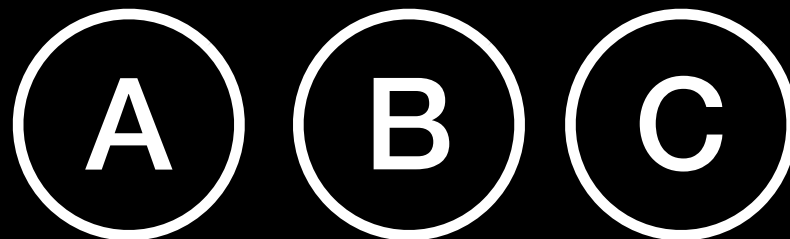
Simulate **breadth-first search** on this graph



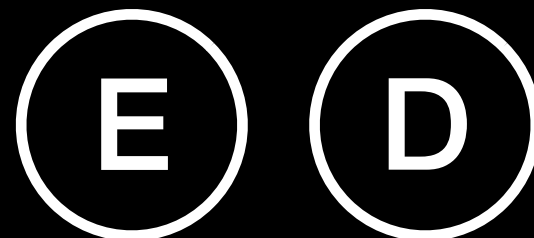
Store vertices in a
queue
(first in, first out)

Add nodes in
counter-clockwise
order

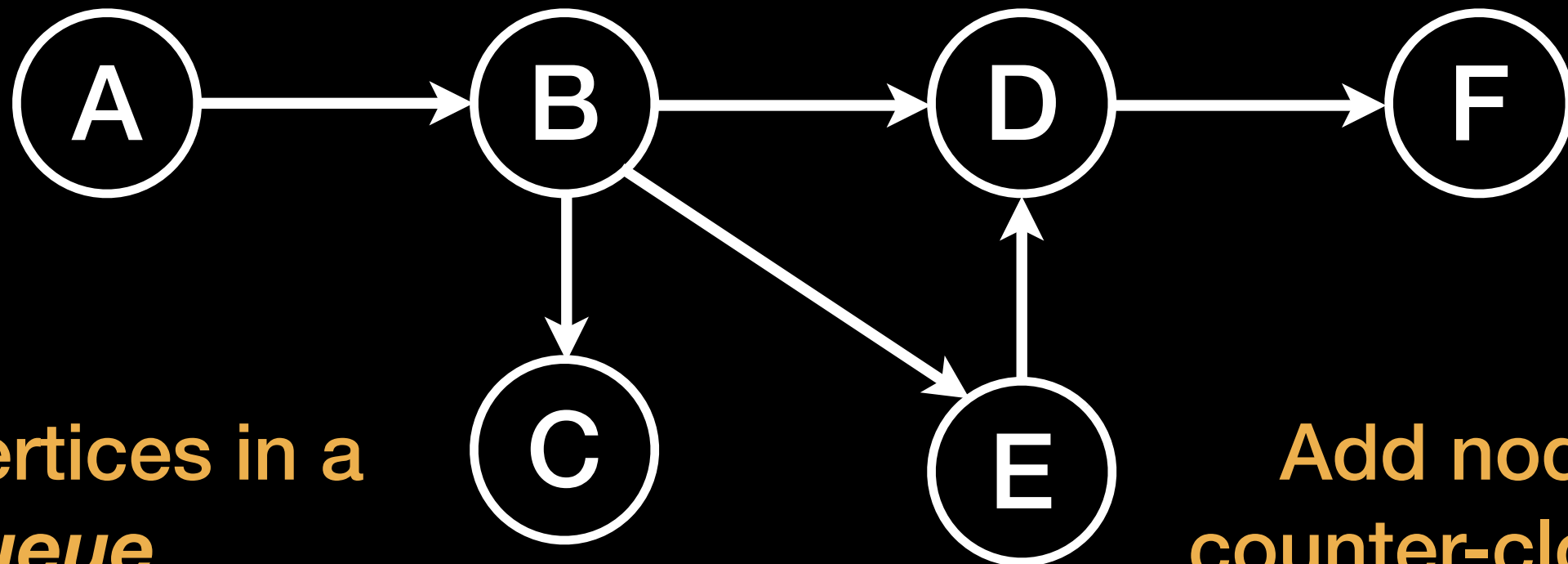
Reachable:



Known:



Simulate **breadth-first search** on this graph



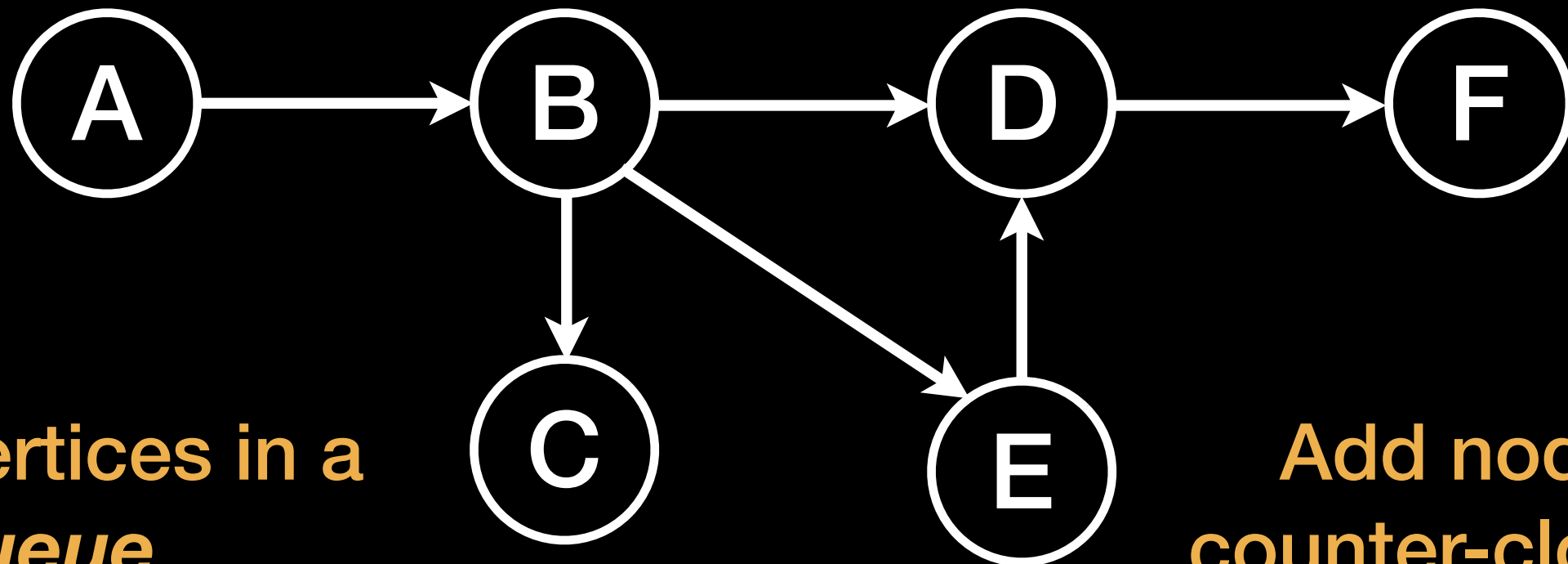
Store vertices in a
queue
(first in, first out)

Add nodes in
counter-clockwise
order

Reachable: A B C E

Known: D

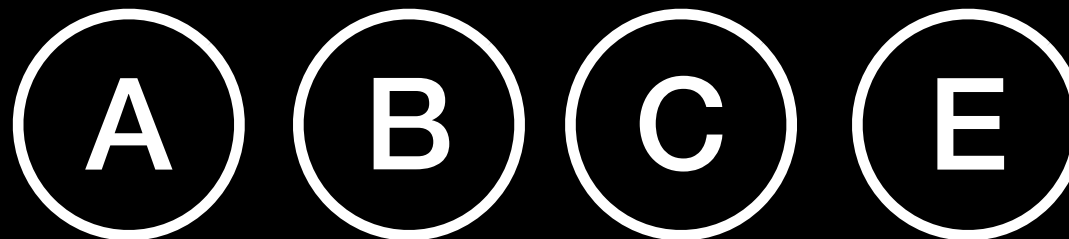
Simulate **breadth-first search** on this graph



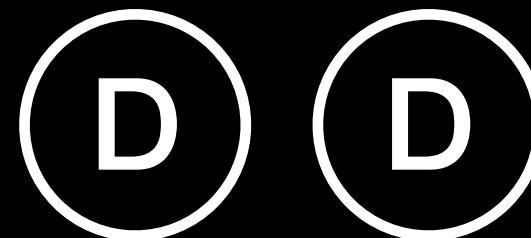
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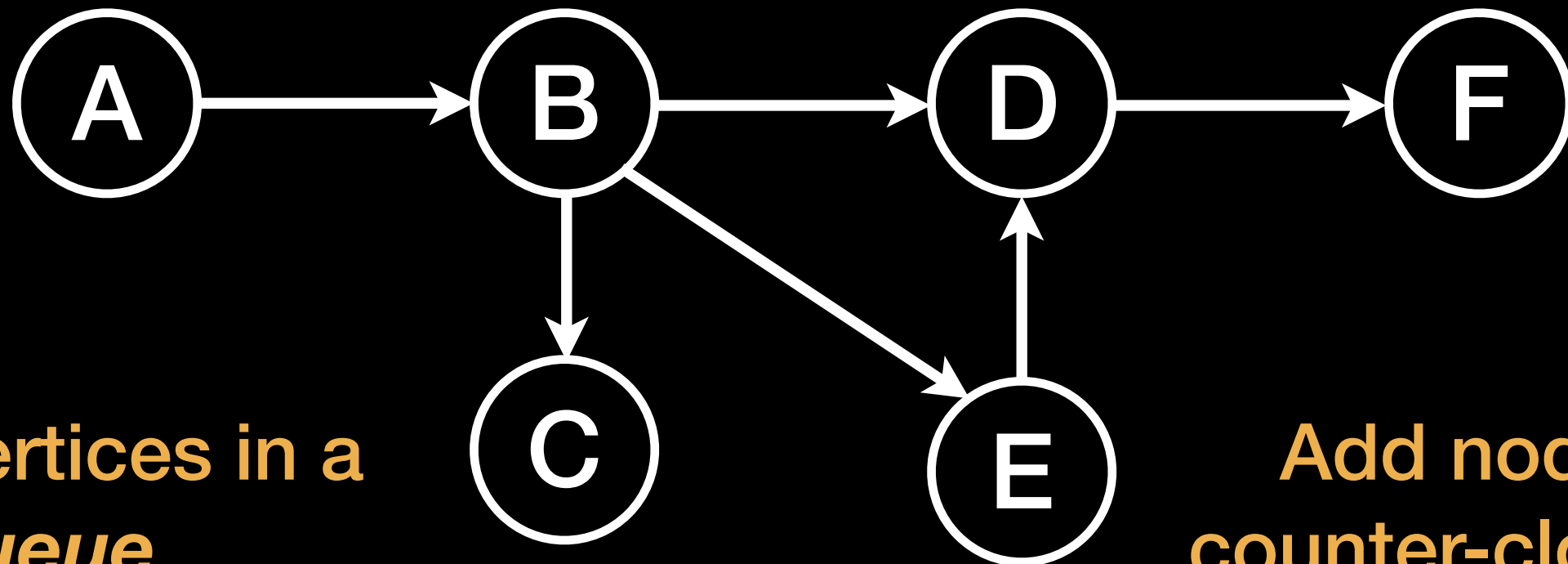
Reachable:



Known:



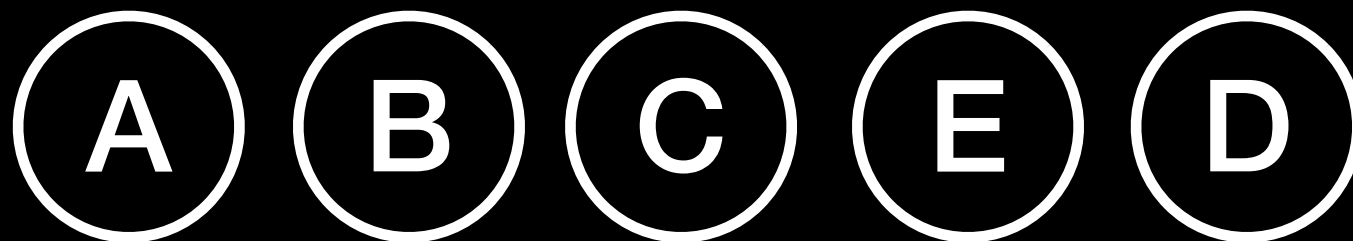
Simulate **breadth-first search** on this graph



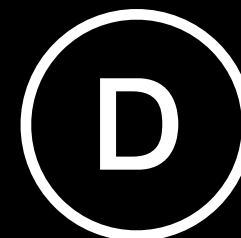
Store vertices in a
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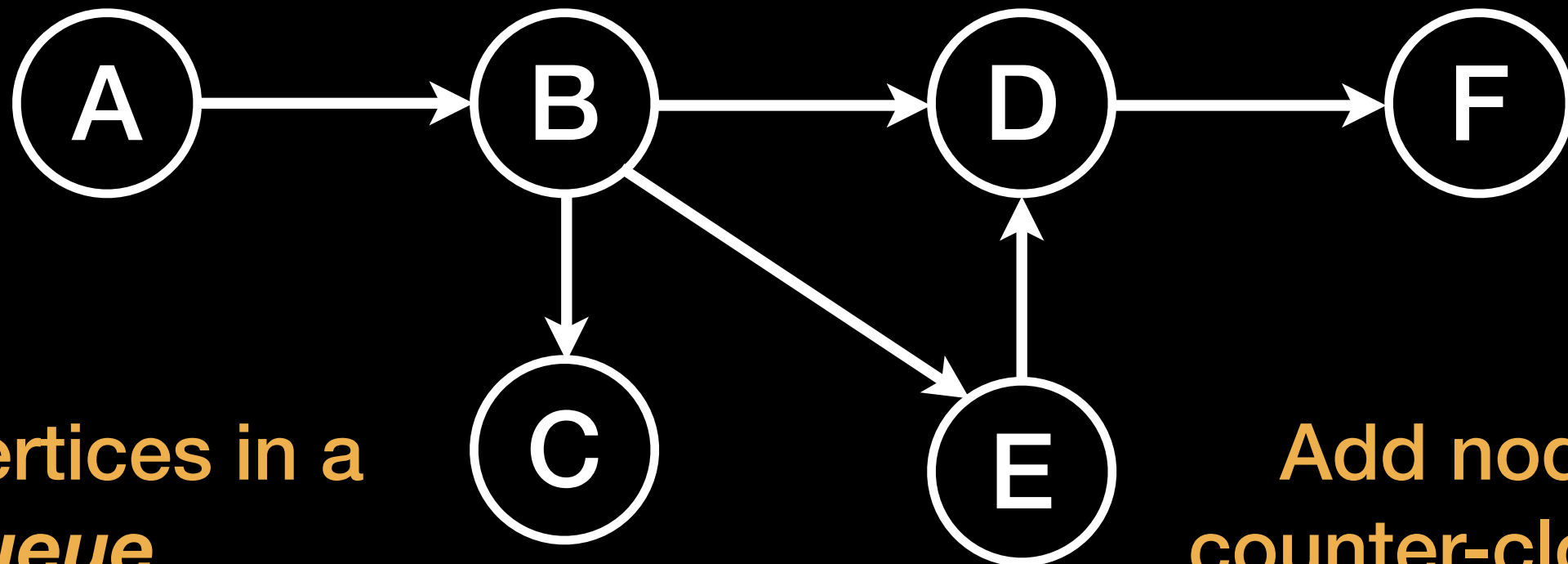
Reachable:



Known:



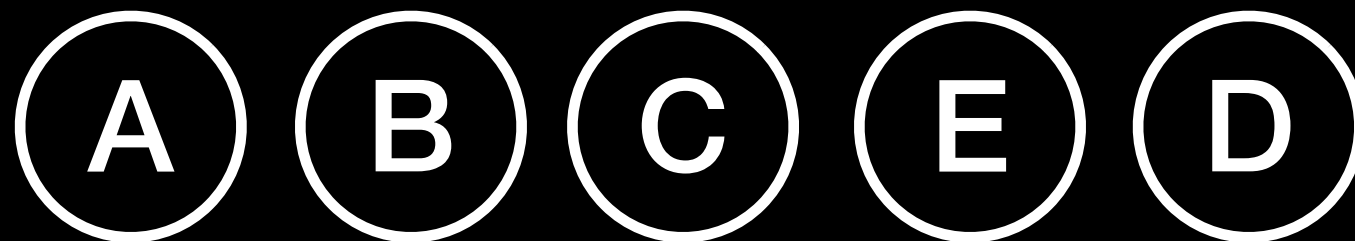
Simulate **breadth-first search** on this graph



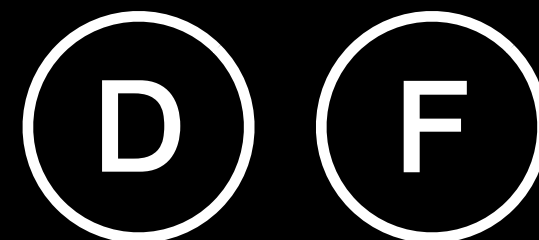
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counter-clockwise
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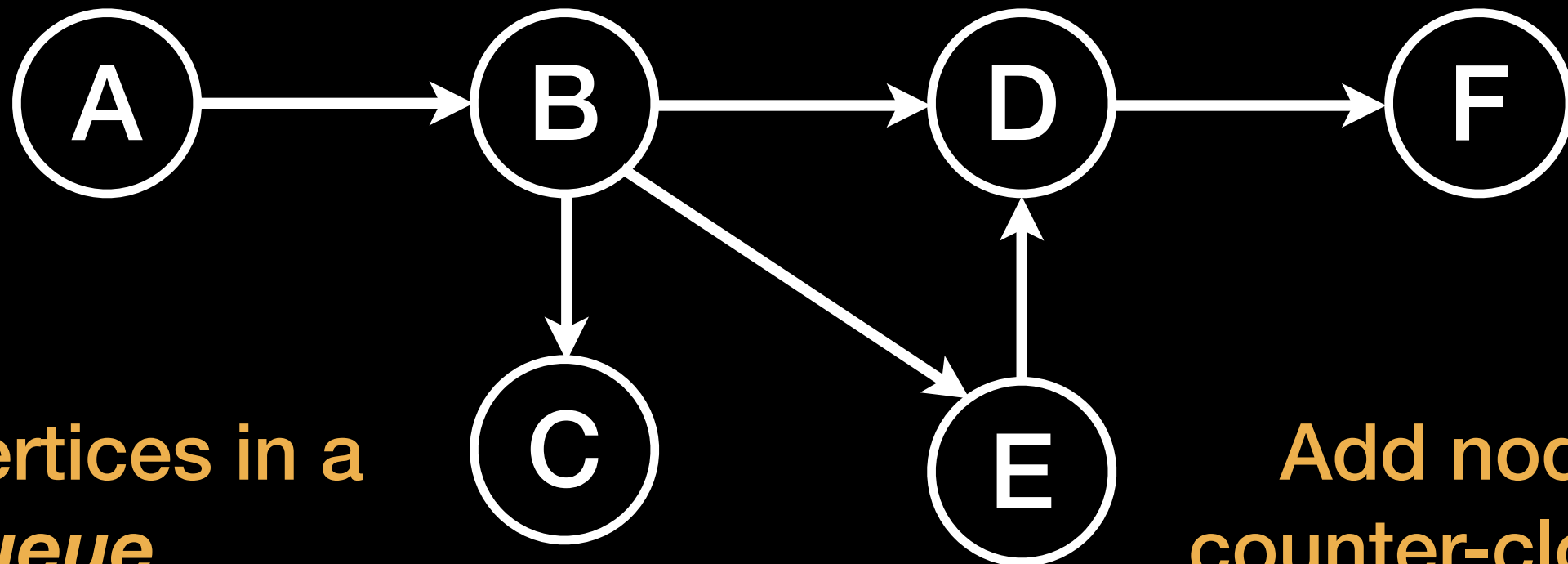
Reachable:



Known:



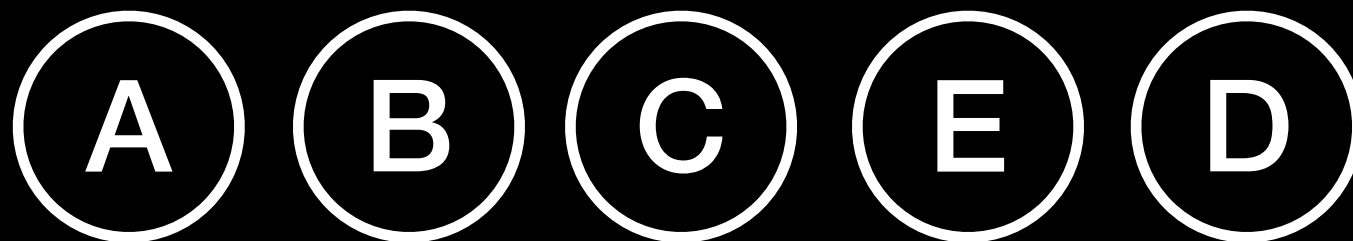
Simulate **breadth-first search** on this graph



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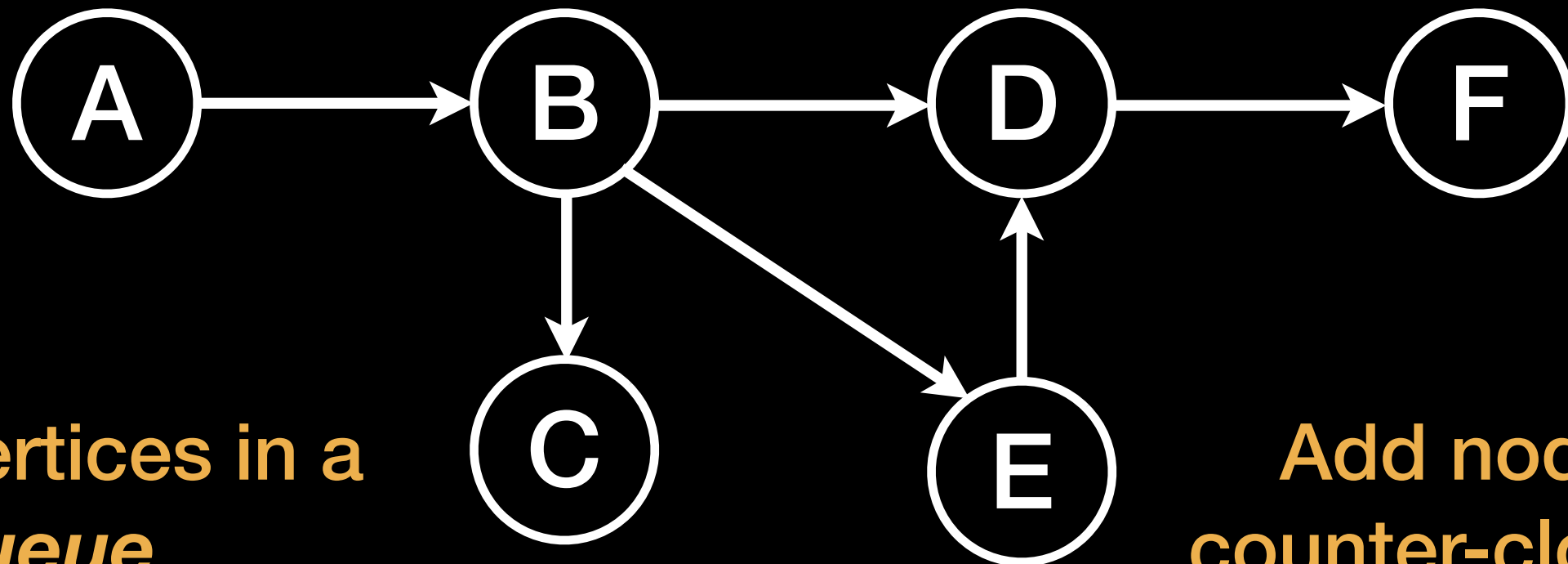
Reachable:



Known:



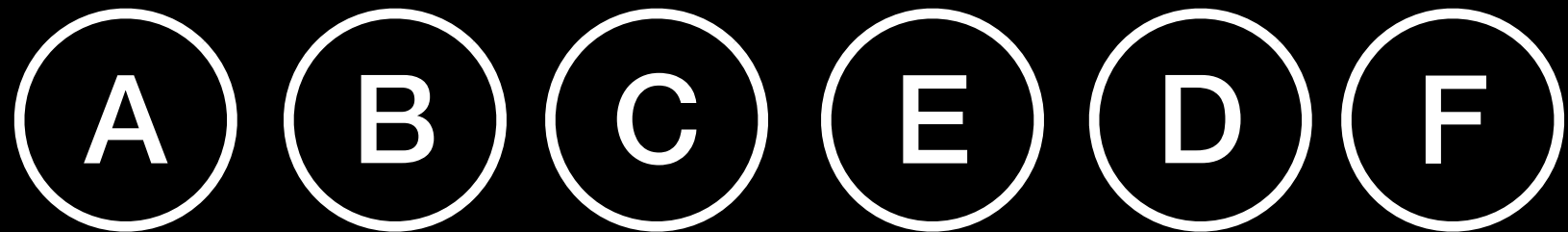
Simulate **breadth-first search** on this graph



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queue
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Add nodes in
counter-clockwise
order

Reachable:



Known: